

# MOTOMAN HC20DT

# Human-Collaborative Robot 6 integrated Sensors

MOTOMAN HC20DT is a 6 axes human-collaborative robot with a payload of up to 20 kg. Operator's safety is assured by a Power and Force Limit technology that stops the robot in case of contact with an operator.

The robot arm can be hand guided by an operator and robot positions and gripper operation can be registered via



"Teach" and "Tool" buttons. These features offer time saving during the robot programming. The robot's arm geometry was designed to avoid pinch points (finger).

The MOTOMAN HC20DT robot can operate without additional protective measures like a safety fence, depending on the risk assessment. This saves space and costs.

# **KEY BENEFITS**

# Controller

• Fully industrial robot controller YRC1000 and YRC1000micro

# **High safety**

- Contact force between operator and robot is limited to a safe level
- Safety by Design: rounded edges without pinch points (finger protections)
- Internal cable routing
- Safety standards applications for industrial robots: ISO 10218-1 (5.10.5 Power and Force Limiting)
- Complies to ISO TS 15066
- Safety functions industrial robot controller: ISO 13849-1, PLd, Cat. 3
- Functional Safety Unit included
- Safe Force/Torque Sensors in all 6 links

# Easy teaching

• Move the robot arm directly via hand guiding function: easy teaching mode with a switch box

# Safety and Speed

• Depending on the application, the MOTOMAN HC20DT can be switched between safe/collaborative mode in phases of man-robot-interaction, and returning into high speed when absence of the operator is detected by additional safety devices

Controlled by

'RC1000

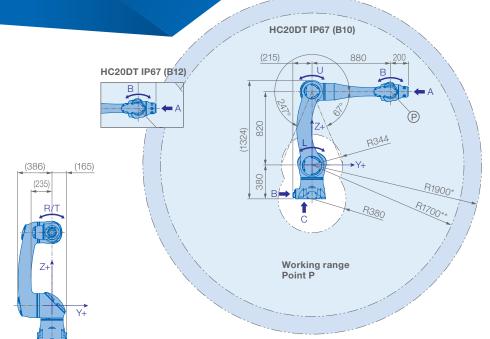
Controlled by

YRC1000





# MOTOMAN HC20DT



Absolute reach: S/L-Axis center of rotation to R/T-Axis center of rotation

(for collaborative operation)

HC20DT IP67 (B10)

10 kg

15 kg

0

200

300 400

R-, T-axis centre of rotation

Lamp A

Switch B

(for restart)

\*\* Effective reach: S/L-Axis center of rotation to Point P

**Allowable wrist load** 

느 300

200

150

R1900\*

R1700\*

P-point

B-axis centre of rotation

HC20DT IP67 (B12)

S-axis

no limit

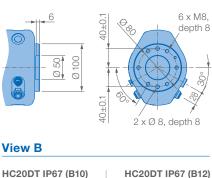
±60 max.

±45 max.

±30 max.

operating

range [deg.]



View A





# View C

## 260 I 30±0.1 106±0.1 106±0.1 53±0.1 153±0.1 30±0.1 $2 \times 0.12$ 4 x Ø 18 depth 12

Mounting options: Floor, ceiling, wall, tilt\* IP Protection: IP67

Internal

I/O cable

connector

(S)

\* tilt with condition of angle - see table left side



(218)



# HC20DT IP67 (B12)

#### Power cable of the external axis cable connector (EX-PW) Ethernet cable connector

Specifications HC20DT IP67 (B10 + B12)						
Axes	Maximum motion range [°]	Maximum speed [°/s]	Allowable moment [Nm]	Allowable moment of inertia [kg · m²]	Controlled axes	6
					Max. payload [kg]	20
S	±180	80	-	-	Repeatability [mm]	±0.05
L	±180	80	-	-	Max. working range R [mm]	1900*/1700**
U	+247/-67	120	-	-	Temperature [°C]	0 to +40
R	±210	130	58.8	4.0	Humidity [%]	20 - 80
В	±180	180	58.8	4.0	Weight [kg]	140
т	±210	180	29.4	2.0	Power supply, average [kVA]	1.5

500

500 LB

\* Absolute reach: S/L-Axis center of rotation to R/T-Axis center of rotation \*\* Effective reach: S/L-Axis center of rotation to Point P

### Yaskawa Europe GmbH

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Robot

installation

angle  $\theta$  [deg.]

 $0 \leq \Theta \leq 30$ 

 $30 < \Theta \leq 35$ 

 $35 < \Theta \leq 45$ 

 $45 < \Theta \leq 90$ 

wall mounting

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YR-1-06VXHC20-B10, YR-1-06VXHC20-B12 C-10-2021, A-No. 204094

All drawing dimensions in mm. Technical data may be subject to change without previous notice. Please request detailed drawings at robotics@yaskawa.eu.com.

