MotoRemote
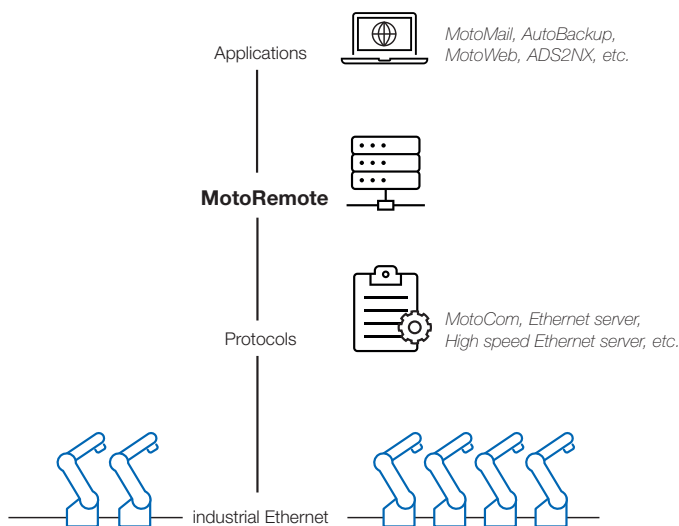
Handling a mixed setup of different controller generations and communication protocols simultaneously.

Applications — *MotoMail, AutoBackup, MotoWeb, ADS2NX, etc.*

MotoRemote

Protocols — *MotoCom, Ethernet server, High speed Ethernet server, etc.*

industrial Ethernet

Compatible with

MRC, XRC, NX100, DX100, DX200, FS100 YRC1000 and YRC1000Micro.

Communication for many-to-many

Multiple applications can share the same MotoRemote and access several robot controllers simultaneously, regardless of communication protocol or individual robot controller generation.

MotoRemote is a generic scalable communication proxy founded with a process scheduler for adding scheduled tasks. It is for example always delivered with the "Auto backup" functionality for scheduled backups of parameters and robot jobs and a function to store statistical robot usage data in a database.

MotoRemote is compatible with the controller generations from MRC to YRC1000. It utilizes MotoNis, MotoCom via Ethernet, Ethernet Server, High Speed Ethernet Server (which is preferable) or RS232 for communication with the robot controllers.

Key benefits

- Automatic backup function.
- Easy to schedule regular backups (hourly, daily, monthly etc.)
- Possible to configure the storage time for backups.