YASKAWA

System SLIO

SM-DIO | | Manual

HB300 | SM-DIO | | en | 25-10

Digital signal modules - SM 02x

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1 General

1.1 About this manual

Objective and contents

This manual describes the Digital signal modules of the System SLIO.

- It describes the structure, configuration and application.
- The manual is targeted at users with good basic knowledge in automation technology.
- The manual does not replace sufficient basic knowledge of automation technology or sufficient familiarity with the specific product.
- The manual consists of chapters. Each chapter describes a completed topic.
- For guidance, the manual provides:
  - An overall table of contents at the beginning of the manual
  - References with pages numbers

Documentation

In the context of the use of the pertinent Yaskawa product, the manual is to be made accessible to the pertinent qualified personnel in:

- Project engineering
- Installation department
- Commissioning
- Operation

Icons and headings

Important passages in the text are highlighted by following icons and headings:

DANGER

- Immediate danger to life and limb of personnel and others.
- Non-compliance will cause death or serious injury.

CAUTION

- Hazardous situation to life and limb of personnel and others. Non-compliance may cause slight injuries.
- This symbol is also used as warning of damages to property.

NOTICE

- Designates a possibly harmful situation.
- Non-compliance can damage the product or something in its environment.

Supplementary information and useful tips.

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1.3 Safety instructions

General safety instructions

DANGER

Danger to life due to non-compliance with safety instructions

Non-compliance with the safety instructions in the manual can result in serious injury or death. The manufacturer is not responsible for any injuries or damage to the equipment.

CAUTION

Before commissioning and operating the components described in this manual, it is essential to note the following:

- Modifications to the automation system must only be done in a voltage-free state!
- Connection and modification only by trained electricians
- National regulations and guidelines in the respective country of use must be observed and complied with (installation, protective measures, EMC, etc.)

Intended use

- It is the customer's responsibility to comply with all pertinent standards, codes, or regulations applicable to the use of the product, including those that apply when the Yaskawa product is used in combination with other products.
- The customer must confirm that the Yaskawa product is suitable for the customer's plant, machinery and equipment.
- If the Yaskawa product is used in a manner not specified by this manual, the protection provided by the Yaskawa product may be impaired and the use may result in material or immaterial damage.
- Contact Yaskawa to determine whether use is permitted in the following applications. If the use in the respective application is permissible, the Yaskawa product is to be used by considering additional risk assessments and specifications, and safety measures are to be provided to minimise the dangers in the event of a fault. Special caution is required and protective measures must be taken in the case of:
  - Outdoor use, use with possible chemical contamination or electrical interference, or use under conditions or in environments which are not described in product catalogs or manuals
  - Nuclear control systems, combustion systems, railway systems, aviation systems, automotive systems, medical devices, amusement machines and equipment that is specifically regulated by industry or government
  - Systems, machines and devices that can pose a risk to life or property
  - Systems that require a high degree of reliability, such as gas, water or electricity supply systems or systems that operate 24 hours a day
  - Other systems that require a similarly high level of security
- Never use the Yaskawa product in an application where failure of the product could cause serious danger to life, limb, health or property without first ensuring that the system is designed to provide the required level of safety with risk warnings and redundancy to avoid the realisation of such dangers and that the Yaskawa product is properly designed and installed.
- The connection examples and other application examples described in the product catalogs and manuals of Yaskawa are for reference purposes. Check the functionality and safety of the devices and systems actually to be used before using the Yaskawa product.
- To avoid accidental harm to third parties, read and understand all prohibitions on use and precautions, and operate the Yaskawa product correctly.

Field of application

- The Yaskawa product is not suited for use in life-support machines or systems.
- Please contact your Yaskawa representative or Yaskawa distributor if considering the use of the Yaskawa product for special purposes, such as machines or systems used in passenger cars, in medical, aircraft and aerospace applications, for power supply of networks, for electrical power distribution or for underwater applications.

DANGER

The device is not permitted for use

– in explosive environments (EX zone)

The system is designed and manufactured for proper use and use in accordance with the user manual and is designed for:

- Communication and process control
- general control and automation tasks
- for industrial use
- operation within the environmental conditions specified in the technical data
- installation in a cabinet

DANGER

If this Yaskawa product is used in applications where failure of the device can result in the loss of human life, a serious accident or physical injury, you must install appropriate safety devices.

– Death or serious injury can result if you do not install the safety devices properly.

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(1) The contractual and legal liability of Yaskawa and the legal representatives and vicarious agents of Yaskawa for compensation and reimbursement of expenses in relation to the content of this documentation is excluded or limited as follows:

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(3) A reversal of the burden of proof is not associated with the provisions above.

Disposal

National rules and regulations apply to the disposal of the unit!

2 Basics and mounting

2.1 Safety notes for the user

DANGER

Protection against dangerous voltages

- When using System SLIO modules, the user must be protected from touching hazardous voltage.
- You must therefore create an insulation concept for your system that includes safe separation of the potential areas of extra-low voltage (ELV) and hazardous voltage.
- Here, observe the insulation voltages between the potential areas specified for the System SLIO modules and take suitable measures, such as using PELV/SELV power supplies for System SLIO modules.

Handling of electrostatic sensitive modules

The modules are equipped with highly integrated components in MOS technology. These components are highly sensitive to over-voltages that occur, e.g. with electrostatic discharge. The following symbol is used to identify these hazardous modules:

The symbol is located on modules, module racks or on packaging and thus indicates electrostatic sensitive modules. Electrostatic sensitive modules can be destroyed by energies and voltages that are far below the limits of human perception. If a person who is not electrically discharged handles electrostatic sensitive modules, voltages can occur and damage components and thus impair the functionality of the modules or render the modules unusable. Modules damaged in this way are in most cases not immediately recognized as faulty. The error can only appear after a long period of operation. Components damaged by static discharge can show temporary faults when exposed to temperature changes, vibrations or load changes. Only the consistent use of protective devices and responsible observance of the handling rules can effectively prevent malfunctions and failures on electrostatic sensitive modules.

Shipping of modules

Please always use the original packaging for shipping.

Measurement and modification of electrostatic sensitive modules

For measurements on electrostatic sensitive modules the following must be observed:

- Floating measuring instruments must be discharged before use.
- Measuring instruments used must be grounded.

When modifying electrostatic sensitive modules, ensure that a grounded soldering iron is used.

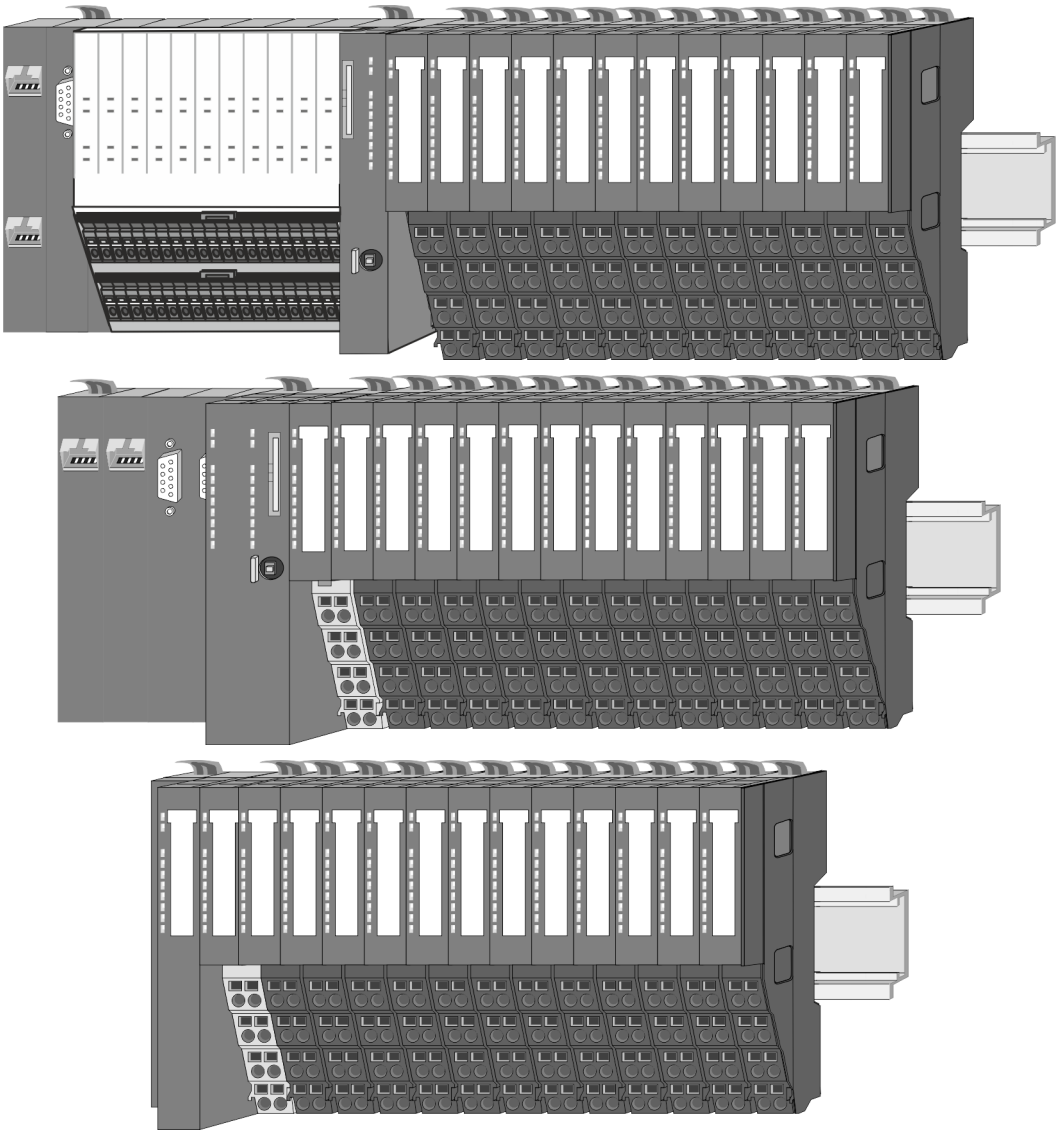
CAUTION

When working with and on electrostatic sensitive modules, make sure that personnel and equipment are adequately grounded.

2.2 System conception

2.2.1 Overview

The System SLIO is a modular automation system for assembly on a 35mm profile rail. By means of the periphery modules with 2, 4, 8 and 16 channels this system may properly be adapted matching to your automation tasks. The wiring complexity is low, because the supply of the DC 24V power section supply is integrated to the backplane bus and defective modules may be replaced with standing wiring. By deployment of the power modules in contrasting colors within the system, further isolated areas may be defined for the DC 24V power section supply, respectively the electronic power supply may be extended with 2A.



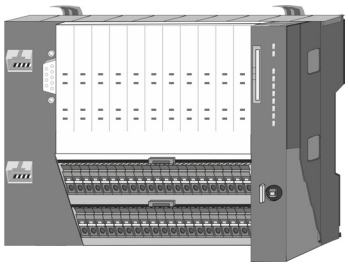
2.2.2 Components

- CPU (head module)
- Bus coupler (head module)
- Line extension
- 8x periphery modules
- 16x periphery modules
- Power modules
- Accessories

CAUTION

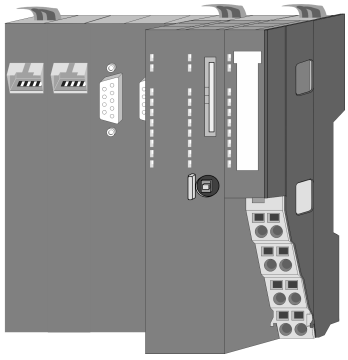
Only Yaskawa modules may be combined. A mixed operation with third-party modules is not allowed!

CPU 01xC



With the CPU 01xC electronic, input/output components and power supply are integrated to one casing. In addition, up to 64 periphery modules of the System SLIO can be connected to the backplane bus. As head module via the integrated power module for power supply CPU electronic and the I/O components are supplied as well as the electronic of the periphery modules, which are connected via backplane bus. To connect the power supply of the I/O components and for DC 24V power section supply of via backplane bus connected periphery modules, the CPU has removable connectors. By installing of up to 64 periphery modules at the backplane bus, these are electrically connected, this means these are assigned to the backplane bus, the electronic modules are power supplied and each periphery module is connected to the DC 24V power section supply.

CPU 01x



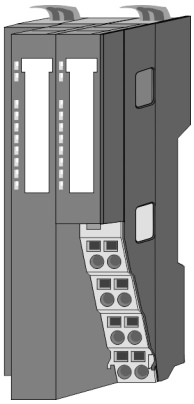
With this CPU 01x, CPU electronic and power supply are integrated to one casing. As head module, via the integrated power module for power supply, CPU electronic and the electronic of the connected periphery modules are supplied. The DC 24V power section supply for the linked periphery modules is established via a further connection of the power module. By installing of up to 64 periphery modules at the backplane bus, these are electrically connected, this means these are assigned to the backplane bus, the electronic modules are power supplied and each periphery module is connected to the DC 24V power section supply.

CAUTION

CPU part and power module may not be separated!

Here you may only exchange the electronic module!

Bus coupler



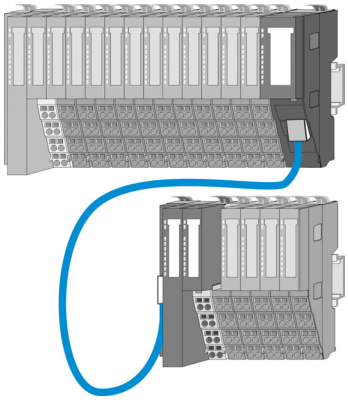
With a bus coupler bus interface and power module is integrated to one casing. With the bus interface you get access to a subordinated bus system. As head module, via the integrated power module for power supply, bus interface and the electronic of the connected periphery modules are supplied. The DC 24V power section supply for the linked periphery modules is established via a further connection of the power module. By installing of up to 64 periphery modules at the bus coupler, these are electrically connected, this means these are assigned to the backplane bus, the electronic modules are power supplied and each periphery module is connected to the DC 24V power section supply.

CAUTION

Bus interface and power module may not be separated!

Here you may only exchange the electronic module!

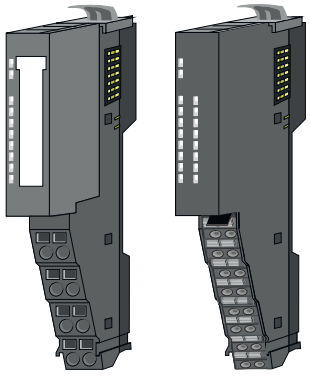
Line extension



In the System SLIO there is the possibility to place up to 64 modules in on line. By means of the line extension you can divide this line into several lines. Here you have to place a line extension MainDevice at each end of a line and the subsequent line has to start with a line extension SubDevice. MainDevice and SubDevice are to be connected via a special connecting cable. In this way, you can divide a line on up to 5 lines. Depending on the line extension, the max. number of pluggable modules at the System SLIO bus is decreased accordingly. To use the line extension no special configuration is required.

Please note that some modules do not support line extensions due to the system. For more information, please refer to the compatibility list. This can be found in the 'Download Center' of www.yaskawa.eu.com under 'System SLIO Compatibility list'.

Periphery modules

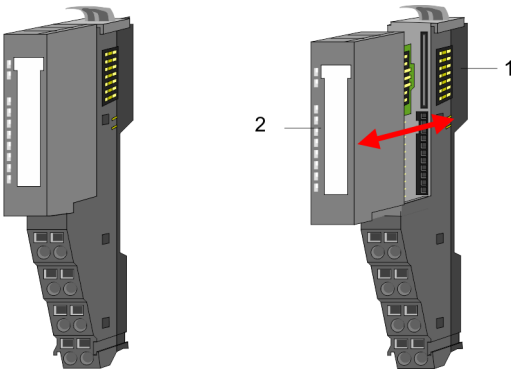


The periphery modules are available in the following 2 versions, whereby of each the electronic part can be replaced with standing wiring:

- 8x periphery module for a maximum of 8 channels.
- 16x periphery module for a maximum of 16 channels.

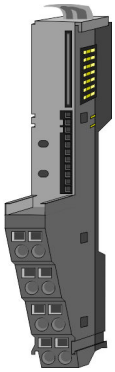
8x periphery modules

Each 8x periphery module consists of a *terminal* and an *electronic module*.



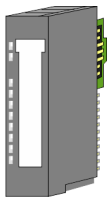
1 Terminal module
2 Electronic module

Terminal module



The *terminal* module serves to carry the electronic module, contains the backplane bus with power supply for the electronic, the DC 24V power section supply and the staircase-shaped terminal for wiring. Additionally the terminal module has a locking system for fixing at a profile rail. By means of this locking system your system may be assembled outside of your switchgear cabinet to be later mounted there as whole system.

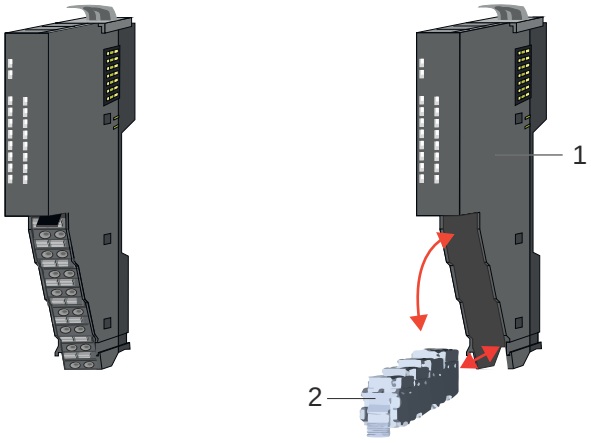
Electronic module



The functionality of a periphery module is defined by the *electronic module*, which is mounted to the terminal module by a sliding mechanism. With an error the defective electronic module may be exchanged for a functional module with standing installation. At the front side there are LEDs for status indication. For simple wiring each module shows corresponding connection information at the front and at the side.

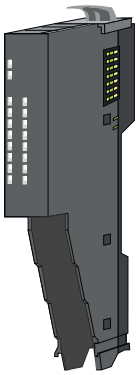
16x periphery modules

Each 16x periphery module consists of an *electronic unit* and a *terminal block*.



1 Electronic unit
2 Terminal block

Electronic unit

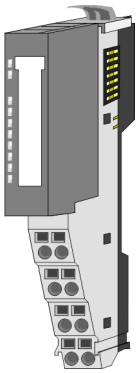


With the 16x periphery module the terminal block is connected to the *electronic unit* via a secure flap mechanism. In the case of an error you can exchange the defective electronic unit for a functional unit with standing wiring. At the front side there are LEDs for status indication. For easy wiring each electronic unit shows corresponding connection information at the side. The electronic unit provides the slot for the terminal block for the wiring and contains the backplane bus with power supply for the electronic and the connection to the DC 24V power section supply. Additionally the electronic unit has a locking system for fixing it at a profile rail. By means of this locking system your system may be assembled outside of your switchgear cabinet to be later mounted there as whole system.

Terminal block

The *terminal block* provides the electrical interface for the signalling and supplies lines of the module. When mounting the terminal block, it is attached to the bottom of the electronic unit and turned towards the electronic unit until it clicks into place. With the wiring a "push-in" spring-clip technique is used. This allows a quick and easy connection of your signal and supply lines. The clamping off takes place by means of a screwdriver.

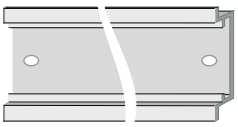
Power module



In the System SLIO the power supply is established by power modules. These are either integrated to the head module or may be installed between the periphery modules. Depending on the power module isolated areas of the DC 24V power section supply may be defined respectively the electronic power supply may be extended with 2A. For better recognition the colour of the power modules are contrasting to the periphery modules.

2.2.3 Accessories

Profile rail



Order no.	Description
290-1AF00	35 mm profile rail length 2000mm
290-1AF30	35 mm profile rail length 530mm

NOTICE

To ensure EMC, the profile rail must be grounded!

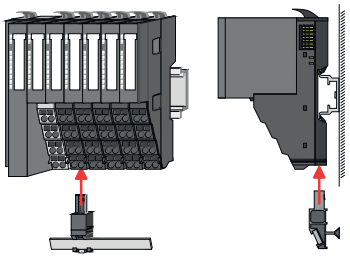
- Ensure that the profile rail is reliably and professionally grounded.
- By mounting them on the grounded profile rail, the modules are automatically connected to the grounding system.

'Grounding guidelines'...page 22

'Installation guidelines'...page 46

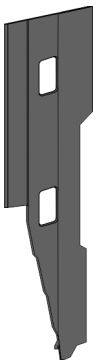
Shield bus carrier

Please note that a shield bus carrier cannot be mounted on a 16x periphery module!



The shield bus carrier (order no.: 000-0AB00) serves to carry the shield bus (10mm x 3mm) to connect cable shields. Shield bus carriers, shield bus and shield fixings are not in the scope of delivery. They are only available as accessories. The shield bus carrier is mounted underneath the terminal of the terminal module. With a flat profile rail for adaptation to a flat profile rail you may remove the spacer of the shield bus carrier.

Bus cover



With each head module, to protect the backplane bus connectors, there is a mounted bus cover in the scope of delivery. You have to remove the bus cover of the head module before mounting a System SLIO module. For the protection of the backplane bus connector you always have to mount the bus cover at the last module of your system again. The bus cover has the order no. 000-0AA00.

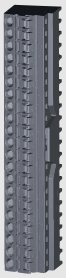
Coding pins

Please note that a coding pin cannot be installed on a 16x periphery module! Here you have to make sure that the associated terminal block is plugged again when the electronics unit is replaced.

There is the possibility to fix the assignment of electronic and terminal module. Here coding pins (order number 000-0AC00) can be used. The coding pin consists of a coding jack and a coding plug. By combining electronic and terminal module with coding pin, the coding jack remains in the electronic module and the coding plug in the terminal module. This ensures that after replacing the electronic module just another electronic module can be plugged with the same encoding.

Spare parts

The following spare parts are available for the System SLIO:

Spare part	Order no.	Description	Packaging unit
	092-9BH00	Terminal block for System SLIO 16x periphery module.	5 pieces
	092-9BK00	Connector for System SLIO CPU 013C.	5 pieces

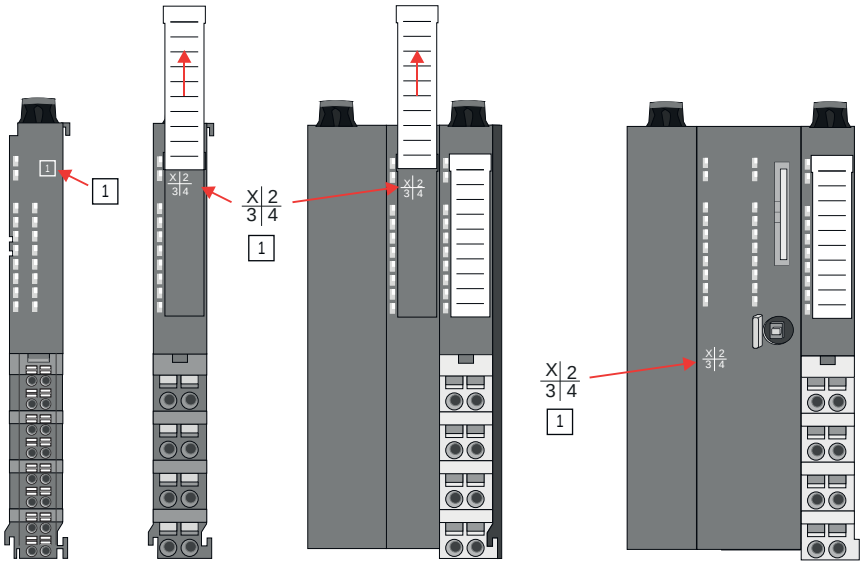
CAUTION

Please note that you may only use the spare parts with Yaskawa modules. Use with third-party modules is not allowed!

2.2.4 Hardware revision

Hardware revision on the front

- The hardware revision is printed on every System SLIO module.
- Since a System SLIO 8x periphery module consists of a terminal and electronic module, you will find a hardware revision printed on each of them.
- Authoritative for the hardware revision of a System SLIO module is the hardware revision of the electronic module. This is located under the labeling strip of the corresponding electronic module.
- Depending on the module type, there are the following 2 variants e.g. to indicate hardware revision 1:
  - With current labelling there is a 1 on the front.
  - With earlier labelling, the 1 is marked with *'X'* on a number grid.



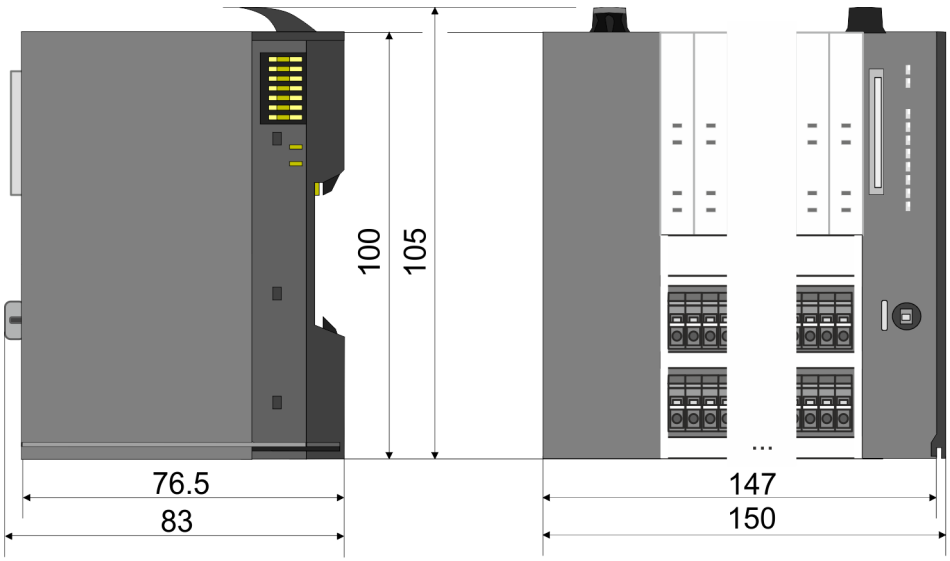
Hardware revision via web server

On the CPUs and some bus couplers, you can check the hardware revision *'HW Revision'* via the integrated web server.

2.3 Dimensions

CPU 01xC

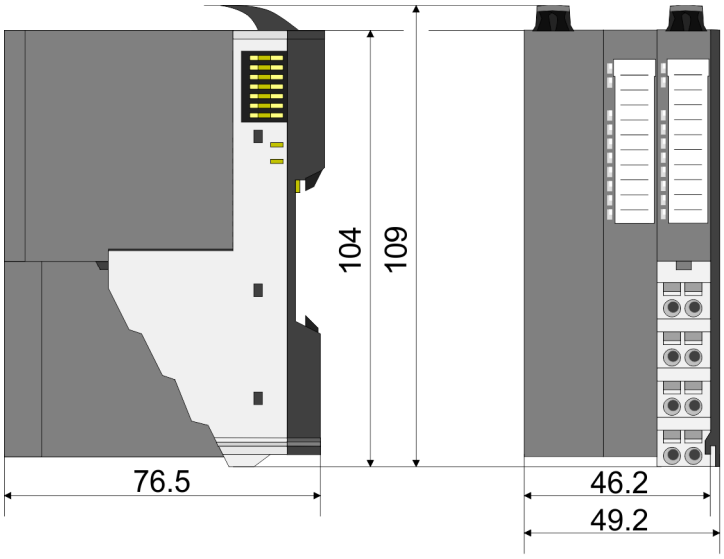
All dimensions are in mm.



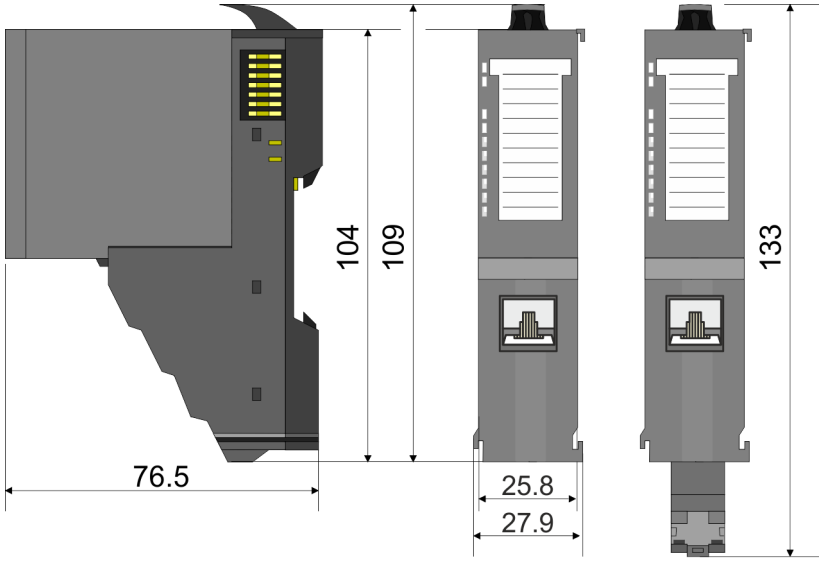
Dimensions

CPU 01x

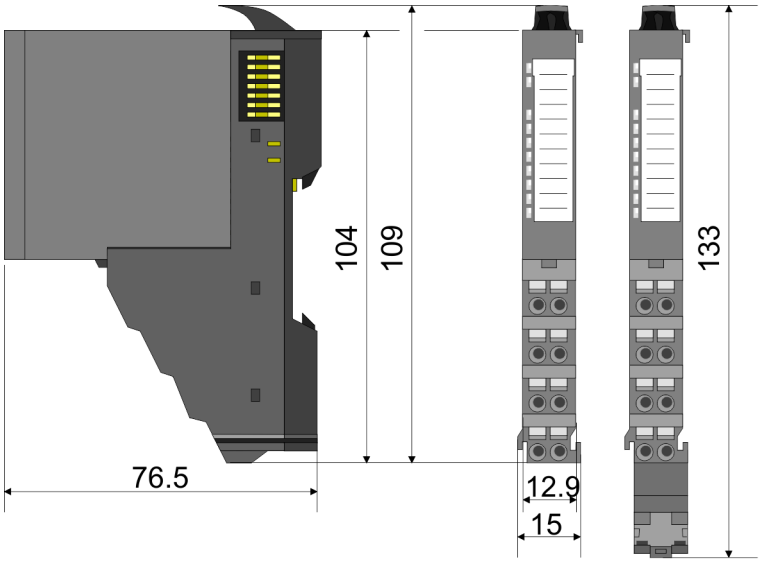
Bus coupler and line extension SubDevice



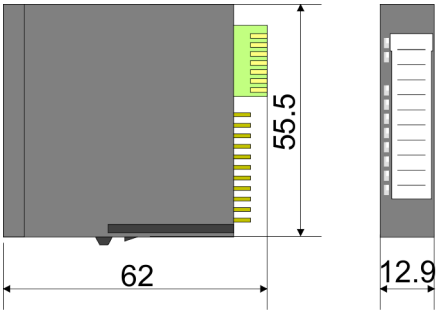
Line extension MainDevice



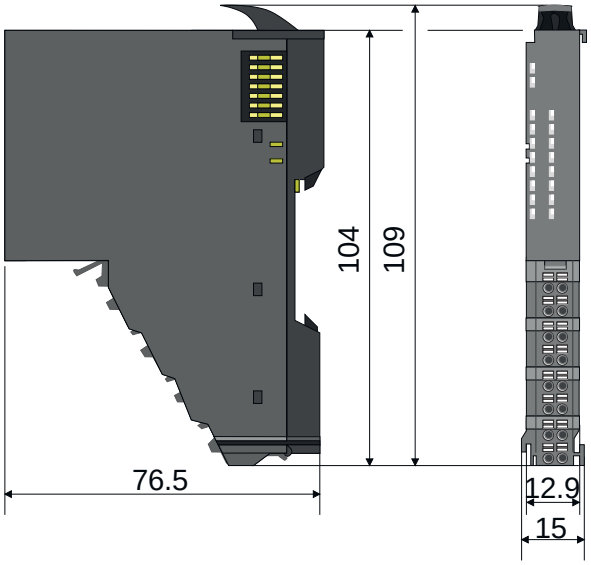
8x periphery module



Electronic module



16x periphery module



2.4 Grounding concept

Grounding guidelines

For reliable grounding, ensure that all common ground connections and the functional earth (FE) of your System SLIO and all connected devices are connected to a central point and grounded there.

NOTICE

To ensure EMC, the profile rail must be grounded!

- Ensure that the profile rail is reliably and professionally grounded.
- By mounting them on the grounded profile rail, the modules are automatically connected to the grounding system.

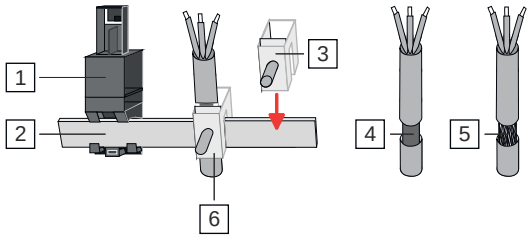
'Installation guidelines'...page 46

- To avoid potential differences, use grounding cables that are as short as possible and have a large cross-section.
- When selecting grounding points, observe the applicable safety regulations.
- When assembling your components, ensure that the inactive metal parts are properly grounded over a large area.
  - Connect all inactive metal parts over a large area and with low impedance.
  - Avoid using aluminium parts if possible. Aluminium is easily oxidizing and is therefore less suitable for grounding.

2.4.1 Shielding

Overview

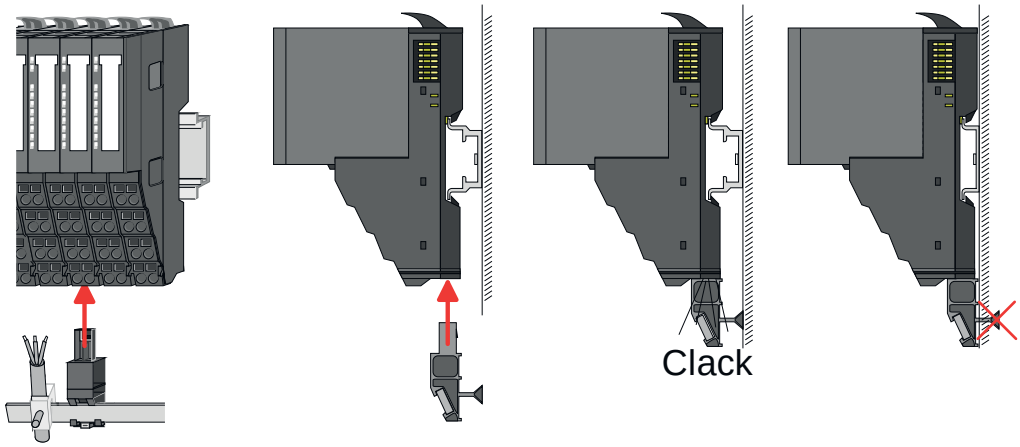
Shielding is required for interference-free signal transmission. This weakens electrical, magnetic or electromagnetic interference fields. To attach the shield the mounting of shield bus carriers are necessary. The shield bus carrier (available as accessory) serves to carry the shield bus to connect cable shields. *'Installation guidelines'...page 46*



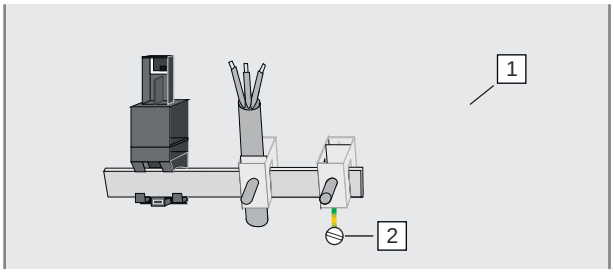
1 Shield bus carrier
2 Shield bus (10mm x 3mm)
3 Shield clamp
4 Cable shield with metal foil
5 Cable shield with wire mesh (close-meshed)
6 Cable shield mounted with shield clamp

Shield attachment

1. System SLIO head and 8x periphery modules have a carrier hole for the shield bus carrier. Push the shield bus carrier, until they engage into the module. With a flat profile rail for adaptation to a flat profile rail you may remove the spacer of the shield bus carrier.
2. Put your shield bus into the shield bus carrier.



3. Attach the cables with the accordingly stripped cable screen and fix it by the shield clamp with the shield bus.
4. The shield bus must always be grounded. Keep all cable connections as short as possible. To ground the shield bus, connect a FE conductor to the shield bus via a shield clamp and screw it to the base plate as close as possible and with low impedance.



1 Base plate
2 FE conductor screwed to base plate

2.5 Mounting 8x periphery modules

CAUTION

Requirements for UL compliance use

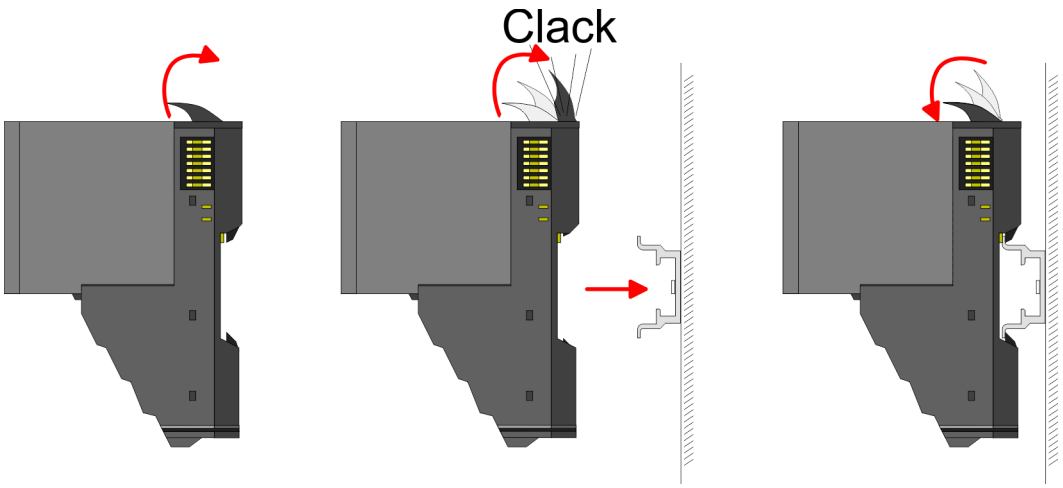
- Use for power supply exclusively SELV/PELV power supplies.
- The System SLIO must be installed and operated in a housing according to IEC 61010-1 9.3.2 c).

CAUTION

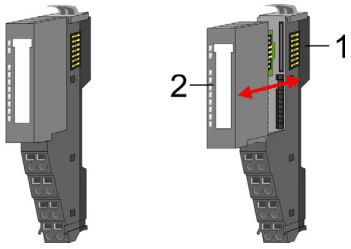
Danger of injury from electrical shock and damage to the unit!

Put the System SLIO in a safe, powered down state before starting installation, disassembly or wiring of the System SLIO modules!

There is a locking lever at the top side of the module. For mounting and demounting this locking lever is to be turned upwards until this engages. For mounting place the module to the module installed before and push the module to the profile rail guided by the strips at the upper and lower side of the module. The module is fixed to the profile rail by pushing downward the locking lever. The modules may either separately be mounted to the profile rail or as block. Here is to be considered that each locking lever is opened. The modules are each installed on a profile rail. The electronic and power section supply are connected via the backplane bus. Up to 64 modules may be mounted. Please consider here that the sum current of the electronic power supply does not exceed the maximum value of 3A. By means of the power module 007-1AB10 the current of the electronic power supply may be expanded accordingly.



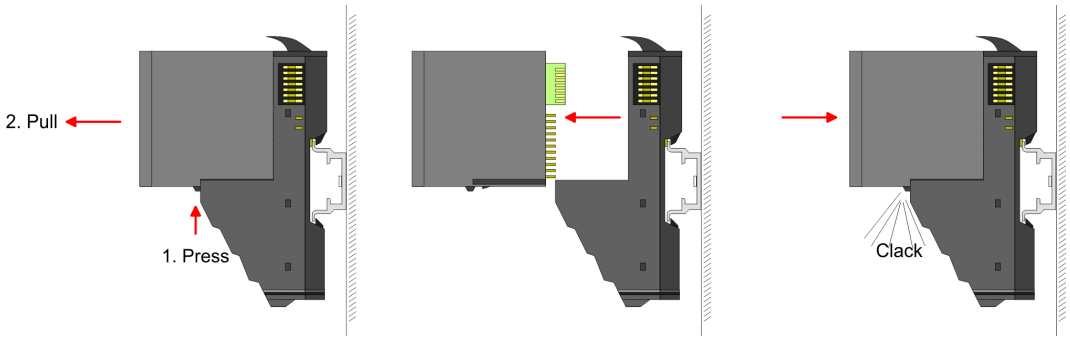
Terminal and electronic module



Each periphery module consists of a *terminal* and an *electronic module*.

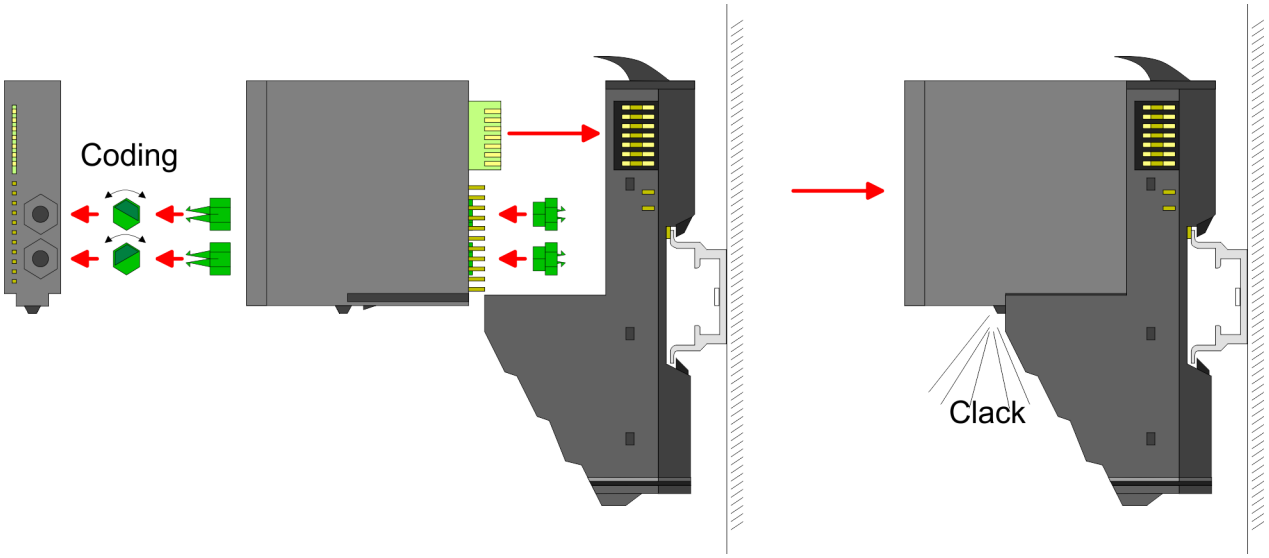
1 Terminal module
2 Electronic module

For the exchange of a electronic module, the electronic module may be pulled forward after pressing the unlocking lever at the lower side of the module. For installation plug the electronic module guided by the strips at the lower side until this engages audible to the terminal module.



Coding

There is the possibility to fix the assignment of electronic and terminal module. Here coding pins (order number 000-0AC00) can be used. The coding pin consists of a coding jack and a coding plug. By combining electronic and terminal module with coding pin, the coding jack remains in the electronic module and the coding plug in the terminal module. This ensures that after replacing the electronics module just another electronic module can be plugged with the same encoding.



Each electronic module has on its back 2 coding sockets for coding jacks. Due to the characteristics, with the coding jack 6 different positions can be plugged, each. Thus there are 36 possible combinations for coding with the use of both coding sockets.

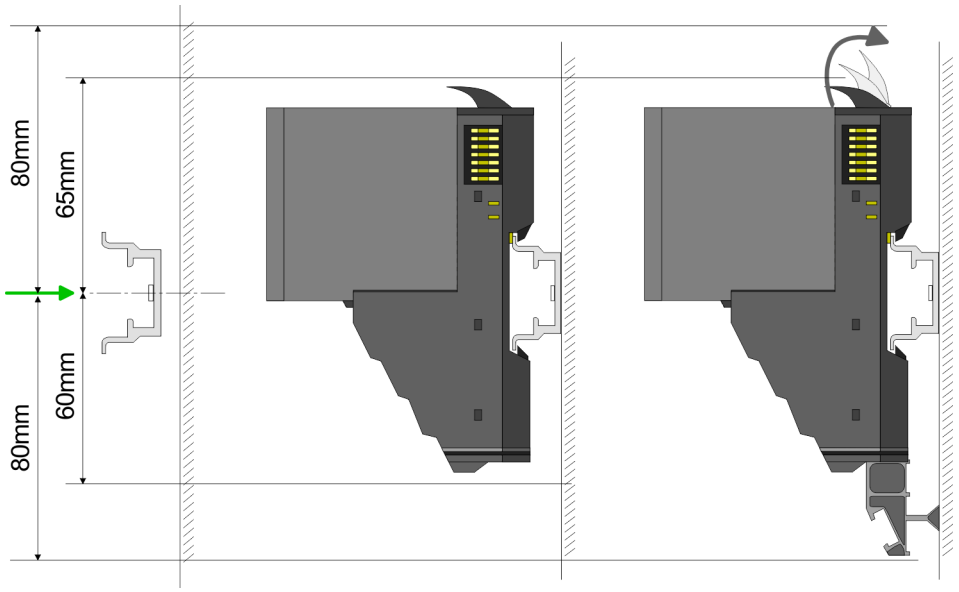
1. Plug, according to your coding, 2 coding jacks in the coding sockets of your electronic module until they lock
2. Now plug the according coding plugs into the coding jacks.
3. To fix the coding put both the electronic and terminal module together until they lock

CAUTION

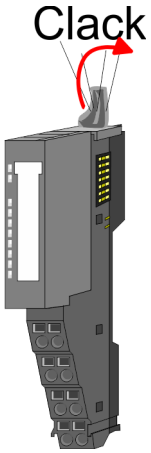
Please consider that when replacing an already coded electronic module, this is always be replaced by an electronic module with the same coding.

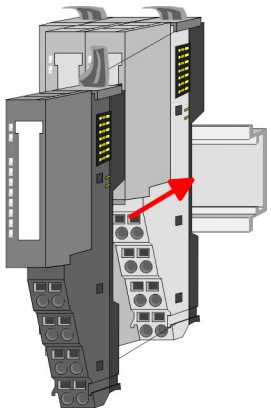
Even with an existing coding on the terminal module, you can plug an electronic module without coding. The user is responsible for the correct usage of the coding pins. Yaskawa assumes no liability for incorrectly attached electronic modules or for damages which arise due to incorrect coding!

Mounting periphery modules

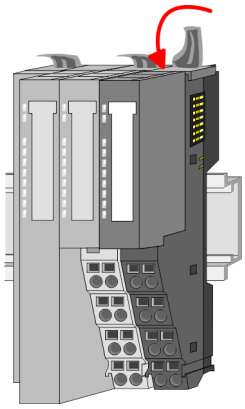


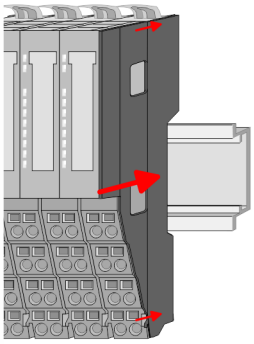
1. Mount the profile rail. Please consider that a clearance from the middle of the profile rail of at least 80mm above and 60mm below, respectively 80mm by deployment of shield bus carriers, exist.
2. Mount your head module such as CPU or field bus coupler.
3. Before mounting the periphery modules you have to remove the bus cover at the right side of the head module by pulling it forward. Keep the cover for later mounting.

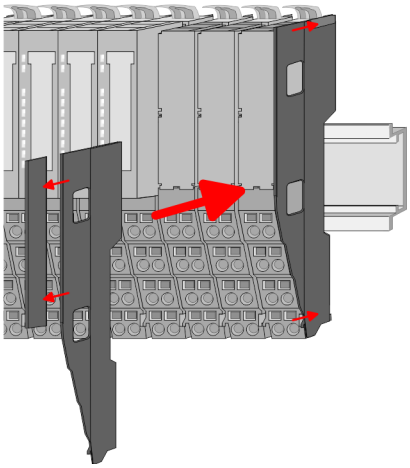




4. For mounting turn the locking lever of the module upwards until it engages.
5. For mounting place the module to the module installed before and push the module to the profile rail guided by the strips at the upper and lower side of the module.
6. Turn the locking lever of the periphery module downward, again.







7. After mounting the whole system, to protect the backplane bus connectors at the last module you have to mount the bus cover, now. If the last module is a clamp module, for adaptation the upper part of the bus cover is to be removed.

2.6 Mounting 16x periphery modules

CAUTION

Requirements for UL compliance use

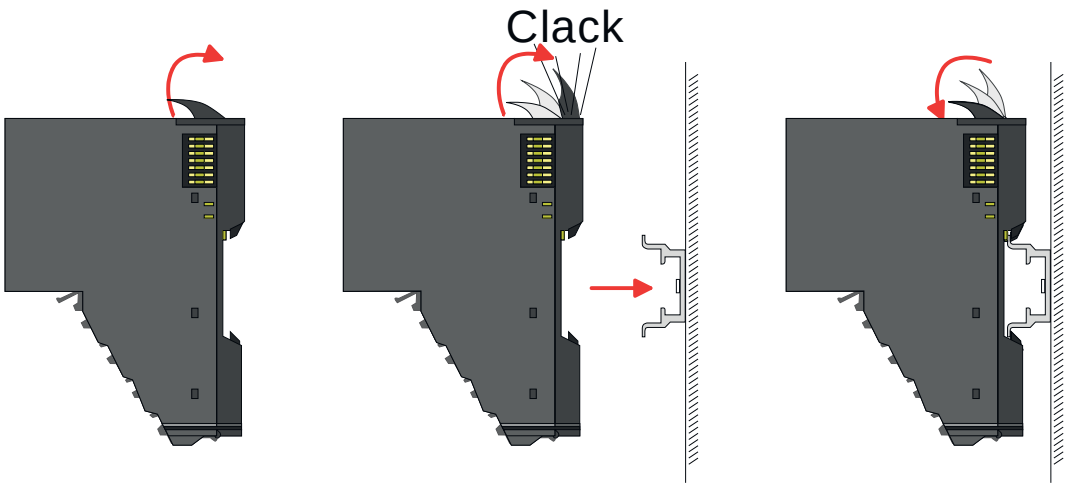
- Use for power supply exclusively SELV/PELV power supplies.
- The System SLIO must be installed and operated in a housing according to IEC 61010-1 9.3.2 c).

CAUTION

Danger of injury from electrical shock and damage to the unit!

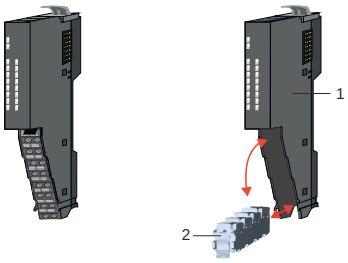
Put the System SLIO in a safe, powered down state before starting installation, disassembly or wiring of the System SLIO modules!

There is a locking lever at the top side of the module. For mounting and demounting this locking lever is to be turned upwards until this engages. For mounting place the module to the module installed before and push the module to the profile rail guided by the strips at the upper and lower side of the module. The module is fixed to the profile rail by pushing downward the locking lever. The modules may either separately be mounted to the profile rail or as block. Here is to be considered that each locking lever is opened. The modules are each installed on a profile rail. The electronic and power section supply are connected via the backplane bus. Up to 64 modules may be mounted. Please consider here that the sum current of the electronic power supply does not exceed the maximum value of 3A. By means of the power module 007-1AB10 the current of the electronic power supply may be expanded accordingly.



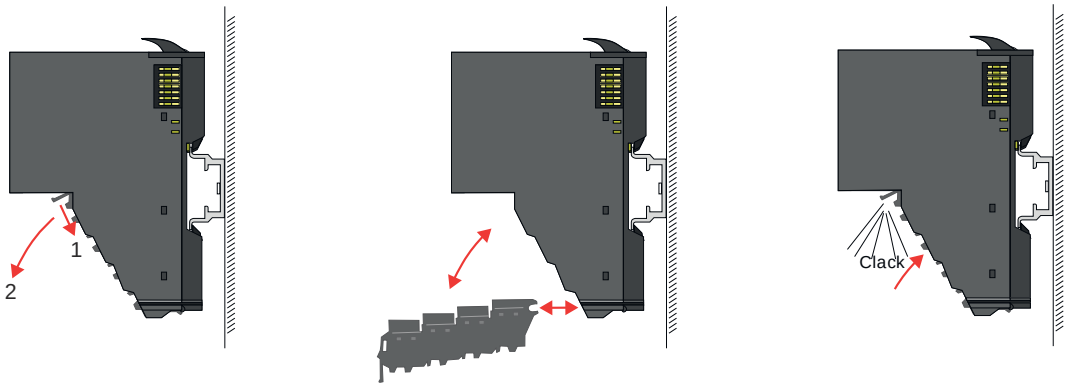
Electronic unit and terminal block

Each 16x periphery module consists of an *electronic unit* and a *terminal block*.

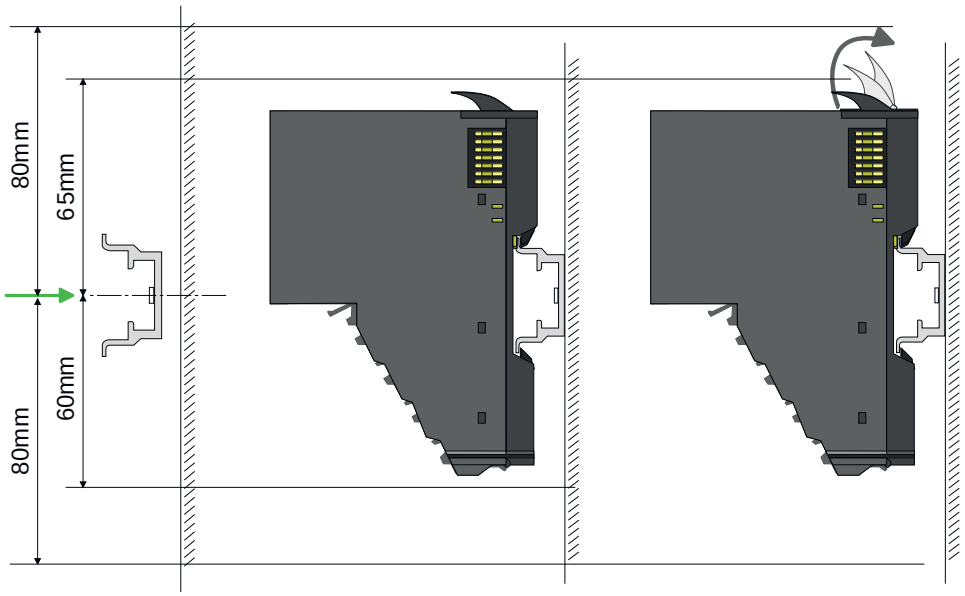


1 Electronic unit
2 Terminal block

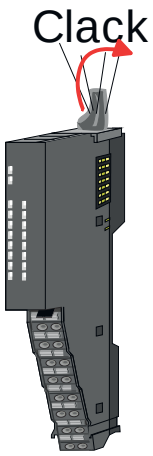
To replace an electronic unit, you can push down and pull off the terminal block after releasing the lock. To mount the terminal block, place it horizontally on the lower side of the electronic unit and push it towards the electronic unit until it clicks into place.

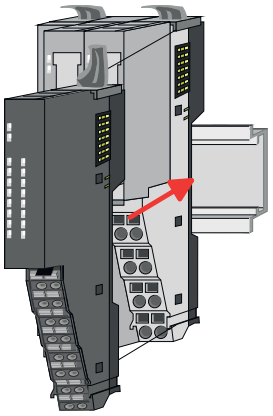


Mounting periphery module

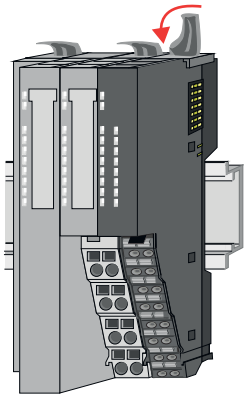


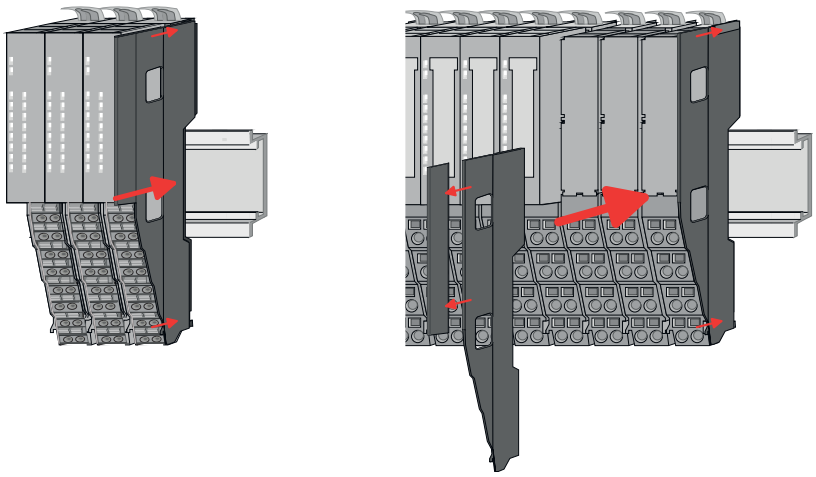
1. Mount the profile rail. Please consider that a clearance from the middle of the profile rail of at least 80mm above and 80mm below exist.
2. Mount your head module such as CPU or field bus coupler.
3. Before mounting the periphery modules you have to remove the bus cover at the right side of the head module by pulling it forward. Keep the cover for later mounting.





4. For mounting turn the locking lever of the module upwards until it engages.
5. For mounting place the module to the module installed before and push the module to the profile rail guided by the strips at the upper and lower side of the module.
6. Turn the locking lever of the periphery module downward, again.





7. After mounting the whole system, to protect the backplane bus connectors at the last module you have to mount the bus cover, now. If the last module is a clamp module, for adaptation the upper part of the bus cover is to be removed.

2.7 Wiring 8x periphery modules

Terminal module terminals

CAUTION

Do not connect hazardous voltages!

If this is not explicitly stated in the corresponding module description, hazardous voltages are not allowed to be connected to the corresponding terminal module!

CAUTION

Danger of injury from electrical shock and damage to the unit!

Put the System SLIO in a safe, powered down state before starting installation, disassembly or wiring of the System SLIO modules!

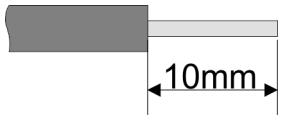
CAUTION

Consider temperature for external cables!

Cables may experience temperature increase due to system heat dissipation. Thus the cabling specification must be chosen 25°C above ambient temperature!

- With wiring the terminal modules, terminals with spring clamp technology are used for wiring. The spring clamp technology allows quick and easy connection of your signal and supply lines. In contrast to screw terminal connections this type of connection is vibration proof.

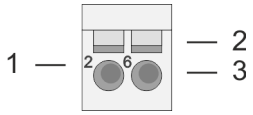
Data



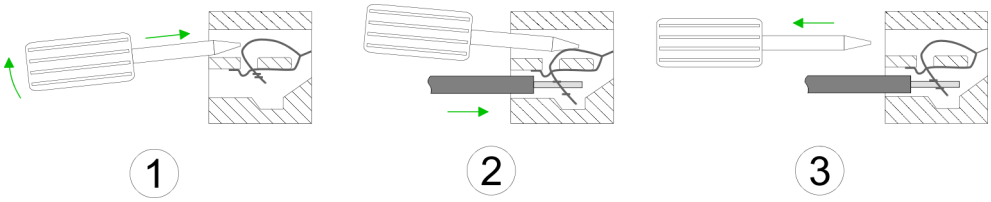
Please use copper wire only!

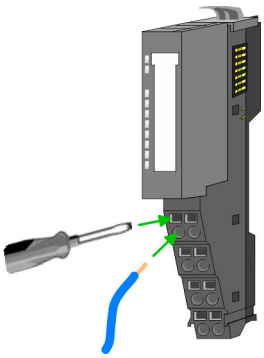
U_{max}	240V AC / 30V DC
I_{max}	10A
Cross section	0.08 ... 1.5mm² (AWG 28 ... 16)
Stripping length	10mm

Wiring procedure



1 Pin number at the connector
2 Opening for screwdriver
3 Connection hole for wire





1. Insert a suited screwdriver at an angel into the square opening as shown. Press and hold the screwdriver in the opposite direction to open the contact spring.
2. Insert the stripped end of wire into the round opening. You can use wires with a cross section of 0.08mm² up to 1.5mm²
3. By removing the screwdriver, the wire is securely fixed via the spring contact to the terminal.

Shield attachment *'Shielding'...page 22*

2.8 Wiring 16x periphery modules

Terminal block connectors

CAUTION

Do not connect hazardous voltages!

If this is not explicitly stated in the corresponding module description, hazardous voltages are not allowed to be connected to the corresponding terminal block!

CAUTION

Danger of injury from electrical shock and damage to the unit!

Put the System SLIO in a safe, powered down state before starting installation, disassembly or wiring of the System SLIO modules!

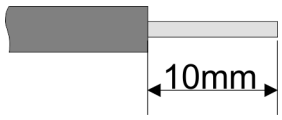
CAUTION

Consider temperature for external cables!

Cables may experience temperature increase due to system heat dissipation. Thus the cabling specification must be chosen 25°C above ambient temperature!

- The 16x periphery module has a removable terminal block for wiring.
- With the wiring of the terminal block a "push-in" spring-clip technique is used. This allows a quick and easy connection of your signal and supply lines.
- The clamping off takes place by means of a screwdriver.

Data



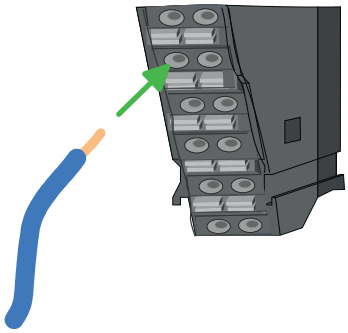
Please use copper wire only!

U_{max}	30V DC
I_{max}	10A
Cross section solid wire	0.25 ... 0.75mm²
Cross section with ferrule	0.14 ... 0.75mm²
AWG	24 ... 16
Stripping length	10mm

Wiring procedure

1 Release area
2 Connection hole for wire

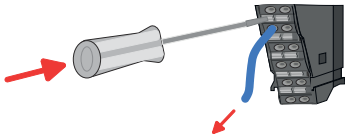
Insert wire



The wiring happens without a tool.

1. Determine according to the casing labelling the connection position.
2. Insert through the round connection hole of the according contact your prepared wire until it stops, so that it is fixed.
   ➥ By pushing the contact spring opens, thus ensuring the necessary contact pressure.

Remove wire



The wire is to be removed by means of a screwdriver with 2.5mm blade width.

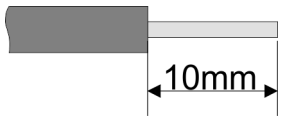
1. Press with your screwdriver vertically at the release button.
   ➥ The contact spring releases the wire.
2. Pull the wire from the round hole.

2.9 Wiring power modules

Terminal module terminals

Power modules are either integrated to the head module or may be installed between the periphery modules. With power modules, terminals with spring clamp technology are used for wiring. The spring clamp technology allows quick and easy connection of your signal and supply lines. In contrast to screw terminal connections this type of connection is vibration proof.

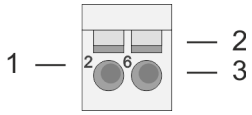
Data



Please use copper wire only!

U_{max}	30V DC
I_{max}	10A
Cross section	0.08 ... 1.5mm² (AWG 28 ... 16)
Stripping length	10mm

Wiring procedure



1 Pin number at the connector
2 Opening for screwdriver
3 Connection hole for wire

CAUTION

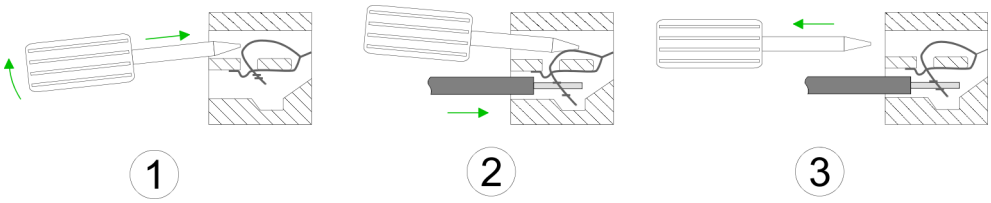
Danger of injury from electrical shock and damage to the unit!

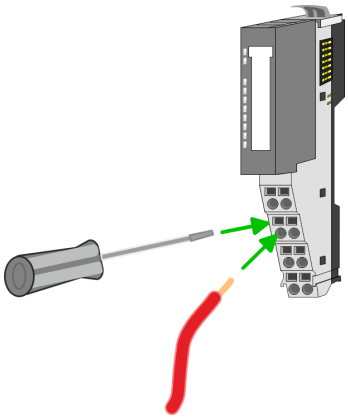
Put the System SLIO in a safe, powered down state before starting installation, disassembly or wiring of the System SLIO modules!

CAUTION

Consider temperature for external cables!

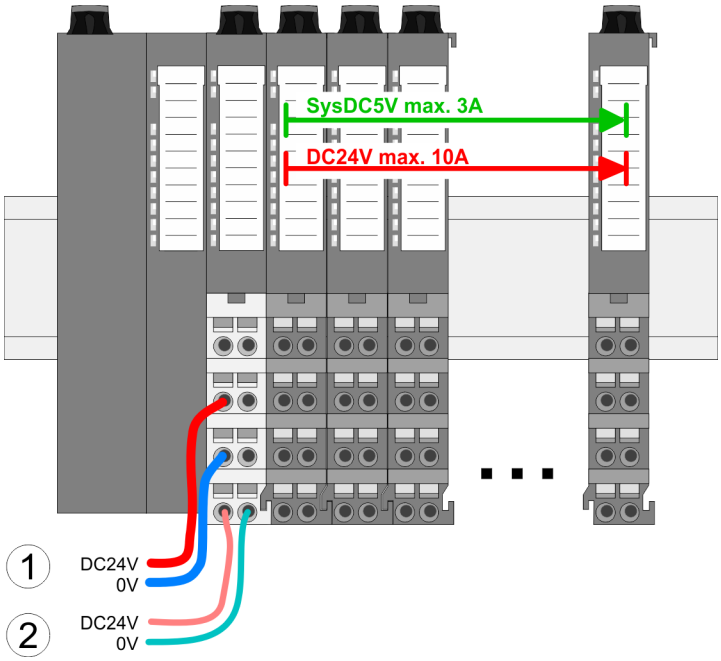
Cables may experience temperature increase due to system heat dissipation. Thus the cabling specification must be chosen 25°C above ambient temperature!





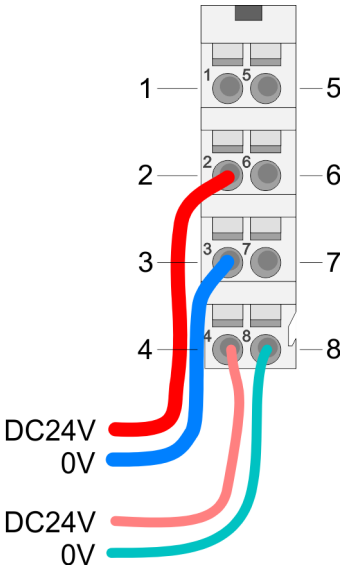
1. Insert a suited screwdriver at an angel into the square opening as shown. Press and hold the screwdriver in the opposite direction to open the contact spring.
2. Insert the stripped end of wire into the round opening. You can use wires with a cross section of 0.08mm² up to 1.5mm²
3. By removing the screwdriver, the wire is securely fixed via the spring contact to the terminal.

Standard wiring



(1) DC 24V for power section supply I/O area (max. 10A)
(2) DC 24V for electronic power supply bus coupler and I/O area

PM - Power module



For wires with a core cross-section of 0.08mm² up to 1.5mm².

Pos.	Function	Type	Description
1	---	---	not connected
2	DC 24V	I	DC 24V for power section supply
3	0V	I	GND for power section supply
4	Sys DC 24V	I	DC 24V for electronic power supply
5	---	---	not connected
6	DC 24V	I	DC 24V for power section supply
7	0V	I	GND for power section supply
8	Sys 0V	I	GND for electronic power supply

I: Input

CAUTION

Since the power section supply is not internally protected, it is to be externally protected with a fuse, which corresponds to the maximum current. This means max. 10A is to be protected by a 10A fuse (fast) respectively by a line circuit breaker 10A characteristics Z and should be UL approved!

The electronic power section supply is internally protected against higher voltage by fuse. The fuse is within the power module. If the fuse releases, its electronic module must be exchanged!

Fusing

- The power section supply is to be externally protected with a fuse, which corresponds to the maximum current. This means max. 10A is to be protected with a 10A fuse (fast) respectively by a line circuit breaker 10A characteristics Z and should be UL approved.
  - For modules with positive logic (PNP), place the fuse on the positive connector.
  - For modules with negative logic (NPN), place the fuse on the negative connector.
  - For mixed logic, one fuse must be placed on the negative and one on the positive connector.
- It is recommended to externally protect the electronic power supply for head modules and I/O area with a 2A fuse (fast) respectively by a line circuit breaker 2A characteristics Z and should be UL approved.
- The electronic power supply for the I/O area of the power module 007-1AB10 should also be externally protected with a 1A fuse (fast) respectively by a line circuit breaker 1A characteristics Z and should be UL approved.

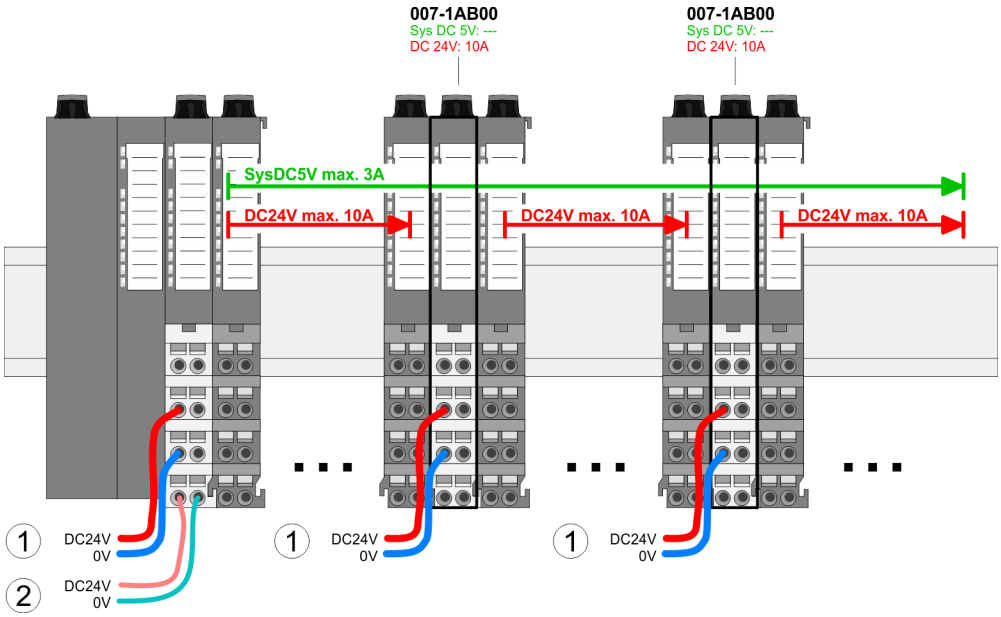
State of the electronic power supply via LEDs

After PowerON of the System SLIO the LEDs RUN respectively MF get on so far as the sum current does not exceed 3A. With a sum current greater than 3A the LEDs may not be activated. Here the power module with the order number 007-1AB10 is to be placed between the peripheral modules.

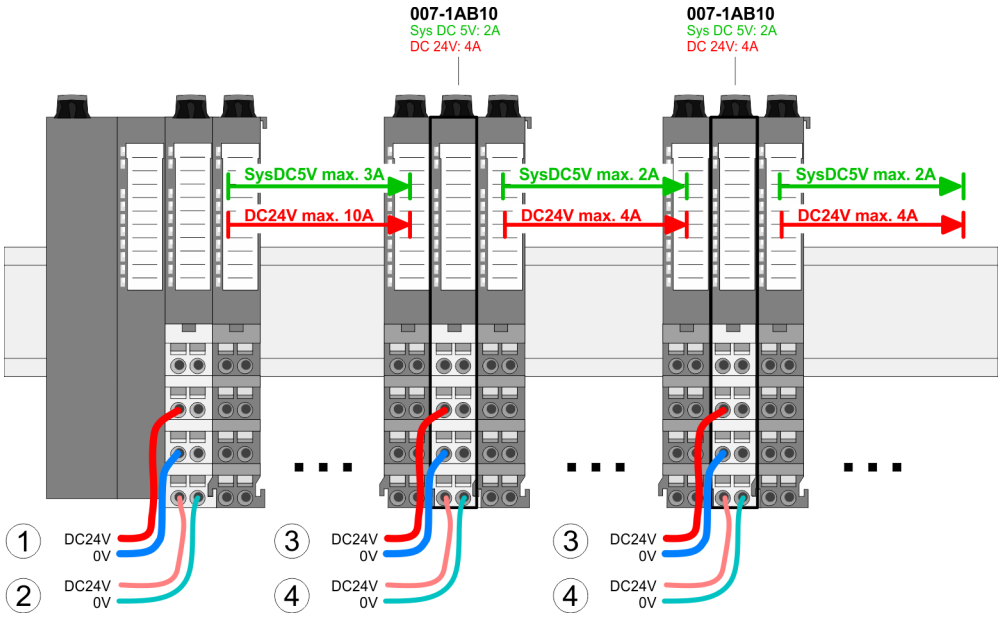
Deployment of the power modules

- If the 10A for the power section supply is no longer sufficient, you may use the power module with the order number 007-1AB00. So you have also the possibility to define isolated groups.
- The power module with the order number 007-1AB10 is to be used if the 3A for the electronic power supply at the backplane bus is no longer sufficient. Additionally you get an isolated group for the DC 24V power section supply with max. 4A.
- By placing the power module 007-1AB10 at the following backplane bus modules may be placed with a sum current of max. 2A. Afterwards a power module is to be placed again. To secure the power supply, the power modules may be mixed used.

Power module 007-1AB00



Power module 007-1AB10



(1) DC 24V for power section supply I/O area (max. 10A)
(2) DC 24V for electronic power supply bus coupler and I/O area
(3) DC 24V for power section supply I/O area (max. 4A)
(4) DC 24V for electronic power supply I/O area

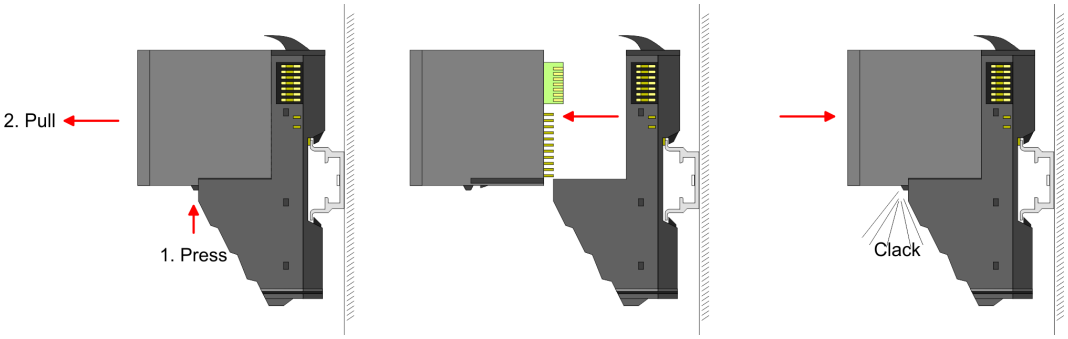
2.10 Demounting 8x periphery modules

Proceeding

Exchange of an electronic module

CAUTION
Put the System SLIO in a safe, powered down state before starting disassembly!

1. Power-off your system.



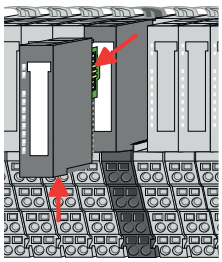
2. For the exchange of a electronic module, the electronic module may be pulled forward after pressing the unlocking lever at the lower side of the module.
3. For installation plug the new electronic module guided by the strips at the lower side until this engages to the terminal module.

➡ Now you can bring your system back into operation.

Easy Maintenance

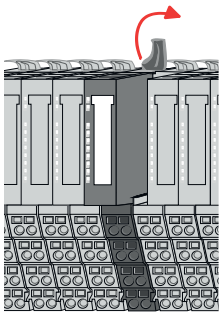
'Easy Maintenance' means the support for adding and removing electronic modules during operation without having to restart the system. If this is supported by your head module, you will find more detailed information on this in the "Deployment" chapter. *'Easy Maintenance'...page 42*

Exchange of a periphery module

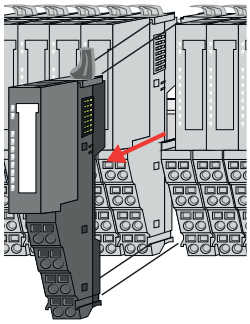


1. Power-off your system.
2. Remove if exists the wiring of the module.
3. *For demounting and exchange of a (head) module or a group of modules, due to mounting reasons you always have to remove the electronic module right beside. After mounting it may be plugged again.*

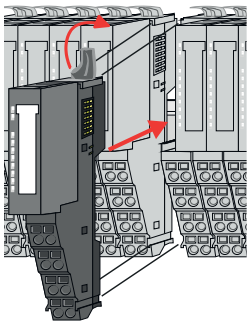
   Press the unlocking lever at the lower side of the just mounted right module and pull it forward.



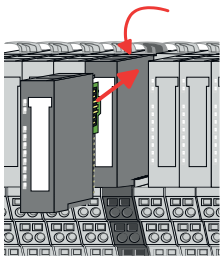
4. Turn the locking lever of the module to be exchanged upwards.



5. Pull the module.
6. For mounting turn the locking lever of the module to be mounted upwards.



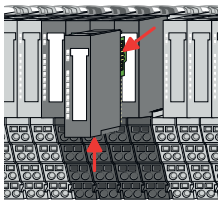
7. To mount the module put it to the gap between the both modules and push it, guided by the stripes at both sides, to the profile rail.
8. Turn the locking lever downward, again.



9. Plug again the electronic module, which you have removed before.
10. Wire your module.

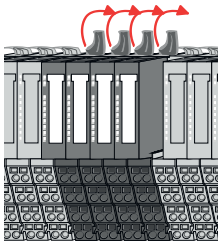
    ➡ Now you can bring your system back into operation.

Exchange of a module group

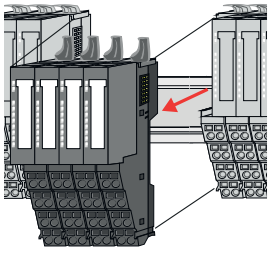


1. Power-off your system.
2. Remove if exists the wiring of the module group.
3. *For demounting and exchange of a (head) module or a group of modules, due to mounting reasons you always have to remove the electronic module right beside. After mounting it may be plugged again.*

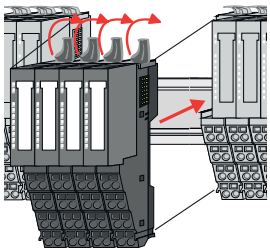
   Press the unlocking lever at the lower side of the just mounted right module near the module group and pull it forward.



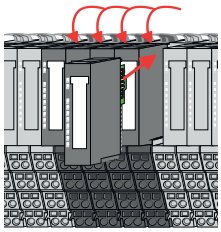
4. Turn all the locking lever of the module group to be exchanged upwards.



5. Pull the module group forward.
6. For mounting turn all the locking lever of the module group to be mounted upwards.



7. To mount the module group put it to the gap between the both modules and push it, guided by the stripes at both sides, to the profile rail.
8. Turn all the locking lever downward, again.



9. Plug again the electronic module, which you have removed before.
10. Wire your module group.

    ➡ Now you can bring your system back into operation.

2.11 Demounting 16x periphery modules

Proceeding

Exchange of an electronic unit

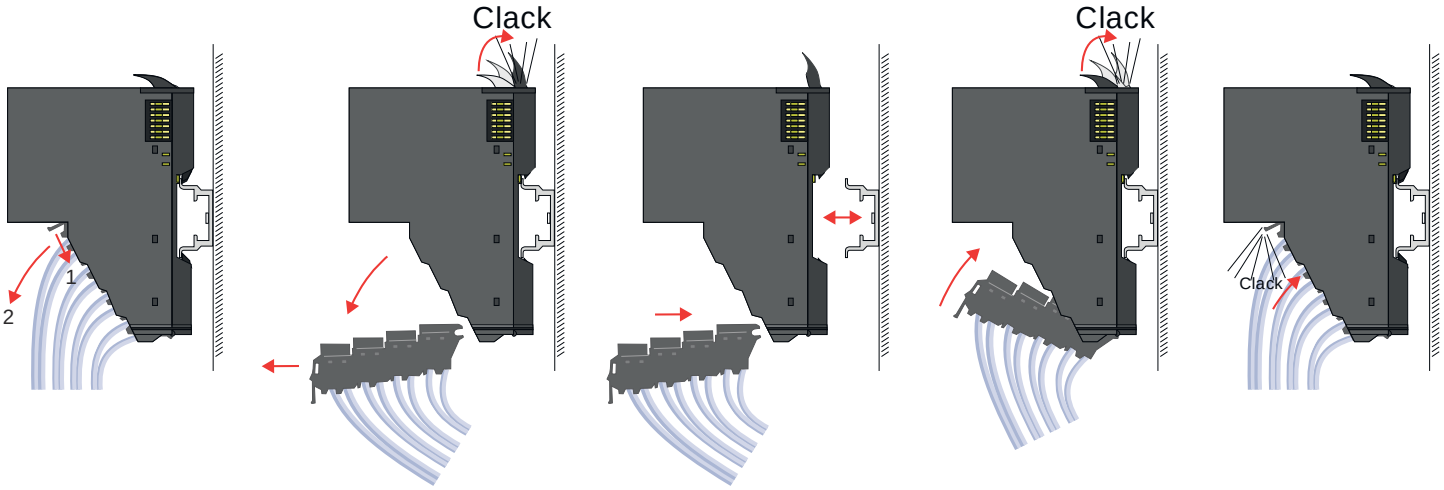
CAUTION

Put the System SLIO in a safe, powered down state before starting disassembly!

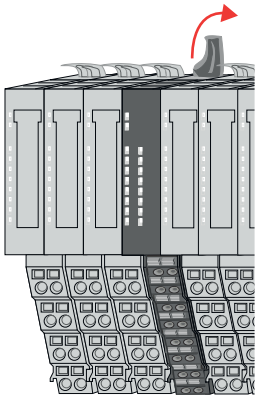
1. Power-off your system.
2. To replace an electronic unit, you can push down and pull off the terminal block after releasing the lock.

   To mount the terminal block, place it horizontally on the lower side of the electronic unit and push it towards the electronic unit until it clicks into place.

   ➡ Now you can bring your system back into operation.

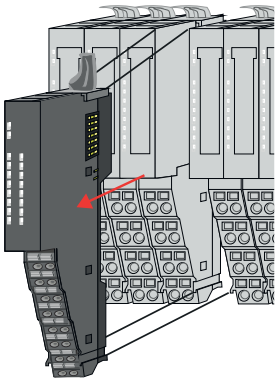


Exchange of a 16x periphery module

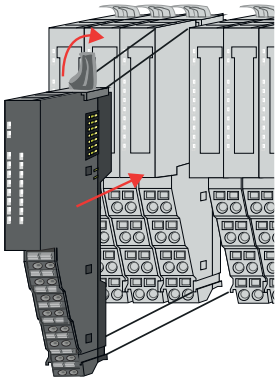


1. Power-off your system.
2. Remove if exists the wiring of the module respectively the wired terminal block.
3. *In contrast to 8x periphery modules, you can directly demount and mount 16x periphery modules.*

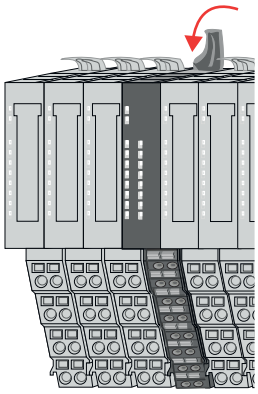
   Turn the locking lever of the module to be exchanged upwards.



4. Pull the module.
5. For mounting turn the locking lever of the module to be mounted upwards.



6. To mount the module put it to the gap between the both modules and push it, guided by the stripes at both sides, to the profile rail.

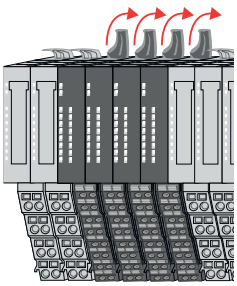


7. Turn the locking lever downward, again.
8. Wire your module respectively plug the wired terminal block again.

➡ Now you can bring your system back into operation.

Exchange of a module group

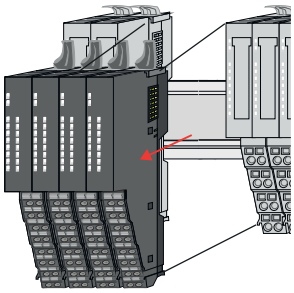
1. Power-off your system.
2. Remove if exists the wiring of the module group respectively the wired terminal blocks.



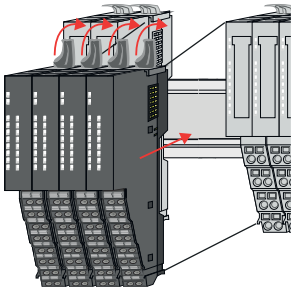
3.

In contrast to 8x periphery modules, you can directly demount and mount 16x periphery modules.

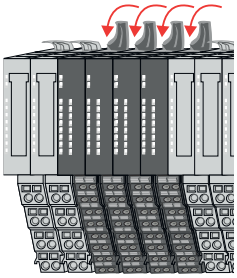
Turn all the locking lever of the module group to be exchanged upwards.



4. Pull the module group forward.
5. For mounting turn all the locking lever of the module group to be mounted upwards.



6. To mount the module group put it to the gap between the both modules and push it, guided by the stripes at both sides, to the profile rail.

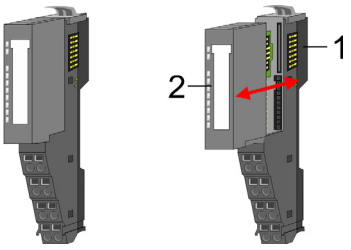


7. Turn all the locking lever downward, again.
8. Wire your module group respectively plug the wired terminal blocks again.

➡ Now you can bring your system back into operation.

2.12 Easy Maintenance

Overview



1 Terminal module
2 Electronic module

Easy Maintenance means the support for adding and removing an electronic module during operation without having to restart the system. Here the following behavior is shown by the example of a CPU:

- Electronic module is removed
  - The CPU detects a module failure on the backplane bus.
  - Diagnostic message *'System SLIO bus failure'* (0x39D0) is triggered.
  - OB 86 is called. If this is not available, the CPU switches to STOP otherwise it remains in RUN.
  - The SF LED of the CPU lights up.
  - The I/O data of all modules become invalid.
- Identical electronic module is plugged
  - The CPU detects the module return on the backplane bus.
  - The SF-LED of the CPU gets off.
  - All RUN LEDs on the modules get on and the MF LEDs get off.
  - Diagnostic message *'System SLIO bus recovery'* (0x38D0) is triggered.
  - OB 86 is called. If this is not available, the CPU switches to STOP otherwise it remains in RUN.
  - The I/O data of all modules become valid again.
- Wrong electronic module is plugged
  - The CPU detects the wrong module.
  - Diagnostic message *'System SLIO bus recovery, but expected configuration does not match actual configuration'* (0x38D1) is triggered.
  - The SF LED of the CPU remains on.
  - The MF LED of the wrong module flashes.
  - OB 86 is called. If this is not available, the CPU switches to STOP otherwise it remains in RUN.
  - With the exception of the wrong module, the I/O data of all modules become valid again.

CAUTION

Please note that only electronic modules may be exchanged during operation! Replacing an 8x or 16x periphery module during operation can damage the module and the system!

Please note that the CPU switches to STOP, if there is no OB 86 configured when adding or removing System SLIO modules!

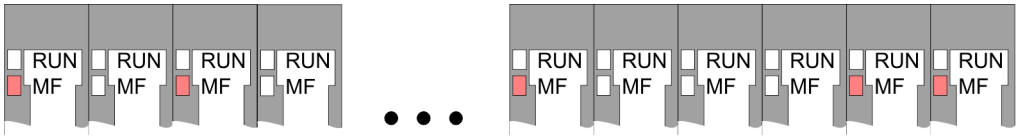
2.13 Trouble shooting - LEDs

General

Each module has the LEDs RUN and MF on its front side. Errors or incorrect modules may be located by means of these LEDs.

In the following illustrations flashing LEDs are marked by ☼.

Sum current of the electronic power supply exceeded

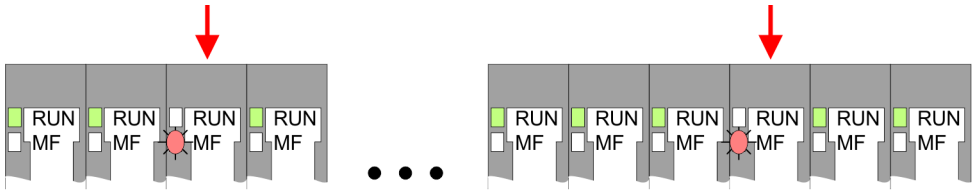


Behavior: After PowerON the RUN LED of each module is off and the MF LED of each module is sporadically on.

Reason: The maximum current for the electronic power supply is exceeded.

Remedy: As soon as the sum current of the electronic power supply is exceeded, always place the power module 007-1AB10. *'Wiring power modules'...page 32*

Error in configuration

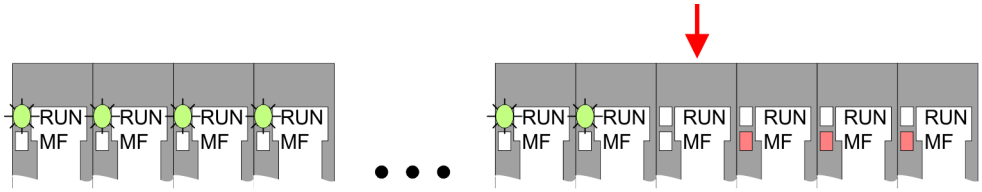


Behavior: After PowerON the MF LED of one module respectively more modules flashes. The RUN LED remains off.

Reason: At this position a module is placed, which does not correspond to the configured module.

Remedy: Match configuration and hardware structure.

Module failure



Behavior: After PowerON all of the RUN LEDs up to the defective module are flashing. With all following modules the MF LED is on and the RUN LED is off.

Reason: The module on the right of the flashing modules is defective.

Remedy: Replace the defective module.

2.14 Industrial security and installation guidelines

2.14.1 Industrial security in information technology

Latest version

This chapter can also be found as a guide *'Industrial IT Security'* in the *'Download Center'* of www.yaskawa.eu.com

Hazards

The topic of data security and access protection has become increasingly important in the industrial environment. The increased networking of entire industrial systems to the network levels within the company together with the functions of remote maintenance have all served to increase vulnerability. Hazards can arise from:

- Internal manipulation such as technical errors, operating and program errors and deliberate program or data manipulation.
- External manipulation such as software viruses, worms and trojans.
- Human carelessness such as password phishing.

Precautions

The most important precautions to prevent manipulation and loss of data security in the industrial environment are:

- Encrypting the data traffic by means of certificates.
- Filtering and inspection of the traffic by means of VPN - "Virtual Private Networks".
- Identification of the user by "Authentication" via save channels.
- Segmenting in protected automation cells, so that only devices in the same group can exchange data.
- Deactivation of unnecessary hardware and software.

Further Information

You can find more information about the measures on the following websites:

- Federal Office for Information Technology ➦ *www.bsi.bund.de*
- Cybersecurity & Infrastructure Security Agency ➦ *us-cert.cisa.gov*
- VDI / VDE Society for Measurement and Automation Technology ➦ *www.vdi.de*

2.14.1.1 Protection of hardware and applications

Precautions

- Do not integrate any components or systems into public networks.
  - Use VPN "Virtual Private Networks" for use in public networks. This allows you to control and filter the data traffic accordingly.
- Always keep your system up-to-date.
  - Always use the latest firmware version for all devices.
  - Update your user software regularly.
- Protect your systems with a firewall.
  - The firewall protects your infrastructure internally and externally.
  - This allows you to segment your network and isolate entire areas.
- Secure access to your plants via user accounts.
  - If possible, use a central user management system.
  - Create a user account for each user for whom authorization is essential.
  - Always keep user accounts up-to-date and deactivate unused user accounts.
- Secure access to your plants via secure passwords.
  - Change the password of a standard login after the first start.
  - Use strong passwords consisting of upper/lower case, numbers and special characters. The use of a password generator or manager is recommended.
  - Change the passwords according to the rules and guidelines that apply to your application.
- Deactivate inactive communication ports respectively protocols.
  - Only the communication ports that are used for communication should be activated.
  - Only the communication protocols that are used for communication should be activated.
- Consider possible defence strategies when planning and securing the system.
  - The isolation of components alone is not sufficient for comprehensive protection. An overall concept is to be drawn up here, which also provides defensive measures in the event of a cyber attack.
  - Periodically carry out threat assessments. Among others, a comparison is made here between the protective measures taken and those required.
- Limit the use of external storage media.
  - Via external storage media such as USB memory sticks or SD memory cards, malware can get directly into a system while bypassing a firewall.
  - External storage media or their slots must be protected against unauthorized physical access, e.g. by using a lockable control cabinet.
  - Make sure that only authorized persons have access.
  - When disposing of storage media, make sure that they are safely destroyed.
- Use secure access paths such as HTTPS or VPN for remote access to your plant.
- Enable security-related event logging in accordance with the applicable security policy and legal requirements for data protection.

2.14.1.2 Protection of PC-based software

Precautions

Since PC-based software is used for programming, configuration and monitoring, it can also be used to manipulate entire systems or individual components. Particular caution is required here!

- Use user accounts on your PC systems.
  - If possible, use a central user management system.
  - Create a user account for each user for whom authorization is essential.
  - Always keep user accounts up-to-date and deactivate unused user accounts.
- Protect your PC systems with secure passwords.
  - Change the password of a standard login after the first start.
  - Use strong passwords consisting of upper/lower case, numbers and special characters. The use of a password generator or manager is recommended.
  - Change the passwords according to the rules and guidelines that apply to your application.
- Enable security-related event logging in accordance with the applicable security policy and legal requirements for data protection.
- Protect your PC systems by security software.
  - Install virus scanners on your PC systems to identify viruses, trojans and other malware.
  - Install software that can detect phishing attacks and actively prevent them.
- Always keep your software up-to-date.
  - Update your operating system regularly.
  - Update your software regularly.
- Make regular backups and store the media at a safe place.
- Regularly restart your PC systems. Only boot from storage media that are protected against manipulation.
- Use encryption systems on your storage media.
- Perform security assessments regularly to reduce the risk of manipulation.
- Use only data and software from approved sources.
- Uninstall software which is not used.
- Disable unused services.
- Activate a password-protected screen lock on your PC systems.
- Always lock your PC systems as soon as you leave your PC workstation.
- Do not click any links that come from unknown sources. If necessary ask, e.g. on e-mails.
- Use secure access paths such as HTTPS or VPN for remote access to your PC system.

2.14.2 Installation guidelines

General

The installation guidelines contain information about the interference free deployment of a PLC system. There is the description of the ways, interference may occur in your PLC, how you can make sure the electromagnetic compatibility (EMC), and how you manage the isolation.

What does EMC mean?

Electromagnetic compatibility (EMC) means the ability of an electrical device, to function error free in an electromagnetic environment without being interfered respectively without interfering the environment.

The components are developed for the deployment in industrial environments and meets high demands on the EMC. Nevertheless you should project an EMC planning before installing the components and take conceivable interference causes into account.

Possible interference causes

Electromagnetic interferences may interfere your control via different ways:

- Electromagnetic fields (RF coupling)
- Magnetic fields with power frequency
- Bus system
- Power supply
- Protected ground conductor

Depending on the spreading medium (lead bound or lead free) and the distance to the interference cause, interferences to your control occur by means of different coupling mechanisms.

There are:

- galvanic coupling
- capacitive coupling
- inductive coupling
- radiant coupling

Basic rules for EMC

In the most times it is enough to take care of some elementary rules to guarantee the EMC. Please regard the following basic rules when installing your PLC.

- Take care of a correct area-wide grounding of the inactive metal parts when installing your components.
  - Connect all inactive metal extensive and impedance-low.
  - Please try not to use aluminium parts. Aluminium is easily oxidizing and is therefore less suitable for grounding.
- When cabling, take care of the correct line routing.
  - Organize your cabling in line groups (high voltage, current supply, signal and data lines).
  - Always lay your high voltage lines and signal respectively data lines in separate channels or bundles.
  - Route the signal and data lines as near as possible beside ground areas (e.g. suspension bars, metal rails, tin cabinet).
- Proof the correct fixing of the lead isolation.
  - Data lines must be shielded.
  - Analog lines must be shielded. When transmitting signals with small amplitudes the one sided laying of the isolation may be favourable.
  - Cables for frequency inverters, servo and stepper motors must be shielded.
  - Lay the line isolation extensively on an isolation/protected ground conductor rail directly after the cabinet entry and fix the isolation with cable clamps.
  - Make sure that the isolation/protected ground conductor rail is connected impedance-low with the cabinet.
  - Use metallic or metallised plug cases for isolated data lines.
- In special use cases you should appoint special EMC actions.
  - Consider to wire all inductivities with erase links.
  - Please consider luminescent lamps can influence signal lines.
- Create a homogeneous reference potential and ground all electrical operating supplies when possible.
  - Please take care for the targeted employment of the grounding actions. The grounding of the PLC serves for protection and functionality activity.
  - Connect installation parts and cabinets with your PLC in star topology with the isolation/protected ground conductor system. So you avoid ground loops.
  - If there are potential differences between installation parts and cabinets, lay sufficiently dimensioned potential compensation lines.

Isolation of conductors

Electrical, magnetically and electromagnetic interference fields are weakened by means of an isolation, one talks of absorption. Via the isolation rail, that is connected conductive with the rack, interference currents are shunt via cable isolation to the ground. Here you have to make sure, that the connection to the protected ground conductor is impedance-low, because otherwise the interference currents may appear as interference cause.

When isolating cables you have to regard the following:

- If possible, use only cables with isolation tangle.
- The hiding power of the isolation should be higher than 80%.
- Normally you should always lay the isolation of cables on both sides. Only by means of the both-sided connection of the isolation you achieve high quality interference suppression in the higher frequency area. Only as exception you may also lay the isolation one-sided. Then you only achieve the absorption of the lower frequencies. A one-sided isolation connection may be convenient, if:
  - the conduction of a potential compensating line is not possible.
  - analog signals (some mV respectively µA) are transferred.
  - foil isolations (static isolations) are used.
- With data lines always use metallic or metallised plugs for serial couplings. Fix the isolation of the data line at the plug rack. Do not lay the isolation on the PIN 1 of the plug bar!
- At stationary operation it is convenient to strip the insulated cable interruption free and lay it on the isolation/protected ground conductor line.
- To fix the isolation tangles use cable clamps out of metal. The clamps must clasp the isolation extensively and have well contact.
- Lay the isolation on an isolation rail directly after the entry of the cable in the cabinet.

CAUTION

Please regard at installation!

At potential differences between the grounding points, there may be a compensation current via the isolation connected at both sides.

Remedy: Potential compensation line

2.15 General data for the System SLIO

Conformity and approval		
Conformity		
CE	2014/35/EU	Low Voltage Directive
	2014/30/EU	EMC Directive
RoHS (EU)	2011/65/EU	Restriction of the use of certain hazardous substances in electrical and electronic equipment
UKCA	2016 No. 1101	Electrical Equipment (Safety) Regulations
	2016 No. 1091	Electromagnetic Compatibility Regulations
RoHS (UK)	2012 No. 3032	Use of Certain Hazardous Substances
Approval		
Certifications	-	Refer to technical data

Protection of persons and device protection		
Type of protection	-	IP20
Electrical isolation		
to the field bus	-	electrically isolated
to the process level	-	electrically isolated
Insulation resistance	-	-
Insulation voltage to reference ground		
Inputs / outputs	-	AC / DC 50V, test voltage AC 500V
Protective measures	-	against short circuit

Environmental conditions to EN 61131-2		
Operation		
Horizontal installation hanging	EN 61131-2	0…+60°C
Horizontal installation lying	EN 61131-2	0…+55°C
Vertical installation	EN 61131-2	0…+50°C
Air humidity	EN 60068-2-30	RH1 (without condensation, rel. humidity 10…95%)
Pollution	EN 61131-2	Degree of pollution 2
Installation altitude max.	-	2000m
Mechanical		
Oscillation	EN 60068-2-6	1g, 9Hz ... 150Hz
Shock	EN 60068-2-27	15g, 11ms

Mounting conditions		
Mounting place	-	In the control cabinet
Mounting position	-	Horizontal and vertical

EMC	Standard		Comment
Emitted interference	EN 61000-6-4		Class A (Industrial area)
Noise immunity zone B	EN 61000-6-2		Industrial area
		EN 61000-4-2	ESD 8kV at air discharge (degree of severity 3), 4kV at contact discharge (degree of severity 2)
		EN 61000-4-3	HF field immunity (casing) 80MHz … 1000MHz, 10V/m, 80% AM (1kHz) 1.4GHz ... 6GHz, 3V/m, 80% AM (1kHz)
		EN 61000-4-6	HF conducted 150kHz … 80MHz, 10V, 80% AM (1kHz)
		EN 61000-4-4	Burst
		EN 61000-4-5	Surge[1]

1) Due to the high-energetic single pulses with Surge an appropriate external protective circuit with lightning protection elements like conductors for lightning and overvoltage is necessary.

2.15.1 Use in difficult operating conditions

Without additional protective measures, the products must not be used in locations with difficult operating conditions; e.g. due to:

- *dust generation*
- *chemically active substances (corrosive vapors or gases)*
- *strong electric or magnetic fields*

2.16 System SLIO product variants for extended application range

The System SLIO product variants listed below only differ from the basic modules only in the extended temperature range and the use under condensation. All other data correspond to those of the basic modules. Information on structure and configuration can be found in the manuals for the basic modules in the *'Download Center'* of www.yaskawa.eu.com

Please note that the product variants listed here may only be operated in combination with one another on the backplane bus! Mixed operation is not possible!

Basic modules	Product variants	Description
053-1PN01	053-1PN01-C	IM - 053-1PN01 - interface module PROFINET
021-1BF00	021-1BF00-C	SM 021 - digital input - 8xDI - DC 24V
022-1BF00	022-1BF00-C	SM 022 - digital output - 8xDO - DC 24V 0.5A
031-1CD30	031-1CD30-C	SM 031 - analog input - 4xAI - 16bit 0 ... 10V
031-1BD80	031-1BD80-C	SM 031 - analog input - 4xAI - 16bit R/RTD
032-1CD30	032-1CD30-C	SM 032 - analog output - 4xAI - 16bit 0 ... 10V

Environmental conditions according to EN 61131-2 for System SLIO basic modules		
Climatic		
Storage / transport	EN 60068-2-14	-25…+70°C
Operation		
Horizontal installation hanging	EN 61131-2	0…+60°C
Horizontal installation lying	EN 61131-2	0…+55°C
Vertical installation	EN 61131-2	0…+50°C
Air humidity	EN 60068-2-30	RH1 (without condensation, rel. humidity 10…95%)
Pollution	EN 61131-2	Degree of pollution 2

Environmental conditions according to EN 61131-2 for System SLIO product variants		
Climatic		
Storage / transport	EN 60068-2-14	-25…+70°C
Operation		
Horizontal installation hanging	EN 61131-2	-25 ... + 60 ° C
Horizontal installation lying	EN 61131-2	-25…+55°C
Vertical installation	EN 61131-2	-25 ... + 50 ° C
Air humidity	EN 60068-2-30	RH1 (without condensation, rel. humidity 10…95%)
Climate	GS 95024-3-1:2010	Condensation
Pollution	EN 61131-2	Degree of pollution 2

3 Digital input

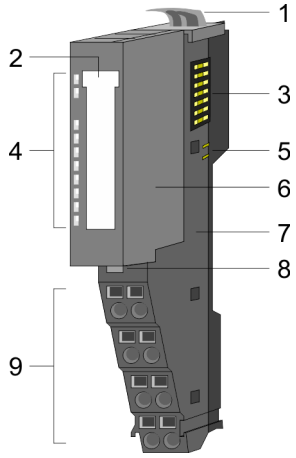
3.1 021-1BB00 - DI 2xDC 24V

Properties

The electronic module collects the binary control signals from the process level and transmits them isolated to the central bus system. It has 2 channels and their status is monitored via LEDs.

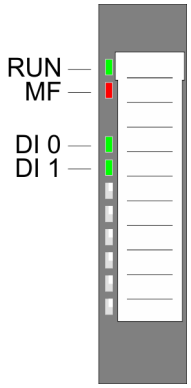
- 2 digital inputs, isolated to the backplane bus
- Suited for switches and approximate switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

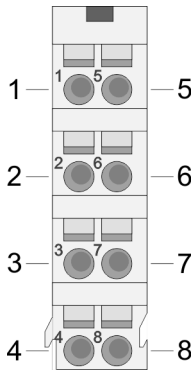
Status indication

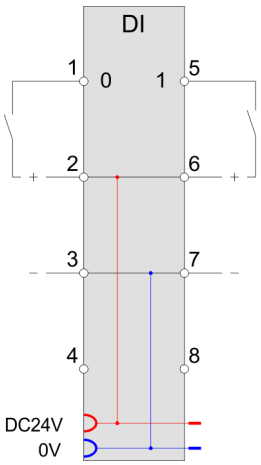


RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	DC 24V	O	DC 24V for sensor
3	0V	O	GND
4	---	---	not connected
5	DI 1	I	Digital input DI 1
6	DC 24V	O	DC 24V for sensor
7	0V	O	GND
8	---	---	not connected

I: Input, O: Output

Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	5000h	
			Bit 0: DI 0		01h
			Bit 1: DI 1		02h
			Bit 7 ... 2: reserved		

Output area

No byte of the output area is used by the module.

3.1.1 Technical data

Order no.	021-1BB00
Type	SM 021 - Digital input
Module ID	0001 9F82
Current consumption/power loss	
Current consumption from backplane bus	65 mA
Power loss	0.5 W
Technical data digital inputs	
Number of inputs	2
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	-
Permitted range	-
Current consumption from power section supply (without load)	-
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 0...5 V
Input voltage for signal "1"	DC 15...28.8 V
Input voltage hysteresis	-
Signal logic input	Sinking input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	3 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	0.5 mA
Input delay of "0" to "1"	3 ms
Input delay of "1" to "0"	3 ms
Number of simultaneously utilizable inputs horizontal configuration	2
Number of simultaneously utilizable inputs vertical configuration	2
Input characteristic curve	IEC 61131-2, type 1
Initial data size	2 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no

Order no.	021-1BB00
Diagnostic functions	no
Diagnostics information read-out	none
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	1
Output bytes	0
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	57 g
Weight including accessories	57 g
Gross weight	72 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

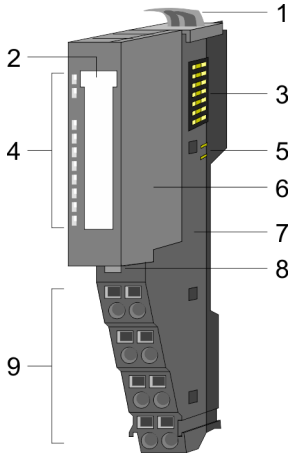
3.2 021-1BB10 - DI 2xDC 24V 2µs...3ms

Properties

The electronic module collects the binary control signals from the process level and transmits them isolated to the central bus system. The module has 2 fast digital input channels and their status is monitored via LEDs.

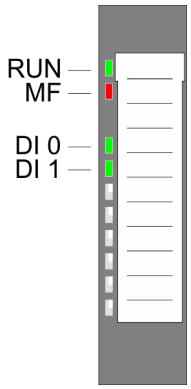
- 2 fast digital inputs, isolated to the backplane bus
- Input filter time delay parameterizable 2µs...3ms
- Interrupt and diagnostics function
- Suited for switches and approximate switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

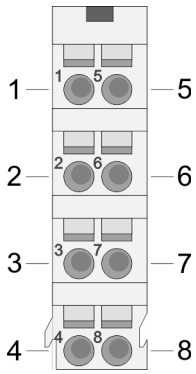
Status indication

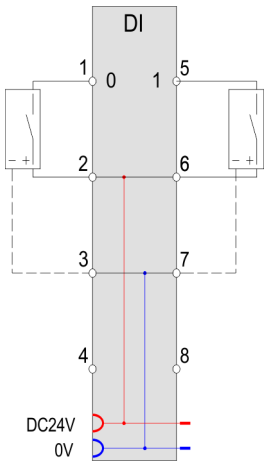


RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	DC 24V	O	DC 24V for sensor
3	0V	O	GND
4	—	—	not connected
5	DI 1	I	Digital input DI 1
6	DC 24V	O	DC 24V for sensor
7	0V	O	GND
8	—	—	not connected

I: Input, O: Output

Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	5000h	
			Bit 0: DI 0		01h
			Bit 1: DI 1		02h
			Bit 7 ... 2: reserved		

Output area

No byte of the output area is used by the module.

3.2.1 Technical data

Order no.	021-1BB10
Type	SM 021 - Digital input
Module ID	000A 1F02
Current consumption/power loss	
Current consumption from backplane bus	100 mA
Power loss	0.9 W
Technical data digital inputs	
Number of inputs	2
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	12 mA
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 0...5 V
Input voltage for signal "1"	DC 15...28.8 V
Input voltage hysteresis	-
Signal logic input	Sinking input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	3 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	0.5 mA
Input delay of "0" to "1"	parameterizable 2µs - 3ms
Input delay of "1" to "0"	parameterizable 2µs - 3ms
Number of simultaneously utilizable inputs horizontal configuration	2
Number of simultaneously utilizable inputs vertical configuration	2
Input characteristic curve	IEC 61131-2, type 1
Initial data size	2 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	yes, parameterizable
Process alarm	yes, parameterizable
Diagnostic interrupt	yes, parameterizable

Order no.	021-1BB10
Diagnostic functions	yes
Diagnostics information read-out	possible
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	1
Output bytes	0
Parameter bytes	9
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	58 g
Weight including accessories	58 g
Gross weight	73 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

3.2.2 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
DIAG_EN	1	Diagnostic interrupt[1]	00h	00h	3100h	01h
CH0D	1	Input delay DI 0	02h	01h	3101h	02h
CH1D	1	Input delay DI 1	02h	01h	3102h	03h
INTRE	1	hardware interrupt at edge 0-1 of DI x	00h	80h	3103h	04h
INTFE	1	hardware interrupt at edge 1-0 of DI x	00h	80h	3104h	05h

1) This record set may only be transferred at STOP state.

DIAG_EN Diagnostic interrupt

Byte	Bit 7 ... 0
0	Diagnostic interrupt 00h: disable 40h: enable

- Here you activate res. de-activate the diagnostic function.

CHxD Input delay

Byte	Function	Possible values	
0	Input delay DI x	00h: 2µs	07h: 86µs
		02h: 4µs	09h: 342µs
		04h: 12µs	0Ch: 2731µs
		Other values are not permissible!	

- *Input delay* allows you to preset a filter for the corresponding channel. With the help of filters you may e.g. filter signal peaks at a blurred input signal.

INTRE Interrupt edge 0-1

Byte	Bit 7 ... 0
0	Bit 0: Process interrupt at edge 0-1 of DI 0 Bit 1: Process interrupt at edge 0-1 of DI 1 (0: disable, 1: enable) Bit 7 ... 2: reserved

INTFE Interrupt edge 1-0

Byte	Bit 7 ... 0
0	Bit 0: Process interrupt at edge 1-0 of DI 0 Bit 1: Process interrupt at edge 1-0 of DI 1 (0: disable, 1: enable) Bit 7 ... 2: reserved

3.2.3 Diagnostics and interrupt

Event	Process interrupt	Diagnostics interrupt	parameterizable
Edge 0-1 DI x	X	-	X
Edge 1-0 DI x	X	-	X
Diagnostics buffer overflow	-	X	-
Process interrupt lost	-	X	-

Hardware interrupt

So you may react to asynchronous events, there is the possibility to activate a hardware interrupt.

- A hardware interrupt interrupts the linear program sequence and jumps depending on the master system to a corresponding Interrupt routine. Here you can react to the hardware interrupt accordingly.
- With CANopen the hardware interrupt data a transferred via an emergency telegram.
- Operating with CPU, PROFIBUS and PROFINET the hardware interrupt data were transferred via diagnostics telegram.

SX - Subindex for access via EtherCAT with Index 5000h

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	SX
PRIT_A	1	Process interrupt data	00h	02h
PRIT_B	1	State of the inputs	00h	03h
PRIT_US	2	µs ticker	00h	04h (high byte) 05h (low byte)

PRIT_A Process interrupt data

Byte	Bit 7 ... 0
0	Bit 0: Edge at Digital input DI 0 Bit 1: Edge at Digital input DI 1 Bit 7 ... 2: reserved

PRIT_B State of the inputs

Byte	Bit 7 ... 0
0	State of the inputs at the moment of the hardware interrupt Bit 0: State Input DI 0 Bit 1: State Input DI 1 Bit 7 ... 2: reserved

PRIT_US µs-Ticker

Byte	Bit 7 ... 0
0 ... 1	Value of the µs ticker at the moment of the hardware interrupt

µs ticker

In the System SLIO module there is a 32 bit timer (µs ticker). With PowerON the timer starts counting with 0. After 2^{32}-1µs the timer starts with 0 again.

PRIT_US represents the lower 2 byte of the µs ticker value (0 ... 2^{16}-1).

Diagnostic data

Via the parameterization you may activate a diagnostic interrupt for the module.

With a diagnostics interrupt the module serves for diagnostics data for diagnostic interrupt incoming.

As soon as the reason for releasing a diagnostic interrupt is no longer present, the diagnostic interrupt going automatically takes place.

All events of a channel between diagnostic interrupt incoming and diagnostic interrupt going are not stored and get lost.

Within this time window (1. diagnostic interrupt incoming until last diagnostic interrupt going) the MF-LED of the module is on.

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

IX - Index for access via CANopen. The access happens by IX 2F01h. Additionally the first 4 bytes may be accessed by IX 2F00h.

SX - Subindex for access via EtherCAT with Index 5005h.

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
ERR_A	1	Diagnostic	00h	01h	2F01h	02h
MODTYP	1	Module information	1Fh			03h
ERR_C	1	reserved	00h			04h
ERR_D	1	Diagnostic	00h			05h
CHTYP	1	Channel type	70h			06h
NUMBIT	1	Number of diagnostics bits per channel	00h			07h
NUMCH	1	Number channels of the module	02h			08h
CHERR	1	Channel error	00h			09h
CH0ERR… CH7ERR	8	reserved	00h			0Ah ... 11h
DIAG_US	4	µs ticker	00h			13h

ERR_A Diagnostic

Byte	Bit 7 ... 0
0	Bit 0: set at module failure Bit 1: reserved Bit 2: set at external error Bit 3: set at channel error Bit 7 ... 4: reserved

MODTYP Module information

Byte	Bit 7 ... 0
0	Bit 3 ... 0: Module class 1111b Digital module Bit 4: Channel information present Bit 7 ... 5: reserved

ERR_C reserved

Byte	Bit 7 ... 0
0	reserved

ERR_D Diagnostic

Byte	Bit 7 ... 0
0	Bit 2 ... 0: reserved Bit 3: set at internal diagnostics buffer overflow Bit 5 ... 4: reserved Bit 6: Process interrupt lost Bit 7: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	Bit 6 ... 0: Channel type 70h: Digital input Bit 7: reserved

NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostics bits of the module per channel (here 00h)

NUMCH Channels

Byte	Bit 7 ... 0
0	Number of channels of the module (here 02h)

CHERR Channel error

Byte	Bit 7 ... 0
0	Bit 0: Edge lost at DI 0 Bit 1: Edge lost at DI 1 Bit 7 ... 2: reserved

CHxERR reserved

Byte	Bit 7 ... 0
0	reserved

DIAG_US µs ticker

Byte	Bit 7 ... 0
0 ... 3	Value of the µs ticker at the moment of the diagnostic

µs ticker

In the System SLIO module there is a 32 bit timer (µs ticker). With PowerON the timer starts counting with 0. After 2^{32}-1µs the timer starts with 0 again.

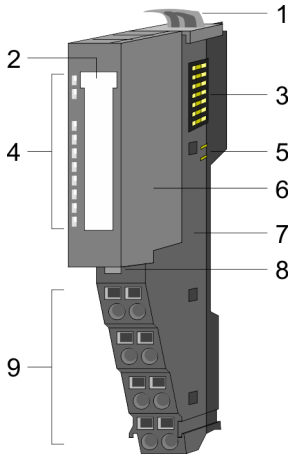
3.3 021-1BD00 - DI 4xDC 24V

Properties

The electronic module collects the binary control signals from the process level and transmits them isolated to the central bus system. It has 4 channels and their status is monitored via LEDs.

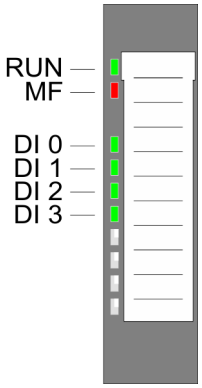
- 4 digital inputs, isolated to the backplane bus
- Suited for switches and approximate switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

Status indication



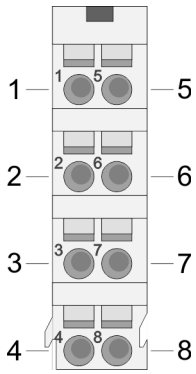
RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"

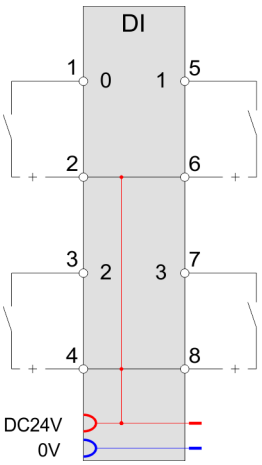
not relevant: X

021-1BD00 - DI 4xDC 24V

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	DC 24V	O	DC 24V for sensor
3	DI 2	I	Digital input DI 2
4	DC 24V	O	DC 24V for sensor
5	DI 1	I	Digital input DI 1
6	DC 24V	O	DC 24V for sensor
7	DI 3	I	Digital input DI 3
8	DC 24V	O	DC 24V for sensor

I: Input, O: Output

Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	5000h	
			Bit 0: DI 0		01h
			Bit 1: DI 1		02h
			Bit 2: DI 2		03h
			Bit 3: DI 3		04h
			Bit 7 ... 4: reserved		

Output area

No byte of the output area is used by the module.

3.3.1 Technical data

Order no.	021-1BD00
Type	SM 021 - Digital input
Module ID	0003 9F84
Current consumption/power loss	
Current consumption from backplane bus	65 mA
Power loss	0.6 W
Technical data digital inputs	
Number of inputs	4
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	-
Permitted range	-
Current consumption from power section supply (without load)	-
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 0...5 V
Input voltage for signal "1"	DC 15...28.8 V
Input voltage hysteresis	-
Signal logic input	Sinking input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	3 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	0.5 mA
Input delay of "0" to "1"	3 ms
Input delay of "1" to "0"	3 ms
Number of simultaneously utilizable inputs horizontal configuration	4
Number of simultaneously utilizable inputs vertical configuration	4
Input characteristic curve	IEC 61131-2, type 1
Initial data size	4 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no

Order no.	021-1BD00
Diagnostic functions	no
Diagnostics information read-out	none
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	1
Output bytes	0
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	57 g
Weight including accessories	57 g
Gross weight	72 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

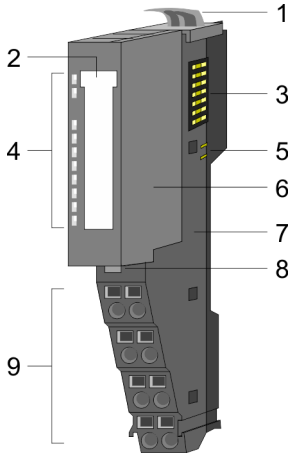
3.4 021-1BD10 - DI 4xDC 24V 2µs...3ms

Properties

The electronic module collects the binary control signals from the process level and transmits them isolated to the central bus system. It has 4 fast digital input channels and their status is monitored via LEDs.

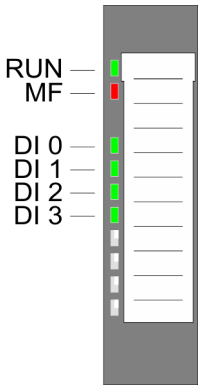
- 4 fast digital inputs, isolated to the backplane bus
- Input filter time delay parameterizable 2µs...3ms
- Interrupt and diagnostics function
- Suited for switches and approximate switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

Status indication

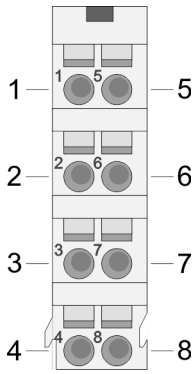


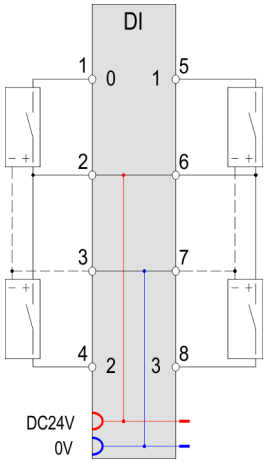
RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"
not relevant: X			

021-1BD10 - DI 4xDC 24V 2µs...3ms

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	DC 24V	O	DC 24V for sensor
3	0V	O	GND
4	DI 2	I	Digital input DI 2
5	DI 1	I	Digital input DI 1
6	DC 24V	O	DC 24V for sensor
7	0V	O	GND
8	DI 3	O	Digital input DI 3

I: Input, O: Output

Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	5000h	
			Bit 0: DI 0		01h
			Bit 1: DI 1		02h
			Bit 2: DI 2		03h
			Bit 3: DI 3		04h
			Bit 7 ... 4: reserved		

Output area

No byte of the output area is used by the module.

3.4.1 Technical data

Order no.	021-1BD10
Type	SM 021 - Digital input
Module ID	0009 1F04
Current consumption/power loss	
Current consumption from backplane bus	100 mA
Power loss	0.95 W
Technical data digital inputs	
Number of inputs	4
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	15 mA
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 0...5 V
Input voltage for signal "1"	DC 15...28.8 V
Input voltage hysteresis	-
Signal logic input	Sinking input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	3 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	0.5 mA
Input delay of "0" to "1"	parameterizable 2µs - 3ms
Input delay of "1" to "0"	parameterizable 2µs - 3ms
Number of simultaneously utilizable inputs horizontal configuration	4
Number of simultaneously utilizable inputs vertical configuration	4
Input characteristic curve	IEC 61131-2, type 1
Initial data size	4 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	yes, parameterizable
Process alarm	yes, parameterizable
Diagnostic interrupt	yes, parameterizable

Order no.	021-1BD10
Diagnostic functions	yes
Diagnostics information read-out	possible
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	1
Output bytes	0
Parameter bytes	11
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	59 g
Weight including accessories	59 g
Gross weight	73 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

3.4.2 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
DIAG_EN	1	Diagnostic interrupt[1]	00h	00h	3100h	01h
CH0D	1	Input delay DI 0	02h	01h	3101h	02h
CH1D	1	Input delay DI 1	02h	01h	3102h	03h
CH2D	1	Input delay DI 2	02h	01h	3103h	04h
CH3D	1	Input delay DI 3	02h	01h	3104h	05h
INTRE	1	Diagnostic interrupt at edge 0-1 of DI x	00h	80h	3105h	06h
INTFE	1	Diagnostic interrupt at edge 1-0 of DI x	00h	80h	3106h	07h

1) This record set may only be transferred at STOP state.

DIAG_EN Diagnostic interrupt

Byte	Bit 7 ... 0
0	Diagnostic interrupt 00h: disable 40h: enable

- Here you activate res. de-activate the diagnostic function.

CHxD Input delay

Byte	Function	Possible values	
0	Input delay DI x	00h: 2µs	07h: 86µs
		02h: 4µs	09h: 342µs
		04h: 12µs	0Ch: 2731µs
		Other values are not permissible!	

- *Input delay* allows you to preset a filter for the corresponding channel. With the help of filters you may e.g. filter signal peaks at a blurred input signal.

INTRE Interrupt edge 0-1

Byte	Bit 7 ... 0
0	Bit 0: Diagnostic interrupt at edge 0-1 of DI 0 Bit 1: Diagnostic interrupt at edge 0-1 of DI 1 Bit 2: Diagnostic interrupt at edge 0-1 of DI 2 Bit 3: Diagnostic interrupt at edge 0-1 of DI 3 (0: disable, 1: enable) Bit 7 ... 4: reserved

INTFE Interrupt edge 1-0

Byte	Bit 7 ... 0
0	Bit 0: Diagnostic interrupt at edge 1-0 of DI 0 Bit 1: Diagnostic interrupt at edge 1-0 of DI 1 Bit 2: Diagnostic interrupt at edge 1-0 of DI 2 Bit 3: Diagnostic interrupt at edge 1-0 of DI 3 (0: disable, 1: enable) Bit 7 ... 4: reserved

3.4.3 Diagnostics and interrupt

Event	Process interrupt	Diagnostics interrupt	parameterizable
Edge 0-1 DI x	X	-	X
Edge 1-0 DI x	X	-	X
Diagnostics buffer overflow	-	X	-
Process interrupt lost	-	X	-

Hardware interrupt

So you may react to asynchronous events, there is the possibility to activate a hardware interrupt.

- A hardware interrupt interrupts the linear program sequence and jumps depending on the master system to a corresponding Interrupt routine. Here you can react to the hardware interrupt accordingly.
- With CANopen the hardware interrupt data a transferred via an emergency telegram.
- Operating with CPU, PROFIBUS and PROFINET the hardware interrupt data were transferred via diagnostics telegram.

SX - Subindex for access via EtherCAT with Index 5000h

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	SX
PRIT_A	1	Process interrupt data	00h	02h
PRIT_B	1	State of the inputs	00h	03h
PRIT_US	2	µs ticker	00h	04h (high byte) 05h (low byte)

PRIT_A Process interrupt data

Byte	Bit 7 ... 0
0	Bit 0: Edge at Digital input DI 0 Bit 1: Edge at Digital input DI 1 Bit 2: Edge at Digital input DI 2 Bit 3: Edge at Digital input DI 3 Bit 7 ... 4: reserved

PRIT_B State of the inputs

Byte	Bit 7 ... 0
0	State of the inputs at the moment of the hardware interrupt Bit 0: State Input DI 0 Bit 1: State Input DI 1 Bit 2: State Input DI 2 Bit 3: State Input DI 3 Bit 7 ... 4: reserved

PRIT_US µs ticker

Byte	Bit 7 ... 0
0 ... 1	Value of the µs ticker at the moment of the hardware interrupt

µs ticker

In the System SLIO module there is a 32 bit timer (µs ticker). With PowerON the timer starts counting with 0. After 2^{32}-1µs the timer starts with 0 again.

PRIT_US represents the lower 2 byte of the µs ticker value (0 ... 2^{16}-1).

Diagnostic data

Via the parameterization you may activate a diagnostic interrupt for the module.

With a diagnostics interrupt the module serves for diagnostics data for diagnostic $interrupt_{incoming}$.

As soon as the reason for releasing a diagnostic interrupt is no longer present, the diagnostic $interrupt_{going}$ automatically takes place.

All events of a channel between diagnostic $interrupt_{incoming}$ and diagnostic $interrupt_{going}$ are not stored and get lost.

Within this time window (1. diagnostic $interrupt_{incoming}$ until last diagnostic $interrupt_{going}$) the MF-LED of the module is on.

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

IX - Index for access via CANopen. The access happens by IX 2F01h. Additionally the first 4 bytes may be accessed by IX 2F00h.

SX - Subindex for access via EtherCAT with Index 5005h.

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
ERR_A	1	Diagnostic	00h	01h	2F01h	02h
MODTYP	1	Module information	1Fh			03h
ERR_C	1	reserved	00h			04h
ERR_D	1	Diagnostic	00h			05h
CHTYP	1	Channel type	70h			06h
NUMBIT	1	Number of diagnostics bits per channel	00h			07h
NUMCH	1	Number channels of the module	04h			08h
CHERR	1	Channel error	00h			09h
CH0ERR… CH7ERR	8	reserved	00h			0Ah ... 11h
DIAG_US	4	µs ticker	00h			13h

ERR_A Diagnostic

Byte	Bit 7 ... 0
0	Bit 0: set at module failure Bit 1: reserved Bit 2: set at external error Bit 3: set at channel error Bit 7 ... 4: reserved

MODTYP Module information

Byte	Bit 7 ... 0
0	Bit 3 ... 0: Module class 1111b: Digital module Bit 4: Channel information present Bit 7 ... 5: reserved

ERR_C reserved

Byte	Bit 7 ... 0
0	reserved

ERR_D Diagnostic

Byte	Bit 7 ... 0
0	Bit 2 ... 0: reserved Bit 3: set at internal diagnostics buffer overflow Bit 5 ... 4: reserved Bit 6: Process interrupt lost Bit 7: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	Bit 6 ... 0: Channel type 70h: Digital input Bit 7: reserved

NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostics bits of the module per channel (here 00h)

NUMCH Channels

Byte	Bit 7 ... 0
0	Number of channels of the module (here 04h)

CHERR Channel error

Byte	Bit 7 ... 0
0	Bit 0: Edge lost at DI 0 Bit 1: Edge lost at DI 1 Bit 2: Edge lost at DI 2 Bit 3: Edge lost at DI 3 Bit 7 ... 4: reserved

CHxERR reserved

Byte	Bit 7 ... 0
0	reserved

DIAG_US µs ticker

Byte	Bit 7 ... 0
0 ... 3	Value of the µs ticker at the moment of the diagnostic

µs ticker

In the System SLIO module there is a 32 bit timer (µs ticker). With PowerON the timer starts counting with 0. After 2^{32}-1µs the timer starts with 0 again.

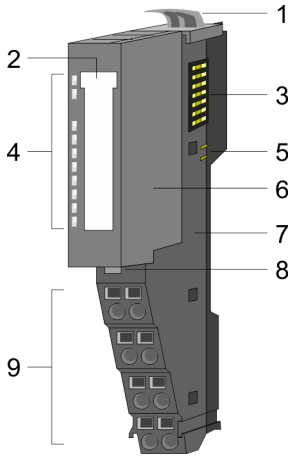
3.5 021-1BD40 - DI 4xDC 24V 3 wire

Properties

The electronic module collects the binary control signals from the process level and transmits them isolated to the central bus system. It has 4 channels and their status is monitored via LEDs.

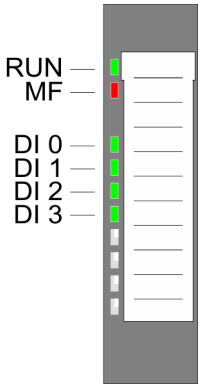
- 4 digital inputs with 3 wire connection, isolated to the backplane bus
- Suited for switches and approximate switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

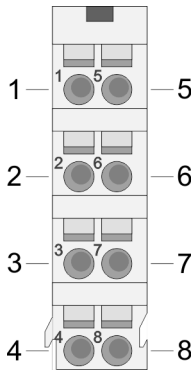
Status indication

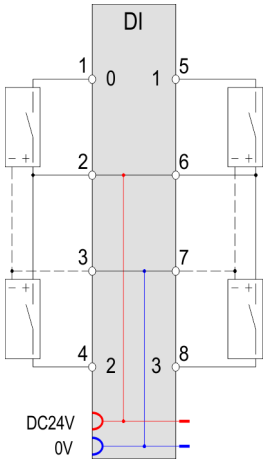


RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	DC 24V	O	DC 24V for sensor
3	0V	O	GND
4	DI 2	I	Digital input DI 2
5	DI 1	I	Digital input DI 1
6	DC 24V	O	DC 24V for sensor
7	0V	O	GND
8	DI 3	I	Digital input DI 3

I: Input, O: Output

Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	5000h	
			Bit 0: DI 0		01h
			Bit 1: DI 1		02h
			Bit 2: DI 2		03h
			Bit 3: DI 3		04h
			Bit 7 ... 4: reserved		

Output area

No byte of the output area is used by the module.

3.5.1 Technical data

Order no.	021-1BD40
Type	SM 021 - Digital input
Module ID	0008 9F84
Current consumption/power loss	
Current consumption from backplane bus	65 mA
Power loss	0.6 W
Technical data digital inputs	
Number of inputs	4
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	-
Permitted range	-
Current consumption from power section supply (without load)	-
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 0...5 V
Input voltage for signal "1"	DC 15...28.8 V
Input voltage hysteresis	-
Signal logic input	Sinking input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	3 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	0.5 mA
Input delay of "0" to "1"	3 ms
Input delay of "1" to "0"	3 ms
Number of simultaneously utilizable inputs horizontal configuration	4
Number of simultaneously utilizable inputs vertical configuration	4
Input characteristic curve	IEC 61131-2, type 1
Initial data size	4 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no

Order no.	021-1BD40
Diagnostic functions	no
Diagnostics information read-out	none
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	1
Output bytes	0
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	57 g
Weight including accessories	57 g
Gross weight	71 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

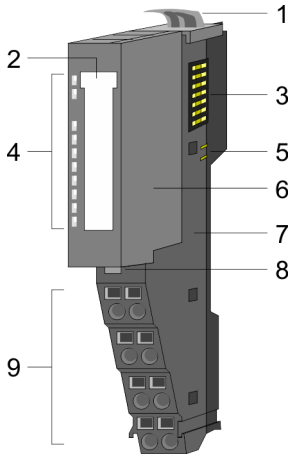
3.6 021-1BD50 - DI 4xDC 24V NPN

Properties

The electronic module collects the binary control signals from the process level and transmits them isolated to the central bus system. It has 4 channels and their status is monitored via LEDs. An input becomes active as soon as it is connected to ground.

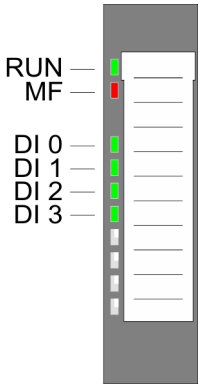
- 4 digital inputs (sourcing input), isolated to the backplane bus
- Suited for switches and approximate switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

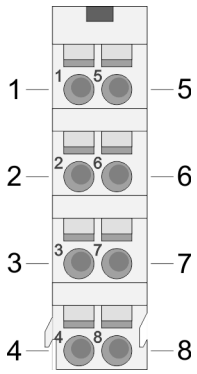
Status indication

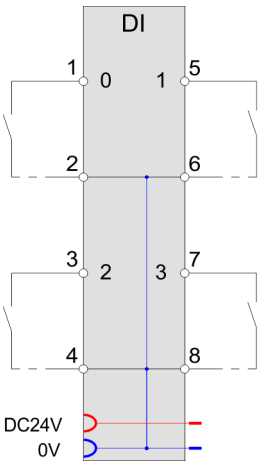


RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	0V	O	GND
3	DI 2	I	Digital input DI 2
4	0V	O	GND
5	DI 1	I	Digital input DI 1
6	0V	O	GND
7	DI 3	I	Digital input DI 3
8	0V	O	GND

I: Input, O: Output

Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	5000h	
			Bit 0: DI 0		01h
			Bit 1: DI 1		02h
			Bit 2: DI 2		03h
			Bit 3: DI 3		04h
			Bit 7 ... 4: reserved		

Output area

No byte of the output area is used by the module.

3.6.1 Technical data

Order no.	021-1BD50
Type	SM 021 - Digital input
Module ID	0004 9F84
Current consumption/power loss	
Current consumption from backplane bus	65 mA
Power loss	0.6 W
Technical data digital inputs	
Number of inputs	4
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	-
Permitted range	-
Current consumption from power section supply (without load)	-
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 15...28.8 V
Input voltage for signal "1"	DC 0...5 V
Input voltage hysteresis	-
Signal logic input	Sourcing input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	3 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	0.5 mA
Input delay of "0" to "1"	3 ms
Input delay of "1" to "0"	3 ms
Number of simultaneously utilizable inputs horizontal configuration	4
Number of simultaneously utilizable inputs vertical configuration	4
Input characteristic curve	-
Initial data size	4 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no

Order no.	021-1BD50
Diagnostic functions	no
Diagnostics information read-out	none
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	1
Output bytes	0
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	58 g
Weight including accessories	58 g
Gross weight	72 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

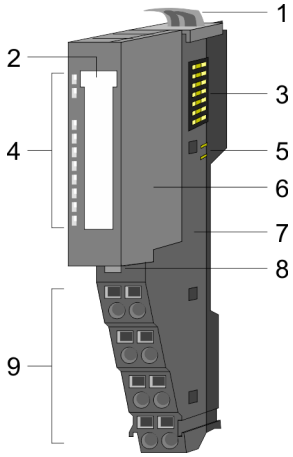
3.7 021-1BD70 - DI 4xDC 24V ETS

Properties

The electronic module collects the binary control signals from the process level and transmits them isolated to the central bus system. It has 4 channels and their status is monitored via LEDs. With configured ETS functionality (ETS = **e**dge **t**ime **s**tamp) and the corresponding (rising/falling) edge the current time value of the System SLIO µs timer is stored together with the state of the inputs in the process image. Depending on the configuration 5 (20byte) respectively 15 (60byte) ETS entries may be stored in the process image one after another.

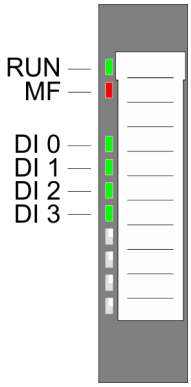
- 4 digital inputs, isolated to the backplane bus
- Configurable ETS functionality for 5 respectively 15 ETS entries (each 4byte)
- Diagnostics function
- Suited for switches and approximate switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

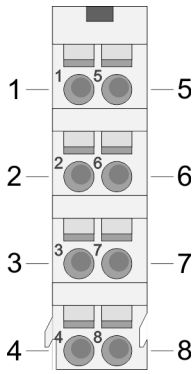
Status indication

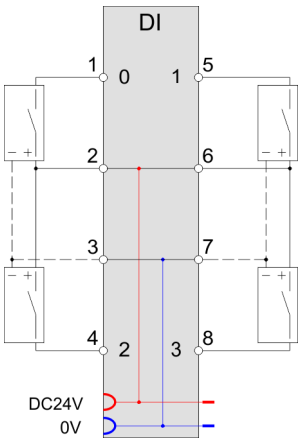


RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	DC 24V	O	DC 24V for sensor
3	0V	O	GND
4	DI 2	I	Digital input DI 2
5	DI 1	I	Digital input DI 1
6	DC 24V	O	DC 24V for sensor
7	0V	O	GND
8	DI 3	I	Digital input DI 3

I: Input, O: Output

Input area

With configured ETS functionality (ETS=**e**dge **t**ime **s**tamp) and the corresponding edge the current time value of the System SLIO µs timer is stored together with the state of the inputs and a running number as ETS entry in the process image. Each ETS entry uses 4byte in the input area. You may configure the following variants:

- 021-1BD70 DI 4xDC24V ETS(20): uses 20byte in the PII for 5 ETS entries
- 021-1BD70 DI 4xDC24V ETS: uses 60byte in the PII for 15 ETS entries

The input range is used for status message. At CPU, PROFIBUS and PROFINET the input respectively output area is embedded to the corresponding address area. More can be found in the according manual of your bus coupler.

IX - IX = Index for access via CANopen. With s = Subindex the corresponding ETS entry is addressed.

SX - Subindex for access via EtherCAT with Index 6000h + EtherCAT-Slot.

021-1BD70 - DI 4xDC 24V ETS

Configured as 021-1BD70 DI 4xDC 24V ETS(20)

20byte - 5 ETS entries

Addr.	PII	IX=5430h	SX	Addr.	RN	IX=5430h	SX	Addr.	ETS-US	IX=5430h	SX
+0	PII-0	s=1	01h	+1	RN-0	s=1	02h	+2	ETS_US-0	s=1	03h
+4	PII-1	s=2	04h	+5	RN-1	s=2	05h	+6	ETS_US-1	s=2	06h
+8	PII-2	s=3	07h	+9	RN-2	s=3	08h	+10	ETS_US-2	s=3	09h
+12	PII-3	s=4	0Ah	+13	RN-3	s=4	0Bh	+14	ETS_US-3	s=4	0Ch
+16	PII-4	s=5	0Dh	+17	RN-4	s=5	0Eh	+18	ETS_US-4	s=5	0Fh

Configured as 021-1BD70 DI 4xDC 24V ETS

60byte - 15 ETS entries

Addr.	PII	IX=5430h	SX	Addr.	RN	IX=5430h	SX	Addr.	ETS-US	IX=5430h	SX
+0	PII-0	s=1	01h	+1	RN-0	s=1	02h	+2	ETS_US-0	s=1	03h
+4	PII-1	s=2	04h	+5	RN-1	s=2	05h	+6	ETS_US-1	s=2	06h
+8	PII-2	s=3	07h	+9	RN-2	s=3	08h	+10	ETS_US-2	s=3	09h
+12	PII-3	s=4	0Ah	+13	RN-3	s=4	0Bh	+14	ETS_US-3	s=4	0Ch
+16	PII-4	s=5	0Dh	+17	RN-4	s=5	0Eh	+18	ETS_US-4	s=5	0Fh
+20	PII-5	s=6	10h	+21	RN-5	s=6	11h	+22	ETS_US-5	s=6	12h
+24	PII-6	s=7	13h	+25	RN-6	s=7	14h	+26	ETS_US-6	s=7	15h
+28	PII-7	s=8	16h	+29	RN-7	s=8	17h	+30	ETS_US-7	s=8	18h
+32	PII-8	s=9	19h	+33	RN-8	s=9	1Ah	+34	ETS_US-8	s=9	1Bh
+36	PII-9	s=10	1Ch	+37	RN-9	s=10	1Dh	+38	ETS_US-9	s=10	1Eh
+40	PII-10	s=11	1Fh	+41	RN-10	s=11	20h	+42	ETS_US-10	s=11	21h
+44	PII-11	s=12	22h	+45	RN-11	s=12	23h	+46	ETS_US-11	s=12	24h
+48	PII-12	s=13	25h	+49	RN-12	s=13	26h	+50	ETS_US-12	s=13	27h
+52	PII-13	s=14	28h	+53	RN-13	s=14	29h	+54	ETS_US-13	s=14	2Ah

Output area No byte of the output area is used by the module.

Structure of an ETS entry

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	5430h/s	01h
+1	RN	1	Running number		02h
+2	ETS_US	2	µs ticker		03h

PII

Here the state of the inputs after an edge change is stored.

The input byte has the following bit assignment:

Bit 0: DI 0

Bit 1: DI 1

Bit 2: DI 2

Bit 3: DI 3

Bit 4 ... 7: 0 (fix)

RN

The **R**unning **N**umber (RN) is a continuous number 0 ... 127, which starts with 1. The RN corresponds to the chronological order of the edges.

ETS_US

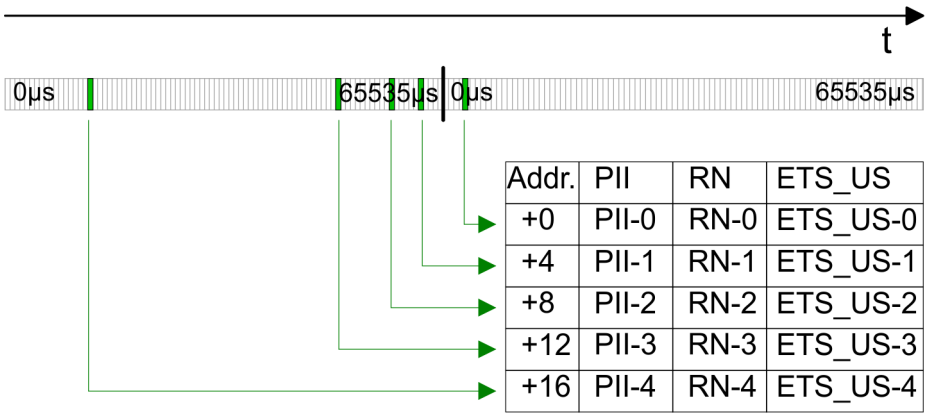
In the System SLIO module there is a 32 bit timer (µs ticker). With PowerON the timer starts counting with 0. After 2^{32}-1µs the timer starts with 0 again.

ETS_US always contains the low word of the µs ticker (0...65535µs).

ETS functionality

With the corresponding edge the value of the timer is stored as ETS entry in the process image as ETS_US together with the state of the inputs PII and the running number RN.

The following figure shows the sequence of how the ETS entries are stored in the input area.



Addr.	PII	RN	ETS_US
+0	PII-0	RN-0	ETS_US-0
+4	PII-1	RN-1	ETS_US-1
+8	PII-2	RN-2	ETS_US-2
+12	PII-3	RN-3	ETS_US-3
+16	PII-4	RN-4	ETS_US-4

The ETS module may only be accessed by the System SLIO CPU by means of SFC 14 or via the process image.

3.7.1 Technical data

Order no.	021-1BD70
Type	SM 021 - Digital input
Module ID	0F03 47C2
Current consumption/power loss	
Current consumption from backplane bus	100 mA
Power loss	0.95 W
Technical data digital inputs	
Number of inputs	4
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	15 mA
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 0...5 V
Input voltage for signal "1"	DC 15...28.8 V
Input voltage hysteresis	-
Signal logic input	Sinking input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	3 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	0.5 mA
Input delay of "0" to "1"	parameterizable 2µs - 3ms
Input delay of "1" to "0"	parameterizable 2µs - 3ms
Number of simultaneously utilizable inputs horizontal configuration	4
Number of simultaneously utilizable inputs vertical configuration	4
Input characteristic curve	IEC 61131-2, type 1
Initial data size	60 Byte
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no

Order no.	021-1BD70
Diagnostic functions	no
Diagnostics information read-out	possible
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	20 / 60
Output bytes	0
Parameter bytes	12
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	58 g
Weight including accessories	58 g
Gross weight	73 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

3.7.2 Parameter data

The following variants may be configured:

- 021-1BD70 DI 4xDC24V ETS(20):
  uses 20byte in the PII for 5 ETS entries
- 021-1BD70 DI 4xDC24V ETS:
  uses 60byte in the PII for 15 ETS entries

3.7.2.1 Parameters

DS - Record set for access via CPU, PROFIBUS and PROFINET

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
PII_L	1	Length process image input data[1, 2]	14h resp. 3Ch (fix)	02h	3100h	01h
PIQ_L	1	Length process image output data[2]	00h (fix)	02h	3101h	02h
CH0D	1	Input delay DI 0	02h	01h	3102h	03h
CH1D	1	Input delay DI 1	02h	01h	3103h	04h
CH2D	1	Input delay DI 2	02h	01h	3104h	05h
CH3D	1	Input delay DI 3	02h	01h	3105h	06h
TSER	1	Raising edge 0-1 at DI x	00h	80h	3106h	07h
TSEF	1	Falling edge 1-0 at DI x	00h	80h	3107h	08h

1) This parameter corresponds of the configured variant.

2) This record set may only be transferred at STOP state.

PII_L

Byte	Bit 7 ... 0
0	The length of the process image of the input data is fix set to the configured variant (14h or 3Ch).

PIQ_L

Byte	Bit 7 ... 0
0	The length of the process image of the output data is fix set to 0 byte.

CHxD DI x

Byte	Description	Possible values	
0	Input delay DI x	00h: 2µs	07h: 86µs
		02h: 4µs	09h: 342µs
		04h: 12µs	0Ch: 2731µs
		Other values are not permissible!	

With the help of filters you may e.g. filter signal peaks at a blurred input signal.

Edge select

Here the ETS function for DI 0 ... DI 3 may be activated. With these 2 bytes you may define the type of edge of the input signal, to which the current µs timer value is stored in the process image together with the state of the inputs.

TSER edge 0-1 DI x

Byte	Bit 7 ... 0
0	Bit 0: ETS record at edge 0-1 (rising edge) DI 0 Bit 1: ETS record at edge 0-1 (rising edge) DI 1 Bit 2: ETS record at edge 0-1 (rising edge) DI 2 Bit 3: ETS record at edge 0-1 (rising edge) DI 3 (0: disable, 1: enable) Bit 7 ... 4: reserved

TSEF edge 1-0 DI x

Byte	Bit 7 ... 0
0	Bit 0: ETS record at edge 1-0 (falling edge) DI 0 Bit 1: ETS record at edge 1-0 (falling edge) DI 1 Bit 2: ETS record at edge 1-0 (falling edge) DI 2 Bit 3: ETS record at edge 1-0 (falling edge) DI 3 (0: disable, 1: enable) Bit 7 ... 4: reserved

3.7.3 Example of the principle of operation

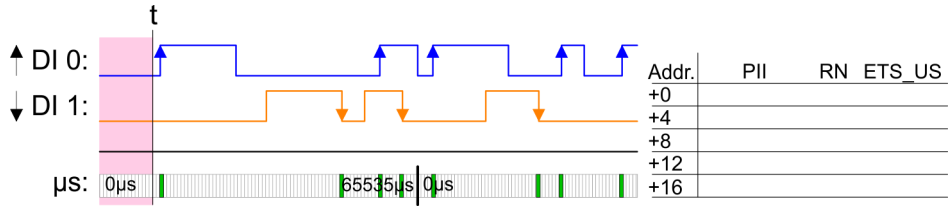
In the following it is demonstrated by an example, in which order the ETS entries are stored. In this example a module is configured, which occupies 20byte for 5 ETS entries. The following edges for the input channels are preset.

- DI 0: Edge 0-1: ↑
- DI 1: Edge 1-0: ↓
- DI 2 and DI 3 are 0 constant

The green area in the diagram indicates the ETS entries available at time "t". ETS entries that are not (or no longer) available are highlighted in red.

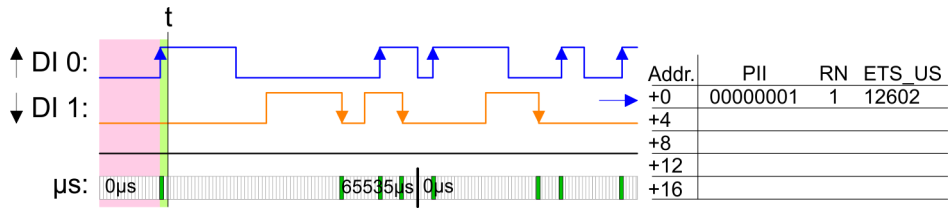
Process image is empty

New ETS entries are always registered starting from address +0. Thereby already existing ETS entries are shifted 4 byte each.



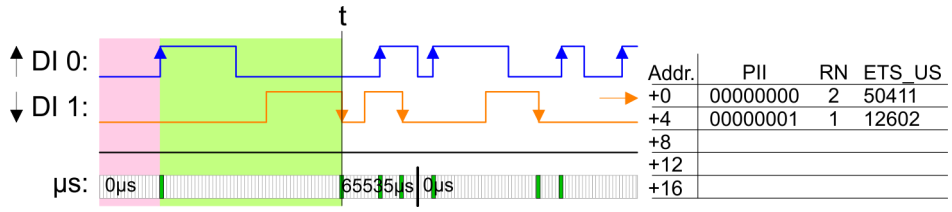
1. ETS entry

Released by an edge 0-1 from DI 0 the 1. ETS entry is registered starting from address +0.



2. ETS entry

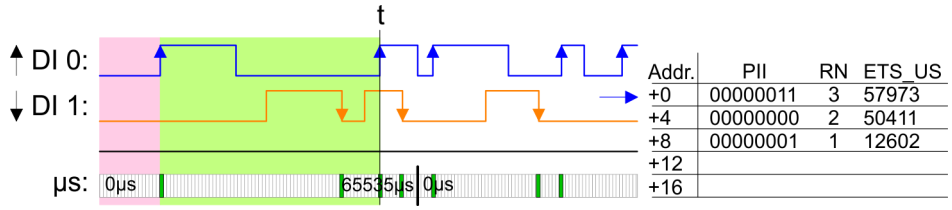
Released by an edge 1-0 from DI 1 the 2. ETS entry is registered starting from address +0 and the 1. ETS entry is shifted 4 byte.



Addr.	PII	RN	ETS_US
+0	00000000	2	50411
+4	00000001	1	12602
+8			
+12			
+16			

3. ETS entry

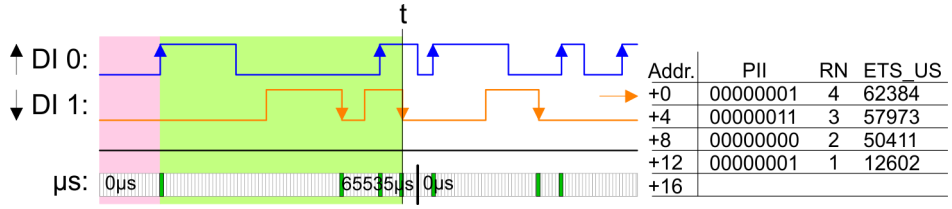
Released by an edge 0-1 from DI 0 the 3. ETS entry is registered starting from address +0 and already existing ETS entries are shifted 4 byte each.



Addr.	PII	RN	ETS_US
+0	00000011	3	57973
+4	00000000	2	50411
+8	00000001	1	12602
+12			
+16			

4. ETS entry

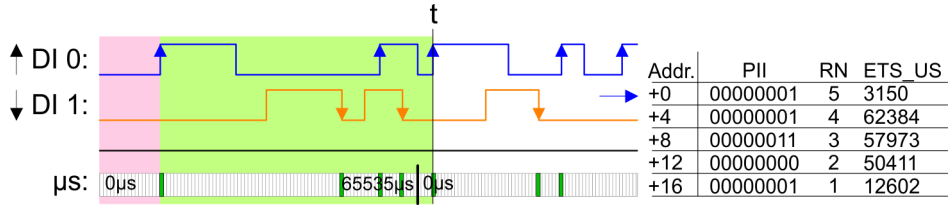
Released by an edge 1-0 from DI 1 the 4. ETS entry is registered starting from address +0 and already existing ETS entries are shifted 4 byte each.



Addr.	PII	RN	ETS_US
+0	00000001	4	62384
+4	00000011	3	57973
+8	00000000	2	50411
+12	00000001	1	12602
+16			

5. ETS entry

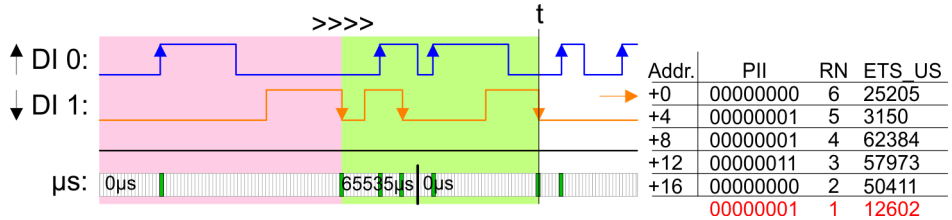
Released by an edge 0-1 from DI 0 the 5. ETS entry is registered starting from address +0 and already existing ETS entries are shifted 4 byte each. The maximum number of ETS entries is reached.



Addr.	PII	RN	ETS_US
+0	00000001	5	3150
+4	00000001	4	62384
+8	00000011	3	57973
+12	00000000	2	50411
+16	00000001	1	12602

6. ETS entry

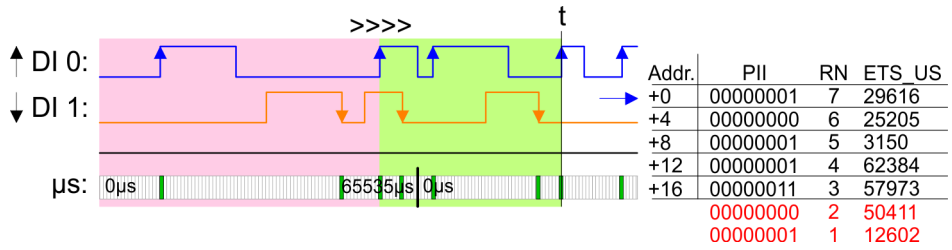
Released by an edge 1-0 from DI 1 the 6. ETS entry is registered starting from address +0 and already existing ETS entries are shifted 4 byte each. Thereby the 1. ETS entry is deleted and is not available any longer.



Addr.	PII	RN	ETS_US
+0	00000000	6	25205
+4	00000001	5	3150
+8	00000001	4	62384
+12	00000011	3	57973
+16	00000000	2	50411
	00000001	1	12602

7. ETS entry

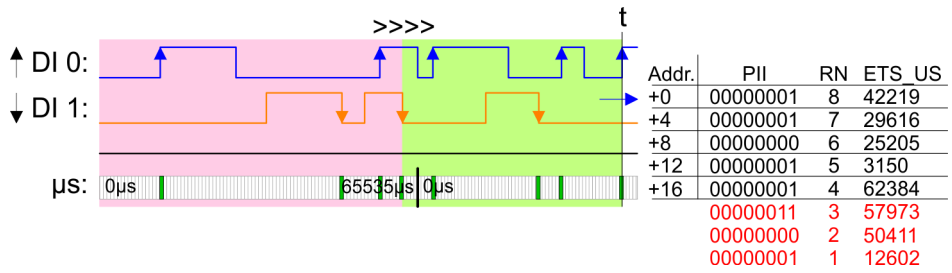
Released by an edge 0-1 from DI 0 the 7. ETS entry is registered starting from address +0 and already existing ETS entries are shifted 4 byte each. Thereby the 2. ETS entry is deleted and is not available any longer.



Addr.	PII	RN	ETS_US
+0	00000001	7	29616
+4	00000000	6	25205
+8	00000001	5	3150
+12	00000001	4	62384
+16	00000011	3	57973
	00000000	2	50411
	00000001	1	12602

8. ETS entry

Released by an edge 0-1 from DI 0 the 8. ETS entry is registered starting from address +0 and already existing ETS entries are shifted 4 byte each. Thereby the 3. ETS entry is deleted and is not available any longer.



Addr.	PII	RN	ETS_US
+0	00000001	8	42219
+4	00000001	7	29616
+8	00000000	6	25205
+12	00000001	5	3150
+16	00000001	4	62384
	00000011	3	57973
	00000000	2	50411
	00000001	1	12602

Please consider the ETS modules can only effectively be used together with head modules, which have an integrated µs ticker. The Ethernet coupler with ModbusTCP 053-1MT00 for example does not have an µs ticker.

3.7.4 Diagnostic data

So this module does not support interrupt functions, the diagnostic data serve the information about this module.

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

IX - Index for access via CANopen. The access happens by IX 2F01h. Additionally the first 4 bytes may be accessed by IX 2F00h.

SX - Subindex for access via EtherCAT with Index 5005h.

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
ERR_A	1	reserved	00h	01h	2F01h	02h
MODTYP	1	Module information	1Fh			03h
ERR_C	1	reserved	00h			04h
ERR_D	1	reserved	00h			05h
CHTYP	1	Channel type	70h			06h
NUMBIT	1	Number diagnostics bits per channel	00h			07h
NUMCH	1	Number channels of the module	04h			08h
CHERR	1	reserved	00h			09h
CH0ERR… CH7ERR	8	reserved	00h			0Ah ... 11h
DIAG_US	4	µs ticker (32bit)	00h			13h

MODTYP Module information

Byte	Bit 7 ... 0
0	Bit 3 ... 0: Module class 1111b Digital module Bit 4: Channel information present Bit 7 ... 5: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	Bit 6 ... 0: Channel type 70h: Digital input Bit 7: 0 (fix)

NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostics bits of the module per channel (here 00h)

NUMCH channels

Byte	Bit 7 ... 0
0	Number of channels of the module (here 04h)

DIAG_US µs ticker

Byte	Bit 7 ... 0
0 ... 3	Value of the µs ticker at the moment of the diagnostic data generation

ERR_A/C/D CHERR, CHxERR reserved

Byte	Bit 7 ... 0
0	reserved

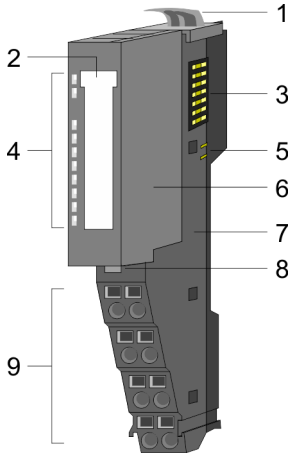
3.8 021-1BD80 - DI 4xDC 24V ETS NPN

Properties

The electronic module collects the binary control signals from the process level and transmits them isolated to the central bus system. It has 4 channels and their status is monitored via LEDs. An input becomes active as soon as it is connected to ground. With configured ETS functionality (ETS = **e**dge **t**ime **s**tamp) and the corresponding (rising/falling) edge the current time value of the System SLIO µs timer is stored together with the state of the inputs in the process image. Depending on the configuration 5 (20byte) respectively 15 (60byte) ETS entries may be stored in the process image one after another.

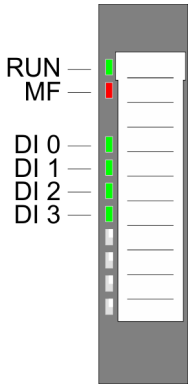
- 4 digital inputs, isolated to the backplane bus
- Configurable ETS functionality for 5 respectively 15 ETS entries (each 4byte)
- Diagnostics function
- Suited for switches and approximate switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

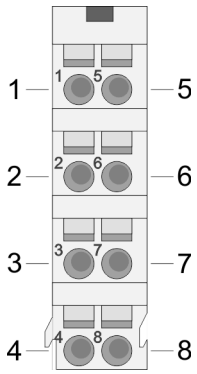
Status indication

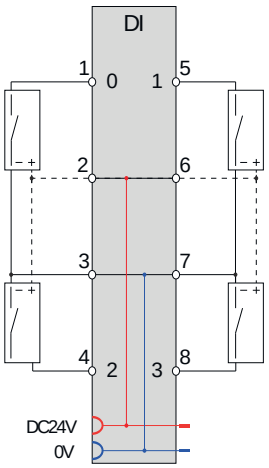


RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"
not relevant: X			

Pin assignment

For wires with a core cross-section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	DC 24V	O	DC 24V for sensor
3	0V	O	GND
4	DI 2	I	Digital input DI 2
5	DI 1	I	Digital input DI 1
6	DC 24V	O	DC 24V for sensor
7	0V	O	GND
8	DI 3	I	Digital input DI 3

I: Input, O: Output

Input area

With configured ETS functionality (ETS=**e**dge **t**ime **s**tamp) and the corresponding edge the current time value of the System SLIO µs timer is stored together with the state of the inputs and a running number as ETS entry in the process image. Each ETS entry uses 4byte in the input area. You may configure the following variants:

- 021-1BD80 DI 4xDC24V ETS NPN(20): uses 20byte in the PII for 5 ETS entries
- 021-1BD80 DI 4xDC24V ETS NPN: uses 60byte in the PII for 15 ETS entries

The input range is used for status message. At CPU, PROFIBUS and PROFINET the input respectively output area is embedded to the corresponding address area. More can be found in the according manual of your bus coupler.

IX - IX = Index for access via CANopen. With s = Subindex the corresponding ETS entry is addressed.

SX - Subindex for access via EtherCAT with Index 6000h + EtherCAT-Slot.

Configured as 021-1BD80 DI 4xDC 24V ETS NPN(20)
20byte - 5 ETS entries

Addr.	PII	IX=5430h	SX	Addr.	RN	IX=5430h	SX	Addr.	ETS-US	IX=5430h	SX
+0	PII-0	s=1	01h	+1	RN-0	s=1	02h	+2	ETS_US-0	s=1	03h
+4	PII-1	s=2	04h	+5	RN-1	s=2	05h	+6	ETS_US-1	s=2	06h
+8	PII-2	s=3	07h	+9	RN-2	s=3	08h	+10	ETS_US-2	s=3	09h
+12	PII-3	s=4	0Ah	+13	RN-3	s=4	0Bh	+14	ETS_US-3	s=4	0Ch
+16	PII-4	s=5	0Dh	+17	RN-4	s=5	0Eh	+18	ETS_US-4	s=5	0Fh

Configured as 021-1BD80 DI 4xDC 24V ETS NPN
60byte - 15 ETS entries

Addr.	PII	IX=5430h	SX	Addr.	RN	IX=5430h	SX	Addr.	ETS-US	IX=5430h	SX
+0	PII-0	s=1	01h	+1	RN-0	s=1	02h	+2	ETS_US-0	s=1	03h
+4	PII-1	s=2	04h	+5	RN-1	s=2	05h	+6	ETS_US-1	s=2	06h
+8	PII-2	s=3	07h	+9	RN-2	s=3	08h	+10	ETS_US-2	s=3	09h
+12	PII-3	s=4	0Ah	+13	RN-3	s=4	0Bh	+14	ETS_US-3	s=4	0Ch
+16	PII-4	s=5	0Dh	+17	RN-4	s=5	0Eh	+18	ETS_US-4	s=5	0Fh
+20	PII-5	s=6	10h	+21	RN-5	s=6	11h	+22	ETS_US-5	s=6	12h
+24	PII-6	s=7	13h	+25	RN-6	s=7	14h	+26	ETS_US-6	s=7	15h
+28	PII-7	s=8	16h	+29	RN-7	s=8	17h	+30	ETS_US-7	s=8	18h
+32	PII-8	s=9	19h	+33	RN-8	s=9	1Ah	+34	ETS_US-8	s=9	1Bh
+36	PII-9	s=10	1Ch	+37	RN-9	s=10	1Dh	+38	ETS_US-9	s=10	1Eh
+40	PII-10	s=11	1Fh	+41	RN-10	s=11	20h	+42	ETS_US-10	s=11	21h
+44	PII-11	s=12	22h	+45	RN-11	s=12	23h	+46	ETS_US-11	s=12	24h
+48	PII-12	s=13	25h	+49	RN-12	s=13	26h	+50	ETS_US-12	s=13	27h
+52	PII-13	s=14	28h	+53	RN-13	s=14	29h	+54	ETS_US-13	s=14	2Ah

Output area No byte of the output area is used by the module.

Structure of an ETS entry

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	5430h/s	01h
+1	RN	1	Running number		02h
+2	ETS_US	2	µs ticker		03h

PII

Here the state of the inputs after an edge change is stored.

The input byte has the following bit assignment:

Bit 0: DI 0

Bit 1: DI 1

Bit 2: DI 2

Bit 3: DI 3

Bit 4 ... 7: 0 (fix)

RN

The **R**unning **N**umber (RN) is a continuous number 0 ... 127, which starts with 1. The RN corresponds to the chronological order of the edges.

ETS_US

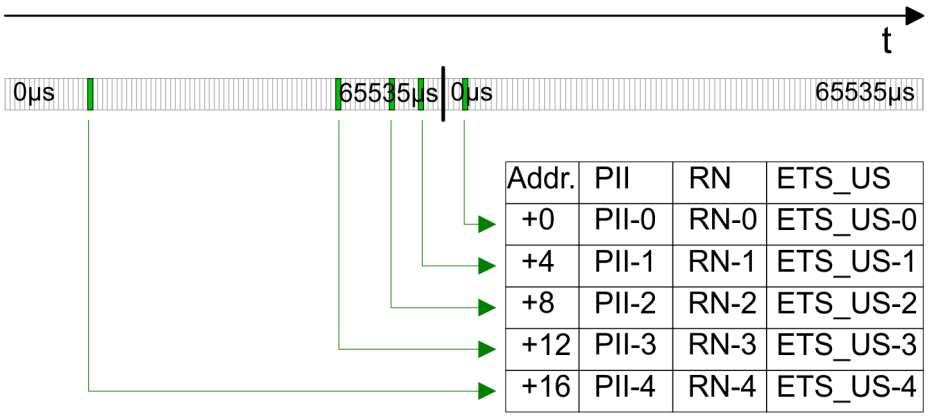
In the System SLIO module there is a 32 bit timer (µs ticker). With PowerON the timer starts counting with 0. After 2^{32}-1µs the timer starts with 0 again.

ETS_US always contains the low word of the µs ticker (0...65535µs).

ETS functionality

With the corresponding edge the value of the timer is stored as ETS entry in the process image as ETS_US together with the state of the inputs PII and the running number RN.

The following figure shows the sequence of how the ETS entries are stored in the input area.



Addr.	PII	RN	ETS_US
+0	PII-0	RN-0	ETS_US-0
+4	PII-1	RN-1	ETS_US-1
+8	PII-2	RN-2	ETS_US-2
+12	PII-3	RN-3	ETS_US-3
+16	PII-4	RN-4	ETS_US-4

The ETS module may only be accessed by the System SLIO CPU by means of SFC 14 or via the process image.

3.8.1 Technical data

Order no.	021-1BD80
Type	SM 021 - Digital input
Module ID	0F06 47C2
Current consumption/power loss	
Current consumption from backplane bus	32 mA
Power loss	0.6 W
Technical data digital inputs	
Number of inputs	4
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	18 mA
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 15...28.8 V
Input voltage for signal "1"	DC 0...5 V
Input voltage hysteresis	-
Signal logic input	Sourcing input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	3 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	0.5 mA
Input delay of "0" to "1"	parameterizable 2µs - 3ms
Input delay of "1" to "0"	parameterizable 2µs - 3ms
Number of simultaneously utilizable inputs horizontal configuration	4
Number of simultaneously utilizable inputs vertical configuration	4
Input characteristic curve	IEC 61131-2, type 3
Initial data size	60 Byte
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no

Order no.	021-1BD80
Diagnostic functions	no
Diagnostics information read-out	possible
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	20 / 60
Output bytes	0
Parameter bytes	12
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	58 g
Weight including accessories	58 g
Gross weight	73 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

3.8.2 Parameter data

The following variants may be configured:

- 021-1BD80 DI 4xDC24V ETS NPN(20):
  uses 20byte in the PII for 5 ETS entries
- 021-1BD80 DI 4xDC24V ETS NPN:
  uses 60byte in the PII for 15 ETS entries

3.8.2.1 Parameters

DS - Record set for access via CPU, PROFIBUS and PROFINET

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
PII_L	1	Length process image input data[1, 2]	14h resp. 3Ch (fix)	02h	3100h	01h
PIQ_L	1	Length process image output data[2]	00h (fix)	02h	3101h	02h
CH0D	1	Input delay DI 0	02h	01h	3102h	03h
CH1D	1	Input delay DI 1	02h	01h	3103h	04h
CH2D	1	Input delay DI 2	02h	01h	3104h	05h
CH3D	1	Input delay DI 3	02h	01h	3105h	06h
TSER	1	Raising edge 0-1 at DI x	00h	80h	3106h	07h
TSEF	1	Falling edge 1-0 at DI x	00h	80h	3107h	08h

1) This parameter corresponds of the configured variant.

2) This record set may only be transferred at STOP state.

PII_L

Byte	Bit 7 ... 0
0	The length of the process image of the input data is fix set to the configured variant (14h or 3Ch).

PIQ_L

Byte	Bit 7 ... 0
0	The length of the process image of the output data is fix set to 0 byte.

CHxD DI x

Byte	Description	Possible values	
0	Input delay DI x	00h: 2µs	07h: 86µs
		02h: 4µs	09h: 342µs
		04h: 12µs	0Ch: 2731µs
		Other values are not permissible!	

With the help of filters you may e.g. filter signal peaks at a blurred input signal.

Edge select

Here the ETS function for DI 0 ... DI 3 may be activated. With these 2 bytes you may define the type of edge of the input signal, to which the current µs timer value is stored in the process image together with the state of the inputs.

TSER edge 0-1 DI x

Byte	Bit 7 ... 0
0	Bit 0: ETS record at edge 0-1 (rising edge) DI 0 Bit 1: ETS record at edge 0-1 (rising edge) DI 1 Bit 2: ETS record at edge 0-1 (rising edge) DI 2 Bit 3: ETS record at edge 0-1 (rising edge) DI 3 (0: disable, 1: enable) Bit 7 ... 4: reserved

TSEF edge 1-0 DI x

Byte	Bit 7 ... 0
0	Bit 0: ETS record at edge 1-0 (falling edge) DI 0 Bit 1: ETS record at edge 1-0 (falling edge) DI 1 Bit 2: ETS record at edge 1-0 (falling edge) DI 2 Bit 3: ETS record at edge 1-0 (falling edge) DI 3 (0: disable, 1: enable) Bit 7 ... 4: reserved

3.8.3 Example of the principle of operation

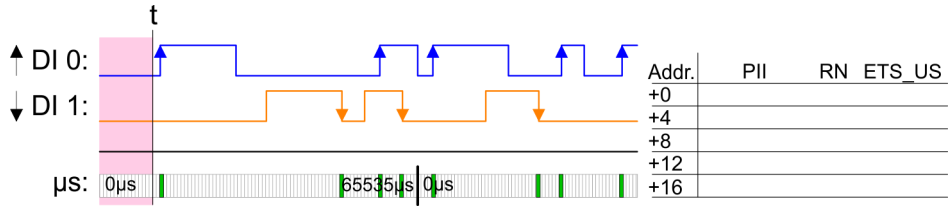
In the following it is demonstrated by an example, in which order the ETS entries are stored. In this example a module is configured, which occupies 20byte for 5 ETS entries. The following edges for the input channels are preset.

- DI 0: Edge 0-1: ↑
- DI 1: Edge 1-0: ↓
- DI 2 and DI 3 are 0 constant

The green area in the diagram indicates the ETS entries available at time "t". ETS entries that are not (or no longer) available are highlighted in red.

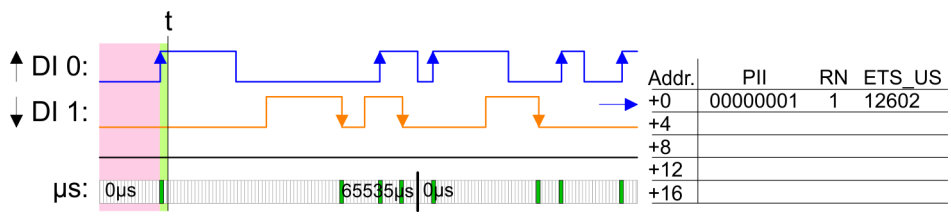
Process image is empty

New ETS entries are always registered starting from address +0. Thereby already existing ETS entries are shifted 4 byte each.



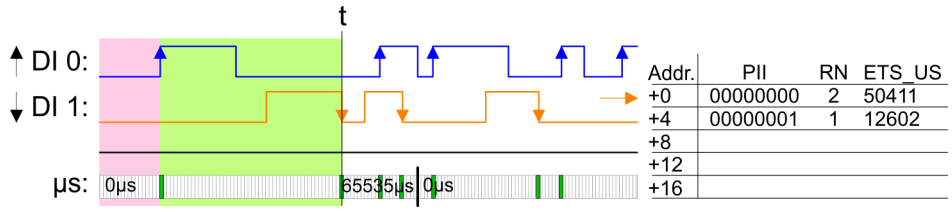
1. ETS entry

Released by an edge 0-1 from DI 0 the 1. ETS entry is registered starting from address +0.



2. ETS entry

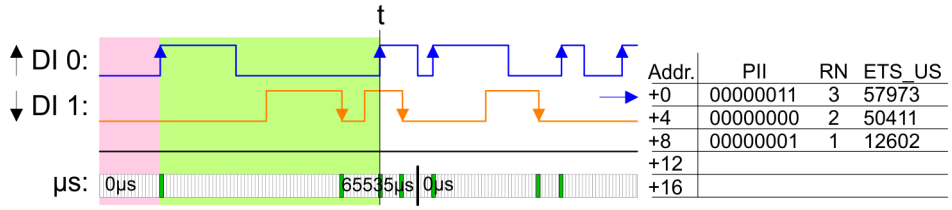
Released by an edge 1-0 from DI 1 the 2. ETS entry is registered starting from address +0 and the 1. ETS entry is shifted 4 byte.



Addr.	PII	RN	ETS_US
+0	00000000	2	50411
+4	00000001	1	12602
+8			
+12			
+16			

3. ETS entry

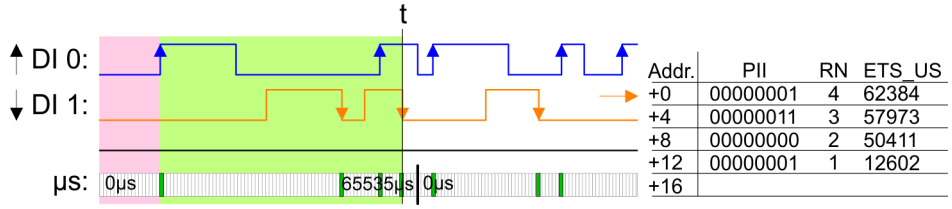
Released by an edge 0-1 from DI 0 the 3. ETS entry is registered starting from address +0 and already existing ETS entries are shifted 4 byte each.



Addr.	PII	RN	ETS_US
+0	00000011	3	57973
+4	00000000	2	50411
+8	00000001	1	12602
+12			
+16			

4. ETS entry

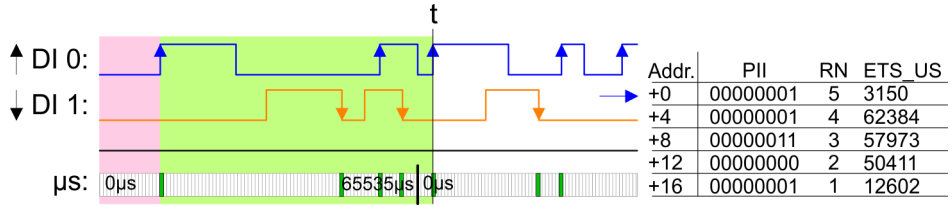
Released by an edge 1-0 from DI 1 the 4. ETS entry is registered starting from address +0 and already existing ETS entries are shifted 4 byte each.



Addr.	PII	RN	ETS_US
+0	00000001	4	62384
+4	00000011	3	57973
+8	00000000	2	50411
+12	00000001	1	12602
+16			

5. ETS entry

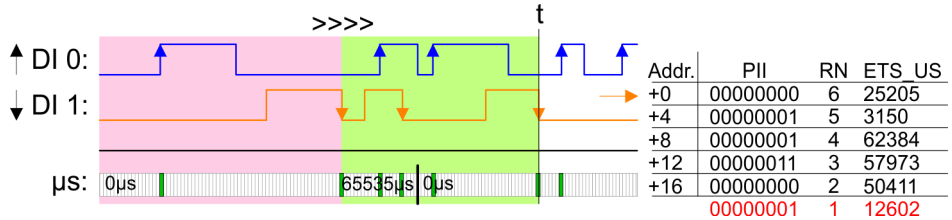
Released by an edge 0-1 from DI 0 the 5. ETS entry is registered starting from address +0 and already existing ETS entries are shifted 4 byte each. The maximum number of ETS entries is reached.



Addr.	PII	RN	ETS_US
+0	00000001	5	3150
+4	00000001	4	62384
+8	00000011	3	57973
+12	00000000	2	50411
+16	00000001	1	12602

6. ETS entry

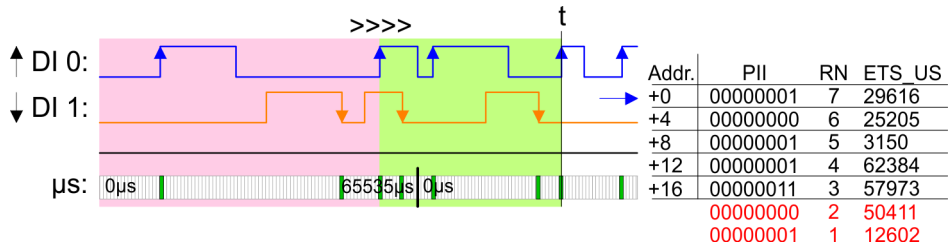
Released by an edge 1-0 from DI 1 the 6. ETS entry is registered starting from address +0 and already existing ETS entries are shifted 4 byte each. Thereby the 1. ETS entry is deleted and is not available any longer.



Addr.	PII	RN	ETS_US
+0	00000000	6	25205
+4	00000001	5	3150
+8	00000001	4	62384
+12	00000011	3	57973
+16	00000000	2	50411
	00000001	1	12602

7. ETS entry

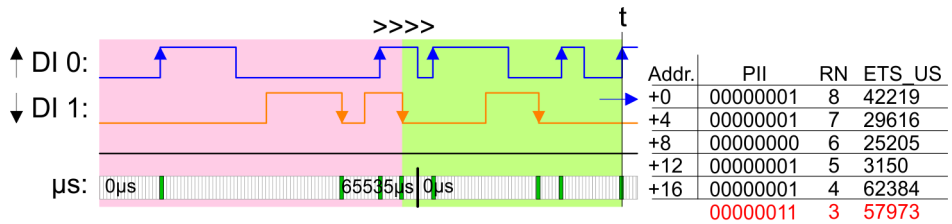
Released by an edge 0-1 from DI 0 the 7. ETS entry is registered starting from address +0 and already existing ETS entries are shifted 4 byte each. Thereby the 2. ETS entry is deleted and is not available any longer.



Addr.	PII	RN	ETS_US
+0	00000001	7	29616
+4	00000000	6	25205
+8	00000001	5	3150
+12	00000001	4	62384
+16	00000011	3	57973
	00000000	2	50411
	00000001	1	12602

8. ETS entry

Released by an edge 0-1 from DI 0 the 8. ETS entry is registered starting from address +0 and already existing ETS entries are shifted 4 byte each. Thereby the 3. ETS entry is deleted and is not available any longer.



Addr.	PII	RN	ETS_US
+0	00000001	8	42219
+4	00000001	7	29616
+8	00000000	6	25205
+12	00000001	5	3150
+16	00000001	4	62384
	00000011	3	57973
	00000000	2	50411
	00000001	1	12602

Please consider the ETS modules can only effectively be used together with head modules, which have an integrated µs ticker. The Ethernet coupler with ModbusTCP 053-1MT00 for example does not have an µs ticker.

3.8.4 Diagnostic data

So this module does not support interrupt functions, the diagnostic data serve the information about this module.

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

IX - Index for access via CANopen. The access happens by IX 2F01h. Additionally the first 4 bytes may be accessed by IX 2F00h.

SX - Subindex for access via EtherCAT with Index 5005h.

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
ERR_A	1	reserved	00h	01h	2F01h	02h
MODTYP	1	Module information	1Fh			03h
ERR_C	1	reserved	00h			04h
ERR_D	1	reserved	00h			05h
CHTYP	1	Channel type	70h			06h
NUMBIT	1	Number diagnostics bits per channel	00h			07h
NUMCH	1	Number channels of the module	04h			08h
CHERR	1	reserved	00h			09h
CH0ERR… CH7ERR	8	reserved	00h			0Ah ... 11h
DIAG_US	4	µs ticker (32bit)	00h			13h

MODTYP Module information

Byte	Bit 7 ... 0
0	Bit 3 ... 0: Module class 1111b Digital module Bit 4: Channel information present Bit 7 ... 5: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	Bit 6 ... 0: Channel type 70h: Digital input Bit 7: 0 (fix)

NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostics bits of the module per channel (here 00h)

NUMCH channels

Byte	Bit 7 ... 0
0	Number of channels of the module (here 04h)

DIAG_US µs ticker

Byte	Bit 7 ... 0
0 ... 3	Value of the µs ticker at the moment of the diagnostic data generation

ERR_A/C/D CHERR, CHxERR reserved

Byte	Bit 7 ... 0
0	reserved

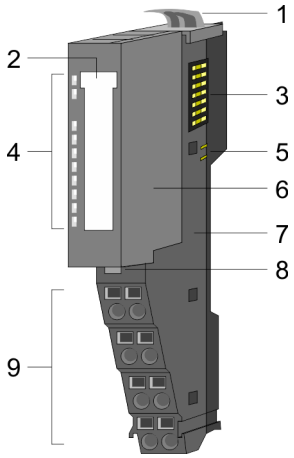
3.9 021-1BF00 - DI 8xDC 24V

Properties

The electronic module collects the binary control signals from the process level and transmits them isolated to the central bus system. It has 8 channels and their status is monitored via LEDs.

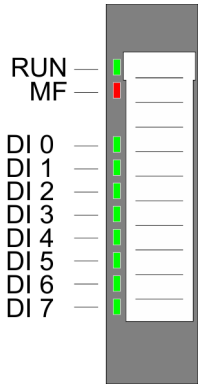
- 8 digital inputs, isolated to the backplane bus
- Suited for switches and approximate switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

Status indication

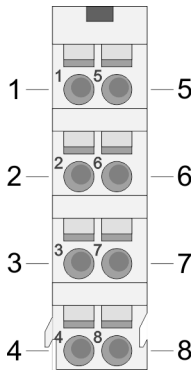


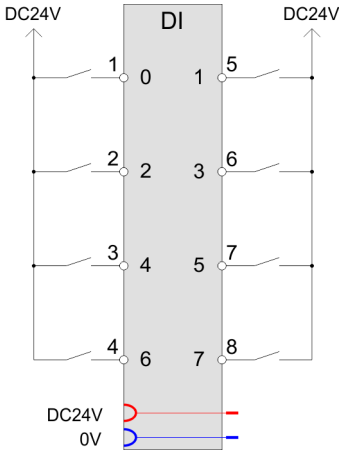
RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"

not relevant: X

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	DI 2	I	Digital input DI 2
3	DI 4	I	Digital input DI 4
4	DI 6	I	Digital input DI 6
5	DI 1	I	Digital input DI 1
6	DI 3	I	Digital input DI 3
7	DI 5	I	Digital input DI 5
8	DI 7	I	Digital input DI 7

I: Input

Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	6000h	
			Bit 0: DI 0		01h
			Bit 1: DI 1		02h
			Bit 2: DI 2		03h
			Bit 3: DI 3		04h
			Bit 4: DI 4		05h
			Bit 5: DI 5		06h
			Bit 6: DI 6		07h
			Bit 7: DI 7		08h

Output area

No byte of the output area is used by the module.

3.9.1 Technical data

Order no.	021-1BF00
Type	SM 021 - Digital input
Module ID	0005 9FC1
Current consumption/power loss	
Current consumption from backplane bus	65 mA
Power loss	0.9 W
Technical data digital inputs	
Number of inputs	8
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	-
Permitted range	-
Current consumption from power section supply (without load)	-
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 0...5 V
Input voltage for signal "1"	DC 15...28.8 V
Input voltage hysteresis	-
Signal logic input	Sinking input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	3 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	0.5 mA
Input delay of "0" to "1"	3 ms
Input delay of "1" to "0"	3 ms
Number of simultaneously utilizable inputs horizontal configuration	8
Number of simultaneously utilizable inputs vertical configuration	8
Input characteristic curve	IEC 61131-2, type 1
Initial data size	8 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no

Order no.	021-1BF00
Diagnostic functions	no
Diagnostics information read-out	none
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	1
Output bytes	0
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	57 g
Weight including accessories	57 g
Gross weight	71 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

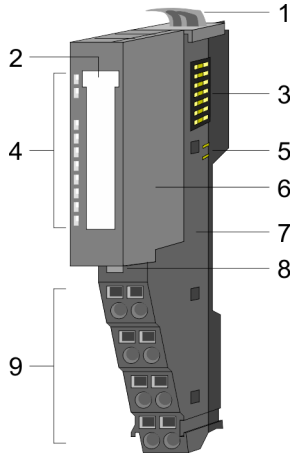
3.10 021-1BF01 - DI 8xDC 24V 0.5ms

Properties

The electronic module collects the binary control signals from the process level and transmits them isolated to the central bus system. It has 8 channels and their status is monitored via LEDs.

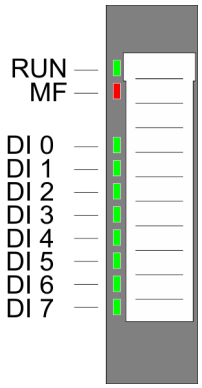
- 8 digital inputs, isolated to the backplane bus
- Input filter time delay 0.5ms
- Suited for switches and approximate switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

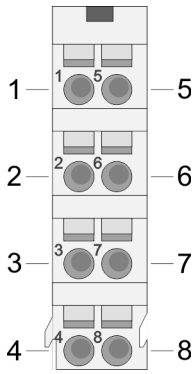
Status indication

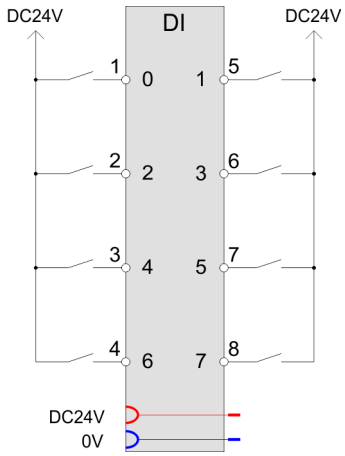


RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	DI 2	I	Digital input DI 2
3	DI 4	I	Digital input DI 4
4	DI 6	I	Digital input DI 6
5	DI 1	I	Digital input DI 1
6	DI 3	I	Digital input DI 3
7	DI 5	I	Digital input DI 5
8	DI 7	I	Digital input DI 7

I: Input

Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	6000h	
			Bit 0: DI 0		01h
			Bit 1: DI 1		02h
			Bit 2: DI 2		03h
			Bit 3: DI 3		04h
			Bit 4: DI 4		05h
			Bit 5: DI 5		06h
			Bit 6: DI 6		07h
			Bit 7: DI 7		08h

Output area

No byte of the output area is used by the module.

3.10.1 Technical data

Order no.	021-1BF01
Type	SM 021 - Digital input
Module ID	0013 9FC1
Current consumption/power loss	
Current consumption from backplane bus	35 mA
Power loss	0.9 W
Technical data digital inputs	
Number of inputs	8
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	-
Permitted range	-
Current consumption from power section supply (without load)	-
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 0...5 V
Input voltage for signal "1"	DC 15...28.8 V
Input voltage hysteresis	-
Signal logic input	Sinking input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	3 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	0.5 mA
Input delay of "0" to "1"	max. 500 µs
Input delay of "1" to "0"	max. 500 µs
Number of simultaneously utilizable inputs horizontal configuration	8
Number of simultaneously utilizable inputs vertical configuration	8
Input characteristic curve	IEC 61131-2, type 1
Initial data size	8 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no

Order no.	021-1BF01
Diagnostic functions	no
Diagnostics information read-out	none
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	1
Output bytes	0
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	57 g
Weight including accessories	57 g
Gross weight	71 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

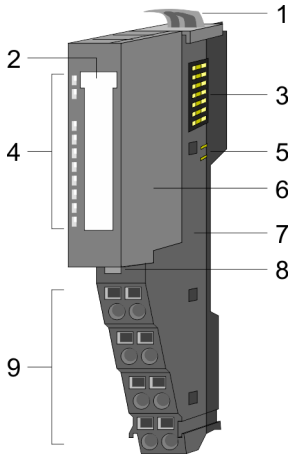
3.11 021-1BF50 - DI 8xDC 24V NPN

Properties

The electronic module collects the binary control signals from the process level and transmits them isolated to the central bus system. It has 8 channels and their status is monitored via LEDs. An input becomes active as soon as it is connected to ground.

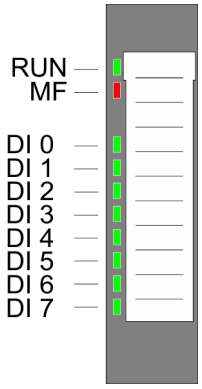
- 8 digital inputs (sourcing input), isolated to the backplane bus
- Suited for switches and approximate switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

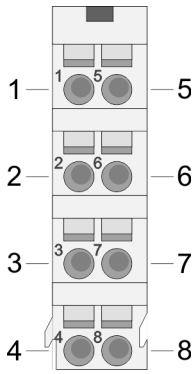
Status indication

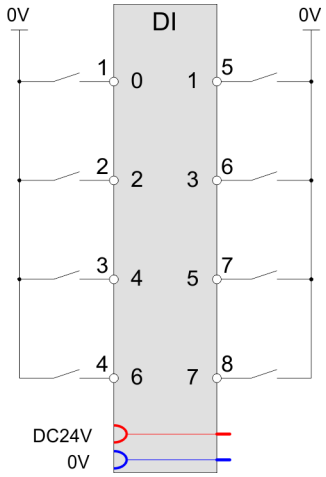


RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	DI 2	I	Digital input DI 2
3	DI 4	I	Digital input DI 4
4	DI 6	I	Digital input DI 6
5	DI 1	I	Digital input DI 1
6	DI 3	I	Digital input DI 3
7	DI 5	I	Digital input DI 5
8	DI 7	I	Digital input DI 7

I: Input

Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	6000h	
			Bit 0: DI 0		01h
			Bit 1: DI 1		02h
			Bit 2: DI 2		03h
			Bit 3: Di 3		04h
			Bit 4: DI 4		05h
			Bit 5: DI 5		06h
			Bit 6: DI 6		07h
			Bit 7: DI 7		08h

Output area

No byte of the output area is used by the module.

3.11.1 Technical data

Order no.	021-1BF50
Type	SM 021 - Digital input
Module ID	0007 9FC1
Current consumption/power loss	
Current consumption from backplane bus	65 mA
Power loss	0.9 W
Technical data digital inputs	
Number of inputs	8
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	-
Permitted range	-
Current consumption from power section supply (without load)	-
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 15...28.8 V
Input voltage for signal "1"	DC 0...5 V
Input voltage hysteresis	-
Signal logic input	Sourcing input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	3 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	0.5 mA
Input delay of "0" to "1"	3 ms
Input delay of "1" to "0"	3 ms
Number of simultaneously utilizable inputs horizontal configuration	8
Number of simultaneously utilizable inputs vertical configuration	8
Input characteristic curve	-
Initial data size	8 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no

Order no.	021-1BF50
Diagnostic functions	no
Diagnostics information read-out	none
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	1
Output bytes	0
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	57 g
Weight including accessories	57 g
Gross weight	71 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

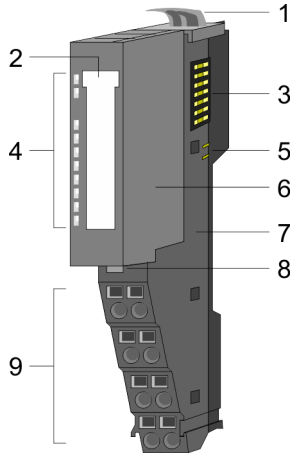
3.12 021-1BF51 - DI 8xDC 24V 0.5ms NPN

Properties

The electronic module collects the binary control signals from the process level and transmits them isolated to the central bus system. It has 8 channels and their status is monitored via LEDs. An input becomes active as soon as it is connected to ground.

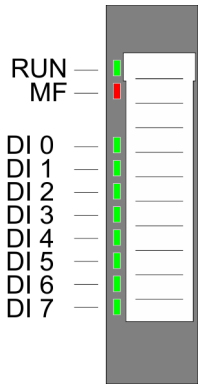
- 8 digital inputs (sourcing input), isolated to the backplane bus
- Input filter time delay 0.5ms
- Suited for switches and approximate switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

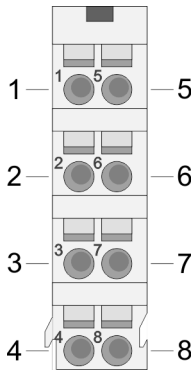
Status indication

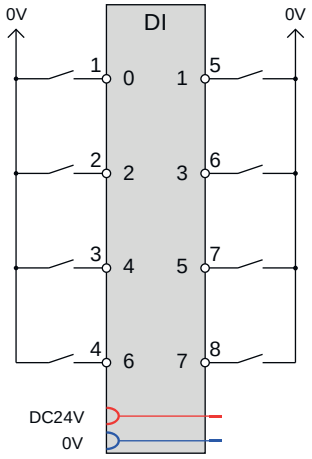


RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	DI 2	I	Digital input DI 2
3	DI 4	I	Digital input DI 4
4	DI 6	I	Digital input DI 6
5	DI 1	I	Digital input DI 1
6	DI 3	I	Digital input DI 3
7	DI 5	I	Digital input DI 5
8	DI 7	I	Digital input DI 7

I: Input

Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	6000h	
			Bit 0: DI 0		01h
			Bit 1: DI 1		02h
			Bit 2: DI 2		03h
			Bit 3: DI 3		04h
			Bit 4: DI 4		05h
			Bit 5: DI 5		06h
			Bit 6: DI 6		07h
			Bit 7: DI 7		08h

Output area

No byte of the output area is used by the module.

3.12.1 Technical data

Order no.	021-1BF51
Type	SM 021 - Digital input
Module ID	0026 9FC1
Current consumption/power loss	
Current consumption from backplane bus	40 mA
Power loss	0.65 W
Technical data digital inputs	
Number of inputs	8
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	-
Permitted range	-
Current consumption from power section supply (without load)	-
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 15...28.8 V
Input voltage for signal "1"	DC 0...5 V
Input voltage hysteresis	-
Signal logic input	Sourcing input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	2.25 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	1.5 mA
Input delay of "0" to "1"	max. 500 µs
Input delay of "1" to "0"	max. 500 µs
Number of simultaneously utilizable inputs horizontal configuration	8
Number of simultaneously utilizable inputs vertical configuration	8
Input characteristic curve	-
Initial data size	8 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no

Order no.	021-1BF51
Diagnostic functions	no
Diagnostics information read-out	none
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	1
Output bytes	0
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	57 g
Weight including accessories	57 g
Gross weight	71 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-40 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

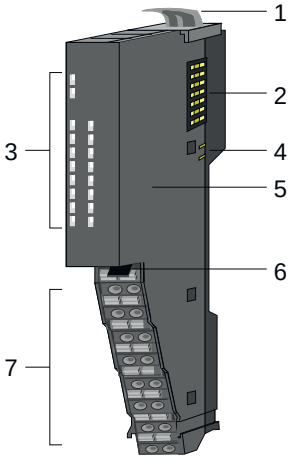
3.13 021-1BH00 - DI 16xDC 24V

Properties

The module detects the binary control signals from the process level and transmits them isolated to the higher-level bus system. It has 16 channels and their status is indicated by LEDs.

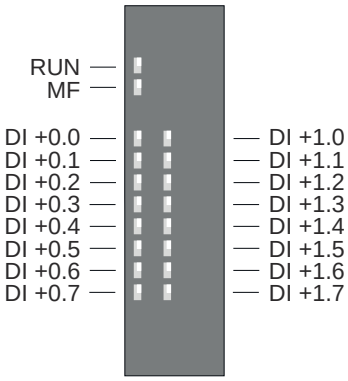
- 16 digital Inputs isolated to the backplane bus
- Input filter time delay parameterizable
- Suitable for switches and proximity switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever module
2 Backplane bus
3 LED status indication
4 DC 24V power section supply
5 Electronic unit
6 Locking lever terminal block
7 Terminal block

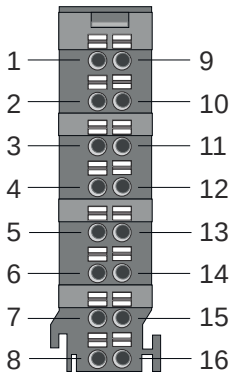
Status indication

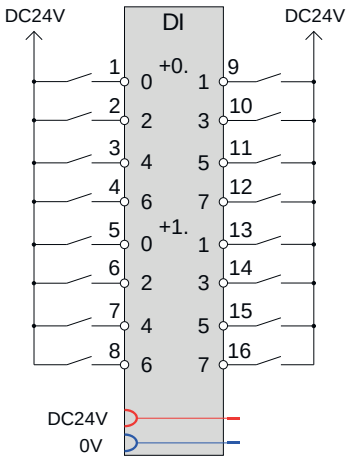


RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Blinking: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"
not relevant: X			

Pin assignment

For wires with a core cross-section of 0.14mm² up to 0.75mm². With a core cross-section < 0.25mm², ferrules must be used. *'Data'...page 32*





Pos.	Function	Type	Description
1	DI +0.0	I	Digital input DI +0.0
2	DI +0.2	I	Digital input DI +0.2
3	DI +0.4	I	Digital input DI +0.4
4	DI +0.6	I	Digital input DI +0.6
5	DI +1.0	I	Digital input DI +1.0
6	DI +1.2	I	Digital input DI +1.2
7	DI +1.4	I	Digital input DI +1.4
8	DI +1.6	I	Digital input DI +1.6
9	DI +0.1	I	Digital input DI +0.1
10	DI +0.3	I	Digital input DI +0.3
11	DI +0.5	I	Digital input DI +0.5
12	DI +0.7	I	Digital input DI +0.7
13	DI +1.1	I	Digital input DI +1.1
14	DI +1.3	I	Digital input DI +1.3
15	DI +1.5	I	Digital input DI +1.5
16	DI +1.7	I	Digital input DI +1.7

I: Input

Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Byte	Function	IX	SX[1]
+0	PII	0	Status of the inputs	6000h	
			Bit 0: DI +0.0		01h
			Bit 1: DI +0.1		02h
			Bit 2: DI +0.2		03h
			Bit 3: DI +0.3		04h
			Bit 4: DI +0.4		05h
			Bit 5: DI +0.5		06h
			Bit 6: DI +0.6		07h
			Bit 7: DI +0.7		08h
		1	Status of the inputs	6001h	
			Bit 0: DI +1.0		09h
			Bit 1: DI +1.1		0Ah
			Bit 2: DI +1.2		0Bh
			Bit 3: DI +1.3		0Ch
			Bit 4: DI +1.4		0Dh
			Bit 5: DI +1.5		0Eh
			Bit 6: DI +1.6		0Fh
			Bit 7: DI +1.7		10h

1) Can be displayed as 16 channels with the names DI 0 to DI 15.

Output area No byte of the output area is used by the module.

3.13.1 Technical data

Order no.	021-1BH00
Type	SM 021 - Digital input
Module ID	0020 1FC2
Current consumption/power loss	
Current consumption from backplane bus	35 mA
Power loss	1.2 W
Technical data digital inputs	
Number of inputs	16
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	-
Permitted range	-
Current consumption from power section supply (without load)	-
Input rated voltage	DC 24 V

Order no.	021-1BH00
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 0...5 V
Input voltage for signal "1"	DC 15...28.8 V
Input voltage hysteresis	-
Signal logic input	Sinking input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	2.3 mA
Connection of Two-Wire-BEROs possible	✓
Max. permissible BERO quiescent current	0.5 mA
Input delay of "0" to "1"	parameterizable 400µs - 23ms
Input delay of "1" to "0"	parameterizable 400µs - 23ms
Number of simultaneously utilizable inputs horizontal configuration	16
Number of simultaneously utilizable inputs vertical configuration	16
Input characteristic curve	IEC 61131-2, type 1
Initial data size	16 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	no
Diagnostics information read-out	none
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	2
Output bytes	0
Parameter bytes	1

Order no.	021-1BH00
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	52 g
Weight including accessories	52 g
Gross weight	72 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

3.13.2 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot

More can be found in the according manual of your bus coupler.

Name	Byte	Function	Default	DS	IX	SX
CHD	1	Input delay DI x	89h	01h	3100h	01h

CHD input delay

Byte	Function	Possible values:	
0	Input delay DI x ■ Bit 3 ... 0: Values filter	06h: 0.4ms 07h: 0.7ms 08h: 1.5ms 09h: 3ms	0Ah: 6ms 0Bh: 12ms 0Ch: 23ms
		Other values are not permitted!	
	■ Bit 6 ... 4: reserved		
	■ Bit 7: Filter (0: block, 1: enable)		

- By specifying the *input delay*, you can specify a filter for all channels here. With the help of filters you may e.g. filter signal peaks at a blurred input signal. By default, an input delay of 3ms is set for all channels.

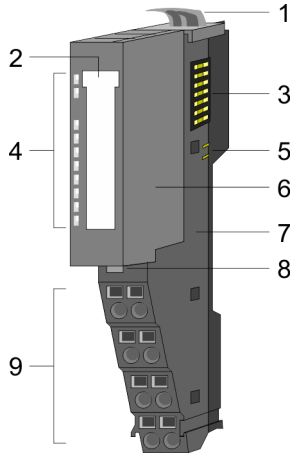
3.14 021-1DF00 - DI 8xDC 24V Diagnosis

Properties

The electronic module with diagnosis collects the binary control signals from the process level and transmits them isolated to the central bus system. It has 8 digital input channels (with parameterizable input delay) and their status is monitored via LEDs.

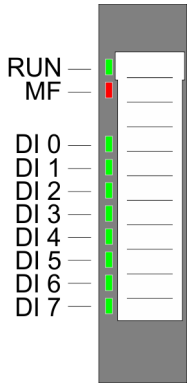
- 8 digital inputs, isolated to the backplane bus
- Input filter time delay parameterizable
- Monitoring wire break
- Diagnostics function
- Suited for switches and approximate switches
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

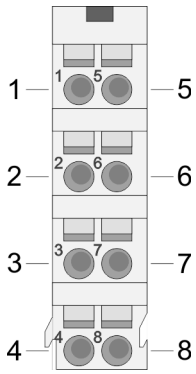
Status indication

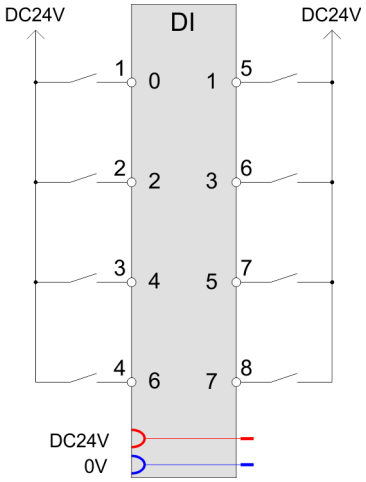


RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	DI 2	I	Digital input DI 2
3	DI 4	I	Digital input DI 4
4	DI 6	I	Digital input DI 6
5	DI 1	I	Digital input DI 1
6	DI 3	I	Digital input DI 3
7	DI 5	I	Digital input DI 5
8	DI 7	I	Digital input DI 7

I: Input

To use wire break detection, there must be a minimum current of 0.5mA with signal state "0". This can be achieved by parallel connecting a resistor (22kΩ ... 47kΩ) on your switch.

Please note that, due to the system, a diagnostic interrupt is triggered at PowerON and when the diagnostic interrupt is enabled or each time the diagnostic interrupt is enabled by means of parameter DIAG_EN.

Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	6000h	
			Bit 0: DI 0		01h
			Bit 1: DI 1		02h
			Bit 2: DI 2		03h
			Bit 3: Di 3		04h
			Bit 4: DI 4		05h
			Bit 5: DI 5		06h
			Bit 6: DI 6		07h
			Bit 7: DI 7		08h

Output area No byte of the output area is used by the module.

3.14.1 Technical data

Order no.	021-1DF00
Type	SM 021 - Digital input
Module ID	0012 1F41
Current consumption/power loss	
Current consumption from backplane bus	60 mA
Power loss	1.1 W
Technical data digital inputs	
Number of inputs	8
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	-
Permitted range	-
Current consumption from power section supply (without load)	-
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 0...5 V
Input voltage for signal "1"	DC 10,8...28,8 V
Input voltage hysteresis	-
Signal logic input	Sinking input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	3 mA
Connection of Two-Wire-BEROs possible	✓

Order no.	021-1DF00
Max. permissible BERO quiescent current	1.5 mA
Input delay of "0" to "1"	parameterizable 100µs - 20ms
Input delay of "1" to "0"	parameterizable 100µs - 20ms
Number of simultaneously utilizable inputs horizontal configuration	8
Number of simultaneously utilizable inputs vertical configuration	8
Input characteristic curve	IEC 61131-2, type 3
Initial data size	8 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	yes
Process alarm	no
Diagnostic interrupt	yes, parameterizable
Diagnostic functions	yes
Diagnostics information read-out	possible
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	1
Output bytes	0
Parameter bytes	12
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	57 g
Weight including accessories	57 g
Gross weight	71 g
Environmental conditions	

Order no.	021-1DF00
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

3.14.2 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET
IX - Index for access via CANopen
SX - Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot
More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
DIAG_EN	1	Diagnostic interrupt[1]	00h	00h	3100h	01h
WIBRK_EN	1	Wire break recognition[1]	00h	00h	3101h	02h
C0_OptionNo	1	Filter time DI 0, DI 1	11h	80h	3102h	03h
C1_OptionNo	1	Filter time DI 2, DI 3	11h	81h	3103h	04h
C2_OptionNo	1	Filter time DI 4, DI 5	11h	82h	3104h	05h
C3_OptionNo	1	Filter time DI 6, DI 7	11h	83h	3105h	06h

1) This record set may only be transferred at STOP state.

DIAG_EN Diagnostic interrupt

Byte	Bit 7 ... 0
0	■ Diagnostic interrupt: – 00h: disable – 40h: enable

- Here you activate res. de-activate the diagnostic function.

WIBRK_EN Wire break recognition

Byte	Bit 7 ... 0
0	■ Bit 0: Wire break recognition DI 0 (1: on) ■ Bit 1: Wire break recognition DI 1 (1: on) ■ ... ■ Bit 7: Wire break recognition DI 7 (1: on)

- Here you activate res. de-activate the Wire break recognition.

Cx_OptionNo Filter time

Byte	Function	Possible values
0	■ Bit 3 ... 0: Filter time DI x ■ Bit 7 ... 4: Filter time DI x+1	1h: 100µs 2h: 400µs 3h: 800µs 4h: 1.6ms 5h: 3.2ms 6h: 10ms 7h: 20ms Other values are not permissible!

- *Filter time* allows you to preset a input delay for the corresponding channel x. With the help of filters you may e.g. filter signal peaks at a blurred input signal.

3.14.3 Diagnostic data

The following errors are listed in the diagnostics data:

- Error project engineering/parameterization
- Wire break (if parameterized)
- Internal communication error
- Internal diagnostics buffer overflow
- External power supply error

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

IX - Index for access via CANopen. The access happens by IX 2F01h. Additionally the first 4 bytes may be accessed by IX 2F00h.

SX - Subindex for access via EtherCAT with Index 5005h.

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
ERR_A	1	Diagnostic	00h	01h	2F01h	02h
MODTYP	1	Module information	1Fh			03h
ERR_C	1	reserved	00h			04h
ERR_D	1	Diagnostic	00h			05h
CHTYP	1	Channel type	70h			06h
NUMBIT	1	Number of diagnostics bits per channel	08h			07h
NUMCH	1	Number channels of the module	08h			08h
CHERR	1	Channel error	00h			09h
CH0ERR	1	Channel specific error DI 1	00h			0Ah
CH1ERR	1	Channel specific error DI 2	00h			0Bh
…		…				…
CH7ERR	1	Channel specific error DI 7	00h			11h
DIAG_US	4	µs ticker (32bit)	00h			13h

ERR_A Diagnostic

Byte	Bit 7 ... 0
0	■ Bit 0: set at module failure ■ Bit 1: set at internal error ■ Bit 2: set at external error ■ Bit 3: set at channel error ■ Bit 4: set at external auxiliary supply missing ■ Bit 6, 5: reserved ■ Bit 7: set at error in parameterization

MODTYP Module information

Byte	Bit 7 ... 0
0	■ Bit 3 ... 0: Module class – 1111b: Digital module ■ Bit 4: Channel information present ■ Bit 7 ... 5: reserved

ERR_C reserved

Byte	Bit 7 ... 0
0	reserved

ERR_D Diagnostic

Byte	Bit 7 ... 0
0	■ Bit 2 ... 0: reserved ■ Bit 3: set at internal diagnostics buffer overflow ■ Bit 4: set at internal communication error ■ Bit 7 ... 5: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	■ Bit 6 ... 0: Channel type – 70h: Digital input ■ Bit 7: reserved

NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostics bits of the module per channel (here 08h)

NUMCH Channels

Byte	Bit 7 ... 0
0	Number of channels of the module (here 08h)

CHERR DI x

Byte	Bit 7 ... 0
0	■ Bit 0: Channel error DI 0 ■ Bit 1: Channel error DI 1 ■ ... ■ Bit 7: Channel error DI 7

CHxERR

Byte	Bit 7 ... 0
0	Channel-specific error: DI x: ■ Bit 0: set at error in project engineering/parameterization ■ Bit 3 ... 1: reserved ■ Bit 4: set at wire break ■ Bit 7 ... 5: reserved

DIAG_US µs ticker

Byte	Bit 7 ... 0
0 ... 3	Value of the µs ticker at the moment of the diagnostic

µs ticker

In the System SLIO module there is a 32 bit timer (µs ticker). With PowerON the timer starts counting with 0. After 2^{32}-1µs the timer starts with 0 again.

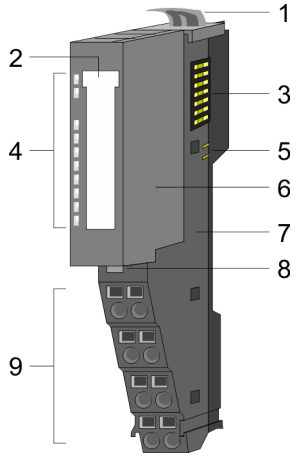
3.15 021-1DF50 - DI 8xDC 24V Diagnosis NPN

Properties

The electronic module with diagnosis collects the binary control signals from the process level and transmits them isolated to the central bus system. It has 8 digital input channels (with parameterizable input delay) and their status is monitored via LEDs. An input becomes active as soon as it is connected to ground.

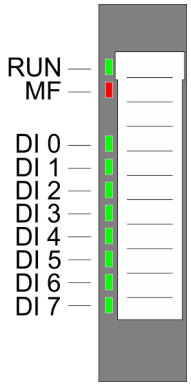
- 8 digital inputs, isolated to the backplane bus
- Suited for switches and approximate switches
- Monitoring wire break
- Parameterizable input delay
- Diagnostics function
- Status indication of the channels via LEDs also with de-activated electronic power supply

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

Status indication

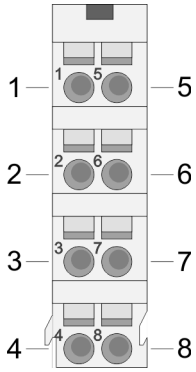


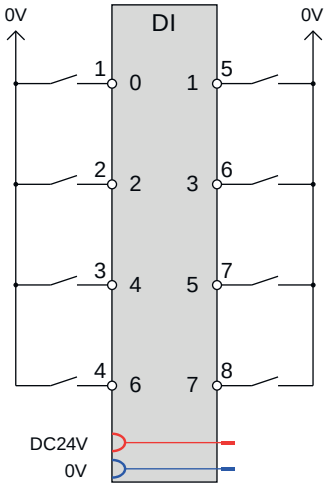
RUN green	MF red	DI x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error
□	■	X	Bus communication is not possible Module status reports an error
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital input has signal "1"
■	□	□	Digital input has signal "0"
not relevant: X			

021-1DF50 - DI 8xDC 24V Diagnosis NPN

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DI 0	I	Digital input DI 0
2	DI 2	I	Digital input DI 2
3	DI 4	I	Digital input DI 4
4	DI 6	I	Digital input DI 6
5	DI 1	I	Digital input DI 1
6	DI 3	I	Digital input DI 3
7	DI 5	I	Digital input DI 5
8	DI 7	I	Digital input DI 7

I: Input

To use wire break detection, there must be a minimum current of 0.5mA with signal state "0". This can be achieved by parallel connecting a resistor (22kΩ ... 47kΩ) on your switch.

Input area

At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PII	1	State of the inputs	6000h	
			Bit 0: DI 0		01h
			Bit 1: DI 1		02h
			Bit 2: DI 2		03h
			Bit 3: Di 3		04h
			Bit 4: DI 4		05h
			Bit 5: DI 5		06h
			Bit 6: DI 6		07h
			Bit 7: DI 7		08h

Output area No byte of the output area is used by the module.

3.15.1 Technical data

Order no.	021-1DF50
Type	SM 021 - Digital input
Module ID	0025 1F41
Current consumption/power loss	
Current consumption from backplane bus	53 mA
Power loss	1.25 W
Technical data digital inputs	
Number of inputs	8
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated voltage power section supply	-
Permitted range	-
Current consumption from power section supply (without load)	-
Input rated voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Input voltage for signal "0"	DC 15...28.8 V
Input voltage for signal "1"	DC 0...5 V
Input voltage hysteresis	-
Signal logic input	Sourcing input
Frequency range	-
Input resistance	-
Input capacitance	-
Input current for signal "1"	2.3 mA
Connection of Two-Wire-BEROs possible	✓

Order no.	021-1DF50
Max. permissible BERO quiescent current	1.5 mA
Input delay of "0" to "1"	parameterizable 100µs - 20ms
Input delay of "1" to "0"	parameterizable 100µs - 20ms
Number of simultaneously utilizable inputs horizontal configuration	8
Number of simultaneously utilizable inputs vertical configuration	8
Input characteristic curve	IEC 61131-2, type 3
Initial data size	8 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	yes
Process alarm	no
Diagnostic interrupt	yes, parameterizable
Diagnostic functions	yes
Diagnostics information read-out	possible
Module state	green LED
Module error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
Datasizes	
Input bytes	1
Output bytes	0
Parameter bytes	12
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	57 g
Weight including accessories	57 g
Gross weight	71 g
Environmental conditions	

Order no.	021-1DF50
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

3.15.2 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET
IX - Index for access via CANopen
SX - Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot
More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
DIAG_EN	1	Diagnostic interrupt[1]	00h	00h	3100h	01h
WIBRK_EN	1	Wire break recognition[1]	00h	00h	3101h	02h
C0_OptionNo	1	Filter time DI 0, DI 1	11h	80h	3102h	03h
C1_OptionNo	1	Filter time DI 2, DI 3	11h	81h	3103h	04h
C2_OptionNo	1	Filter time DI 4, DI 5	11h	82h	3104h	05h
C3_OptionNo	1	Filter time DI 6, DI 7	11h	83h	3105h	06h

1) This record set may only be transferred at STOP state.

DIAG_EN Diagnostic interrupt

Byte	Bit 7 ... 0
0	■ Diagnostic interrupt: – 00h: disable – 40h: enable

- Here you activate res. de-activate the diagnostic function.

WIBRK_EN Wire break recognition

Byte	Bit 7 ... 0
0	■ Bit 0: Wire break recognition DI 0 (1: on) ■ Bit 1: Wire break recognition DI 1 (1: on) ■ ... ■ Bit 7: Wire break recognition DI 7 (1: on)

- Here you activate res. de-activate the Wire break recognition.

Cx_OptionNo Filter time

Byte	Function	Possible values
0	■ Bit 3 ... 0: Filter time DI x ■ Bit 7 ... 4: Filter time DI x+1	1h: 100µs 2h: 400µs 3h: 800µs 4h: 1.6ms 5h: 3.2ms 6h: 10ms 7h: 20ms Other values are not permissible!

- *Filter time* allows you to preset a input delay for the corresponding channel x. With the help of filters you may e.g. filter signal peaks at a blurred input signal.

3.15.3 Diagnostic data

The following errors are listed in the diagnostics data:

- Error project engineering/parameterization
- Wire break (if parameterized)
- Internal communication error
- Internal diagnostics buffer overflow
- External power supply error

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

IX - Index for access via CANopen. The access happens by IX 2F01h. Additionally the first 4 bytes may be accessed by IX 2F00h.

SX - Subindex for access via EtherCAT with Index 5005h.

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
ERR_A	1	Diagnostic	00h	01h	2F01h	02h
MODTYP	1	Module information	1Fh			03h
ERR_C	1	reserved	00h			04h
ERR_D	1	Diagnostic	00h			05h
CHTYP	1	Channel type	70h			06h
NUMBIT	1	Number of diagnostics bits per channel	08h			07h
NUMCH	1	Number channels of the module	08h			08h
CHERR	1	Channel error	00h			09h
CH0ERR	1	Channel specific error DI 1	00h			0Ah
CH1ERR	1	Channel specific error DI 2	00h			0Bh
…		…				…
CH7ERR	1	Channel specific error DI 7	00h			11h
DIAG_US	4	µs ticker (32bit)	00h			13h

ERR_A Diagnostic

Byte	Bit 7 ... 0
0	■ Bit 0: set at module failure ■ Bit 1: set at internal error ■ Bit 2: set at external error ■ Bit 3: set at channel error ■ Bit 4: set at external auxiliary supply missing ■ Bit 6, 5: reserved ■ Bit 7: set at error in parameterization

MODTYP Module information

Byte	Bit 7 ... 0
0	■ Bit 3 ... 0: Module class – 1111b: Digital module ■ Bit 4: Channel information present ■ Bit 7 ... 5: reserved

ERR_C reserved

Byte	Bit 7 ... 0
0	reserved

ERR_D Diagnostic

Byte	Bit 7 ... 0
0	■ Bit 2 ... 0: reserved ■ Bit 3: set at internal diagnostics buffer overflow ■ Bit 4: set at internal communication error ■ Bit 7 ... 5: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	■ Bit 6 ... 0: Channel type – 70h: Digital input ■ Bit 7: reserved

NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostics bits of the module per channel (here 08h)

NUMCH Channels

Byte	Bit 7 ... 0
0	Number of channels of the module (here 08h)

CHERR DI x

Byte	Bit 7 ... 0
0	■ Bit 0: Channel error DI 0 ■ Bit 1: Channel error DI 1 ■ ... ■ Bit 7: Channel error DI 7

CHxERR

Byte	Bit 7 ... 0
0	Channel-specific error: DI x: ■ Bit 0: set at error in project engineering/parameterization ■ Bit 3 ... 1: reserved ■ Bit 4: set at wire break ■ Bit 7 ... 5: reserved

DIAG_US µs ticker

Byte	Bit 7 ... 0
0 ... 3	Value of the µs ticker at the moment of the diagnostic

µs ticker

In the System SLIO module there is a 32 bit timer (µs ticker). With PowerON the timer starts counting with 0. After 2^{32}-1µs the timer starts with 0 again.

4 Digital output

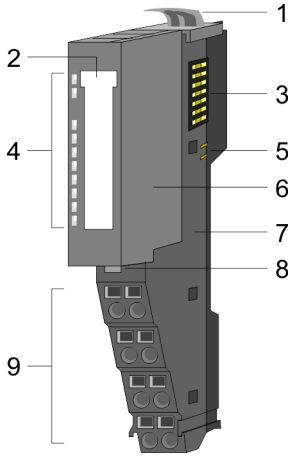
4.1 022-1BB00 - DO 2xDC 24V 0.5A

Properties

The electronic module accepts binary control signals from the central bus system and transfers them to the process level via outputs. It has 2 channels and their status is monitored via LEDs.

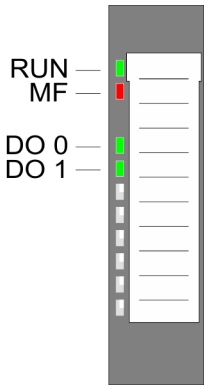
- 2 digital outputs, isolated to the backplane bus
- Status indication of the channels via LEDs

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

Status indication

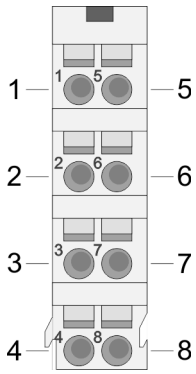


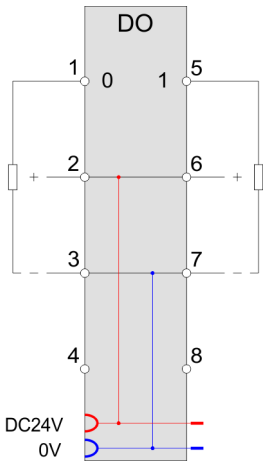
RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital output has "1" signal
■	□	□	Digital output has "0" signal
not relevant: X			

022-1BB00 - DO 2xDC 24V 0.5A

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DO 0	O	Digital output DO 0
2	DC 24V	O	DC 24V
3	0V	O	GND for actuator
4	---	---	not connected
5	DO 1	O	Digital output DO 1
6	DC 24V	O	DC 24V
7	0V	O	GND for actuator
8	---	---	not connected

O: Output

CAUTION

Feeding in voltage at an output is not allowed and can destroy the module!

Input area

No byte of the input area is used by the module.

Output area

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PIQ	1	State of the outputs	5200h	
			Bit 0: DO 0		01h
			Bit 1: DO 1		02h
			Bit 7 ... 2: reserved		

4.1.1 Technical data

Order no.	022-1BB00
Type	SM 022 - Digital output
Module ID	0101 AF90
Current consumption/power loss	
Current consumption from backplane bus	70 mA
Power loss	0.4 W
Technical data digital outputs	
Number of outputs	2
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	5 mA
Total current per group, horizontal configuration, 40°C	1 A
Total current per group, horizontal configuration, 60°C	1 A
Total current per group, vertical configuration	1 A
Output current at signal "1", rated value	0.5 A
Signal logic output	Sourcing output
Output delay of "0" to "1"	30 µs
Output delay of "1" to "0"	175 µs
Minimum load current	-
Lamp load	10 W
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	✓
Switching frequency with resistive load	max. 1000 Hz
Switching frequency with inductive load	max. 0.5 Hz
Switching frequency on lamp load	max. 10 Hz
Internal limitation of inductive shut-off voltage	L+ (-45 V)
Short-circuit protection of output	yes, electronic
Trigger level	1 A
Number of operating cycle of relay outputs	-
Switching capacity of contacts	-
Output data size	2 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	no
Diagnostics information read-out	none
Supply voltage display	green LED
Group error display	red LED
Channel error display	none

Order no.	022-1BB00
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
PWM data	
PWM channels	-
PWM time basis	-
Period length	-
Minimum pulse width	-
Type of output	-
Datasizes	
Input bytes	0
Output bytes	1
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	58 g
Weight including accessories	58 g
Gross weight	72 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

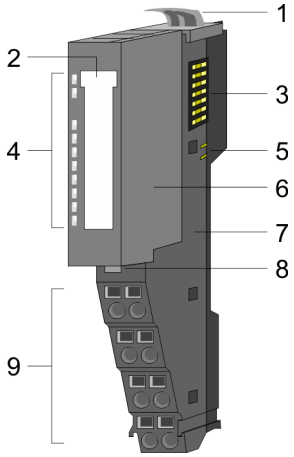
4.2 022-1BB90 - DO 2xDC 24V 0.5A PWM

Properties

The electronic has 2 output channels with PWM functionality (PWM = **p**ulse **w**idth **m**odulation). By presetting of time parameter a pulse sequence with according pulse/break ratio may be issued at the corresponding output channel.

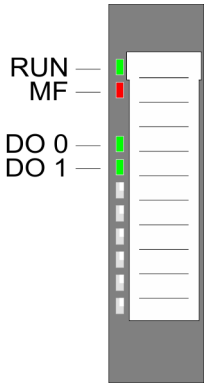
- 2 PWM outputs, isolated to the backplane bus
- PWM outputs switchable between *push/pull* and *high side*
- Diagnostics function
- PWM status
- Variable period duration and pulse duty ratio
- Status indication of the channels via LEDs

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

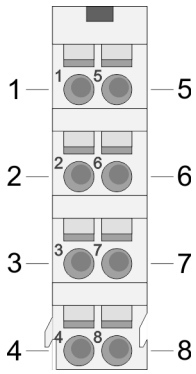
Status indication

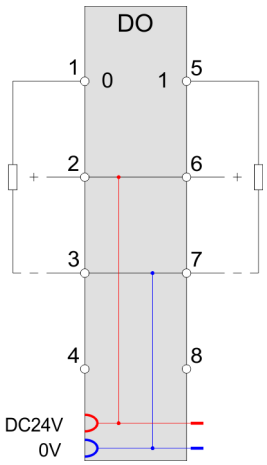


RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	PWM output has "1" signal
■	□	□	PWM output has "0" signal
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DO 0	O	PWM output DO 0
2	DC 24V	O	DC 24V
3	0V	O	GND for actuator
4	—	—	not connected
5	DO 1	O	PWM output DO 1
6	DC 24V	O	DC 24V
7	0V	O	GND for actuator
8	—	—	not connected

O: Output

CAUTION

Feeding in voltage at an output is not allowed and can destroy the module!

Input area 4byte

At CPU, PROFIBUS and PROFINET the input respectively output area is embedded to the corresponding address area.

IX - Index for access via CANopen with s = subindex, depends on number of PWM modules

SX - Subindex for access via EtherCAT with Index 6000h + EtherCAT-Slot

More can be found in the according manual of your bus coupler.

Addr.	Name	Bytes	Function	IX	SX
+0	PWMSTS_I	2	PWM 0: Status	5420h/s	01h
+2	PWMSTS_II	2	PWM 1: Status	5420h/s+1	02h

Status PWM x

Bit	Name	Function
0	-	reserved
1	STS_PWM	Status PWM 0: PWM output stopped 1: PWM output activated
2	STS_OUTBV	Status output 0: Push/Pull output 1: High side output
3 ... 15	-	reserved

Output area 12byte

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area.

IX - Index for access via CANopen with s = subindex, depends on number of PWM modules

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

More can be found in the according manual of your bus coupler.

Addr.	Name	Bytes	Function	IX	SX
+0	PWMPD_I	4	PWM 0: Pulse duration	5620h/s	01h
+4	PWMPD_II	4	PWM 1: Pulse duration	5620h/s+1	02h
+8	PWMCTRL_I	2	PWM 0: Control word	5621h/s	03h
+10	PWMCTRL_II	2	PWM 1: Control word	5621h/s+1	04h

PWMPD_I PWMPD_II Pulse duration

Here you have to define the pulse duty ratio for the configured *period duration*, by presetting the high level for the corresponding PWM channel. The pulse duration is to be preset as factor to the base 20.83ns.

Range of values: 48 ... 8388607 (1µs ... ca. 175ms)

PWMCTRL_I PWMCTRL_II Control word

Here for the corresponding channel the PWM output behavior may be preset and the PWM output may be started respectively stopped.

Bit	Name	Function
0 ... 1	-	reserved
2	CTRL_OUTBV	PWM output behavior 0: Push/Pull output 1: High side output With *Push/Pull* operation it is active switched to high and low level. With *High side* operation it is only active switched to high level.
3 ... 7	-	reserved
8	CTRL_STRT	Edge 0-1 starts PWM output at channel x
9	CTRL_STP	Edge 0-1 stops PWM output at channel x
10 ... 15	-	reserved

4.2.1 Technical data

Order no.	022-1BB90
Type	SM 022 - Digital output
Module ID	0901 4880
Current consumption/power loss	
Current consumption from backplane bus	105 mA
Power loss	0.95 W
Technical data digital outputs	
Number of outputs	2
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	15 mA
Total current per group, horizontal configuration, 40°C	1 A
Total current per group, horizontal configuration, 60°C	1 A
Total current per group, vertical configuration	1 A
Output current at signal "1", rated value	0.5 A
Signal logic output	Sourcing output
Output delay of "0" to "1"	max. 500 ns
Output delay of "1" to "0"	max. 500 ns
Minimum load current	-
Lamp load	10 W

Order no.	022-1BB90
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	✓
Switching frequency with resistive load	max. 40 kHz
Switching frequency with inductive load	max. 40 kHz
Switching frequency on lamp load	max. 40 kHz
Internal limitation of inductive shut-off voltage	L+ (-52 V)
Short-circuit protection of output	yes, electronic, and only highside
Trigger level	2.5 A
Number of operating cycle of relay outputs	-
Switching capacity of contacts	-
Output data size	12 Byte
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	no
Diagnostics information read-out	possible
Supply voltage display	green LED
Group error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
PWM data	
PWM channels	2
PWM time basis	20.83ns
Period length	1200...8388607 * time base
Minimum pulse width	1 µs
Type of output	Push pull / highside
Datasizes	
Input bytes	4
Output bytes	12
Parameter bytes	12
Diagnostic bytes	20

Order no.	022-1BB90
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	61 g
Weight including accessories	61 g
Gross weight	75 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

4.2.2 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
PWMPD_I	4	PWM 0: Period duration (Base time: 20.83ns)	1F40h	80h	3100h ... 3103	01h
PWMPD_II	4	PWM 1: Period duration (Base time: 20.83ns)	1F40h	81h	3104h ... 3107	02h

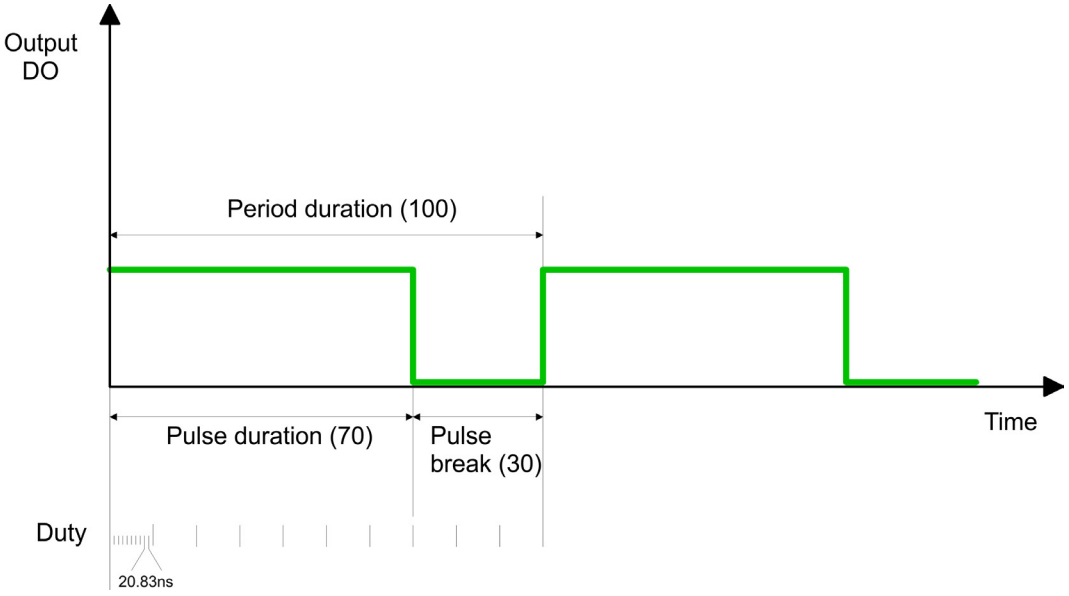
PWMPD_x Period duration

Byte	Bit 7 ... 0
0 ... 3	PWM x Period duration Here you have to configure the whole time for *Pulse duration* and Pulse break. The time is to be preset as factor to the base 20.83ns. Values lower than 25µs are ignored. Is the *pulse duration* value greater than or equal the value of *period duration* the output is permanently set. Range of values: 1200 ... 8388607 (25µs ... ca. 175ms)

Principle of operation

By presetting the *period duration* via parameterization and the *pulse duration* via the output area, the pulse duty ratio for the corresponding PWM output channel may be defined.

By changing the pulse duty ration e.g. a drive system, which is connected via PWM may be controlled by the user program.



4.2.3 Diagnostic data

So this module does not support hardware interrupts, the diagnostics data serve for information about this module.

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

IX - Index for access via CANopen. The access happens by IX 2F01h. Additionally the first 4 bytes may be accessed by IX 2F00h.

SX - Subindex for access via EtherCAT with Index 5005h.

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
ERR_A	1	reserved	00h	01h	2F01h	02h
MODTYP	1	Module information	1Fh			03h
ERR_C	1	reserved	00h			04h
ERR_D	1	reserved	00h			05h
CHTYP	1	Channel type	72h			06h
NUMBIT	1	Number of diagnostics bits per channel	00h			07h
NUMCH	1	Number channels of the module	02h			08h
CHERR	1	reserved	00h			09h
CH0ERR… CH7ERR	8	reserved	00h			0Ah ... 11h
DIAG_US	4	µs ticker (32bit)	00h			13h

MODTYP Module information

Byte	Bit 7 ... 0
0	Bit 3 ... 0: Module class 1111b: Digital module Bit 4: Channel information present Bit 7 ... 5: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	Bit 6 ... 0: Channel type 72h: Digital output Bit 7: reserved

NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostics bits of the module per channel (here 00h)

NUMCH Channels

Byte	Bit 7 ... 0
0	Number of channels of the module (here 02h)

DIAG_US µs ticker

Byte	Bit 7 ... 0
0 ... 3	Value of the µs ticker at the moment of the diagnostic data generation

ERR_C/D CHERR, CHxERR reserved

Byte	Bit 7 ... 0
0	reserved

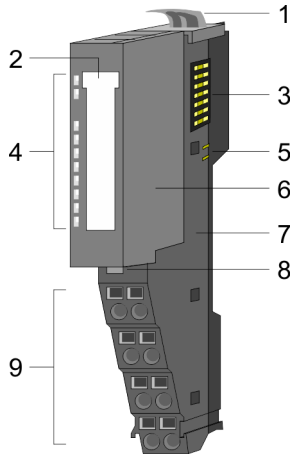
4.3 022-1BD00 - DO 4xDC 24V 0.5A

Properties

The electronic module accepts binary control signals from the central bus system and transfers them to the process level via outputs. It has 4 channels and their status is monitored via LEDs.

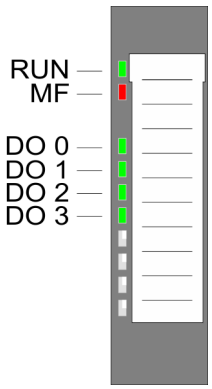
- 4 digital outputs, isolated to the backplane bus
- Status indication of the channels via LEDs

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

Status indication

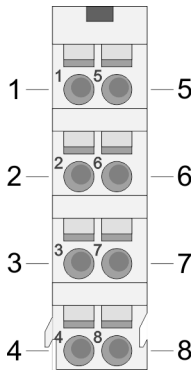


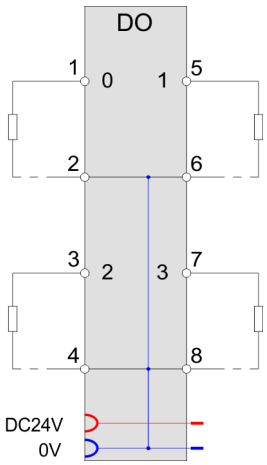
RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital output has "1" signal
■	□	□	Digital output has "0" signal
not relevant: X			

022-1BD00 - DO 4xDC 24V 0.5A

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DO 0	O	Digital output DO 0
2	0V	O	GND for actuator DO 0
3	DO 2	O	Digital output DO 2
4	0V	O	GND for actuator DO 2
5	DO 1	O	Digital output DO 1
6	0V	O	GND for actuator DO 1
7	DO 3	O	Digital output DO 3
8	0V	O	GND for actuator DO 3

O: Output

CAUTION

Feeding in voltage at an output is not allowed and can destroy the module!

Input area

No byte of the input area is used by the module.

Output area

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PIQ	1	State of the outputs	5200h	
			Bit 0: DO 0		01h
			Bit 1: DO 1		02h
			Bit 2: DO 2		03h
			Bit 3: DO 3		04h
			Bit 7 ... 4: reserved		

4.3.1 Technical data

Order no.	022-1BD00
Type	SM 022 - Digital output
Module ID	0104 AFA0
Current consumption/power loss	
Current consumption from backplane bus	75 mA
Power loss	0.5 W
Technical data digital outputs	
Number of outputs	4
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	10 mA
Total current per group, horizontal configuration, 40°C	2 A
Total current per group, horizontal configuration, 60°C	2 A
Total current per group, vertical configuration	2 A
Output current at signal "1", rated value	0.5 A
Signal logic output	Sourcing output
Output delay of "0" to "1"	30 µs
Output delay of "1" to "0"	175 µs
Minimum load current	-
Lamp load	10 W
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	✓
Switching frequency with resistive load	max. 1000 Hz
Switching frequency with inductive load	max. 0.5 Hz
Switching frequency on lamp load	max. 10 Hz
Internal limitation of inductive shut-off voltage	L+ (-45 V)
Short-circuit protection of output	yes, electronic
Trigger level	1 A
Number of operating cycle of relay outputs	-
Switching capacity of contacts	-
Output data size	4 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	no
Diagnostics information read-out	none
Supply voltage display	green LED
Group error display	red LED
Channel error display	none

Order no.	022-1BD00
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
PWM data	
PWM channels	-
PWM time basis	-
Period length	-
Minimum pulse width	-
Type of output	-
Datasizes	
Input bytes	0
Output bytes	1
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	57 g
Weight including accessories	57 g
Gross weight	71 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

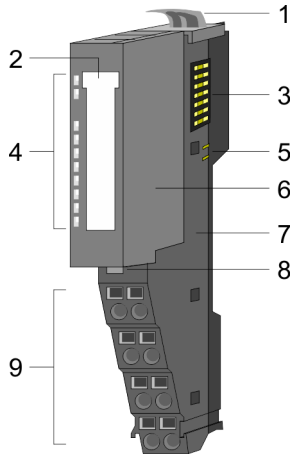
4.4 022-1BD20 - DO 4xDC 24V 2A

Properties

The electronic module accepts binary control signals from the central bus system and transfers them to the process level via outputs. It has 4 channels and their status is monitored via LEDs.

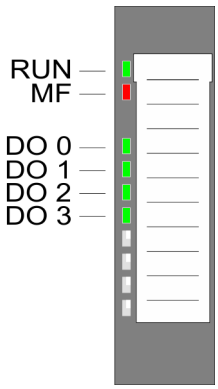
- 4 digital 2A outputs, isolated to the backplane bus
- Status indication of the channels via LEDs

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

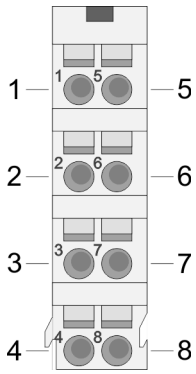
Status indication

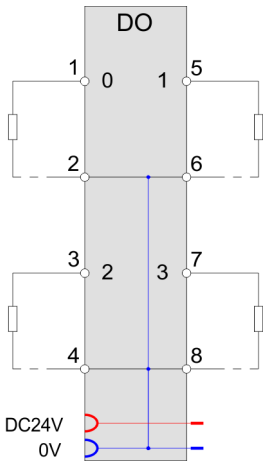


RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital output has "1" signal
■	□	□	Digital output has "0" signal
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DO 0	O	Digital output DO 0
2	0V	O	GND for actuator DO 0
3	DO 2	O	Digital output DO 2
4	0V	O	GND for actuator DO 2
5	DO 1	O	Digital output DO 1
6	0V	O	GND for actuator DO 1
7	DO 3	O	Digital output DO 3
8	0V	O	GND for actuator DO 3

O: Output

CAUTION

Feeding in voltage at an output is not allowed and can destroy the module!

Input area

No byte of the input area is used by the module.

Output area

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PIQ	1	State of the outputs	5200h	
			Bit 0: DO 0		01h
			Bit 1: DO 1		02h
			Bit 2: DO 2		03h
			Bit 3: DO 3		04h
			Bit 7 ... 4: reserved		

4.4.1 Technical data

Order no.	022-1BD20
Type	SM 022 - Digital output
Module ID	0108 AFA0
Current consumption/power loss	
Current consumption from backplane bus	75 mA
Power loss	0.8 W
Technical data digital outputs	
Number of outputs	4
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	20 mA
Total current per group, horizontal configuration, 40°C	4 A
Total current per group, horizontal configuration, 60°C	4 A
Total current per group, vertical configuration	4 A
Output current at signal "1", rated value	2 A
Signal logic output	Sourcing output
Output delay of "0" to "1"	100 µs
Output delay of "1" to "0"	250 µs
Minimum load current	-
Lamp load	10 W
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	✓
Switching frequency with resistive load	max. 1000 Hz
Switching frequency with inductive load	max. 0.5 Hz
Switching frequency on lamp load	max. 10 Hz
Internal limitation of inductive shut-off voltage	L+ (-52 V)
Short-circuit protection of output	yes, electronic
Trigger level	2.7 A
Number of operating cycle of relay outputs	-
Switching capacity of contacts	-
Output data size	4 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	no
Diagnostics information read-out	none
Supply voltage display	green LED
Group error display	red LED
Channel error display	none

Order no.	022-1BD20
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
PWM data	
PWM channels	-
PWM time basis	-
Period length	-
Minimum pulse width	-
Type of output	-
Datasizes	
Input bytes	0
Output bytes	1
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	58 g
Weight including accessories	58 g
Gross weight	73 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

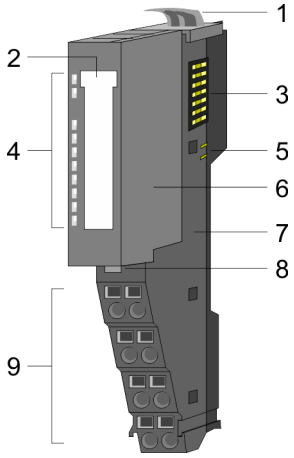
4.5 022-1BD50 - DO 4xDC 24V 0.5A NPN

Properties

The electronic module accepts binary control signals from the central bus system and transfers them to the process level via outputs. It has 4 channels connected to the power supply, which operate as low-side switch and their status is monitored via LEDs. Low-side switches are suited to switch grounds. With a short circuit between switch line and ground the load is activated but the power supply is not influenced.

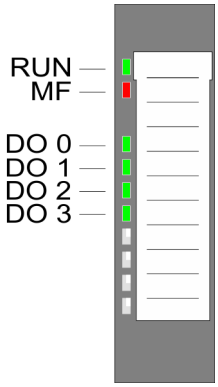
- 4 digital low-side outputs, isolated to the backplane bus
- Status indication of the channels via LEDs

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

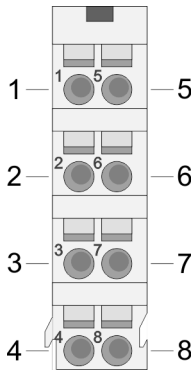
Status indication

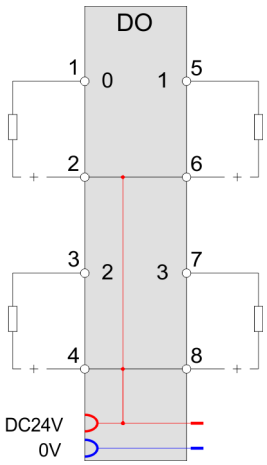


RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital output has "1" signal
■	□	□	Digital output has "0" signal
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DO 0	O	Digital output DO 0
2	DC 24V	O	DC 24V for actuator DO 0
3	DO 2	O	Digital output DO 2
4	DC 24V	O	DC 24V for actuator DO 2
5	DO 1	O	Digital output DO 1
6	DC 24V	O	DC 24V for actuator DO 1
7	DO 3	O	Digital output DO 3
8	DC 24V	O	DC 24V for actuator DO 3

O: Output

CAUTION

Feeding in voltage at an output is not allowed and can destroy the module!

Input area

No byte of the input area is used by the module.

Output area

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PIQ	1	State of the outputs	5200h	
			Bit 0: DO 0		01h
			Bit 1: DO 1		02h
			Bit 2: DO 2		03h
			Bit 3: DO 3		04h
			Bit 7 ... 4: reserved		

4.5.1 Technical data

Order no.	022-1BD50
Type	SM 022 - Digital output
Module ID	0105 AFA0
Current consumption/power loss	
Current consumption from backplane bus	75 mA
Power loss	0.5 W
Technical data digital outputs	
Number of outputs	4
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	5 mA
Total current per group, horizontal configuration, 40°C	2 A
Total current per group, horizontal configuration, 60°C	2 A
Total current per group, vertical configuration	2 A
Output current at signal "1", rated value	0.5 A
Signal logic output	Sinking output
Output delay of "0" to "1"	30 µs
Output delay of "1" to "0"	100 µs
Minimum load current	-
Lamp load	10 W
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	✓
Switching frequency with resistive load	max. 1000 Hz
Switching frequency with inductive load	max. 0.5 Hz
Switching frequency on lamp load	max. 10 Hz
Internal limitation of inductive shut-off voltage	+45 V
Short-circuit protection of output	yes, electronic
Trigger level	1.7 A
Number of operating cycle of relay outputs	-
Switching capacity of contacts	-
Output data size	4 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	no
Diagnostics information read-out	none
Supply voltage display	green LED
Group error display	red LED
Channel error display	none

Order no.	022-1BD50
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
PWM data	
PWM channels	-
PWM time basis	-
Period length	-
Minimum pulse width	-
Type of output	-
Datasizes	
Input bytes	0
Output bytes	1
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	57 g
Weight including accessories	57 g
Gross weight	72 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

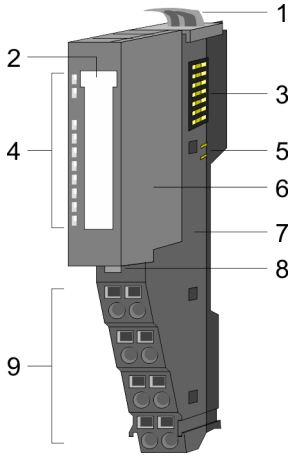
4.6 022-1BD70 - DO 4xDC 24V 0.5A ETS

Properties

The electronic module accepts binary control signals from the central bus system and transfers them time-controlled by means of ETS functionality to the process level via outputs. It has 4 channels and their status is monitored via LEDs. With configured ETS functionality (ETS = **e**dge **t**ime **s**tamp) depending on the configuration 5 (20byte) respectively 15 (60byte), you may transfer the states for the outputs together with a time value of the µs ticker as an ETS entry to the FIFO stack. The FIFO memory serves for space for max. 31 ETS entries.

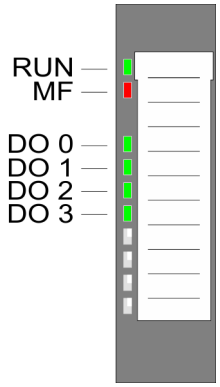
- 4 digital outputs, isolated to the backplane bus
- FIFO stack for 5 respectively 15 ETS entries (each 4byte)
- Diagnostics function
- Controlling by process image respectively handling blocks
- Status indication of the channels via LEDs

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

Status indication

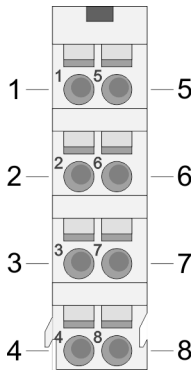


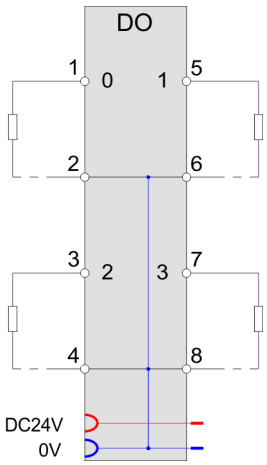
RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital output has "1" signal
■	□	□	Digital output has "0" signal
not relevant: X			

022-1BD70 - DO 4xDC 24V 0.5A ETS

Pin assignment

For wires with a core cross-section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DO 0	O	Digital output DO 0
2	0V	O	GND for actuator DO 0
3	DO 2	O	Digital output DO 2
4	0V	O	GND for actuator DO 2
5	DO 1	O	Digital output DO 1
6	0V	O	GND for actuator DO 1
7	DO 3	O	Digital output DO 3
8	0V	O	GND for actuator DO 3

O: Output

CAUTION

Feeding in voltage at an output is not allowed and can destroy the module!

Input area

The input range is used for status message. At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the according manual of your bus coupler.

IX - IX = Index for access via CANopen.

SX - Subindex for access via EtherCAT with Index 6000h + EtherCAT-Slot.

Please consider, with a full FIFO stack no further ETS entries may be accepted.

To ensure that your ETS entries are kept, you should always check the state of the FIFO stack by STS_FIFO in the input area before.

Addr.	Name	Bytes	Function	IX	SX
+0	RN_LAST	1	Bit 5 ... 0: RN last FIFO entry Bit 6: 1 (fix) Bit 7: 0 (fix)	5440h	01h
+1	RN_NEXT	1	Bit 5 ... 0: RN next FIFO entry to be processed Bit 6: 1 (fix) Bit 7: 1 (fix)		02h
+2	STS_FIFO	1	State of the FIFO stack		03h
+3	NUM_ETS	1	Number of ETS entries in the FIFO stack		04h

RN_LAST

Bit 5 ... 0: Here the RN of the last ETS entry may be found, which was recognized as valid and written into the FIFO memory of the module.

Bit 6: 1 (fix) - serves for the identification in the process image

Bit 7: 0 (fix) - serves for the identification in the process image

RN_NEXT

Bit 5 ... 0: Here the RN of the ETS entry may be found, which will be executed next in the FIFO memory of the module.

Please consider Bit 6 and 7 of RN_NEXT are always set.

Bit 6: 1 (fix) - serves for the identification in the process image

Bit 7: 1 (fix) - serves for the identification in the process image

STS_FIFO

The *State* informs about the state of the FIFO stack:

STS_FIFO	Description
00h/80h	Everything is OK. You will get this message directly after the storage in the FIFO memory of the module.
01h/81h	There is no following ETS entry in the FIFO. The RN does not correspond to the expected RN. Please check your RN in the output area.
02h/82h	There are no new ETS entries in the FIFO.
03h/83h	FIFO stack is full. There is no more place for further ETS entries.

If there are less ETS entries written as possible, additionally bit 6 of the last RN must be set. This is necessary; otherwise you have to overwrite the following entries with a "not valid" entry. The module ignores entries after an entry with a set bit 6. If there is an ETS entry in the FIFO memory, whose bit 6 is set, STS_FIFO is always returned ored with 80h.

NUM_ETS

Here always the current number of the ETS entries in the FIFO memory of the module may be found.

Output area

With configured ETS functionality (ETS=**e**dge **t**ime **s**tamp) a time value (ETS_US) together with the state of the outputs (PIQ) and a running number (RN) may be stored as ETS entry in the process image. Depending on the configuration you can transfer 5 (20byte) respectively 15 (60byte) states for the outputs together with a time value of the µs ticker to the FIFO memory as an ETS entry. You may configure the following variants:

- 022-1BD70 DO 4xDC 24V ETS(20): FIFO with 20byte for 5 ETS entries
- 022-1BD70 DO 4xDC 24V ETS: FIFO with 60byte for 15 ETS entries

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the according manual of your bus coupler.

IX - Index for access via CANopen. With s = Subindex the corresponding ETS entry is addressed.

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot.

Configured as 022-1BD70 DO 4xDC 24V ETS(20)

20byte - 5 ETS entries

Addr.	PIQ	IX=5640h	SX	Addr.	RN	IX=5640h	SX	Addr.	ETS-US	IX=5640h	SX
+0	PIQ+0	s=1	01h	+1	RN+0	s=1	02h	+2	ETS_US+0	s=1	03h
+4	PIQ+1	s=2	04h	+5	RN+1	s=2	05h	+6	ETS_US+1	s=2	06h
+8	PIQ+2	s=3	07h	+9	RN+2	s=3	08h	+10	ETS_US+2	s=3	09h
+12	PIQ+3	s=4	0Ah	+13	RN+3	s=4	0Bh	+14	ETS_US+3	s=4	0Ch
+16	PIQ+4	s=5	0Dh	+17	RN+4	s=5	0Eh	+18	ETS_US+4	s=5	0Fh

Configured as 022-1BD70 DO 4xDC 24V ETS

60byte - 15 ETS entries

Addr.	PIQ	IX=5640h	SX	Addr.	RN	IX=5640h	SX	Addr.	ETS-US	IX=5640h	SX
+0	PIQ+0	s=1	01h	+1	RN+0	s=1	02h	+2	ETS_US+0	s=1	03h
+4	PIQ+1	s=2	04h	+5	RN+1	s=2	05h	+6	ETS_US+1	s=2	06h
+8	PIQ+2	s=3	07h	+9	RN+2	s=3	08h	+10	ETS_US+2	s=3	09h
+12	PIQ+3	s=4	0Ah	+13	RN+3	s=4	0Bh	+14	ETS_US+3	s=4	0Ch
+16	PIQ+4	s=5	0Dh	+17	RN+4	s=5	0Eh	+18	ETS_US+4	s=5	0Fh
+20	PIQ+5	s=6	10h	+21	RN+5	s=6	11h	+22	ETS_US+5	s=6	12h
+24	PIQ+6	s=7	13h	+25	RN+6	s=7	14h	+26	ETS_US+6	s=7	15h
+28	PIQ+7	s=8	16h	+29	RN+7	s=8	17h	+30	ETS_US+7	s=8	18h
+32	PIQ+8	s=9	19h	+33	RN+8	s=9	1Ah	+34	ETS_US+8	s=9	1Bh
+36	PIQ+9	s=10	1Ch	+37	RN+9	s=10	1Dh	+38	ETS_US+9	s=10	1Eh
+40	PIQ+10	s=11	1Fh	+41	RN+10	s=11	20h	+42	ETS_US+10	s=11	21h
+44	PIQ+11	s=12	22h	+45	RN+11	s=12	23h	+46	ETS_US+11	s=12	24h
+48	PIQ+12	s=13	25h	+49	RN+12	s=13	26h	+50	ETS_US+12	s=13	27h
+52	PIQ+13	s=14	28h	+53	RN+13	s=14	29h	+54	ETS_US+13	s=14	2Ah
+56	PIQ+14	s=15	2Bh	+57	RN+14	s=15	2Ch	+58	ETS_US+14	s=15	2Dh

Structure of an ETS entry

Addr.	Name	Bytes	Function	IX	SX
+0	PIQ	1	Output byte	5640h/s	01h
+1	RN	1	Running number		02h
+2	ETS_US	2	µs ticker		03h

PIQ

Here the state of the outputs for the corresponding time may be defined and the output channels may be enabled respectively disabled. The output byte has the following bit allocation:

Bit 3 ... 0: 0 (fix)

Bit 4: State DO 3

Bit 5: State DO 2

Bit 6: State DO 1

Bit 7: State DO 0

RN

RN (**R**unning **N**umber) is a continuous number 0 ... 63, which has to start with 1. With the RN the chronological order of the ETS entries may be defined. With each ETS entry RN is to be incremented, otherwise the ETS entry may not be recognized by the module.

If there are less ETS entries written as possible, additionally bit 6 of the last RN must be set. This is necessary; otherwise you have to overwrite the following entries with a "not valid" entry. The module ignores entries after an entry with a set bit 6.

ETS_US

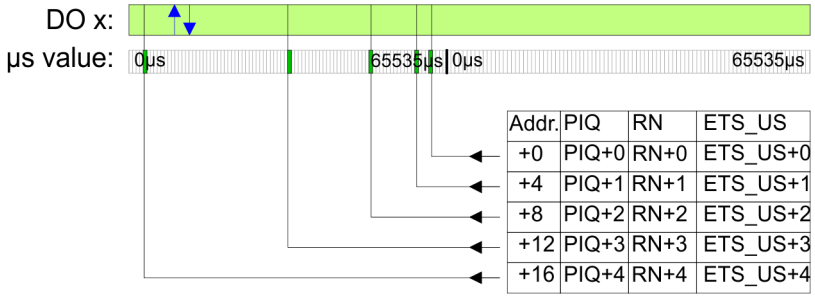
In the System SLIO module there is a 32 bit timer (µs ticker). With PowerON the timer starts counting. After 2^{32}-1µs the timer starts with 0 again. For ETS_US of an ETS entry you have to define a time value from the low word of the µs ticker (0...65535µs).

Here please enter a time value in µs, to which the state of the outputs is to be taken.

Range of values: 0 ... 65535

ETS functionality

The following picture shows how the ETS entries are to be preset in the output area, so that these can be stored in the FIFO memory.



The ETS module may only be accessed by the System SLIO CPU by means of SFC 15 or via the process image. Only the input data of the ETS module may be read by individual accesses.

4.6.1 Technical data

Order no.	022-1BD70
Type	SM 022 - Digital output
Module ID	0F43 57E2
Current consumption/power loss	
Current consumption from backplane bus	105 mA
Power loss	0.95 W
Technical data digital outputs	
Number of outputs	4
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	25 mA
Total current per group, horizontal configuration, 40°C	2 A
Total current per group, horizontal configuration, 60°C	2 A
Total current per group, vertical configuration	2 A
Output current at signal "1", rated value	0.5 A
Signal logic output	Sourcing output
Output delay of "0" to "1"	max. 500 ns
Output delay of "1" to "0"	max. 500 ns
Minimum load current	-
Lamp load	10 W
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	✓
Switching frequency with resistive load	max. 40 kHz
Switching frequency with inductive load	max. 40 kHz
Switching frequency on lamp load	max. 40 kHz
Internal limitation of inductive shut-off voltage	L+ (-45 V)
Short-circuit protection of output	yes, electronic, and only highside
Trigger level	1 A
Number of operating cycle of relay outputs	-
Switching capacity of contacts	-
Output data size	60 Byte
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	no
Diagnostics information read-out	possible
Supply voltage display	green LED
Group error display	red LED
Channel error display	none

Order no.	022-1BD70
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
PWM data	
PWM channels	-
PWM time basis	-
Period length	-
Minimum pulse width	-
Type of output	-
Datasizes	
Input bytes	4
Output bytes	20 / 60
Parameter bytes	6
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	61 g
Weight including accessories	61 g
Gross weight	76 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

4.6.2 Parameter data

The following variants may be configured:

- 022-1BD70 DO 4xDC 24V ETS(20):
  uses 20byte in the PII for 5 ETS entries
- 022-1BD70 DO 4xDC 24V ETS:
  uses 60byte in the PII for 15 ETS entries

4.6.2.1 Parameters

The module has the following parameter data, which were fix set and may not be altered.

DS - Record set for access via CPU, PROFIBUS and PROFINET

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
PII_L	1	Length process image input data[1]	04h (fix)	02h	3100h	01h
PIQ_L	1	Length process image output data[1, 2]	14h resp. 3Ch (fix)	02h	3101h	02h

1) This record set may only be transferred at STOP state.

2) This parameter depends on the configured variant.

PII_L

Byte	Bit 7 ... 0
0	The length of the process image of the input data is fix set to 4byte.

PIQ_L

Byte	Bit 7 ... 0
0	The length of the process image of the output data is fix set to the configured variant (14h or 3Ch).

4.6.3 Example for the principle of operation

ETS values

In the following it is demonstrated by an example, in which order the ETS entries are stored and processed.

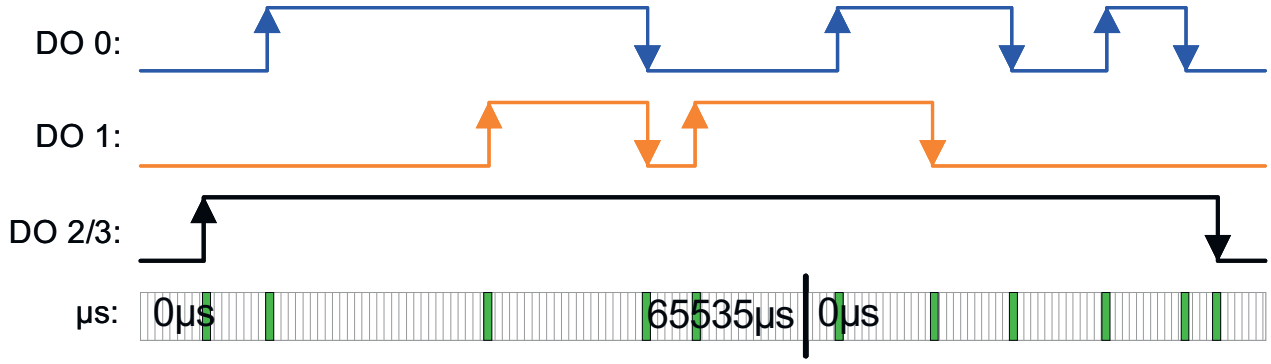
With this example a module is configured, which uses 20byte for 5 ETS entries in the output area PIQ.

With the following times of the µs ticker the following states of the outputs should be taken:

RN	ETS_US in µs	PIQ DO 0 (Bit 7)	PIQ DO 1 (Bit 6)	PIQ DO2 (Bit 5)	PIQ DO 3 (Bit 4)
01h	6000	0	0	1	1
02h	12506	1	0	1	1
03h	34518	1	1	1	1
04h	49526	0	0	1	1
05h	54529	0	1	1	1
06h	3500	1	1	1	1
07h	12443	1	0	1	1
08h	20185	0	0	1	1
09h	30140	1	0	1	1
0Ah	37330	0	0	1	1
0Bh	40000	0	0	0	0

Time diagram

From the table you get the following time diagram:

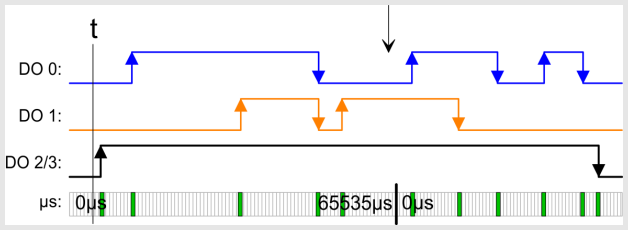


Writing 5 ETS entries

After writing the ETS entries into the process output image they are directly stored in the FIFO memory of the module.

The state of the outputs are shown in the diagram at the time "t".

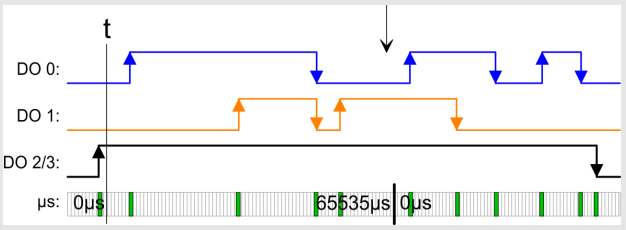
In the PII you will find the status bytes.

Addr.	PIQ	RN	ETS_US	→	FIFO	PIQ	RN	ETS_US	PII
+0	00110000	01h	6000		1	00110000	01h	6000	RN_LAST: 45h
+4	10110000	02h	12506		2	10110000	02h	12506	RN_NEXT: C1h
+8	11110000	03h	34518		3	11110000	03h	34518	STS_FIFO: 00h
+12	00110000	04h	49526		4	00110000	04h	49526	NUM_ETS: 05h
+16	01110000	05h	54529		5	01110000	05h	54529	
					6	00000000	00h	0	
					7	00000000	00h	0	
					8	00000000	00h	0	
					9	00000000	00h	0	
					...	00000000	00h	0	
					31	00000000	00h	0	

Executing ETS function for RN = 01h

The 1. ETS entry (RN = 01h) is executed and deleted in the FIFO.

Addr.	PIQ	RN	ETS_US	→
+0	00110000	01h	6000	
+4	10110000	02h	12506	
+8	11110000	03h	34518	
+12	00110000	04h	49526	
+16	01110000	05h	54529	

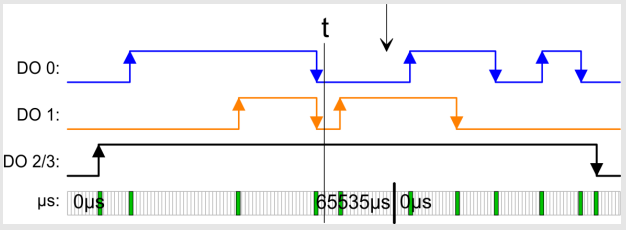


FIFO	PIQ	RN	ETS_US	PII
1	10110000	02h	12506	RN_LAST: 45h
2	11110000	03h	34518	RN_NEXT: C2h
3	00110000	04h	49526	STS_FIFO: 00h/02h
4	01110000	05h	54529	NUM_ETS: 04h
5	00000000	00h	0	
6	00000000	00h	0	
7	00000000	00h	0	
8	00000000	00h	0	
9	00000000	00h	0	
...	00000000	00h	0	
31	00000000	00h	0	

Executing ETS function for RN = 02h ... 04h

The states of RN = 02h ... RN 04h are successively issued and deleted in the FIFO.

Addr.	PIQ	RN	ETS_US	→
+0	00110000	01h	6000	
+4	10110000	02h	12506	
+8	11110000	03h	34518	
+12	00110000	04h	49526	
+16	01110000	05h	54529	

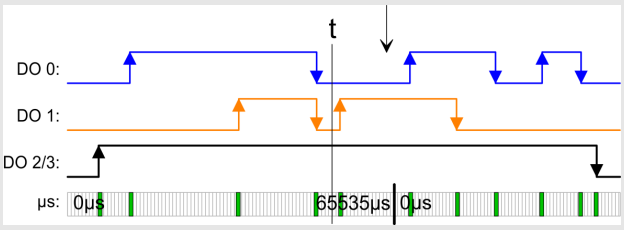


FIFO	PIQ	RN	ETS_US	PII
1	01110000	05h	54529	RN_LAST: 45h
2	00000000	00h	0	RN_NEXT: C5h
3	00000000	00h	0	STS_FIFO: 00h/02h
4	00000000	00h	0	NUM_ETS: 01h
5	00000000	00h	0	
6	00000000	00h	0	
7	00000000	00h	0	
8	00000000	00h	0	
9	00000000	00h	0	
...	00000000	00h	0	
31	00000000	00h	0	

Writing 5 ETS entries

After writing the next 5 ETS entries into the process output image they are directly stored in the FIFO memory of the module.

Addr.	PIQ	RN	ETS_US	→
+0	11110000	06h	3500	
+4	10110000	07h	12443	
+8	00110000	08h	20185	
+12	10110000	09h	30140	
+16	00110000	0Ah	37330	

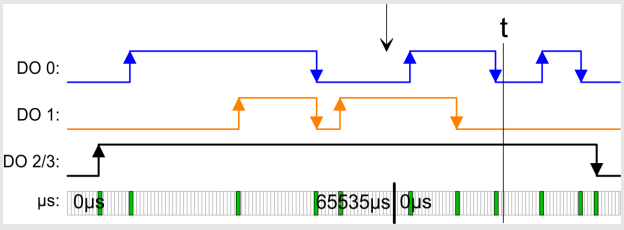


FIFO	PIQ	RN	ETS_US	PII
1	01110000	05h	54529	RN_LAST: 4Ah
2	11110000	06h	3500	RN_NEXT: C5h
3	10110000	07h	12443	STS_FIFO: 00h/02h
4	00110000	08h	20185	NUM_ETS: 06h
5	10110000	09h	30140	
6	00110000	0Ah	37330	
7	00000000	00h	0	
8	00000000	00h	0	
9	00000000	00h	0	
...	00000000	00h	0	
31	00000000	00h	0	

Executing ETS function for RN = 06h ... 08h

The states of RN = 06h ... RN 08h are successively issued and deleted in the FIFO.

Addr.	PIQ	RN	ETS_US	→
+0	11110000	06h	3500	
+4	10110000	07h	12443	
+8	00110000	08h	20185	
+12	10110000	09h	30140	
+16	00110000	0Ah	37330	

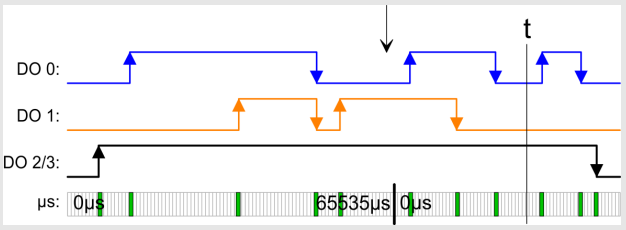


FIFO	PIQ	RN	ETS_US	PII
1	10110000	09h	30140	RN_LAST: 4Ah
2	00110000	0Ah	37330	RN_NEXT: C5h
3	00000000	00h	0	STS_FIFO: 00h/02h
4	00000000	00h	0	NUM_ETS: 02h
5	00000000	00h	0	
6	00000000	00h	0	
7	00000000	00h	0	
8	00000000	00h	0	
9	00000000	00h	0	
...	00000000	00h	0	
31	00000000	00h	0	

Writing last ETS entry

Since less than 5 ETS entries are written, bit 6 of RN of the last ETS entry must always be set. RN = 0Bh becomes 4Bh.

Addr.	PIQ	RN	ETS_US	→
+0	00000000	4Bh	40000	
+4	10110000	07h	12443	
+8	00110000	08h	20185	
+12	10110000	09h	30140	
+16	00110000	0Ah	37330	

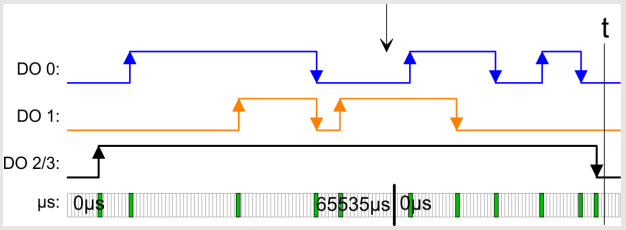


FIFO	PIQ	RN	ETS_US	PII
1	10110000	09h	30140	RN_LAST: 4Bh
2	00110000	0Ah	37330	RN_NEXT: C9h
3	00000000	4Bh	40000	STS_FIFO: 80h/82h
4	00000000	00h	0	NUM_ETS: 03h
5	00000000	00h	0	
6	00000000	00h	0	
7	00000000	00h	0	
8	00000000	00h	0	
9	00000000	00h	0	
...	00000000	00h	0	
31	00000000	00h	0	

Executing ETS function for RN = 09h ... 4Bh

The states of RN = 09h ... RN 4Bh are successively issued and deleted in the FIFO.

Addr.	PIQ	RN	ETS_US	→
+0	00000000	4Bh	40000	
+4	10110000	07h	12443	
+8	00110000	08h	20185	
+12	10110000	09h	30140	
+16	00110000	0Ah	37330	



FIFO	PIQ	RN	ETS_US	PII
1	00000000	00h	0	RN_LAST: 4Bh
2	00000000	00h	0	RN_NEXT: CCh
3	00000000	00h	0	STS_FIFO: 80h/82h
4	00000000	00h	0	NUM_ETS: 00h
5	00000000	00h	0	
6	00000000	00h	0	
7	00000000	00h	0	
8	00000000	00h	0	
9	00000000	00h	0	
...	00000000	00h	0	
31	00000000	00h	0	

Please consider the ETS modules can only effectively be used together with head modules, which have an integrated µs ticker. The Ethernet coupler with ModbusTCP 053-1MT00 for example does not have an µs ticker.

4.6.4 Diagnostic data

This module does not support interrupt functions, the diagnostic data serve the information about this module.

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

IX - Index for access via CANopen. The access happens by IX 2F01h. Additionally the first 4 bytes may be accessed by IX 2F00h.

SX - Subindex for access via EtherCAT with Index 5005h.

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
ERR_A	1	reserved	00h	01h	2F01h	02h
MODTYP	1	Module information	1Fh			03h
ERR_C	1	reserved	00h			04h
ERR_D	1	reserved	00h			05h
CHTYP	1	Channel type	72h			06h
NUMBIT	1	Number of diagnostics bits per channel	00h			07h
NUMCH	1	Number channels of the module	04h			08h
CHERR	1	reserved	00h			09h
CH0ERR… CH7ERR	8	reserved	00h			0Ah ... 11h
DIAG_US	4	µs ticker (32bit)	00h			13h

MODTYP Module information

Byte	Bit 7 ... 0
0	Bit 3 ... 0: Module class 1111b Digital module Bit 4: Channel information present Bit 7 ... 5: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	Bit 6 ... 0: Channel type 72h: Digital output Bit 7: 0 (fix)

NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostics bits of the module per channel (here 00h)

NUMCH Number of channels

Byte	Bit 7 ... 0
0	Number of channels of the module (here 04h)

DIAG_US µs ticker

Byte	Bit 7 ... 0
0 ... 3	Value of the µs ticker at the moment of the diagnostic data generation

ERR_A/C/D CHERR, CHxERR reserved

Byte	Bit 7 ... 0
0	reserved

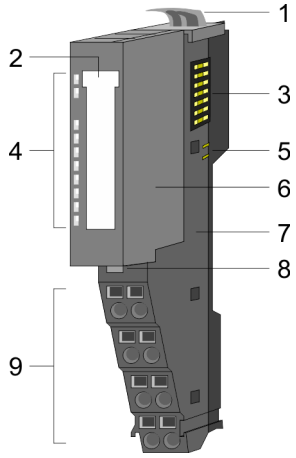
4.7 022-1BD80 - DO 4xDC 24V 0.5A ETS NPN

Properties

The electronic module accepts binary control signals from the central bus system and transfers them time-controlled by means of ETS functionality to the process level via outputs. It has 4 channels connected to the power supply, which operate as low-side switch and their status is monitored via LEDs. Low-side switches are suited to switch grounds. With a short circuit between switch line and ground the load is activated but the power supply is not influenced. With configured ETS functionality (ETS = **e**dge **t**ime **s**tamp) depending on the configuration 5 (20byte) respectively 15 (60byte), you may transfer the states for the outputs together with a time value of the µs ticker to the FIFO memory as an ETS entry. The FIFO memory serves for space for max. 31 ETS entries.

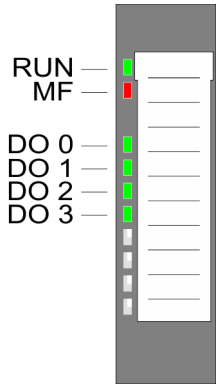
- 4 digital low-side outputs, isolated to the backplane bus
- FIFO stack for 15 ETS entries (each 4byte)
- Diagnostics function
- Controlling by process image respectively handling blocks
- Status indication of the channels via LEDs

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

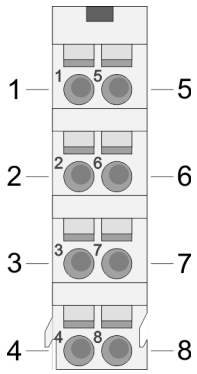
Status indication

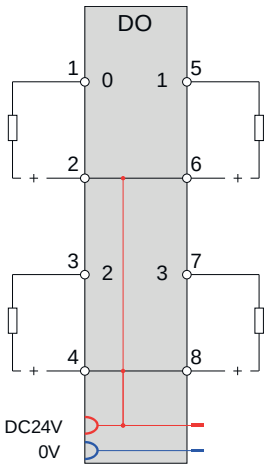


RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital output has "1" signal
■	□	□	Digital output has "0" signal
not relevant: X			

Pin assignment

For wires with a core cross-section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DO 0	O	Digital output DO 0
2	DC 24V	O	DC 24V for actuator DO 0
3	DO 2	O	Digital output DO 2
4	DC 24V	O	DC 24V for actuator DO 2
5	DO 1	O	Digital output DO 1
6	DC 24V	O	DC 24V for actuator DO 1
7	DO 3	O	Digital output DO 3
8	DC 24V	O	DC 24V for actuator DO 3

O: Output

Input area

The input range is used for status message. At CPU, PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the according manual of your bus coupler.

IX - IX = Index for access via CANopen.

SX - Subindex for access via EtherCAT with Index 6000h + EtherCAT-Slot.

Please consider, with a full FIFO stack no further ETS entries may be accepted.

To ensure that your ETS entries are kept, you should always check the state of the FIFO stack by STS_FIFO in the input area before.

Please note the special behavior of the module after a STOP-RUN transition. *'STOP-RUN behavior'...page 188*

Addr.	Name	Bytes	Function	IX	SX
+0	RN_LAST	1	Bit 5 ... 0: RN last FIFO entry Bit 6: 1 (fix) Bit 7: 0 (fix)	5440h	01h
+1	RN_NEXT	1	Bit 5 ... 0: RN next FIFO entry to be processed Bit 6: 1 (fix) Bit 7: 1 (fix)		02h
+2	STS_FIFO	1	State of the FIFO stack		03h
+3	NUM_ETS	1	Number of ETS entries in the FIFO stack		04h

RN_LAST

Bit 5 ... 0: Here the RN of the last ETS entry may be found, which was recognized as valid and written into the FIFO memory of the module.

Bit 6: 1 (fix) - serves for the identification in the process image

Bit 7: 0 (fix) - serves for the identification in the process image

RN_NEXT

Bit 5 ... 0: Here the RN of the ETS entry may be found, which will be executed next in the FIFO memory of the module.

Please consider Bit 6 and 7 of RN_NEXT are always set.

Bit 6: 1 (fix) - serves for the identification in the process image

Bit 7: 1 (fix) - serves for the identification in the process image

STS_FIFO

The *State* informs about the state of the FIFO stack:

STS_FIFO	Description
00h/80h	Everything is OK. You will get this message directly after the storage in the FIFO memory of the module.
01h/81h	There is no following ETS entry in the FIFO. The RN does not correspond to the expected RN. Please check your RN in the output area.
02h/82h	There are no new ETS entries in the FIFO.
03h/83h	FIFO stack is full. There is no more place for further ETS entries.

If there are less ETS entries written as possible, additionally bit 6 of the last RN must be set. This is necessary; otherwise you have to overwrite the following entries with a "not valid" entry. The module ignores entries after an entry with a set bit 6. If there is an ETS entry in the FIFO memory, whose bit 6 is set, STS_FIFO is always returned ored with 80h.

NUM_ETS

Here always the current number of the ETS entries in the FIFO memory of the module may be found.

Output area

With configured ETS functionality (ETS=**e**dge **t**ime **s**tamp) a time value (ETS_US) together with the state of the outputs (PIQ) and a running number (RN) may be stored as ETS entry in the process image. Depending on the configuration you can transfer 5 (20byte) respectively 15 (60byte) states for the outputs together with a time value of the µs ticker to the FIFO memory as an ETS entry. You may configure the following variants:

- 022-1BD80 DO 4xDC 24V ETS NPN(20): FIFO with 20byte for 5 ETS entries
- 022-1BD80 DO 4xDC 24V ETS NPN: FIFO with 60byte for 15 ETS entries

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the according manual of your bus coupler.

IX - Index for access via CANopen. With s = Subindex the corresponding ETS entry is addressed.

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot.

Configured as 022-1BD80 DO 4xDC 24V ETS NPN(20)

20byte - 5 ETS entries

Addr.	PIQ	IX=5640h	SX	Addr.	RN	IX=5640h	SX	Addr.	ETS-US	IX=5640h	SX
+0	PIQ+0	s=1	01h	+1	RN+0	s=1	02h	+2	ETS_US+0	s=1	03h
+4	PIQ+1	s=2	04h	+5	RN+1	s=2	05h	+6	ETS_US+1	s=2	06h
+8	PIQ+2	s=3	07h	+9	RN+2	s=3	08h	+10	ETS_US+2	s=3	09h
+12	PIQ+3	s=4	0Ah	+13	RN+3	s=4	0Bh	+14	ETS_US+3	s=4	0Ch
+16	PIQ+4	s=5	0Dh	+17	RN+4	s=5	0Eh	+18	ETS_US+4	s=5	0Fh

Configured as 022-1BD80 DO 4xDC 24V ETS NPN

60byte - 15 ETS entries

Addr.	PIQ	IX=5640h	SX	Addr.	RN	IX=5640h	SX	Addr.	ETS-US	IX=5640h	SX
+0	PIQ+0	s=1	01h	+1	RN+0	s=1	02h	+2	ETS_US+0	s=1	03h
+4	PIQ+1	s=2	04h	+5	RN+1	s=2	05h	+6	ETS_US+1	s=2	06h
+8	PIQ+2	s=3	07h	+9	RN+2	s=3	08h	+10	ETS_US+2	s=3	09h
+12	PIQ+3	s=4	0Ah	+13	RN+3	s=4	0Bh	+14	ETS_US+3	s=4	0Ch
+16	PIQ+4	s=5	0Dh	+17	RN+4	s=5	0Eh	+18	ETS_US+4	s=5	0Fh
+20	PIQ+5	s=6	10h	+21	RN+5	s=6	11h	+22	ETS_US+5	s=6	12h
+24	PIQ+6	s=7	13h	+25	RN+6	s=7	14h	+26	ETS_US+6	s=7	15h
+28	PIQ+7	s=8	16h	+29	RN+7	s=8	17h	+30	ETS_US+7	s=8	18h
+32	PIQ+8	s=9	19h	+33	RN+8	s=9	1Ah	+34	ETS_US+8	s=9	1Bh
+36	PIQ+9	s=10	1Ch	+37	RN+9	s=10	1Dh	+38	ETS_US+9	s=10	1Eh
+40	PIQ+10	s=11	1Fh	+41	RN+10	s=11	20h	+42	ETS_US+10	s=11	21h
+44	PIQ+11	s=12	22h	+45	RN+11	s=12	23h	+46	ETS_US+11	s=12	24h
+48	PIQ+12	s=13	25h	+49	RN+12	s=13	26h	+50	ETS_US+12	s=13	27h
+52	PIQ+13	s=14	28h	+53	RN+13	s=14	29h	+54	ETS_US+13	s=14	2Ah
+56	PIQ+14	s=15	2Bh	+57	RN+14	s=15	2Ch	+58	ETS_US+14	s=15	2Dh

Structure of an ETS entry

Addr.	Name	Bytes	Function	IX	SX
+0	PIQ	1	Output byte	5640h/s	01h
+1	RN	1	Running number		02h
+2	ETS_US	2	µs ticker		03h

PIQ

Here the state of the outputs for the corresponding time may be defined and the output channels may be enabled respectively disabled. The output byte has the following bit allocation:

Bit 3 ... 0: 0 (fix)

Bit 4: State DO 3

Bit 5: State DO 2

Bit 6: State DO 1

Bit 7: State DO 0

RN

RN (**R**unning **N**umber) is a continuous number 0 ... 63, which has to start with 1. With the RN the chronological order of the ETS entries may be defined. With each ETS entry RN is to be incremented, otherwise the ETS entry may not be recognized by the module.

If there are less ETS entries written as possible, additionally bit 6 of the last RN must be set. This is necessary; otherwise you have to overwrite the following entries with a "not valid" entry. The module ignores entries after an entry with a set bit 6.

ETS_US

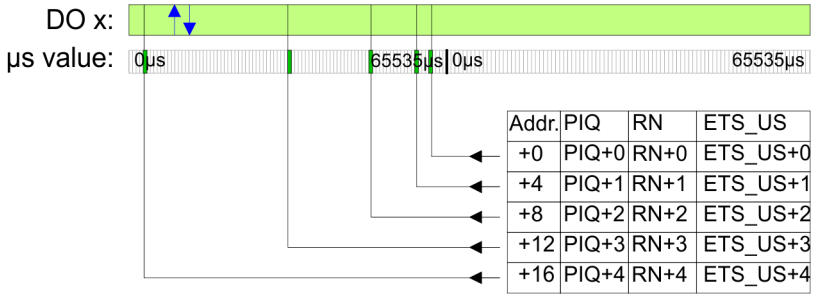
In the System SLIO module there is a 32 bit timer (µs ticker). With PowerON the timer starts counting. After 2^{32}-1µs the timer starts with 0 again. For ETS_US of an ETS entry you have to define a time value from the low word of the µs ticker (0...65535µs).

Here please enter a time value in µs, to which the state of the outputs is to be taken.

Range of values: 0 ... 65535

ETS functionality

The following picture shows how the ETS entries are to be preset in the output area, so that these can be stored in the FIFO memory.



The ETS module may only be accessed by the System SLIO CPU by means of SFC 15 or via the process image. Only the input data of the ETS module may be read by individual accesses.

STOP-RUN behavior

Please note that the data in the input area are no longer consistent after a STOP-RUN transition. Here, *RN_NEXT* and *NUM_ETS* output incorrect values until a new ETS output value is written.

Procedure after a STOP-RUN transition:

1. In the input area, use *RN_LAST* to determine the last RN (running number) of the last ETS entry written.
2. Create an ETS entry with the following parameters:
   - PIQ: Wished state of the outputs
   - RN: Determined *RN_LAST* + 1
   - ETS_US: Wished time value for the ETS entry

   ➡ Once the ETS entry is transferred, the data in the input area is consistent again.

4.7.1 Technical data

Order no.	022-1BD80
Type	SM 022 - Digital output
Module ID	0F45 57E2
Current consumption/power loss	
Current consumption from backplane bus	30 mA
Power loss	0.9 W
Technical data digital outputs	
Number of outputs	4
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	25 mA
Total current per group, horizontal configuration, 40°C	2 A
Total current per group, horizontal configuration, 60°C	2 A
Total current per group, vertical configuration	2 A
Output current at signal "1", rated value	0.5 A
Signal logic output	Sinking output
Output delay of "0" to "1"	max. 500 ns
Output delay of "1" to "0"	max. 500 ns
Minimum load current	-
Lamp load	10 W
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	✓
Switching frequency with resistive load	max. 40 kHz
Switching frequency with inductive load	max. 40 kHz
Switching frequency on lamp load	max. 40 kHz
Internal limitation of inductive shut-off voltage	L+ (-45 V)
Short-circuit protection of output	yes, electronic, and only highside
Trigger level	1 A
Number of operating cycle of relay outputs	-

Order no.	022-1BD80
Switching capacity of contacts	-
Output data size	60 Byte
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	no
Diagnostics information read-out	possible
Supply voltage display	green LED
Group error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
PWM data	
PWM channels	-
PWM time basis	-
Period length	-
Minimum pulse width	-
Type of output	-
Datasizes	
Input bytes	4
Output bytes	20 / 60
Parameter bytes	0
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	61 g
Weight including accessories	61 g
Gross weight	76 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

4.7.2 Parameter data

The following variants may be configured:

- 022-1BD80 DO 4xDC 24V ETS NPN(20):
  uses 20byte in the PII for 5 ETS entries
- 022-1BD80 DO 4xDC 24V ETS NPN:
  uses 60byte in the PII for 15 ETS entries

4.7.2.1 Parameters

The module has the following parameter data, which were fix set and may not be altered.

DS - Record set for access via CPU, PROFIBUS and PROFINET

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
PII_L	1	Length process image input data[1]	04h (fix)	02h	3100h	01h
PIQ_L	1	Length process image output data[1, 2]	14h resp. 3Ch (fix)	02h	3101h	02h

1) This record set may only be transferred at STOP state.

2) This parameter depends on the configured variant.

PII_L

Byte	Bit 7 ... 0
0	The length of the process image of the input data is fix set to 4byte.

PIQ_L

Byte	Bit 7 ... 0
0	The length of the process image of the output data is fix set to the configured variant (14h or 3Ch).

4.7.3 Example for the principle of operation

ETS values

The following example shows the order in which the ETS entries are stored and processed.

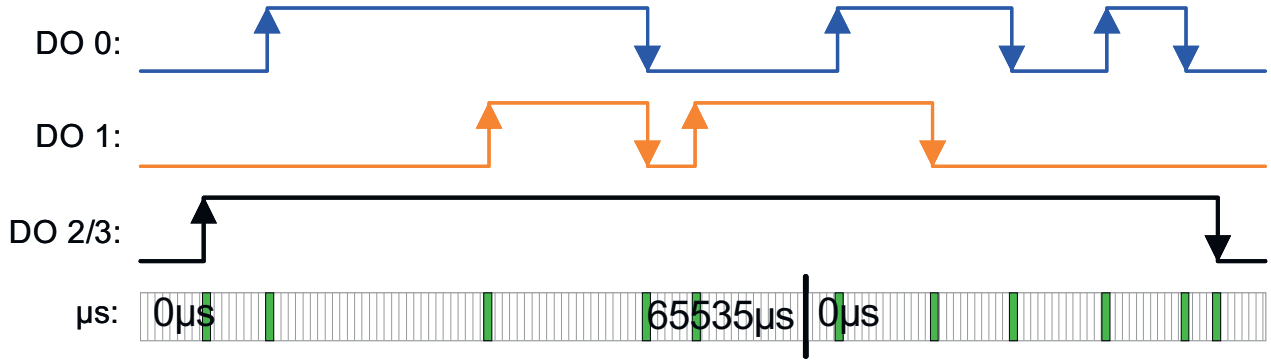
With this example a module is configured, which uses 20byte for 5 ETS entries in the output area PIQ.

With the following times of the µs ticker the following states of the outputs should be taken:

RN	ETS_US in µs	PIQ DO 0 (Bit 7)	PIQ DO 1 (Bit 6)	PIQ DO2 (Bit 5)	PIQ DO 3 (Bit 4)
01h	6000	0	0	1	1
02h	12506	1	0	1	1
03h	34518	1	1	1	1
04h	49526	0	0	1	1
05h	54529	0	1	1	1
06h	3500	1	1	1	1
07h	12443	1	0	1	1
08h	20185	0	0	1	1
09h	30140	1	0	1	1
0Ah	37330	0	0	1	1
0Bh	40000	0	0	0	0

Time diagram

From the table you get the following time diagram:

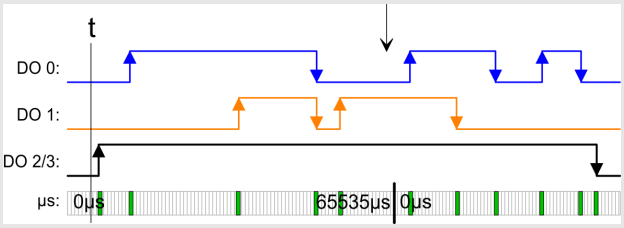


Writing 5 ETS entries

Due to the limitation of the address range to 20 bytes for this example, after writing the 5 ETS entries into the process output data, these are transferred directly to the FIFO memory of the module. With the 022-1BD80, this only takes place after 15 ETS entries are written.

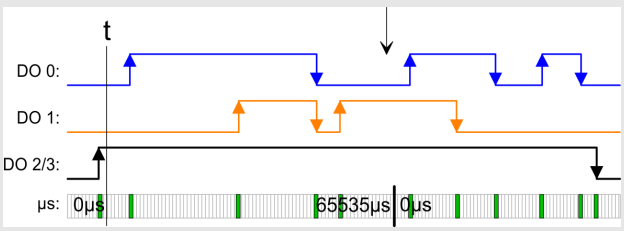
The state of the outputs are shown in the diagram at the time "t".

In the PII you will find the status bytes.

Addr.	PIQ	RN	ETS_US	→	FIFO	PIQ	RN	ETS_US	PII
+0	00110000	01h	6000		1	00110000	01h	6000	RN_LAST: 45h
+4	10110000	02h	12506		2	10110000	02h	12506	RN_NEXT: C1h
+8	11110000	03h	34518		3	11110000	03h	34518	STS_FIFO: 00h
+12	00110000	04h	49526		4	00110000	04h	49526	NUM_ETS: 05h
+16	01110000	05h	54529		5	01110000	05h	54529	
					6	00000000	00h	0	
					7	00000000	00h	0	
					8	00000000	00h	0	
					9	00000000	00h	0	
					...	00000000	00h	0	
					31	00000000	00h	0	

Executing ETS function for RN = 01h

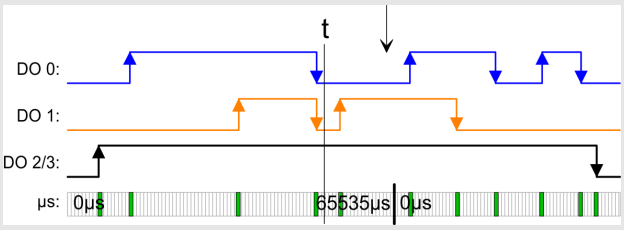
The 1. ETS entry (RN = 01h) is executed and deleted in the FIFO.

Addr.	PIQ	RN	ETS_US	→	FIFO	PIQ	RN	ETS_US	PII
+0	00110000	01h	6000		1	10110000	02h	12506	RN_LAST: 45h
+4	10110000	02h	12506		2	11110000	03h	34518	RN_NEXT: C2h
+8	11110000	03h	34518		3	00110000	04h	49526	STS_FIFO: 00h/02h
+12	00110000	04h	49526		4	01110000	05h	54529	NUM_ETS: 04h
+16	01110000	05h	54529		5	00000000	00h	0	
					6	00000000	00h	0	
					7	00000000	00h	0	
					8	00000000	00h	0	
					9	00000000	00h	0	
					...	00000000	00h	0	
					31	00000000	00h	0	

Executing ETS function for RN = 02h ... 04h

The states of RN = 02h ... RN 04h are successively issued and deleted in the FIFO.

Addr.	PIQ	RN	ETS_US	→
+0	00110000	01h	6000	
+4	10110000	02h	12506	
+8	11110000	03h	34518	
+12	00110000	04h	49526	
+16	01110000	05h	54529	

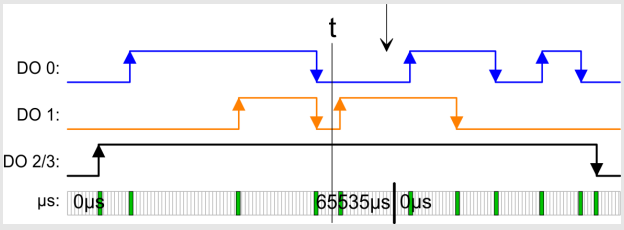


FIFO	PIQ	RN	ETS_US	PII
1	01110000	05h	54529	RN_LAST: 45h
2	00000000	00h	0	RN_NEXT: C5h
3	00000000	00h	0	STS_FIFO: 00h/02h
4	00000000	00h	0	NUM_ETS: 01h
5	00000000	00h	0	
6	00000000	00h	0	
7	00000000	00h	0	
8	00000000	00h	0	
9	00000000	00h	0	
...	00000000	00h	0	
31	00000000	00h	0	

Writing 5 ETS entries

After writing the next 5 ETS entries into the process output image they are directly stored in the FIFO memory of the module for this example. With the 022-1BD80, this only takes place after 15 ETS entries are written.

Addr.	PIQ	RN	ETS_US	→
+0	11110000	06h	3500	
+4	10110000	07h	12443	
+8	00110000	08h	20185	
+12	10110000	09h	30140	
+16	00110000	0Ah	37330	

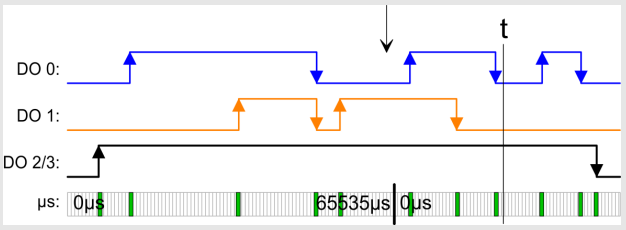


FIFO	PIQ	RN	ETS_US	PII
1	01110000	05h	54529	RN_LAST: 4Ah
2	11110000	06h	3500	RN_NEXT: C5h
3	10110000	07h	12443	STS_FIFO: 00h/02h
4	00110000	08h	20185	NUM_ETS: 06h
5	10110000	09h	30140	
6	00110000	0Ah	37330	
7	00000000	00h	0	
8	00000000	00h	0	
9	00000000	00h	0	
...	00000000	00h	0	
31	00000000	00h	0	

Executing ETS function for RN = 06h ... 08h

The states of RN = 06h ... RN 08h are successively issued and deleted in the FIFO.

Addr.	PIQ	RN	ETS_US	→
+0	11110000	06h	3500	
+4	10110000	07h	12443	
+8	00110000	08h	20185	
+12	10110000	09h	30140	
+16	00110000	0Ah	37330	

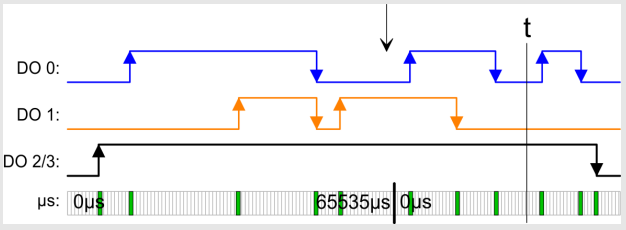


FIFO	PIQ	RN	ETS_US	PII
1	10110000	09h	30140	RN_LAST: 4Ah
2	00110000	0Ah	37330	RN_NEXT: C5h
3	00000000	00h	0	STS_FIFO: 00h/02h
4	00000000	00h	0	NUM_ETS: 02h
5	00000000	00h	0	
6	00000000	00h	0	
7	00000000	00h	0	
8	00000000	00h	0	
9	00000000	00h	0	
...	00000000	00h	0	
31	00000000	00h	0	

Writing last ETS entry

Since less than 5 ETS entries are written in this example, bit 6 of RN of the last ETS entry must always be set. RN = 0Bh becomes 4Bh.

Addr.	PIQ	RN	ETS_US	→
+0	00000000	4Bh	40000	
+4	10110000	07h	12443	
+8	00110000	08h	20185	
+12	10110000	09h	30140	
+16	00110000	0Ah	37330	

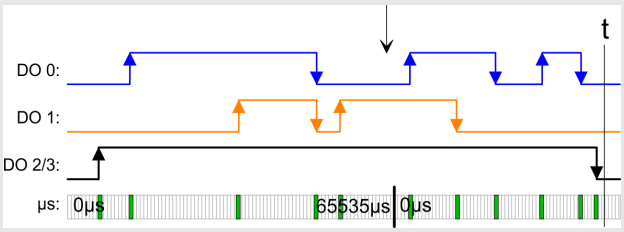


FIFO	PIQ	RN	ETS_US	PII
1	10110000	09h	30140	RN_LAST: 4Bh
2	00110000	0Ah	37330	RN_NEXT: C9h
3	00000000	4Bh	40000	STS_FIFO: 80h/82h
4	00000000	00h	0	NUM_ETS: 03h
5	00000000	00h	0	
6	00000000	00h	0	
7	00000000	00h	0	
8	00000000	00h	0	
9	00000000	00h	0	
...	00000000	00h	0	
31	00000000	00h	0	

Executing ETS function for RN = 09h ... 4Bh

The states of RN = 09h ... RN 4Bh are successively issued and deleted in the FIFO.

Addr.	PIQ	RN	ETS_US
+0	00000000	4Bh	40000
+4	10110000	07h	12443
+8	00110000	08h	20185
+12	10110000	09h	30140
+16	00110000	0Ah	37330



→

FIFO	PIQ	RN	ETS_US	PII
1	00000000	00h	0	RN_LAST: 4Bh
2	00000000	00h	0	RN_NEXT: CCh
3	00000000	00h	0	STS_FIFO: 80h/82h
4	00000000	00h	0	NUM_ETS: 00h
5	00000000	00h	0	
6	00000000	00h	0	
7	00000000	00h	0	
8	00000000	00h	0	
9	00000000	00h	0	
...	00000000	00h	0	
31	00000000	00h	0	

Please consider the ETS modules can only effectively be used together with head modules, which have an integrated µs ticker. The Ethernet coupler with ModbusTCP 053-1MT00 for example does not have an µs ticker.

4.7.4 Diagnostic data

This module does not support interrupt functions, the diagnostic data serve the information about this module.

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

IX - Index for access via CANopen. The access happens by IX 2F01h. Additionally the first 4 bytes may be accessed by IX 2F00h.

SX - Subindex for access via EtherCAT with Index 5005h.

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
ERR_A	1	reserved	00h	01h	2F01h	02h
MODTYP	1	Module information	1Fh			03h
ERR_C	1	reserved	00h			04h
ERR_D	1	reserved	00h			05h
CHTYP	1	Channel type	72h			06h
NUMBIT	1	Number of diagnostics bits per channel	00h			07h
NUMCH	1	Number channels of the module	04h			08h
CHERR	1	reserved	00h			09h
CH0ERR… CH7ERR	8	reserved	00h			0Ah ... 11h
DIAG_US	4	µs ticker (32bit)	00h			13h

MODTYP Module information

Byte	Bit 7 ... 0
0	Bit 3 ... 0: Module class 1111b Digital module Bit 4: Channel information present Bit 7 ... 5: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	Bit 6 ... 0: Channel type 72h: Digital output Bit 7: 0 (fix)

NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostics bits of the module per channel (here 00h)

NUMCH Number of channels

Byte	Bit 7 ... 0
0	Number of channels of the module (here 04h)

DIAG_US µs ticker

Byte	Bit 7 ... 0
0 ... 3	Value of the µs ticker at the moment of the diagnostic data generation

ERR_A/C/D CHERR, CHxERR reserved

Byte	Bit 7 ... 0
0	reserved

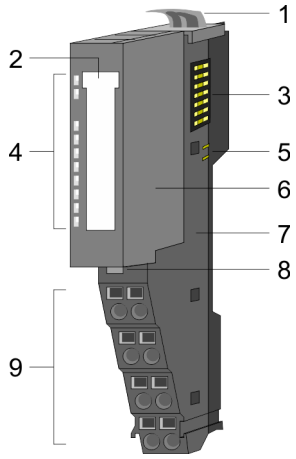
4.8 022-1BF00 - DO 8xDC 24V 0.5A

Properties

The electronic module accepts binary control signals from the central bus system and transfers them to the process level via outputs. It has 8 channels and their status is monitored via LEDs.

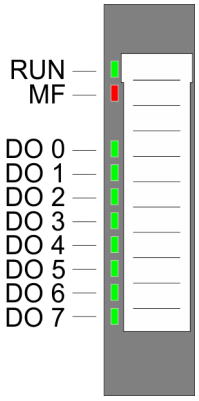
- 8 digital outputs, isolated to the backplane bus
- Status indication of the channels via LEDs

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

Status indication

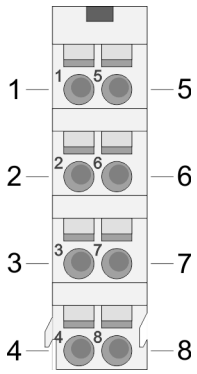


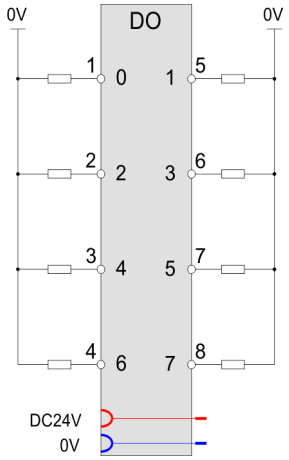
RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital output has "1" signal
■	□	□	Digital output has "0" signal
not relevant: X			

022-1BF00 - DO 8xDC 24V 0.5A

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DO 0	O	Digital output DO 0
2	DO 2	O	Digital output DO 2
3	DO 4	O	Digital output DO 4
4	DO 6	O	Digital output DO 6
5	DO 1	O	Digital output DO 1
6	DO 3	O	Digital output DO 3
7	DO 5	O	Digital output DO 5
8	DO 7	O	Digital output DO 7

O: Output

CAUTION

Feeding in voltage at an output is not allowed and can destroy the module!

Input area

No byte of the input area is used by the module.

Output area

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PIQ	1	State of the outputs	6200h	
			Bit 0: DO 0		01h
			Bit 1: DO 1		02h
			Bit 2: DO 2		03h
			Bit 3: DO 3		04h
			Bit 4: DO 4		05h
			Bit 5: DO 5		06h
			Bit 6: DO 6		07h
			Bit 7: DO 7		08h

4.8.1 Technical data

Order no.	022-1BF00
Type	SM 022 - Digital output
Module ID	0106 AFC8
Current consumption/power loss	
Current consumption from backplane bus	80 mA
Power loss	0.7 W
Technical data digital outputs	
Number of outputs	8
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	15 mA
Total current per group, horizontal configuration, 40°C	4 A
Total current per group, horizontal configuration, 60°C	4 A
Total current per group, vertical configuration	4 A
Output current at signal "1", rated value	0.5 A
Signal logic output	Sourcing output
Output delay of "0" to "1"	30 µs
Output delay of "1" to "0"	175 µs
Minimum load current	-
Lamp load	10 W
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	✓
Switching frequency with resistive load	max. 1000 Hz

Order no.	022-1BF00
Switching frequency with inductive load	max. 0.5 Hz
Switching frequency on lamp load	max. 10 Hz
Internal limitation of inductive shut-off voltage	L+ (-45 V)
Short-circuit protection of output	yes, electronic
Trigger level	1 A
Number of operating cycle of relay outputs	-
Switching capacity of contacts	-
Output data size	8 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	no
Diagnostics information read-out	none
Supply voltage display	green LED
Group error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
PWM data	
PWM channels	-
PWM time basis	-
Period length	-
Minimum pulse width	-
Type of output	-
Datasizes	
Input bytes	0
Output bytes	1
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	

Order no.	022-1BF00
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	58 g
Weight including accessories	58 g
Gross weight	73 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

4.9 022-1BF01 - DO 8xDC 24V 0.5A

Properties

The electronic module collects the binary control signals from the higher-level bus system and transports them to the process level via the outputs. It has 8 channels and their status is monitored via LEDs.

- 8 digital outputs isolated to the backplane bus
- Status indication of the channels via LEDs

The module is identical to the module with the order no. 022-1BF00 with the following difference:

- *The module has a new type designation due to the new order number. This requires updating the GSDML and the hardware configuration. You can find the refreshed 'GSDML SLIO' in the 'Download Center' of ➦ www.yaskawa.eu.com*
- *Due to the internal wiring, the module has a different 'Protective behavior of the outputs' and 'Special behavior of the MF-LED'.*

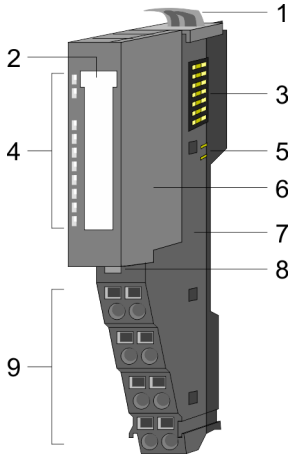
Protective behavior of the outputs

In the event of a short circuit or overload at an output, the output current is initially limited. If the short circuit or overload persists, an integrated thermal protection switches off permanently. Please note that the output has an increased leakage current (< 0.3mA) to DC 24V in this switch-off state, so that a voltmeter for this output shows DC 24V. When the overload on the output is eliminated, the output can only be reactivated after the DC 24V power section supply has been switched off/on.

Special behavior of the MF LED

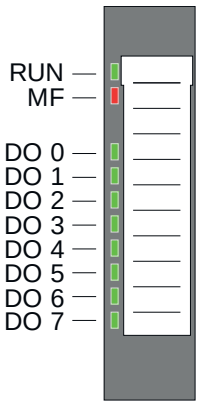
Please note that the MF LED shows the saved error status of an output. The MF LED lights up in the event of overload, short circuit or overtemperature as long as the corresponding output is activated by the PLC. When the overload on the output is eliminated, the output can only be reactivated after the DC 24V power section supply has been switched off/on.

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

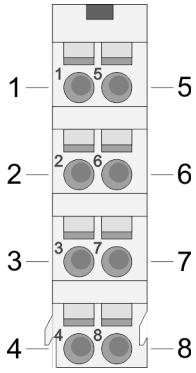
Status indication

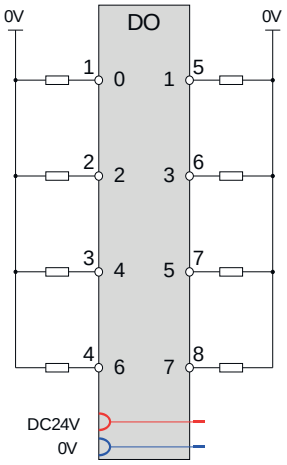


RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital output is controlled with "1" signal
■	□	□	Digital output is controlled with "0" signal
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DO 0	O	Digital output DO 0
2	DO 2	O	Digital output DO 2
3	DO 4	O	Digital output DO 4
4	DO 6	O	Digital output DO 6
5	DO 1	O	Digital output DO 1
6	DO 3	O	Digital output DO 3
7	DO 5	O	Digital output DO 5
8	DO 7	O	Digital output DO 7

O: Output

CAUTION
Feeding in voltage at an output is not allowed and can destroy the module!

Input area

No byte of the input area is used by the module.

Output area

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PIQ	1	State of the outputs	6200h	
			Bit 0: DO 0		01h
			Bit 1: DO 1		02h
			Bit 2: DO 2		03h
			Bit 3: DO 3		04h
			Bit 4: DO 4		05h
			Bit 5: DO 5		06h
			Bit 6: DO 6		07h
			Bit 7: DO 7		08h

4.9.1 Technical data

Order no.	022-1BF01
Type	SM 022 - Digital output
Module ID	0125 AFC8
Current consumption/power loss	
Current consumption from backplane bus	50 mA
Power loss	0.7 W
Technical data digital outputs	
Number of outputs	8
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	15 mA
Total current per group, horizontal configuration, 40°C	4 A
Total current per group, horizontal configuration, 60°C	4 A
Total current per group, vertical configuration	4 A

Order no.	022-1BF01
Output current at signal "1", rated value	0.5 A
Signal logic output	Sourcing output
Output delay of "0" to "1"	70 µs
Output delay of "1" to "0"	175 µs
Minimum load current	-
Lamp load	10 W
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	✓
Switching frequency with resistive load	max. 1000 Hz
Switching frequency with inductive load	max. 0.5 Hz
Switching frequency on lamp load	max. 10 Hz
Internal limitation of inductive shut-off voltage	L+ (-53 V)
Short-circuit protection of output	yes, electronic
Trigger level	1 A
Number of operating cycle of relay outputs	-
Switching capacity of contacts	-
Output data size	8 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	no
Diagnostics information read-out	none
Supply voltage display	green LED
Group error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
PWM data	
PWM channels	-
PWM time basis	-
Period length	-
Minimum pulse width	-

Order no.	022-1BF01
Type of output	-
Datasizes	
Input bytes	0
Output bytes	1
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	58 g
Weight including accessories	58 g
Gross weight	73 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	-
KC certification	-
UKCA certification	-
ChinaRoHS certification	-

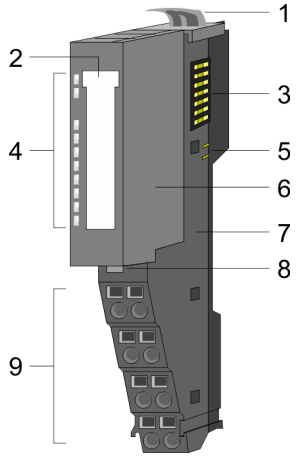
4.10 022-1BF50 - DO 8xDC 24V 0.5A NPN

Properties

The electronic module accepts binary control signals from the central bus system and transfers them to the process level via outputs. It has 8 channels connected to the power supply, which operate as low-side switch and their status is monitored via LEDs. Low-side switches are suited to switch grounds. With a short circuit between switch line and ground the load is activated but the power supply is not influenced.

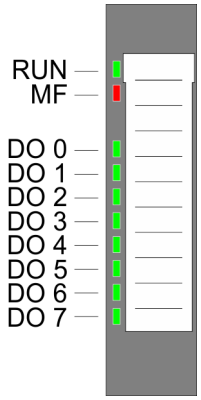
- 8 digital low-side outputs, isolated to the backplane bus
- Status indication of the channels via LEDs

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

Status indication

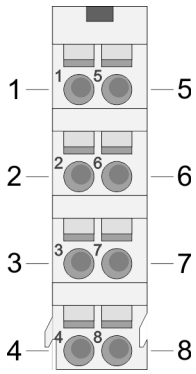


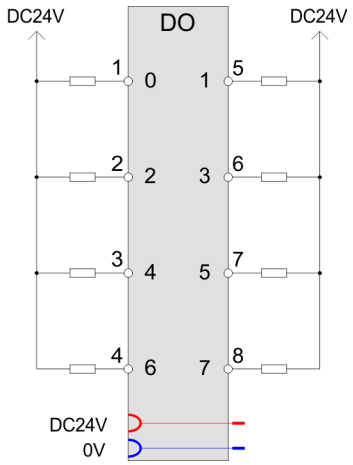
RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital output has "1" signal
■	□	□	Digital output has "0" signal
not relevant: X			

022-1BF50 - DO 8xDC 24V 0.5A NPN

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DO 0	O	Digital output DO 0
2	DO 2	O	Digital output DO 2
3	DO 4	O	Digital output DO 4
4	DO 6	O	Digital output DO 6
5	DO 1	O	Digital output DO 1
6	DO 3	O	Digital output DO 3
7	DO 5	O	Digital output DO 5
8	DO 7	O	Digital output DO 7

O: Output

CAUTION

Feeding in voltage at an output is not allowed and can destroy the module!

Input area

No byte of the input area is used by the module.

Output area

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PIQ	1	State of the outputs	6200h	
			Bit 0: DO 0		01h
			Bit 1: DO 1		02h
			Bit 2: DO 2		03h
			Bit 3: DO 3		04h
			Bit 4: DO 4		05h
			Bit 5: DO 5		06h
			Bit 6: DO 6		07h
			Bit 7: DO 7		08h

4.10.1 Technical data

Order no.	022-1BF50
Type	SM 022 - Digital output
Module ID	0107 AFC8
Current consumption/power loss	
Current consumption from backplane bus	80 mA
Power loss	0.6 W
Technical data digital outputs	
Number of outputs	8
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	10 mA
Total current per group, horizontal configuration, 40°C	2.5 A
Total current per group, horizontal configuration, 60°C	2.5 A
Total current per group, vertical configuration	2.5 A
Output current at signal "1", rated value	0.5 A
Signal logic output	Sinking output
Output delay of "0" to "1"	30 µs
Output delay of "1" to "0"	100 µs
Minimum load current	-
Lamp load	10 W
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	✓
Switching frequency with resistive load	max. 1000 Hz

Order no.	022-1BF50
Switching frequency with inductive load	max. 0.5 Hz
Switching frequency on lamp load	max. 10 Hz
Internal limitation of inductive shut-off voltage	+45 V
Short-circuit protection of output	yes, electronic
Trigger level	1.7 A
Number of operating cycle of relay outputs	-
Switching capacity of contacts	-
Output data size	8 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	no
Diagnostics information read-out	none
Supply voltage display	green LED
Group error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
PWM data	
PWM channels	-
PWM time basis	-
Period length	-
Minimum pulse width	-
Type of output	-
Datasizes	
Input bytes	0
Output bytes	1
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	

Order no.	022-1BF50
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	58 g
Weight including accessories	58 g
Gross weight	73 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

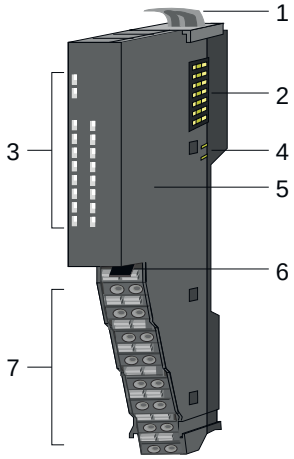
4.11 022-1BH00 - DO 16xDC 24V 0.5A

Properties

The module detects the binary control signals from the higher-level bus system and transports them to the process level via the outputs. It has 16 channels and their status is indicated by LEDs.

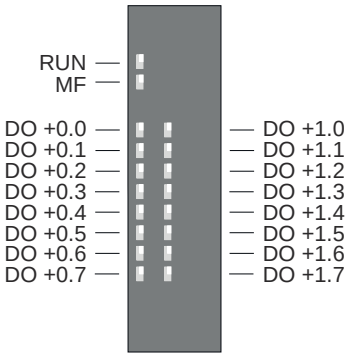
- 16 digital outputs isolated to the backplane bus
- Diagnostic function
- Status indication of the channels via LEDs

Structure



1 Locking lever module
2 Backplane bus
3 LED status indication
4 DC 24V power section supply
5 Electronic unit
6 Locking lever terminal block
7 Terminal block

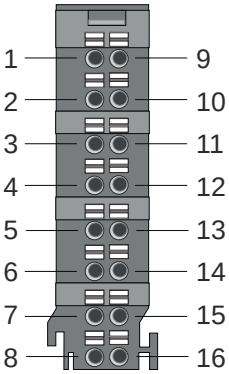
Status indication

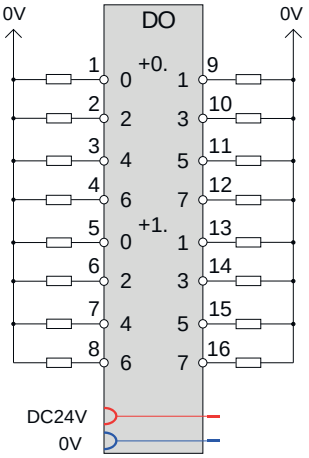


RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Blinking: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital output is controlled with "1" signal
■	□	□	Digital output is controlled with "0" signal
not relevant: X			

Pin assignment

For wires with a core cross-section of 0.14mm² up to 0.75mm². With a core cross-section < 0.25mm², ferrules must be used. *'Data'...page 32*





Pos.	Function	Type	Description
1	DO +0.0	O	Digital output DO +0.0
2	DO +0.2	O	Digital output DO +0.2
3	DO +0.4	O	Digital output DO +0.4
4	DO +0.6	O	Digital output DO +0.6
5	DO +1.0	O	Digital output DO +1.0
6	DO +1.2	O	Digital output DO +1.2
7	DO +1.4	O	Digital output DO +1.4
8	DO +1.6	O	Digital output DO +1.6
9	DO +0.1	O	Digital output DO +0.1
10	DO +0.3	O	Digital output DO +0.3
11	DO +0.5	O	Digital output DO +0.5
12	DO +0.7	O	Digital output DO +0.7
13	DO +1.1	O	Digital output DO +1.1
14	DO +1.3	O	Digital output DO +1.3
15	DO +1.5	O	Digital output DO +1.5
16	DO +1.7	O	Digital output DO +1.7

O: Output

CAUTION

Feeding in voltage at an output is not allowed and can destroy the module!

Input area

No byte of the input area is used by the module.

Output area

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

Addr.	Name	Byte	Function	IX	SX[1]
+0	PIQ	1	Status of the outputs	6200h	
			Bit 0: DO +0.0		01h
			Bit 1: DO +0.1		02h
			Bit 2: DO +0.2		03h
			Bit 3: DO +0.3		04h
			Bit 4: DO +0.4		05h
			Bit 4: DO +0.5		06h
			Bit 4: DO +0.6		07h
			Bit 4: DO +0.7		08h
		1	Status of the outputs	6201h	
			Bit 0: DO +1.0		09h
			Bit 1: DO +1.1		0Ah
			Bit 2: DO +1.2		0Bh
			Bit 3: DO +1.3		0Ch
			Bit 4: DO +1.4		0Dh
			Bit 4: DO +1.5		0Eh
			Bit 4: DO +1.6		0Fh
			Bit 4: DO +1.7		10h

1) Can be displayed as 16 channels with the names DO0 to DO15.

4.11.1 Technical data

Order no.	022-1BH00
Type	SM 022 - Digital output
Module ID	0124 2F50
Current consumption/power loss	
Current consumption from backplane bus	35 mA
Power loss	1 W
Technical data digital outputs	
Number of outputs	16
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	20 mA
Total current per group, horizontal configuration, 40°C	8 A
Total current per group, horizontal configuration, 60°C	8 A
Total current per group, vertical configuration	8 A

Order no.	022-1BH00
Output current at signal "1", rated value	0.5 A
Signal logic output	Sourcing output
Output delay of "0" to "1"	30 µs
Output delay of "1" to "0"	175 µs
Minimum load current	-
Lamp load	10 W
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	✓
Switching frequency with resistive load	max. 1000 Hz
Switching frequency with inductive load	max. 0.5 Hz
Switching frequency on lamp load	max. 10 Hz
Internal limitation of inductive shut-off voltage	L+ (-45 V)
Short-circuit protection of output	yes, electronic
Trigger level	1 A
Number of operating cycle of relay outputs	-
Switching capacity of contacts	-
Output data size	16 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	yes, parameterizable
Process alarm	no
Diagnostic interrupt	yes, parameterizable
Diagnostic functions	yes, parameterizable
Diagnostics information read-out	none
Supply voltage display	green LED
Group error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
PWM data	
PWM channels	-
PWM time basis	-
Period length	-
Minimum pulse width	-

Order no.	022-1BH00
Type of output	-
Datasizes	
Input bytes	0
Output bytes	2
Parameter bytes	1
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	60 g
Weight including accessories	60 g
Gross weight	80 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

4.11.2 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET
IX - Index for access via CANopen
SX - Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot
More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
DIAG_EN	1	Diagnostic interrupt[1]	00h	00h	3100h	01h

1) This record set may only be transferred at STOP state.

DIAG_EN Diagnostic interrupt

Byte	Bit 7 ... 0
0	Diagnostic interrupt 00h: disable 40h: enable

- Here you activate respectively de-activate the diagnostic function.

4.11.3 Diagnostic data

Via the parametrization you may activate a diagnostic interrupt for the module. With a diagnostic interrupt the module serves for diagnostic data for diagnostic$_{incoming}$. As soon as the reason for releasing a diagnostic interrupt is no longer present, the diagnostic interrupt$_{going}$ automatically takes place.

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

IX - Index for access via CANopen. The access happens by IX 2F01h. Additionally the first 4 bytes may be accessed by IX 2F00h.

SX - Subindex for access via EtherCAT with Index 5005h.

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
ERR_A	1	Diagnostic	00h	01h	2F01h	02h
MODTYP	1	Module information	1Fh			03h
ERR_C	1	reserved	00h			04h
ERR_D	1	reserved	00h			05h
CHTYP	1	Channel type	72h			06h
NUMBIT	1	reserved	00h			07h
NUMCH	1	reserved	00h			08h
CHERR	1	reserved	00h			09h
CH0ERR	1	reserved	00h			0Ah
CH1ERR	1	reserved	00h			0Bh
...	...	...	...			...
CH7ERR	1	reserved	00h			11h
DIAG_US	4	µs ticker (32bit)	00h			13h

ERR_A Diagnostic

Byte	Bit 7 ... 0
0	Bit 0: set at module failure Bit 1: set at internal error Bit 2: set at external error Bit 3: reserved Bit 4: set at overload at an output Bit 6 ... 5: reserved Bit 7: set at error in parameterization

MODTYP Module information

Byte	Bit 7 ... 0
0	Bit 3 ... 0: module class 1111b: Digital module Bit 7 ... 4: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	Bit 6 ... 0: channel type 72h: Digital output Bit 7: reserved

DIAG_US µs ticker

Byte	Bit 7 ... 0
0...3	Value of the µs ticker at the moment of the diagnostic

µs ticker

In the System SLIO module there is a timer (µs ticker). With PowerON the timer starts counting with 0. After 2^{32}-1µs the timer starts with 0 again.

ERR_C/D, NUMBIT, NUMCH, CHERR, CHxERR reserved

Byte	Bit 7 ... 0
0	reserved

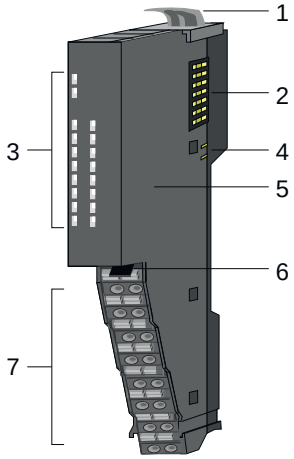
4.12 022-1BH50 - DO 16xDC 24V 0.5A NPN

Properties

The module detects the binary control signals from the higher-level bus system and transports them to the process level via the outputs. It has 16 channels connected to the power supply, which operate as low-side switch and their status is monitored via LEDs. Low-side switches are suited to switch grounds. With a short circuit between switch line and ground the load is activated but the power supply is not influenced.

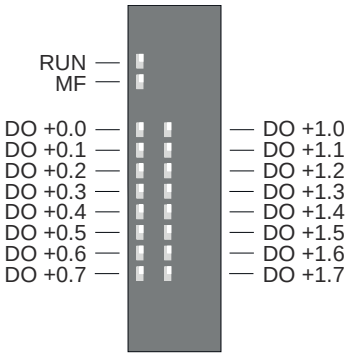
- 16 digital low-side outputs isolated to the backplane bus
- Diagnostic function
- Status indication of the channels via LEDs

Structure



1 Locking lever module
2 Backplane bus
3 LED status indication
4 DC 24V power section supply
5 Electronic unit
6 Locking lever terminal block
7 Terminal block

Status indication

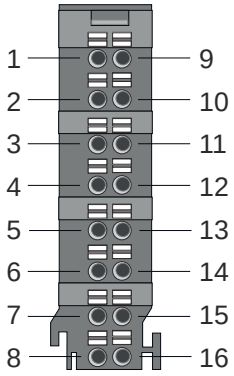


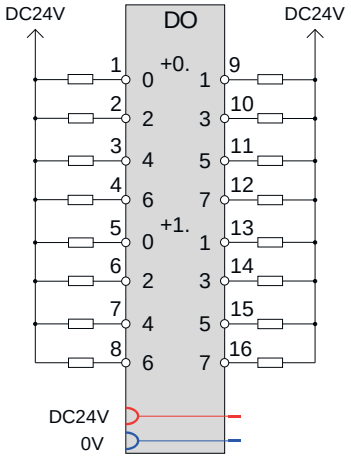
RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Blinking: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital output is controlled with "1" signal
■	□	□	Digital output is controlled with "0" signal
not relevant: X			

022-1BH50 - DO 16xDC 24V 0.5A NPN

Pin assignment

For wires with a core cross-section of 0.14mm² up to 0.75mm². With a core cross-section < 0.25mm², ferrules must be used. *'Data'...page 32*





Pos.	Function	Type	Description
1	DO +0.0	O	Digital output DO +0.0
2	DO +0.2	O	Digital output DO +0.2
3	DO +0.4	O	Digital output DO +0.4
4	DO +0.6	O	Digital output DO +0.6
5	DO +1.0	O	Digital output DO +1.0
6	DO +1.2	O	Digital output DO +1.2
7	DO +1.4	O	Digital output DO +1.4
8	DO +1.6	O	Digital output DO +1.6
9	DO +0.1	O	Digital output DO +0.1
10	DO +0.3	O	Digital output DO +0.3
11	DO +0.5	O	Digital output DO +0.5
12	DO +0.7	O	Digital output DO +0.7
13	DO +1.1	O	Digital output DO +1.1
14	DO +1.3	O	Digital output DO +1.3
15	DO +1.5	O	Digital output DO +1.5
16	DO +1.7	O	Digital output DO +1.7

O: Output

CAUTION

Feeding in voltage at an output is not allowed and can destroy the module!

Due to the system, you will receive a diagnostic message when switching the DC 24V power supply on or off on the module.

Input area

No byte of the input area is used by the module.

Output area

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

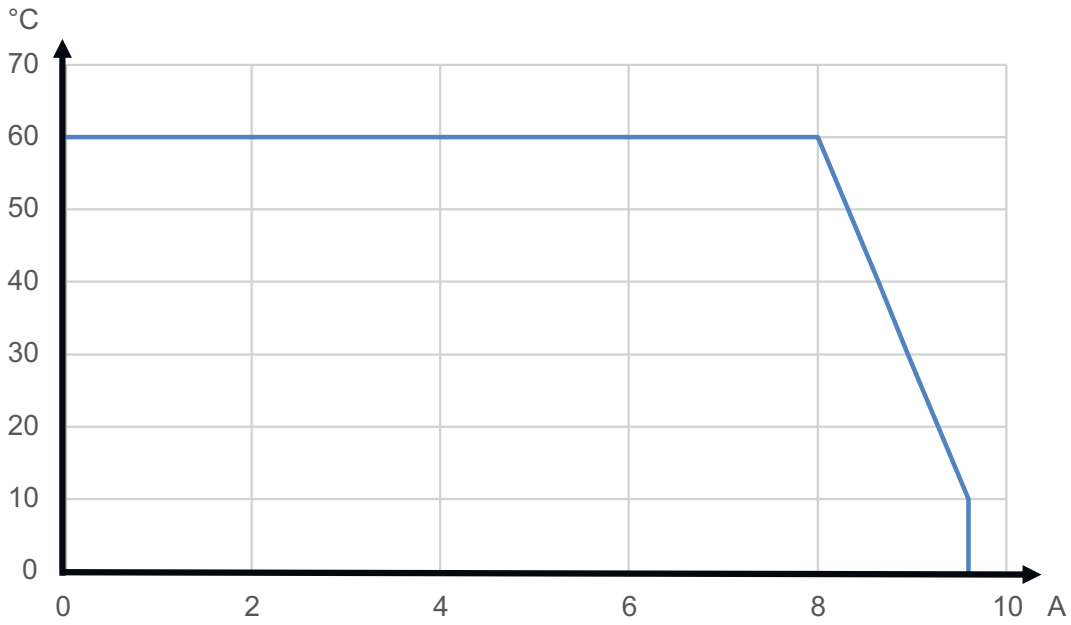
SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

Addr.	Name	Byte	Function	IX	SX[1]
+0	PIQ	1	Status of the outputs	6200h	
			Bit 0: DO +0.0		01h
			Bit 1: DO +0.1		02h
			Bit 2: DO +0.2		03h
			Bit 3: DO +0.3		04h
			Bit 4: DO +0.4		05h
			Bit 4: DO +0.5		06h
			Bit 4: DO +0.6		07h
			Bit 4: DO +0.7		08h
		1	Status of the outputs	6201h	
			Bit 0: DO +1.0		09h
			Bit 1: DO +1.1		0Ah
			Bit 2: DO +1.2		0Bh
			Bit 3: DO +1.3		0Ch
			Bit 4: DO +1.4		0Dh
			Bit 4: DO +1.5		0Eh
			Bit 4: DO +1.6		0Fh
			Bit 4: DO +1.7		10h

1) Can be displayed as 16 channels with the names DO0 to DO15.

Derating

Please note the following derating for the total current at the corresponding ambient temperature:



4.12.1 Technical data

Order no.	022-1BH50
Type	SM 022 - Digital output
Module ID	0126 2F50
Current consumption/power loss	
Current consumption from backplane bus	60 mA
Power loss	1.3 W
Technical data digital outputs	
Number of outputs	16
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	11 mA
Total current per group, horizontal configuration, 40°C	8 A
Total current per group, horizontal configuration, 60°C	8 A
Total current per group, vertical configuration	8 A
Output current at signal "1", rated value	0.5 A
Signal logic output	Sinking output
Output delay of "0" to "1"	30 µs
Output delay of "1" to "0"	175 µs
Minimum load current	-
Lamp load	10 W

Order no.	022-1BH50
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	✓
Switching frequency with resistive load	max. 1000 Hz
Switching frequency with inductive load	max. 0.5 Hz
Switching frequency on lamp load	max. 10 Hz
Internal limitation of inductive shut-off voltage	+49 V
Short-circuit protection of output	yes, electronic
Trigger level	0.7 A
Number of operating cycle of relay outputs	-
Switching capacity of contacts	-
Output data size	16 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	yes, parameterizable
Process alarm	no
Diagnostic interrupt	yes, parameterizable
Diagnostic functions	yes, parameterizable
Diagnostics information read-out	possible
Supply voltage display	green LED
Group error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
PWM data	
PWM channels	-
PWM time basis	-
Period length	-
Minimum pulse width	-
Type of output	-
Datasizes	
Input bytes	0
Output bytes	2
Parameter bytes	1
Diagnostic bytes	20

Order no.	022-1BH50
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	58 g
Weight including accessories	58 g
Gross weight	79 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes (DC general use)
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

4.12.2 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
DIAG_EN	1	Diagnostic interrupt[1]	00h	00h	3100h	01h

1) This record set may only be transferred at STOP state.

DIAG_EN Diagnostic interrupt

Byte	Bit 7 ... 0
0	Diagnostic interrupt 00h: disable 40h: enable

- Here you activate respectively de-activate the diagnostic function.

4.12.3 Diagnostic data

Via the parametrization you may activate a diagnostic interrupt for the module. With a diagnostic interrupt the module serves for diagnostic data for diagnostic$_{incoming}$. As soon as the reason for releasing a diagnostic interrupt is no longer present, the diagnostic interrupt$_{going}$ automatically takes place.

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

IX - Index for access via CANopen. The access happens by IX 2F01h. Additionally the first 4 bytes may be accessed by IX 2F00h.

SX - Subindex for access via EtherCAT with Index 5005h.

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
ERR_A	1	Diagnostic	00h	01h	2F01h	02h
MODTYP	1	Module information	1Fh			03h
ERR_C	1	reserved	00h			04h
ERR_D	1	reserved	00h			05h
CHTYP	1	Channel type	72h			06h
NUMBIT	1	reserved	00h			07h
NUMCH	1	reserved	00h			08h
CHERR	1	reserved	00h			09h
CH0ERR	1	reserved	00h			0Ah
CH1ERR	1	reserved	00h			0Bh
...	...	...	...			...
CH7ERR	1	reserved	00h			11h
DIAG_US	4	µs ticker (32bit)	00h			13h

ERR_A Diagnostic

Byte	Bit 7 ... 0
0	Bit 0: set at module failure Bit 1: set at internal error Bit 2: set at external error Bit 3: reserved Bit 4: set at overload at an output Bit 6 ... 5: reserved Bit 7: set at error in parameterization

MODTYP Module information

Byte	Bit 7 ... 0
0	Bit 3 ... 0: module class 1111b: Digital module Bit 7 ... 4: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	Bit 6 ... 0: channel type 72h: Digital output Bit 7: reserved

DIAG_US µs ticker

Byte	Bit 7 ... 0
0...3	Value of the µs ticker at the moment of the diagnostic

µs ticker

In the System SLIO module there is a timer (µs ticker). With PowerON the timer starts counting with 0. After 2^{32}-1µs the timer starts with 0 again.

ERR_C/D, NUMBIT, NUMCH, CHERR, CHxERR reserved

Byte	Bit 7 ... 0
0	reserved

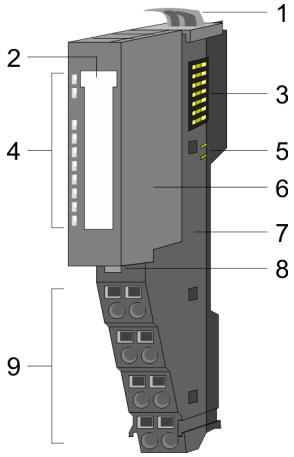
4.13 022-1DF00 - DO 8xDC 24V 0.5A Diagnosis

Properties

The electronic module with diagnosis accepts binary control signals from the central bus system and transfers them to the process level via outputs. It has 8 channels and their status is monitored via LEDs.

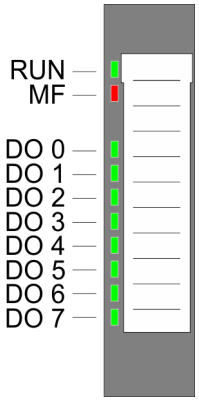
- 8 digital outputs, isolated to the backplane bus
- Monitoring wire-break and short-circuit
- Diagnostics function
- Status indication of the channels via LEDs

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

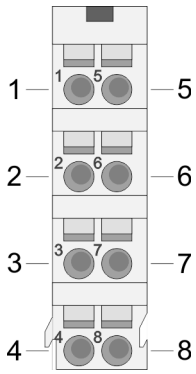
Status indication

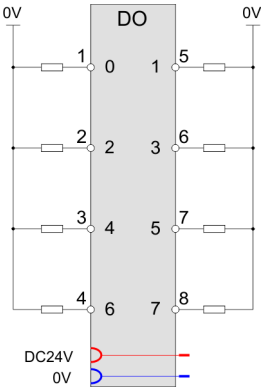


RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with wire-break and short-circuit
□	■	X	Bus communication is not possible Module status reports an error with wire-break and short-circuit
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Digital output has "1" signal
■	□	□	Digital output has "0" signal
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DO 0	O	Digital output DO 0
2	DO 2	O	Digital output DO 2
3	DO 4	O	Digital output DO 4
4	DO 6	O	Digital output DO 6
5	DO 1	O	Digital output DO 1
6	DO 3	O	Digital output DO 3
7	DO 5	O	Digital output DO 5
8	DO 7	O	Digital output DO 7

O: Output

CAUTION

Feeding in voltage at an output is not allowed and can destroy the module!

Please note that, due to the system, a diagnostic interrupt is triggered at PowerON and when the diagnostic interrupt is enabled or each time the diagnostic interrupt is enabled by means of parameter DIAG_EN.

Input area

No byte of the input area is used by the module.

Output area

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PIQ	1	State of the outputs	6200h	
			Bit 0: DO 0		01h
			Bit 1: DO 1		02h
			Bit 2: DO 2		03h
			Bit 3: DO 3		04h
			Bit 4: DO 4		05h
			Bit 5: DO 5		06h
			Bit 6: DO 6		07h
			Bit 7: DO 7		08h

4.13.1 Technical data

Order no.	022-1DF00
Type	SM 022 - Digital output
Module ID	0113 2F48
Current consumption/power loss	
Current consumption from backplane bus	70 mA
Power loss	1 W
Technical data digital outputs	
Number of outputs	8
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 24 V
Permitted range	DC 20.4...28.8 V
Current consumption from power section supply (without load)	11 mA
Total current per group, horizontal configuration, 40°C	4 A
Total current per group, horizontal configuration, 60°C	4 A
Total current per group, vertical configuration	4 A
Output current at signal "1", rated value	0.5 A
Signal logic output	Sourcing output
Output delay of "0" to "1"	max. 350 µs
Output delay of "1" to "0"	max. 350 µs
Minimum load current	-
Lamp load	10 W
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	✓
Switching frequency with resistive load	max. 1000 Hz

Order no.	022-1DF00
Switching frequency with inductive load	max. 0.5 Hz
Switching frequency on lamp load	max. 10 Hz
Internal limitation of inductive shut-off voltage	L+ (-52 V)
Short-circuit protection of output	yes, electronic
Trigger level	1 A
Number of operating cycle of relay outputs	-
Switching capacity of contacts	-
Output data size	8 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	yes, parameterizable
Process alarm	no
Diagnostic interrupt	yes, parameterizable
Diagnostic functions	yes
Diagnostics information read-out	possible
Supply voltage display	green LED
Group error display	red LED
Channel error display	none
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	DC 500 V
PWM data	
PWM channels	-
PWM time basis	-
Period length	-
Minimum pulse width	-
Type of output	-
Datasizes	
Input bytes	0
Output bytes	1
Parameter bytes	7
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	

Order no.	022-1DF00
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	57 g
Weight including accessories	57 g
Gross weight	71 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

4.13.2 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET
IX - Index for access via CANopen
SX - Subindex for access via EtherCAT with Index 3100h + EtherCAT-Slot
More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
DIAG_EN	1	Diagnostics[1]	00h	00h	3100h	01h
WIBRK_EN	1	Wire-break recognition[1]	00h	00h	3101h	02h
CH0D_EN	1	Short-circuit recognition[1]	00h	00h	3102h	03h

1) This record set may only be transferred at STOP state.

DIAG_EN Diagnostic interrupt

Byte	Bit 7 ... 0
0	Diagnostic interrupt 00h: disable 40h: enable

- Here you activate res. de-activate the diagnostic function.

WIBRK_EN Wire-break recognition

Byte	Bit 7 ... 0
0	Bit 0: Wire-break recognition channel 0 (1: on) Bit 1: Wire-break recognition channel 1 (1: on) ... Bit 7: Wire-break recognition channel 7 (1: on)

- Here you activate res. de-activate the Wire-break recognition.

CH0D_EN Short-circuit recognition

Byte	Bit 7 ... 0
0	Bit 0: Short-circuit recognition channel 0 (1: on) Bit 1: Short-circuit recognition channel 1 (1: on) ... Bit 7: Short-circuit recognition channel 7 (1: on)

- Here you activate res. de-activate the Short-circuit recognition.

4.13.3 Diagnostic data

The following errors are listed in the diagnostics data:

- Error in project engineering / parameterization
- Wire-break
- Short-circuit
- Error external auxiliary supply

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

IX - Index for access via CANopen. The access happens by IX 2F01h. Additionally the first 4 bytes may be accessed by IX 2F00h.

SX - Subindex for access via EtherCAT with Index 5005h.

More can be found in the according manual of your bus coupler.

Name	Bytes	Function	Default	DS	IX	SX
ERR_A	1	Diagnostic	00h	01h	2F01h	02h
MODTYP	1	Module information	1Fh			03h
RES2	1	reserved	00h			04h
ERR_D	1	Diagnostic	00h			05h
CHTYP	1	Channel type	72h			06h
NUMBIT	1	Number diagnostic bits per channel	08h			07h
NUMCH	1	Number of channels of a module	08h			08h
CHERR	1	Channel error	00h			09h
CH0ERR	1	Channel-specific error channel 0	00h			0Ah
CH1ERR	1	Channel-specific error channel 1	00h			0Bh
...	...	...	...			...
CH7ERR	1	Channel-specific error channel 7	00h			11h
DIAG_US	4	µs ticker (32bit)	00h			13h

ERR_A Diagnostic

Byte	Bit 7 ... 0
0	Bit 0: set at module failure Bit 1: set at internal error Bit 2: set at external error Bit 3: set at channel error Bit 4: set at external auxiliary supply missing Bit 5, 6: reserved Bit 7: set at error in parameterization

MODTYP Module information

Byte	Bit 7 ... 0
0	Bit 3 ... 0: module class 1111b: Digital module Bit 4: set at channel information present Bit 7 ... 5: reserved

ERR_D Diagnostic

Byte	Bit 7 ... 0
0	Bit 3 ... 0: reserved Bit 4: set at internal communication error Bit 7 ... 5: reserved

CHTYP Channel type

Byte	Bit 7 ... 0
0	Bit 6 ... 0: channel type 72h: Digital output Bit 7: reserved

NUMBIT Diagnostic bits

Byte	Bit 7 ... 0
0	Number of diagnostic bits per channel (here 08h)

NUMCH Channels

Byte	Bit 7 ... 0
0	Number of channels of a module (here 08h)

CHERR Channel error

Byte	Bit 7 ... 0
0	Bit 0: set at error in channel 0 Bit 1: set at error in channel 1 ... Bit 7: set at error in channel 7

CH0ERR ... CH7ERR Channel specific

Byte	Bit 7 ... 0
0	Channel-specific error channel x: Bit 0: set at configuring- / parameter assignment error Bit 1: reserved Bit 2: short-circuit to +DC 24V Bit 3: short-circuit to M Bit 4: set at wire-break Bit 7 ... 5: reserved

DIAG_US µs ticker

Byte	Bit 7 ... 0
0...3	Value of the µs ticker at the moment of the diagnostic

µs ticker

In the System SLIO module there is a timer (µs ticker). With PowerON the timer starts counting with 0. After 2^{32}-1µs the timer starts with 0 again.

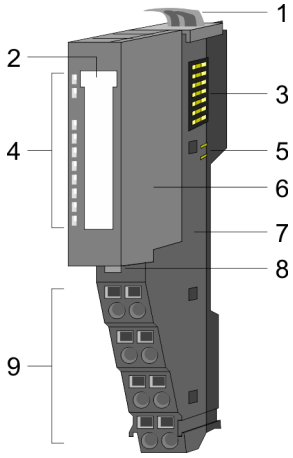
4.14 022-1HB10 - DO 2xRelay

Properties

The electronic module accepts binary control signals from the central bus system and transfers them to the process level via relay outputs. It has 2 channels that operate as switches and the status of each channel is monitored via LEDs.

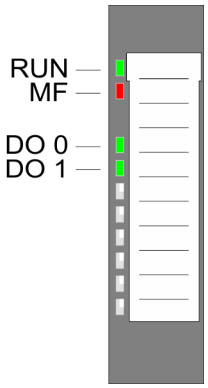
- 2 relay outputs, isolated to the backplane bus
- DC 30V / AC 230V, 3A
- Status indication of the channels via LEDs

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

Status indication



RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Relay output has "1" signal
■	□	□	Relay output has "0" signal
not relevant: X			

DANGER

The mixed operation of touch and non touch voltages is not permitted!

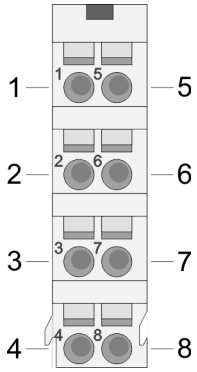
With HW state 04, an interference suppression capacitor (15nF) has been connected parallel to each relay contact in order to improve the EMC resistance.

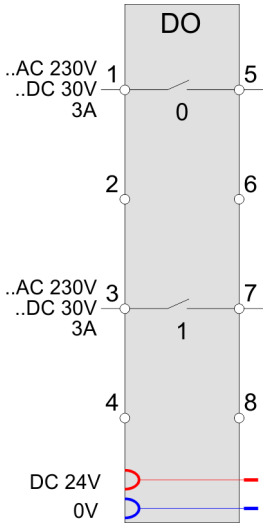
Please note!

- *When using inductive loads, use a suitable protective circuit (see installation guidelines).*
- *When using loads with a high inrush current, such as electronic ballasts, use a suitable current limiter.*

Pin assignment

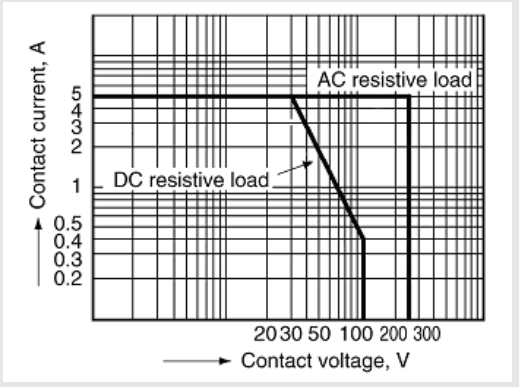
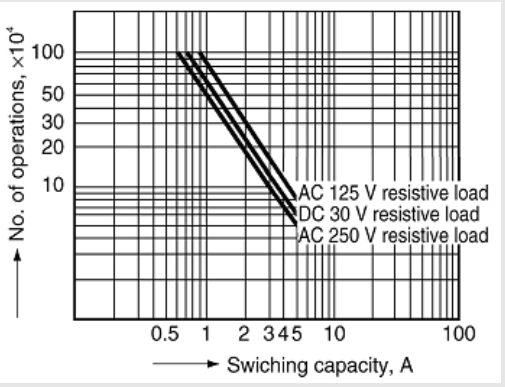
For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DO 0	O	Relay output DO 0
2	—	—	not connected
3	DO 1	O	Relay output DO 1
4	—	—	not connected
5	DO 0	O	Relay output DO 0
6	—	—	not connected
7	DO 1	O	Relay output DO 1
8	—	—	not connected

O: Output

Maximum load	Service life
	

Input area

No byte of the input area is used by the module.

Output area

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area. More can be found in the corresponding manual.

IX - Index for access via CANopen

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	IX	SX
+0	PIQ	1	State of the outputs	5200h	
			Bit 0: DO 0		01h
			Bit 1: DO 1		02h
			Bit 7 ... 2: reserved		

4.14.1 Technical data

Order no.	022-1HB10
Type	SM 022 - Digital output
Module ID	0109 AF90
Current consumption/power loss	
Current consumption from backplane bus	120 mA
Power loss	0.7 W
Technical data digital outputs	
Number of outputs	2
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 30 V/ AC 230 V
Permitted range	-
Current consumption from power section supply (without load)	-
Total current per group, horizontal configuration, 40°C	3 A

Order no.	022-1HB10
Total current per group, horizontal configuration, 60°C	3 A
Total current per group, vertical configuration	3 A
Output current at signal "1", rated value	3 A
Signal logic output	Isolated
Output delay of "0" to "1"	10 ms
Output delay of "1" to "0"	5 ms
Minimum load current	-
Lamp load	-
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	-
Switching frequency with resistive load	max. 0.33 Hz
Switching frequency with inductive load	max. 0.33 Hz
Switching frequency on lamp load	max. 0.33 Hz
Internal limitation of inductive shut-off voltage	-
Short-circuit protection of output	-
Trigger level	-
Number of operating cycle of relay outputs	-
Switching capacity of contacts	3 A
Output data size	2 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	no
Diagnostics information read-out	none
Supply voltage display	green LED
Group error display	red LED
Channel error display	none
Isolation	
Between channels	✓
Between channels of groups to	-
Between channels and backplane bus	✓
Insulation tested with	AC 2200 V
PWM data	
PWM channels	-
PWM time basis	-

Order no.	022-1HB10
Period length	-
Minimum pulse width	-
Type of output	-
Datasizes	
Input bytes	0
Output bytes	1
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	62 g
Weight including accessories	62 g
Gross weight	76 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

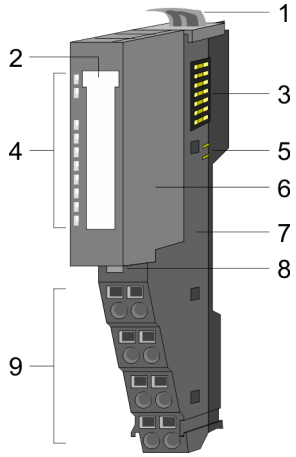
4.15 022-1HD10 - DO 4xRelay

Properties

The electronic module accepts binary control signals from the central bus system and transfers them to the process level via relay outputs. It has 4 channels that operate as switches and the status of each channel is monitored via LEDs.

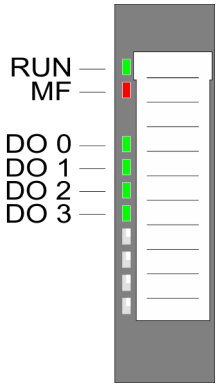
- 4 relay outputs
  - in groups of two, each with a common terminal
  - isolated between channels and backplane bus
  - isolated between channels of groups
- DC 30V / AC 230V, 1.8 A
- Status indication of the channels via LEDs

Structure



1 Locking lever terminal module
2 Labeling strip
3 Backplane bus
4 LED status indication
5 DC 24V power section supply
6 Electronic module
7 Terminal module
8 Locking lever electronic module
9 Terminal

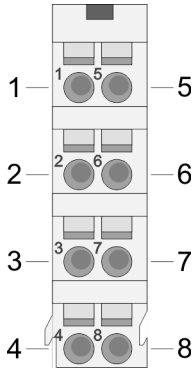
Status indication

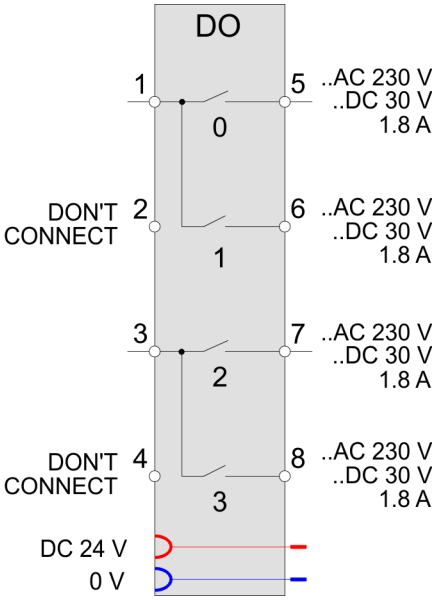


RUN green	MF red	DO x green	Description
■	□	X	Bus communication is OK Module status is OK
■	■	X	Bus communication is OK Module status reports an error with overload, short circuit or overheat
□	■	X	Bus communication is not possible Module status reports an error with overload, short circuit or overheat
□	□	X	Error at bus power supply
X	◪	X	Flashing: Error in configuration *'Trouble shooting - LEDs'...page 43*
■	□	■	Relay output has "1" signal
■	□	□	Relay output has "0" signal
not relevant: X			

Pin assignment

For wires with a cross section of 0.08mm² up to 1.5mm².





Pos.	Function	Type	Description
1	DO 0/1	O	Relay output DO 0 and DO 1
2	—	—	must not be connected
3	DO 2/3	O	Relay output DO 2 and DO 3
4	—	—	must not be connected
5	DO 0	O	Relay output DO 0
6	DO 1	O	Relay output DO 1
7	DO 2	O	Relay output DO 2
8	DO 3	O	Relay output DO 3

O: Output

DANGER

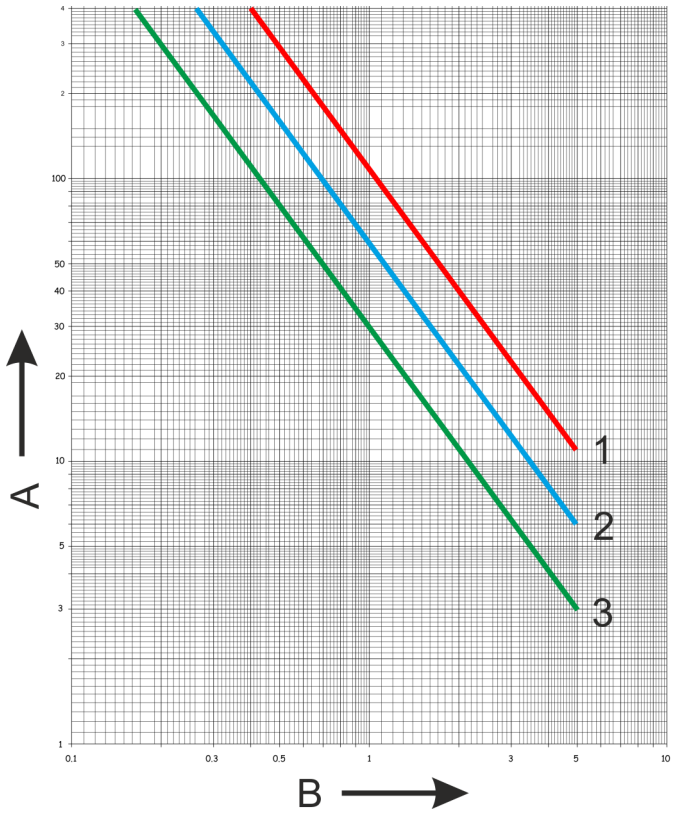
- Due to the hardware the pins 2 and 4 must not be connected!
- The mixed operation of touch and non touch voltages is not permitted!

With HW state 03, an interference suppression capacitor (15nF) has been connected parallel to each relay contact in order to improve the EMC resistance.

Please note!

- *When using inductive loads, use a suitable protective circuit (see installation guidelines).*
- *When using loads with a high inrush current, such as electronic ballasts, use a suitable current limiter.*

Maximum load / Service life (typical)



A Operating cycles (x 10^4)
B Current in A
1 DC 30V resistive load
2 AC 250V resistive load, DC 30V L/R = 7ms
3 AC 250V cosφ = 0.4

Input area

No byte of the input area is used by the module.

Output area

At CPU, PROFIBUS and PROFINET the output area is embedded to the corresponding address area.

IX - Index for access via CANopen with s = Subindex, depends on number and type of analog modules

SX - Subindex for access via EtherCAT with Index 7000h + EtherCAT-Slot

More can be found in the according manual of your bus coupler.

Addr.	Name	Bytes	Function	IX	SX
+0	PIQ	1	State of the outputs	5200h	
			Bit 0: DO 0		01h
			Bit 1: DO 1		02h
			Bit 2: DO 2		03h
			Bit 3: DO 3		04h
			Bit 7 ... 4: reserved		

4.15.1 Technical data

Order no.	022-1HD10
Type	SM 022 - Digital output
Module ID	010A AFA0
Current consumption/power loss	
Current consumption from backplane bus	120 mA
Power loss	0.7 W
Technical data digital outputs	
Number of outputs	4
Cable length, shielded	1000 m
Cable length, unshielded	600 m
Rated load voltage	DC 30 V/ AC 230 V
Permitted range	-
Current consumption from power section supply (without load)	-
Total current per group, horizontal configuration, 40°C	3.6 A
Total current per group, horizontal configuration, 60°C	3 A
Total current per group, vertical configuration	3.6 A
Output current at signal "1", rated value	1.8 A
Signal logic output	Isolated
Output delay of "0" to "1"	10 ms
Output delay of "1" to "0"	5 ms
Minimum load current	-
Lamp load	-
Parallel switching of outputs for redundant control of a load	not possible
Parallel switching of outputs for increased power	not possible
Actuation of digital input	-
Switching frequency with resistive load	max. 0.33 Hz
Switching frequency with inductive load	max. 0.33 Hz
Switching frequency on lamp load	max. 0.33 Hz
Internal limitation of inductive shut-off voltage	-
Short-circuit protection of output	-
Trigger level	-
Number of operating cycle of relay outputs	-
Switching capacity of contacts	5 A
Output data size	4 Bit
Status information, alarms, diagnostics	
Status display	green LED per channel
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	no
Diagnostics information read-out	none
Supply voltage display	green LED
Group error display	red LED
Channel error display	none

Order no.	022-1HD10
Isolation	
Between channels	-
Between channels of groups to	2
Between channels and backplane bus	✓
Insulation tested with	AC 2200 V
PWM data	
PWM channels	-
PWM time basis	-
Period length	-
Minimum pulse width	-
Type of output	-
Datasizes	
Input bytes	0
Output bytes	1
Parameter bytes	0
Diagnostic bytes	0
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	12.9 mm x 109 mm x 76.5 mm
Net weight	69 g
Weight including accessories	69 g
Gross weight	83 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	yes
KC certification	yes
UKCA certification	yes
ChinaRoHS certification	yes

5 Virtual modules

Virtual modules

Virtual modules are listed in the hardware catalog in the *'VM'* category. For compatibility reasons respectively for internal purposes, depending on the head module, you will find further virtual modules with associated function description there.

5.1 Virtual clock module - 090-0VT00

090-0VT00
Module ID: 0x78DF1143

The virtual clock module returns the current value of the µs ticker as a 32-bit value. This value is used to match process data, which contain a timestamp, such as ETS modules.

- In the hardware configuration, the virtual clock module must always be configured after the real modules.
- The virtual clock module occupies 4 bytes in the input address range and returns the current value of the µs ticker via this.
- The virtual clock module has parameters that are only shown and cannot be changed.

Input area

At PROFIBUS and PROFINET the input area is embedded to the corresponding address area. More can be found in the corresponding manual.

SX - Subindex for access via EtherCAT with index 6000h + EtherCAT-Slot

Addr.	Name	Bytes	Function	SX
+0	V_US	4	µs ticker	01h

Please note that when using EtherCAT, the 'Download Slot Configuration' option must be enabled on the EtherCAT SubDevice. Otherwise, the virtual clock module is not applied to the configuration.

Output area

No byte of the output area is used by the virtual clock module.

Diagnostic data

The virtual clock module has no diagnostic data.