

System 300S⁺

CPU | 317-4NE23 | Manual

HB140 | CPU | 317-4NE23 | en | 18-02

SPEED7 CPU 317SN



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1 General

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1.2 About this manual

Objective and contents

This manual describes the SPEED7 CPU 317-4NE23 of the CPU from Yaskawa. It contains a description of the construction, project implementation and usage.

| Product | Order no. | as of state: | | | |
|---------|-----------|--------------|--------|--------|--------|
| | | CPU-HW | CPU-FW | DPM-FW | CP-FW |
| 317SN | 317-4NE23 | 01 | V3.7.3 | V3.3.5 | V3.1.1 |

Target audience

The manual is targeted at users who have a background in automation technology.

Structure of the manual

The manual consists of chapters. Every chapter provides a self-contained description of a specific topic.

Guide to the document

The following guides are available in the manual:

- An overall table of contents at the beginning of the manual
- References with page numbers

Availability

The manual is available in:

- printed form, on paper
- in electronic form as PDF-file (Adobe Acrobat Reader)

Icons Headings

Important passages in the text are highlighted by following icons and headings:

**DANGER!**

Immediate or likely danger. Personal injury is possible.

**CAUTION!**

Damages to property is likely if these warnings are not heeded.



Supplementary information and useful tips.

1.3 Safety information

Applications conforming with specifications

The system is constructed and produced for:

- communication and process control
- general control and automation tasks
- industrial applications
- operation within the environmental conditions specified in the technical data
- installation into a cubicle



DANGER!

This device is not certified for applications in

- in explosive environments (EX-zone)

Documentation

The manual must be available to all personnel in the

- project design department
- installation department
- commissioning
- operation



CAUTION!

The following conditions must be met before using or commissioning the components described in this manual:

- Hardware modifications to the process control system should only be carried out when the system has been disconnected from power!
- Installation and hardware modifications only by properly trained personnel.
- The national rules and regulations of the respective country must be satisfied (installation, safety, EMC ...)

Disposal

National rules and regulations apply to the disposal of the unit!

2 Basics

2.1 Safety information for users

Handling of electrostatic sensitive modules

The modules make use of highly integrated components in MOS-Technology. These components are extremely sensitive to over-voltages that can occur during electrostatic discharges. The following symbol is attached to modules that can be destroyed by electrostatic discharges.



The Symbol is located on the module, the module rack or on packing material and it indicates the presence of electrostatic sensitive equipment. It is possible that electrostatic sensitive equipment is destroyed by energies and voltages that are far less than the human threshold of perception. These voltages can occur where persons do not discharge themselves before handling electrostatic sensitive modules and they can damage components thereby, causing the module to become inoperable or unusable. Modules that have been damaged by electrostatic discharges can fail after a temperature change, mechanical shock or changes in the electrical load. Only the consequent implementation of protection devices and meticulous attention to the applicable rules and regulations for handling the respective equipment can prevent failures of electrostatic sensitive modules.

Shipping of modules

Modules must be shipped in the original packing material.

Measurements and alterations on electrostatic sensitive modules

When you are conducting measurements on electrostatic sensitive modules you should take the following precautions:

- Floating instruments must be discharged before use.
- Instruments must be grounded.

Modifying electrostatic sensitive modules you should only use soldering irons with grounded tips.



CAUTION!

Personnel and instruments should be grounded when working on electrostatic sensitive modules.

2.2 Operating structure of a CPU

2.2.1 General

The CPU contains a standard processor with internal program memory. In combination with the integrated SPEED7 technology the unit provides a powerful solution for process automation applications within the System 300S family. A CPU supports the following modes of operation:

- cyclic operation
- timer processing
- alarm controlled operation
- priority based processing

Cyclic processing

Cyclic processing represents the major portion of all the processes that are executed in the CPU. Identical sequences of operations are repeated in a never-ending cycle.

Timer processing

Where a process requires control signals at constant intervals you can initiate certain operations based upon a **timer**, e.g. not critical monitoring functions at one-second intervals.

Alarm controlled processing

If a process signal requires a quick response you would allocate this signal to an **alarm controlled** procedure. An alarm can activate a procedure in your program.

Priority based processing

The above processes are handled by the CPU in accordance with their **priority**. Since a timer or an alarm event requires a quick reaction, the CPU will interrupt the cyclic processing when these high-priority events occur to react to the event. Cyclic processing will resume, once the reaction has been processed. This means that cyclic processing has the lowest priority.

2.2.2 Applications

The program that is present in every CPU is divided as follows:

- System routine
- User application

System routine

The system routine organizes all those functions and procedures of the CPU that are not related to a specific control application.

User application

This consists of all the functions that are required for the processing of a specific control application. The operating modules provide the interfaces to the system routines.

2.2.3 Operands

The following series of operands is available for programming the CPU:

- Process image and periphery
- Bit memory
- Timers and counters
- Data blocks

Process image and periphery

The user application can quickly access the process image of the inputs and outputs PIO/PII. You may manipulate the following types of data:

- individual Bits
- Bytes
- Words
- Double words

You may also gain direct access to peripheral modules via the bus from user application. The following types of data are available:

- Bytes
- Words
- Blocks

Bit Memory

The bit memory is an area of memory that is accessible by means of certain operations. Bit memory is intended to store frequently used working data.

You may access the following types of data:

- individual Bits
- Bytes
- Words
- Double words

Timers and counters

In your program you may load cells of the timer with a value between 10ms and 9990s. As soon as the user application executes a start-operation, the value of this timer is decremented by the interval that you have specified until it reaches zero.

You may load counter cells with an initial value (max. 999) and increment or decrement these when required.

Data Blocks

A data block contains constants or variables in the form of bytes, words or double words. You may always access the current data block by means of operands.

You may access the following types of data:

- individual Bits
- Bytes
- Words
- Double words

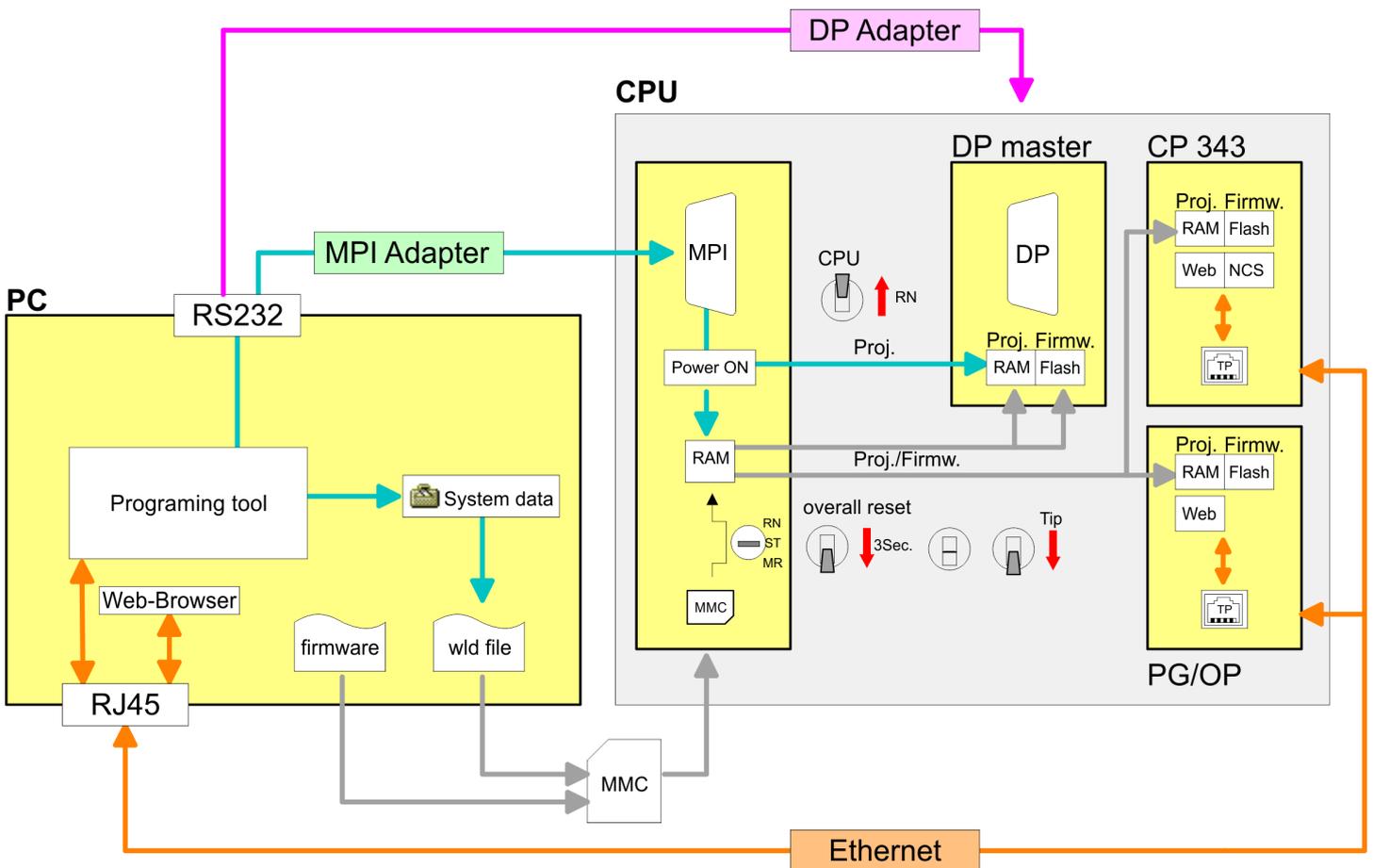
2.3 CPU 317-4NE23

Overview

The CPU 317-4NE23 bases upon the SPEED7 technology. This supports the CPU at programming and communication by means of co-processors that causes a power improvement for highest needs.

- The CPU is programmed in STEP®7 from Siemens. For this you may use the SIMATIC Manager or TIA Portal from Siemens. Here the instruction set of the S7-400 from Siemens is used.
- The CPU has a parallel SPEED-Bus that enables the additional connection of up to 10 modules from the SPEED-Bus periphery. While the standard peripheral modules are plugged at the right side of the CPU, the SPEED-Bus peripheral modules are connected via a SPEED-Bus bus connector at the left side of the CPU.
- Modules and CPUs of the System 300S from VIPA and Siemens may be used at the bus as a mixed configuration.
- The user application is stored in the battery buffered RAM or on an additionally pluggable MMC storage module.
- The CPU is configured as CPU 317-2DP (6ES7 317-2AK14 V3.3) from Siemens.

Access



Please always use the **CPU 317-2DP (6ES7 317-2AK14 V3.3)** from Siemens of the hardware catalog to configure this CPU from Yaskawa. For the project engineering, a thorough knowledge of the Siemens SIMATIC Manager and the hardware configurator from Siemens is required!

| | |
|---|--|
| Memory | <p>The CPU has an integrated memory. Information about the capacity of the memory may be found at the front of the CPU. The memory is divided into the following parts:</p> <ul style="list-style-type: none"> ■ Load memory 8Mbyte ■ Code memory (50% of the work memory) ■ Data memory (50% of the work memory) ■ Work memory 4Mbyte <ul style="list-style-type: none"> – There is the possibility to extend the work memory to its maximum printed capacity 8Mbyte by means of a memory extension card. |
| SPEED-Bus | <ul style="list-style-type: none"> ■ The SPEED-Bus is a 32bit parallel bus developed from VIPA. ■ Via the SPEED-Bus you may connect up to 10 SPEED-Bus modules to your CPU. ■ In opposite to the "standard" backplane bus where the modules are plugged-in at the right side of the CPU by means of single bus connectors, the modules at the SPEED-Bus are plugged-in at the left side of the CPU via a special SPEED-Bus rail. ■ VIPA delivers profile rails with integrated SPEED-Bus for 2, 6, or 10 SPEED-Bus peripheral modules with different lengths. ■ Each SPEED-Bus rail has a slot for an external power supply. This allows you to raise the maximum current at the back plane bus. Only the "SLOT1 DCDC" allows you to plug-in either a SPEED-Bus module or an additional power supply (307-1FB70). |
| Integrated PROFIBUS DP master/slave respectively PtP functionality | <p>The CPU has a PROFIBUS/PtP interface with a fix pinout. After an overall reset the interface is deactivated. By appropriate configuration, the following functions for this interface may be enabled:</p> <ul style="list-style-type: none"> ■ PROFIBUS DP master operation: Configuration via PROFIBUS sub module with 'Operation mode' master in the hardware configuration. ■ PROFIBUS DP slave operation: Configuration via PROFIBUS sub module with 'Operation mode' slave in the hardware configuration. ■ PtP functionality: Configuration as virtual PROFIBUS master system by including the Yaskawa SPEEDBUS.GSD. |
| Integrated CP 343 | <p>The integrated CP 343 offers you a communication processor. This serves PG/OP channels and by Siemens NetPro respectively by user program configurable productive connections.</p> |
| Integrated Ethernet PG/OP channel | <p>The CPU has an Ethernet interface for PG/OP communication. After assigning IP address parameters with your configuration tool, via the "PLC" functions you may directly access the Ethernet PG/OP channel and program res. remote control your CPU. You may also access the CPU with a visualization software via these connections.</p> |
| Operation Security | <ul style="list-style-type: none"> ■ Wiring by means of spring pressure connections (CageClamps) at the front connector ■ Core cross-section 0.08...2.5mm² ■ Total isolation of the wiring at module change ■ Potential separation of all modules to the backplane bus |
| Dimensions/ Weight | <p>Dimensions of the basic enclosure:</p> <ul style="list-style-type: none"> ■ 2tier width: (WxHxD) in mm: 80x125x120 |
| Integrated power supply | <p>The CPU comes with an integrated power supply. The power supply is to be supplied with DC 24V. By means of the supply voltage, the internal electronic is supplied as well as the connected modules via backplane bus. The power supply is protected against inverse polarity and overcurrent.</p> |

General data

2.4 General data

| Conformity and approval | | |
|-------------------------|------------|---|
| Conformity | | |
| CE | 2014/35/EU | Low-voltage directive |
| | 2014/30/EU | EMC directive |
| Approval | | |
| UL | | Refer to Technical data |
| others | | |
| RoHS | 2011/65/EU | Restriction of the use of certain hazardous substances in electrical and electronic equipment |

| Protection of persons and device protection | | |
|---|---|-----------------------------------|
| Type of protection | - | IP20 |
| Electrical isolation | | |
| to the field bus | - | electrically isolated |
| to the process level | - | electrically isolated |
| Insulation resistance | | - |
| Insulation voltage to reference earth | | |
| Inputs / outputs | - | AC / DC 50V, test voltage AC 500V |
| Protective measures | - | against short circuit |

| Environmental conditions to EN 61131-2 | | |
|--|---------------|--|
| Climatic | | |
| Storage / transport | EN 60068-2-14 | -25...+70°C |
| Operation | | |
| Horizontal installation hanging | EN 61131-2 | 0...+60°C |
| Horizontal installation lying | EN 61131-2 | 0...+55°C |
| Vertical installation | EN 61131-2 | 0...+50°C |
| Air humidity | EN 60068-2-30 | RH1 (without condensation, rel. humidity 10...95%) |
| Pollution | EN 61131-2 | Degree of pollution 2 |
| Installation altitude max. | - | 2000m |
| Mechanical | | |
| Oscillation | EN 60068-2-6 | 1g, 9Hz ... 150Hz |
| Shock | EN 60068-2-27 | 15g, 11ms |

| Mounting conditions | | |
|---------------------|---|-------------------------|
| Mounting place | - | In the control cabinet |
| Mounting position | - | Horizontal and vertical |

| EMC | Standard | Comment | |
|-----------------------|--------------|---------------------------|---|
| Emitted interference | EN 61000-6-4 | Class A (Industrial area) | |
| Noise immunity zone B | EN 61000-6-2 | Industrial area | |
| | | EN 61000-4-2 | ESD 8kV at air discharge (degree of severity 3), 4kV at contact discharge (degree of severity 2) |
| | | EN 61000-4-3 | HF field immunity (casing) 80MHz ... 1000MHz, 10V/m, 80% AM (1kHz) 1.4GHz ... 2.0GHz, 3V/m, 80% AM (1kHz) 2GHz ... 2.7GHz, 1V/m, 80% AM (1kHz) |
| | | EN 61000-4-6 | HF conducted 150kHz ... 80MHz, 10V, 80% AM (1kHz) |
| | | EN 61000-4-4 | Burst, degree of severity 3 |
| | | EN 61000-4-5 | Surge, degree of severity 3 * |

*) Due to the high-energetic single pulses with Surge an appropriate external protective circuit with lightning protection elements like conductors for lightning and overvoltage is necessary.

2.4.1 Use in difficult operating conditions



Without additional protective measures, the products must not be used in locations with difficult operating conditions; e.g. due to:

- *dust generation*
- *chemically active substances (corrosive vapors or gases)*
- *strong electric or magnetic fields*

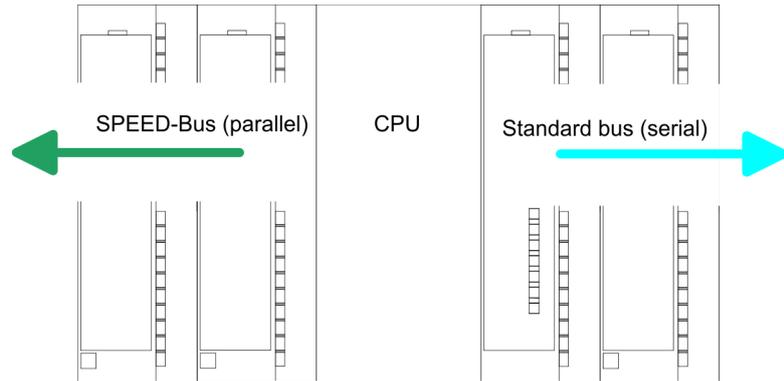
3 Assembly and installation guidelines

3.1 Overview

General

This CPU is provided with a parallel SPEED-Bus that enables the additional connection of up to 10 modules from the SPEED-Bus periphery. While the standard peripheral modules are plugged-in at the right side of the CPU, the SPEED-Bus peripheral modules are connected via a SPEED-Bus bus connector at the left side of the CPU.

VIPA delivers profile rails with integrated SPEED-Bus for 2, 6 or 10 SPEED-Bus peripheral modules with different lengths.



Serial Standard bus

The single modules are directly installed on a profile rail and connected via the backplane bus coupler. Before installing the modules you have to clip the backplane bus coupler to the module from the backside. The backplane bus couplers are included in the delivery of the peripheral modules.

Parallel SPEED-Bus

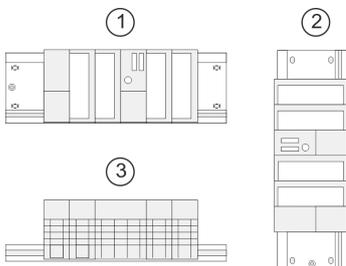
With SPEED-Bus the bus connection happens via a SPEED-Bus rail integrated in the profile rail at the left side of the CPU. Due to the parallel SPEED-Bus not all slots must be occupied in sequence.

SLOT 1 for additional power supply

At slot (SLOT 1 DCDC) you may plug either a SPEED-Bus module or an additional power supply.

Assembly possibilities

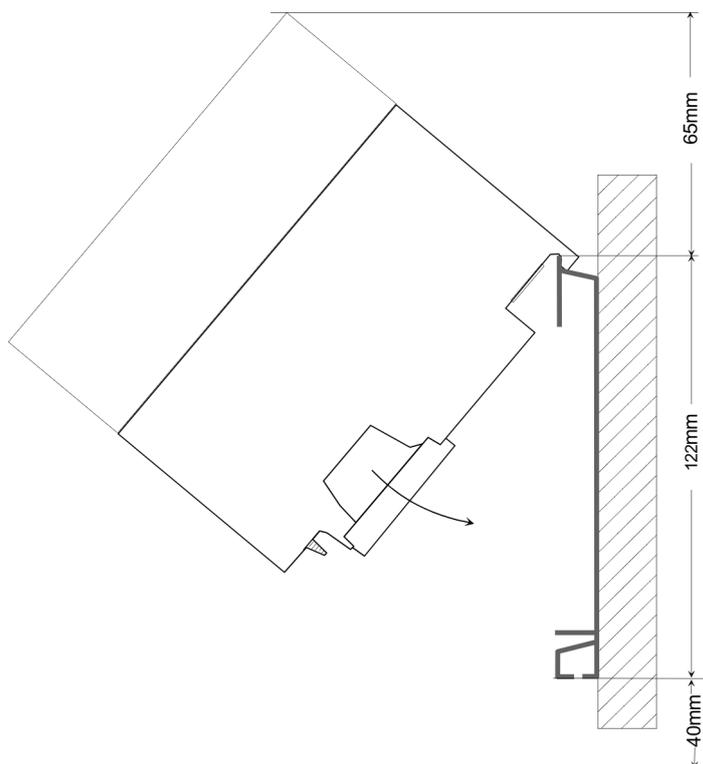
You may assemble the System 300 horizontally, vertically or lying. Please regard the allowed environment temperatures:



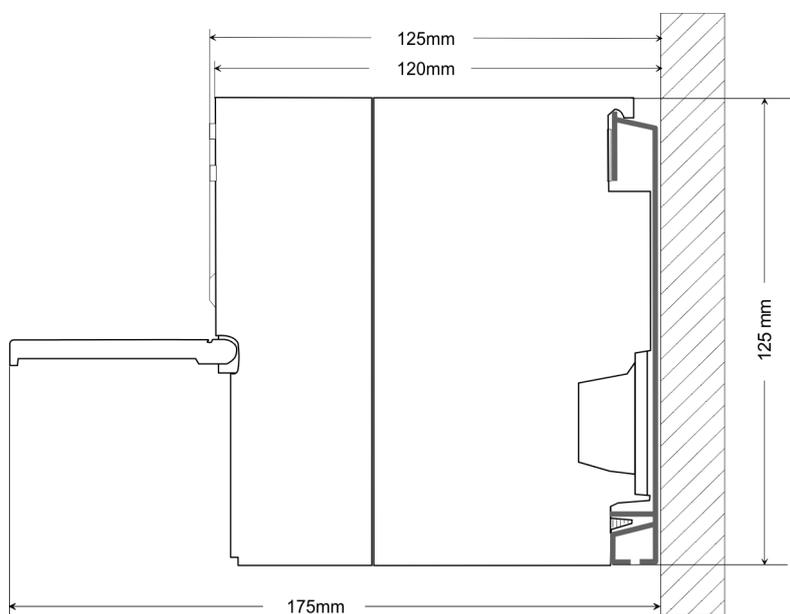
- 1 horizontal assembly: from 0 to 60°C
- 2 vertical assembly: from 0 to 50°C
- 3 lying assembly: from 0 to 55°C

3.2 Installation dimensions

Dimensions Basic enclosure 2tier width (WxHxD) in mm: 80 x 125 x 120



Installation dimensions



3.3 Assembly SPEED-Bus

Pre-manufactured SPEED-Bus profile rail

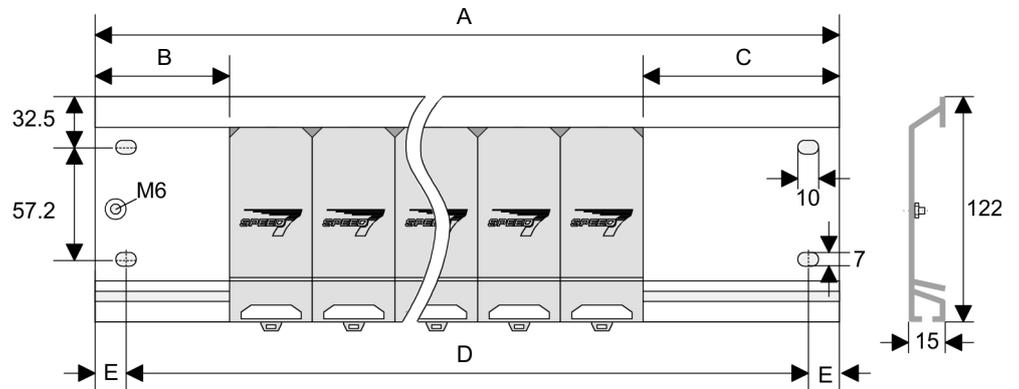
For the deployment of SPEED-Bus modules, a pre-manufactured SPEED-Bus rail is required. This is available mounted on a profile rail with 2, 6 or 10 extension slots.



Dimensions

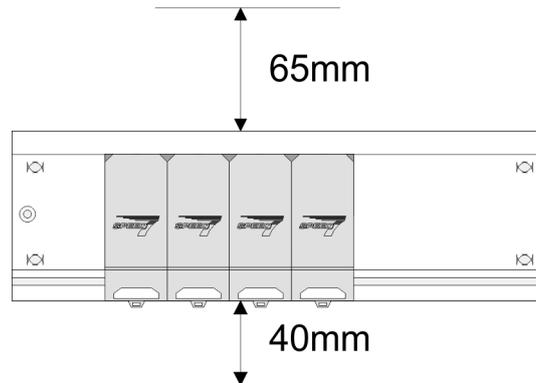
| Order number | Number of modules SPEED-Bus/Standard bus | A | B | C | D | E |
|--------------|--|-----|-----|-----|-----|----|
| 391-1AF10 | 2/6 | 530 | 100 | 268 | 510 | 10 |
| 391-1AF30 | 6/2 | 530 | 100 | 105 | 510 | 10 |
| 391-1AF50 | 10/0 | 530 | 20 | 20 | 510 | 10 |
| 391-1AJ10 | 2/15 | 830 | 22 | 645 | 800 | 15 |
| 391-1AJ30 | 6/11 | 830 | 22 | 480 | 800 | 15 |
| 391-1AJ50 | 10/7 | 830 | 22 | 320 | 800 | 15 |

Measures in mm

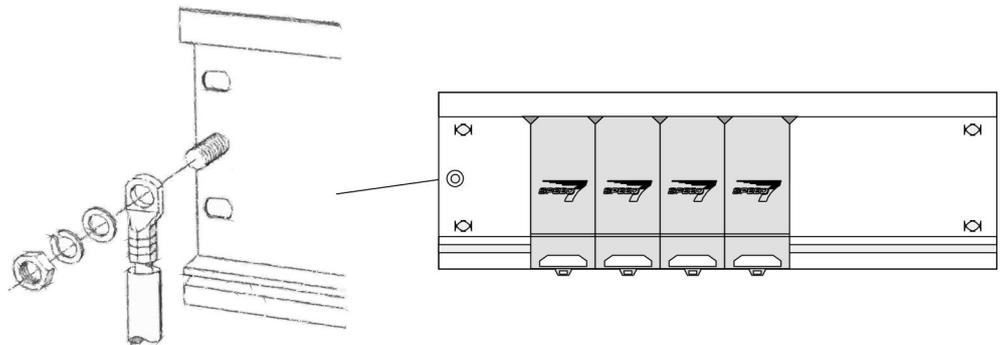


Installation of the profile rail

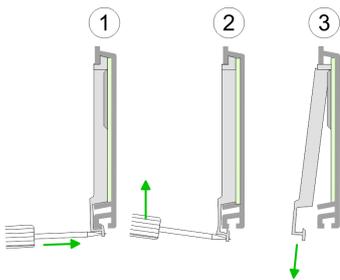
1. Bolt the profile rail with the background (screw size: M6), so that you still have minimum 65mm space above and 40mm below the profile rail. Please look for a low-impedance connection between profile rail and background.



2. Connect the profile rail with the protected earth conductor. The minimum cross-section of the cable to the protected earth conductor has to be 10mm².

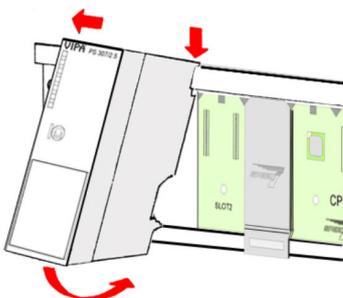


Installation SPEED-Bus module



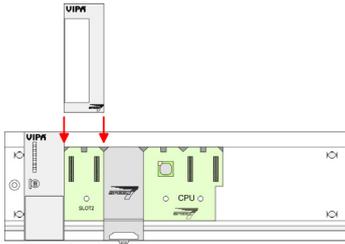
1. Dismantle the according protection flaps of the SPEED-Bus slot with a screw driver (open and pull down).

For the SPEED-Bus is a parallel bus, not every SPEED-Bus slot must be used in series. Leave the protection flap installed at an unused SPEED-Bus slot.



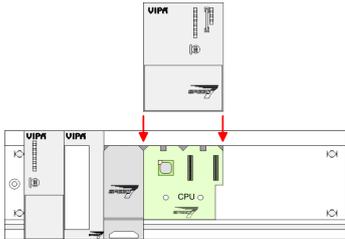
2. At deployment of a DC 24V power supply, install it at the shown position at the profile rail at the left side of the SPEED-Bus and push it to the left to the isolation bolt of the profile rail.
3. Fix the power supply by screwing.

Assembly SPEED-Bus

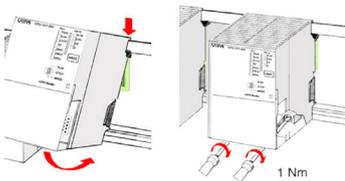


4. ➤ To connect the SPEED-Bus modules, plug it between the triangular positioning helps to a slot marked with "SLOT ..." and pull it down.
5. ➤ Only the "SLOT1 DCDC" allows you to plug-in either a SPEED-Bus module or an additional power supply.
6. ➤ Fix the CPU by screwing.

Installation CPU without Standard-Bus-Modules

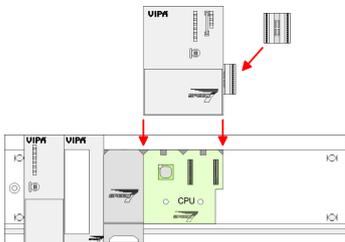


1. ➤ To deploy the SPEED7-CPU exclusively at the SPEED-Bus, plug it between the triangular positioning helps to the slot marked with "CPU SPEED7" and pull it down.

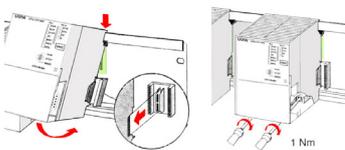


2. ➤ Fix the CPU by screwing.

Installation CPU with Standard-Bus-Modules

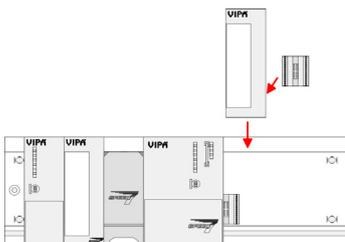


1. ➤ If also standard modules shall be plugged, take a bus coupler and click it at the CPU from behind like shown in the picture. Plug the CPU between the triangular positioning helps to the slot marked with "CPU SPEED7" and pull it down.



2. ➤ Fix the CPU by screwing.

Installation Standard-Bus-Modules



- Repeat this procedure with the peripheral modules, by clicking a backplane bus coupler, stick the module right from the modules you've already fixed, click it downwards and connect it with the backplane bus coupler of the last module and bolt it.

**CAUTION!**

- The power supplies must be released before installation and repair tasks, i.e. before handling with the power supply or with the cabling you must disconnect current/voltage (pull plug, at fixed connection switch off the concerning fuse)!
- Installation and modifications only by properly trained personnel!

3.4 Assembly standard bus

General

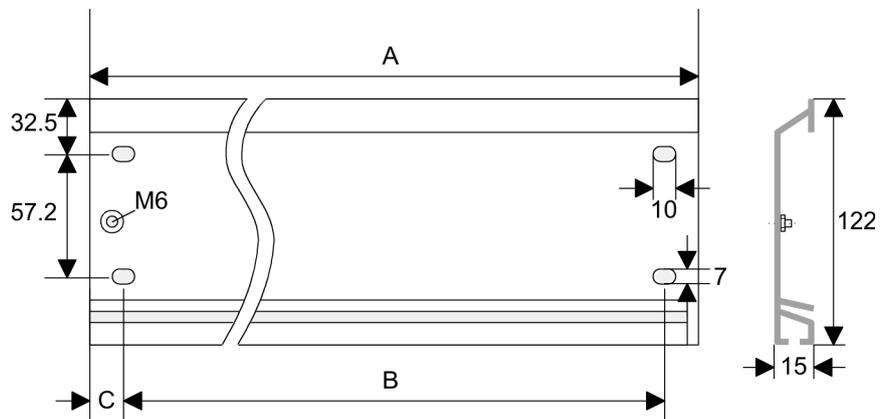
The single modules are directly installed on a profile rail and connected via the backplane bus connector. Before installing the modules you have to clip the backplane bus connector to the module from the backside. The backplane bus connector is delivered together with the peripheral modules.

Profile rail

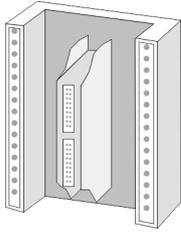
| Order number | A | B | C |
|--------------|------|---------------------|-----|
| 390-1AB60 | 160 | 140 | 10 |
| 390-1AE80 | 482 | 466 | 8.3 |
| 390-1AF30 | 530 | 500 | 15 |
| 390-1AJ30 | 830 | 800 | 15 |
| 390-9BC00* | 2000 | Drillings only left | 15 |

*) Unit pack: 10 pieces

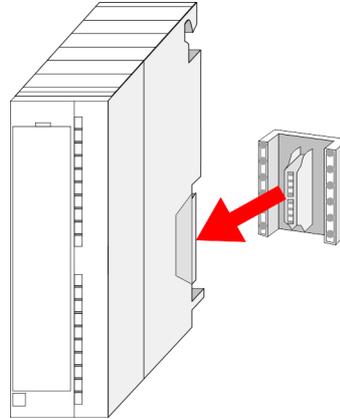
Measures in mm

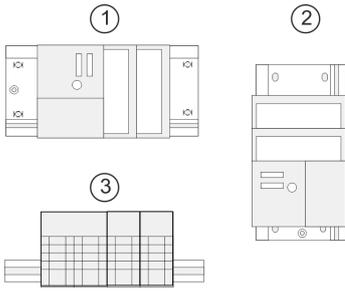


Bus connector



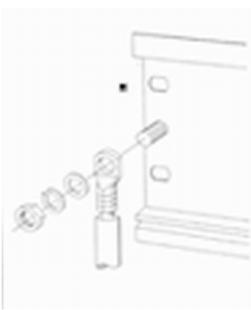
For the communication between the modules the System 300S uses a backplane bus connector. Backplane bus connectors are included in the delivering of the peripheral modules and are clipped at the module from the backside before installing it to the profile rail.



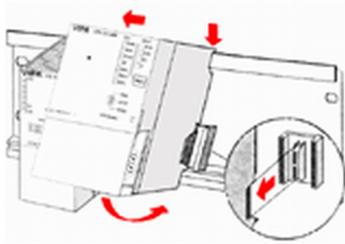
Assembly possibilities

Please regard the allowed environment temperatures:

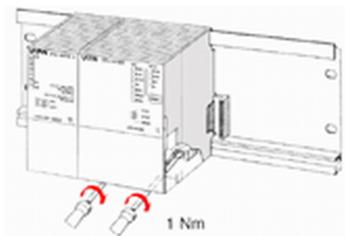
- 1 horizontal assembly: from 0 to 60°C
- 2 vertical assembly: from 0 to 50°C
- 3 lying assembly: from 0 to 55°C

Approach

1. Bolt the profile rail with the background (screw size: M6), so that you still have minimum 65mm space above and 40mm below the profile rail.
2. If the background is a grounded metal or device plate, please look for a low-impedance connection between profile rail and background.
3. Connect the profile rail with the protected earth conductor. For this purpose there is a bolt with M6-thread.
4. The minimum cross-section of the cable to the protected earth conductor has to be 10mm².



5. Stick the power supply to the profile rail and pull it to the left side to the grounding bolt of the profile rail.
6. Fix the power supply by screwing.
7. Take a backplane bus connector and click it at the CPU from the backside like shown in the picture.
8. Stick the CPU to the profile rail right from the power supply and pull it to the power supply.



9. Click the CPU downwards and bolt it like shown.
10. Repeat this procedure with the peripheral modules, by clicking a backplane bus connector, stick the module right from the modules you've already fixed, click it downwards and connect it with the backplane bus connector of the last module and bolt it.

3.5 Cabling



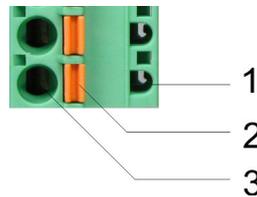
CAUTION!

- The power supplies must be released before installation and repair tasks, i.e. before handling with the power supply or with the cabling you must disconnect current/voltage (pull plug, at fixed connection switch off the concerning fuse)!
- Installation and modifications only by properly trained personnel!

CageClamp technology (green)

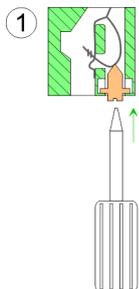
For the cabling of power supply of a CPU, a green plug with CageClamp technology is deployed. The connection clamp is realized as plug that may be clipped off carefully if it is still cabled.

Here wires with a cross-section of 0.08mm² to 2.5mm² may be connected. You can use flexible wires without end case as well as stiff wires.

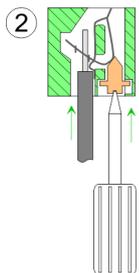


- 1 Test point for 2mm test tip
- 2 Locking (orange) for screwdriver
- 3 Round opening for wires

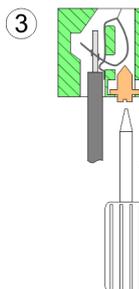
The picture on the left side shows the cabling step by step from top view.



1. ➔ For cabling you push the locking vertical to the inside with a suitable screwdriver and hold the screwdriver in this position.



2. ➔ Insert the de-isolated wire into the round opening. You may use wires with a cross-section from 0.08mm² to 2.5mm²



3. ➔ By removing the screwdriver the wire is connected safely with the plug connector via a spring.

3.6 Installation guidelines

General

The installation guidelines contain information about the interference free deployment of a PLC system. There is the description of the ways, interference may occur in your PLC, how you can make sure the electromagnetic compatibility (EMC), and how you manage the isolation.

What does EMC mean?

Electromagnetic compatibility (EMC) means the ability of an electrical device, to function error free in an electromagnetic environment without being interfered respectively without interfering the environment.

The components of Yaskawa are developed for the deployment in industrial environments and meets high demands on the EMC. Nevertheless you should project an EMC planning before installing the components and take conceivable interference causes into account.

Possible interference causes

Electromagnetic interferences may interfere your control via different ways:

- Electromagnetic fields (RF coupling)
- Magnetic fields with power frequency
- Bus system
- Power supply
- Protected earth conductor

Depending on the spreading medium (lead bound or lead free) and the distance to the interference cause, interferences to your control occur by means of different coupling mechanisms.

There are:

- galvanic coupling
- capacitive coupling
- inductive coupling
- radiant coupling

Basic rules for EMC

In the most times it is enough to take care of some elementary rules to guarantee the EMC. Please regard the following basic rules when installing your PLC.

- Take care of a correct area-wide grounding of the inactive metal parts when installing your components.
 - Install a central connection between the ground and the protected earth conductor system.
 - Connect all inactive metal extensive and impedance-low.
 - Please try not to use aluminium parts. Aluminium is easily oxidizing and is therefore less suitable for grounding.
- When cabling, take care of the correct line routing.
 - Organize your cabling in line groups (high voltage, current supply, signal and data lines).
 - Always lay your high voltage lines and signal respectively data lines in separate channels or bundles.
 - Route the signal and data lines as near as possible beside ground areas (e.g. suspension bars, metal rails, tin cabinet).

- Proof the correct fixing of the lead isolation.
 - Data lines must be shielded.
 - Analog lines must be shielded. When transmitting signals with small amplitudes the one sided laying of the isolation may be favourable.
 - Cables for frequency inverters, servo and stepper motors must be shielded.
 - Lay the line isolation extensively on an isolation/protected earth conductor rail directly after the cabinet entry and fix the isolation with cable clamps.
 - Make sure that the isolation/protected earth conductor rail is connected impedance-low with the cabinet.
 - Use metallic or metallised plug cases for isolated data lines.
- In special use cases you should appoint special EMC actions.
 - Consider to wire all inductivities with erase links.
 - Please consider luminescent lamps can influence signal lines.
- Create a homogeneous reference potential and ground all electrical operating supplies when possible.
 - Please take care for the targeted employment of the grounding actions. The grounding of the PLC serves for protection and functionality activity.
 - Connect installation parts and cabinets with your PLC in star topology with the isolation/protected earth conductor system. So you avoid ground loops.
 - If there are potential differences between installation parts and cabinets, lay sufficiently dimensioned potential compensation lines.

Isolation of conductors

Electrical, magnetically and electromagnetic interference fields are weakened by means of an isolation, one talks of absorption. Via the isolation rail, that is connected conductive with the rack, interference currents are shunt via cable isolation to the ground. Here you have to make sure, that the connection to the protected earth conductor is impedance-low, because otherwise the interference currents may appear as interference cause.

When isolating cables you have to regard the following:

- If possible, use only cables with isolation tangle.
- The hiding power of the isolation should be higher than 80%.
- Normally you should always lay the isolation of cables on both sides. Only by means of the both-sided connection of the isolation you achieve high quality interference suppression in the higher frequency area. Only as exception you may also lay the isolation one-sided. Then you only achieve the absorption of the lower frequencies. A one-sided isolation connection may be convenient, if:
 - the conduction of a potential compensating line is not possible.
 - analog signals (some mV respectively μ A) are transferred.
 - foil isolations (static isolations) are used.
- With data lines always use metallic or metallised plugs for serial couplings. Fix the isolation of the data line at the plug rack. Do not lay the isolation on the PIN 1 of the plug bar!
- At stationary operation it is convenient to strip the insulated cable interruption free and lay it on the isolation/protected earth conductor line.
- To fix the isolation tangles use cable clamps out of metal. The clamps must clasp the isolation extensively and have well contact.
- Lay the isolation on an isolation rail directly after the entry of the cable in the cabinet. Lead the isolation further on to your PLC and don't lay it on there again!



CAUTION!

Please regard at installation!

At potential differences between the grounding points, there may be a compensation current via the isolation connected at both sides.

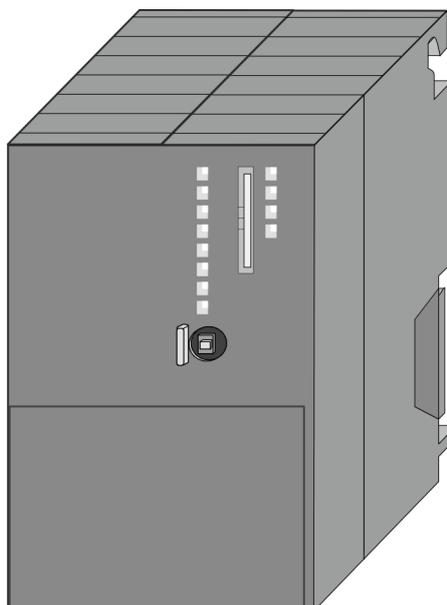
Remedy: Potential compensation line

4 Hardware description

4.1 Properties

CPU 317-4NE23

- SPEED7 technology and SPEED-Bus integrated
- 4Mbyte work memory integrated (2Mbyte code, 2Mbyte data)
- Memory expandable to max. 8Mbyte (4Mbyte code, 4Mbyte data)
- 8Mbyte load memory
- PROFIBUS DP master integrated (DP-V0, DP-V1)
- CP 343 communication processor integrated
 - ↳ *Chap. 4.3 'Technical data' page 35*
 - Productive connections via Siemens NetPro
 - Productive connections via user program
 - PG/OP connections
- RS485 interface configurable for PROFIBUS DP master respectively PtP communication
- Ethernet PG/OP interface integrated
- MPI interface
- Slot for external memory cards (lockable)
- Status LEDs for operating state and diagnostics
- Real-time clock battery buffered
- I/O address range digital/analog 8191byte
- 2048 timer
- 2048 counter
- 16384 flag byte



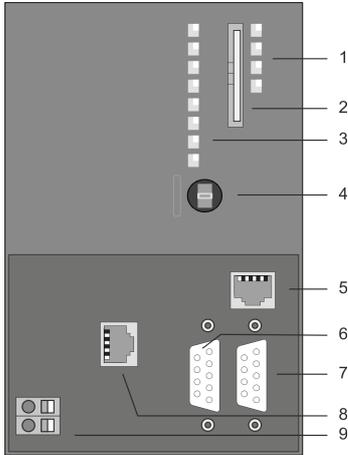
Ordering data

| Type | Order number | Description |
|-------|--------------|--|
| 317SN | 317-4NE23 | SPEED-Bus, MPI interface, card slot, real time clock, Ethernet interface for PG/OP, PROFIBUS DP master, CP 343 |

4.2 Structure

4.2.1 General

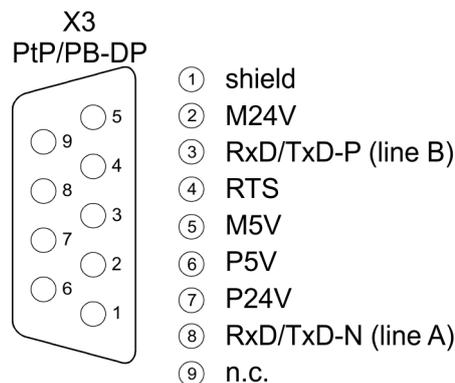
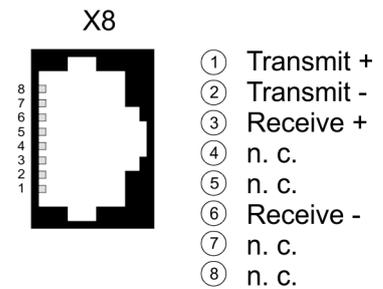
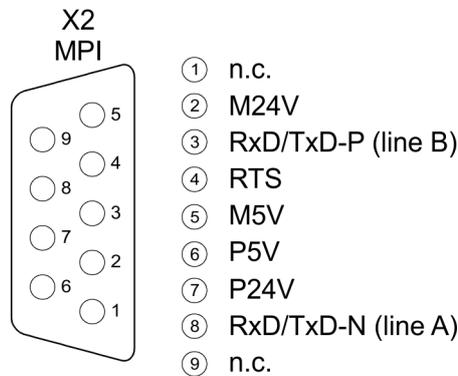
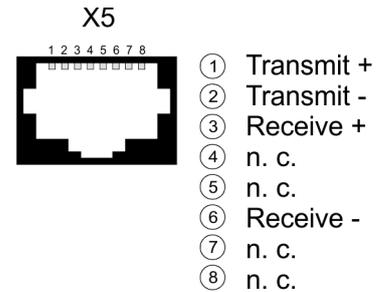
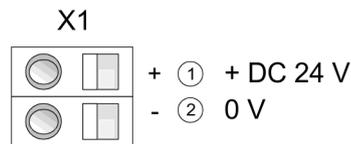
CPU 317-4NE23



- 1 LEDs of the integrated PROFIBUS DP master
- 2 Storage media slot (lockable)
- 3 LEDs of the CPU part
- 4 Operating mode switch CPU
- 5 Twisted pair interface for Ethernet PG/OP channel
- 6 MPI interface
- 7 PROFIBUS DP/PtP interface
- 8 Twisted Pair interface for CP 343
- 9 Slot for DC 24V power supply

The components 5 - 9 are under the front flap!

4.2.2 Interfaces



- X1: Power supply**
- The CPU has an integrated power supply:
- The power supply has to be provided with DC 24V. For this serves the double DC 24V slot, that is underneath the flap.
 - Via the power supply not only the internal electronic is provided with voltage, but by means of the backplane bus also the connected modules.
 - The power supply is protected against polarity inversion and overcurrent.
 - The internal electronic is galvanically connected with the supply voltage.
- X2: MPI interface**
- 9pin SubD jack:*
- The MPI interface serves for the connection between programming unit and CPU.
 - By means of this the project engineering and programming happens.
 - MPI serves for communication between several CPUs or between HMIs and CPU.
 - Standard setting is MPI Address 2.
- X5: Ethernet PG/OP channel**
- 8pin RJ45 jack:*
- The RJ45 jack serves the interface to the Ethernet PG/OP channel.
 - This interface allows you to program res. remote control your CPU, to access the internal web site or to connect a visualization.
 - Configurable connections are not possible.
 - For online access to the CPU via Ethernet PG/OP channel valid IP address parameters have to be assigned to this.
- X3: PROFIBUS/PtP interface with configurable functionality**
- 9pin SubD jack:*
- The CPU has a PROFIBUS/PtP interface with a fix pinout. After an overall reset the interface is deactivated. By appropriate configuration, the following functions for this interface may be enabled:
- PROFIBUS DP master operation
 - Configuration via PROFIBUS sub module X1 (MPI/DP) with ‘*Operation mode*’ master in the hardware configuration.
 - PROFIBUS DP slave operation
 - Configuration via PROFIBUS sub module X1 (MPI/DP) with ‘*Operation mode*’ slave in the hardware configuration.
 - PtP functionality
 - Using the PtP functionality the RS485 interface is allowed to connect via serial point-to-point connection to different source res. target systems.
 - Here the following protocols are supported: ASCII, STX/ETX, 3964R, USS and Modbus-Master (ASCII, RTU).
 - The activation of the PtP functionality happens by embedding the SPEEDBUS.GSD from VIPA in the hardware catalog. After the installation the CPU may be configured in a PROFIBUS master system and here the interface may be switched to PtP communication.
- Communication processor CP 343 X8**
- 8pin RJ45 jack:*
- Communication processor CP 343 for connection to Ethernet
 - Productive connections via Siemens NetPro
 - Productive connections via user program
 - PG/OP connections



Number of connections ↪ Chap. 4.3 'Technical data' page 35

4.2.3 Memory management

Memory

The CPU has an integrated memory. Information about the capacity of the memory may be found at the front of the CPU. The memory is divided into the following parts:

- Load memory 8Mbyte
- Code memory (50% of the work memory)
- Data memory (50% of the work memory)
- Work memory 4Mbyte
 - There is the possibility to extend the work memory to its maximum printed capacity 8Mbyte by means of a memory extension card.

4.2.4 Slot for storage media

At this slot the following storage media can be plugged:

- SD respectively MCC (**M**ultimedia **C**ard)
 - External memory card for programs and firmware.
- MCC - **M**emory **C**onfiguration **C**ard
 - External memory card (MMC) for programs and firmware with the possibility to unlock additional work memory.
 - The additional memory can be purchased separately. ↪ Chap. 5.17 'Deployment storage media - MMC, MCC' page 76
 - To activate the corresponding card is to be installed and an *Overall reset* is to be established. ↪ Chap. 5.14 'Overall reset' page 72

4.2.5 Battery backup for clock and RAM

A rechargeable battery is installed on every CPU to safeguard the contents of the RAM when power is removed. This battery is also used to buffer the internal clock. The rechargeable battery is maintained by a charging circuit that receives its power from the internal power supply and that maintain the clock and RAM for a max. period of 30 days.



- Please connect the CPU at least for 24 hours to the power supply, so that the internal accumulator/battery is loaded accordingly.
- Please note that in case of repeated discharge cycles (charging/buffering) can reduce the buffer time continuously. Only after a charging time of 24 hours there is a buffer for max. 30 days.



CAUTION!

- After a power reset and with an empty battery the CPU starts with a BAT error and executes an overall reset. The loading procedure is not influenced by the BAT error.
- The BAT error can be deleted again, if once during power cycle the time between switching on and off the power supply is at least 30sec. and the battery is fully loaded. Otherwise with a short power cycle the BAT error still exists and an overall reset is executed.

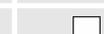
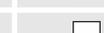
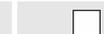
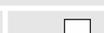
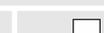
4.2.6 Operating mode switch



- With the operating mode switch you may switch the CPU between STOP and RUN.
- During the transition from STOP to RUN the operating mode START-UP is driven by the CPU.
- Placing the switch to MR (Memory Reset), you request an overall reset with following load from memory card, if a project there exists.

4.2.7 LEDs

LEDs CPU

| RN (RUN)  green | ST (STOP)  yellow | SF (SFAIL)  red | FC (FRCE)  yellow | MC (MMC)  yellow | Meaning |
|---|--|--|--|---|---|
| Boot-up after PowerON - as soon as the CPU is supplied with 5V, the green PW-LED (Power) is on. | | | | | |
|  |  10Hz |  |  |  | Firmware is loaded. |
|  |  |  |  |  | Initialization: Phase 1 |
|  |  |  |  |  | Initialization: Phase 2 |
|  |  |  |  |  | Initialization: Phase 3 |
|  |  |  |  |  | Initialization: Phase 4 |
| Operation | | | | | |
|  |  | X | X | X | CPU is in STOP state. |
|  2Hz |  | X | X | X | CPU is in start-up state. As long as the OB 100 is processed, the RUN LED blinks for at least 3s. |
|  |  |  | X | X | CPU is in state RUN without error. |
| X | X |  | X | X | There is a system fault. More information can be found in the diagnostics buffer of the CPU. |
| X | X | X |  | X | Variables are forced. |
| X | X | X | X |  | Accessing the memory card |
| X |  10Hz |  |  |  | Configuration is loaded. |
| Overall reset | | | | | |
|  |  2Hz | X | X | X | Overall reset is requested |
|  |  10Hz | X | X | X | Overall reset is executed. |
| Factory reset | | | | | |
|  |  |  |  |  | Reset to factory setting is executed. |
|  |  |  |  |  | Reset to factory setting finished without error |
| Firmware update | | | | | |
|  |  |  2Hz |  2Hz |  | The alternate blinking indicates that there is new firmware on the memory card. |
|  |  |  2Hz |  2Hz |  | The alternate blinking indicates that a firmware update is executed. |
|  |  |  |  |  | Firmware update finished without error. |
|  |  10Hz |  10Hz |  10Hz |  10Hz | Error during Firmware update. |
| not relevant: X | | | | | |

Ethernet PG/OP channel

| L/A (Link/Activity)  green | S (Speed)  green | Meaning |
|---|---|--|
|  | X | The Ethernet PG/OP channel is physically connected to Ethernet. |
| <input type="checkbox"/> | X | There is no physical connection. |
|  flickers | X | Shows Ethernet activity. |
|  |  | The Ethernet interface of the Ethernet PG/OP channel has a transfer rate of 100Mbit. |
|  | <input type="checkbox"/> | The Ethernet interface of the Ethernet PG/OP channel has a transfer rate of 10Mbit. |
| not relevant: X | | |

LEDs PROFIBUS/PtP interface X3

Dependent on the mode of operation the LEDs show information about the state of operation of the PROFIBUS part according to the following pattern:

Master operation

| RN (RUN)  green | ER (ERR)  red | DE  green | IF  red | Meaning |
|--|--|---|---|--|
| <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | Master has no project, this means the interface is deactivated respectively PtP is active. |
|  | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | Master has bus parameters and is in RUN without slaves. |
|  | <input type="checkbox"/> |  2Hz | <input type="checkbox"/> | Master is in "clear" state (safety state). The inputs of the slaves may be read. The outputs are disabled. |
|  | <input type="checkbox"/> |  | <input type="checkbox"/> | Master is in "operate" state, this means data exchange between master and slaves. The outputs may be accessed. |
|  |  |  | <input type="checkbox"/> | CPU is in RUN state, at least 1 slave is missing. |
|  |  |  2Hz | <input type="checkbox"/> | CPU is in STOP, at least 1 slave is missing. |
| <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |  | Initialization error at faulty parametrization. |
| <input type="checkbox"/> |  | <input type="checkbox"/> |  | Wait state for start command from CPU. |

Slave operation

| RN (RUN)  green | ER (ERR)  red | DE  green | IF  red | Meaning |
|--|--|---|---|--|
| <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | Slave has no configuration respectively PtP is active. |
|  2Hz | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | Slave is without master. |

Structure > LEDs

| RN (RUN)  green | ER (ERR)  red | DE  green | IF  red | Meaning |
|--|--|---|---|---|
|  2Hz | <input type="checkbox"/> |  2Hz | <input type="checkbox"/> | Alternate blinking at configuration faults. |
|  | <input type="checkbox"/> |  | <input type="checkbox"/> | Slave exchanges data with the master. |

4.3 Technical data

| Order no. | 317-4NE23 |
|--|---|
| Type | CPU 317SN |
| SPEED-Bus | ✓ |
| Technical data power supply | |
| Power supply (rated value) | DC 24 V |
| Power supply (permitted range) | DC 20.4...28.8 V |
| Reverse polarity protection | ✓ |
| Current consumption (no-load operation) | 270 mA |
| Current consumption (rated value) | 1.5 A |
| Inrush current | 5 A |
| I ² t | 0.5 A ² s |
| Max. current drain at backplane bus | 4 A |
| Max. current drain load supply | - |
| Power loss | 10 W |
| Load and working memory | |
| Load memory, integrated | 8 MB |
| Load memory, maximum | 8 MB |
| Work memory, integrated | 4 MB |
| Work memory, maximal | 8 MB |
| Memory divided in 50% program / 50% data | ✓ |
| Memory card slot | SD/MMC-Card with max. 2 GB |
| Hardware configuration | |
| Racks, max. | 4 |
| Modules per rack, max. | 8 in multiple-, 32 in a single-rack configuration |
| Number of integrated DP master | 1 |
| Number of DP master via CP | 4 |
| Operable function modules | 8 |
| Operable communication modules PtP | 16 |
| Operable communication modules LAN | 8 |
| Status information, alarms, diagnostics | |
| Status display | yes |
| Interrupts | no |
| Process alarm | no |
| Diagnostic interrupt | no |
| Diagnostic functions | no |
| Diagnostics information read-out | possible |

Technical data

| | |
|--|--------------------------|
| Order no. | 317-4NE23 |
| Supply voltage display | green LED |
| Group error display | red SF LED |
| Channel error display | none |
| Command processing times | |
| Bit instructions, min. | 0.01 µs |
| Word instruction, min. | 0.01 µs |
| Double integer arithmetic, min. | 0.01 µs |
| Floating-point arithmetic, min. | 0.06 µs |
| Timers/Counters and their retentive characteristics | |
| Number of S7 counters | 2048 |
| S7 counter remanence | adjustable 0 up to 2048 |
| S7 counter remanence adjustable | C0 .. C7 |
| Number of S7 times | 2048 |
| S7 times remanence | adjustable 0 up to 2048 |
| S7 times remanence adjustable | not retentive |
| Data range and retentive characteristic | |
| Number of flags | 16384 Byte |
| Bit memories retentive characteristic adjustable | adjustable 0 up to 16384 |
| Bit memories retentive characteristic preset | MB0 .. MB15 |
| Number of data blocks | 8190 |
| Max. data blocks size | 64 KB |
| Number range DBs | 1 ... 8190 |
| Max. local data size per execution level | 1024 Byte |
| Max. local data size per block | 1024 Byte |
| Blocks | |
| Number of OBs | 23 |
| Maximum OB size | 64 KB |
| Total number DBs, FBs, FCs | - |
| Number of FBs | 8191 |
| Maximum FB size | 64 KB |
| Number range FBs | 0 ... 8190 |
| Number of FCs | 8191 |
| Maximum FC size | 64 KB |
| Number range FCs | 0 ... 8190 |
| Maximum nesting depth per priority class | 16 |
| Maximum nesting depth additional within an error OB | 4 |

| | |
|-------------------------------------|---------------------------------------|
| Order no. | 317-4NE23 |
| Time | |
| Real-time clock buffered | ✓ |
| Clock buffered period (min.) | 6 w |
| Type of buffering | Vanadium Rechargeable Lithium Battery |
| Load time for 50% buffering period | 20 h |
| Load time for 100% buffering period | 48 h |
| Accuracy (max. deviation per day) | 10 s |
| Number of operating hours counter | 8 |
| Clock synchronization | ✓ |
| Synchronization via MPI | Master/Slave |
| Synchronization via Ethernet (NTP) | Slave |
| Address areas (I/O) | |
| Input I/O address area | 8192 Byte |
| Output I/O address area | 8192 Byte |
| Process image adjustable | ✓ |
| Input process image preset | 256 Byte |
| Output process image preset | 256 Byte |
| Input process image maximal | 8192 Byte |
| Output process image maximal | 8192 Byte |
| Digital inputs | 65536 |
| Digital outputs | 65536 |
| Digital inputs central | 1024 |
| Digital outputs central | 1024 |
| Integrated digital inputs | - |
| Integrated digital outputs | - |
| Analog inputs | 4096 |
| Analog outputs | 4096 |
| Analog inputs, central | 256 |
| Analog outputs, central | 256 |
| Integrated analog inputs | - |
| Integrated analog outputs | - |
| Communication functions | |
| PG/OP channel | ✓ |
| Global data communication | ✓ |
| Number of GD circuits, max. | 8 |
| Size of GD packets, max. | 54 Byte |

Technical data

| | |
|---|--------------------------|
| Order no. | 317-4NE23 |
| S7 basic communication | ✓ |
| S7 basic communication, user data per job | 76 Byte |
| S7 communication | ✓ |
| S7 communication as server | ✓ |
| S7 communication as client | - |
| S7 communication, user data per job | 160 Byte |
| Number of connections, max. | 32 |
| Functionality Sub-D interfaces | |
| Type | X2 |
| Type of interface | RS485 |
| Connector | Sub-D, 9-pin, female |
| Electrically isolated | ✓ |
| MPI | ✓ |
| MP ² I (MPI/RS232) | - |
| DP master | - |
| DP slave | - |
| Point-to-point interface | - |
| 5V DC Power supply | max. 90mA, isolated |
| 24V DC Power supply | max. 100mA, non-isolated |
| Functionality X3 interfaces | |
| Type | X3 |
| Type of interface | RS485 |
| Connector | Sub-D, 9-pin, female |
| Electrically isolated | ✓ |
| MPI | - |
| MP ² I (MPI/RS232) | - |
| DP master | yes |
| DP slave | yes |
| Point-to-point interface | ✓ |
| 5V DC Power supply | max. 90mA, isolated |
| 24V DC Power supply | max. 100mA, non-isolated |
| Functionality MPI | |
| Number of connections, max. | 32 |
| PG/OP channel | ✓ |
| Routing | ✓ |
| Global data communication | ✓ |

| Order no. | 317-4NE23 |
|---|-------------|
| S7 basic communication | ✓ |
| S7 communication | ✓ |
| S7 communication as server | ✓ |
| S7 communication as client | - |
| Transmission speed, min. | 19.2 kbit/s |
| Transmission speed, max. | 12 Mbit/s |
| Functionality PROFIBUS master | |
| Number of connections, max. | 32 |
| PG/OP channel | ✓ |
| Routing | ✓ |
| S7 basic communication | ✓ |
| S7 communication | ✓ |
| S7 communication as server | ✓ |
| S7 communication as client | - |
| Activation/deactivation of DP slaves | ✓ |
| Direct data exchange (slave-to-slave communication) | - |
| DPV1 | ✓ |
| Transmission speed, min. | 9.6 kbit/s |
| Transmission speed, max. | 12 Mbit/s |
| Number of DP slaves, max. | 124 |
| Address range inputs, max. | 8 KB |
| Address range outputs, max. | 8 KB |
| User data inputs per slave, max. | 244 Byte |
| User data outputs per slave, max. | 244 Byte |
| Functionality PROFIBUS slave | |
| Number of connections, max. | 32 |
| PG/OP channel | ✓ |
| Routing | ✓ |
| S7 communication | ✓ |
| S7 communication as server | ✓ |
| S7 communication as client | - |
| Direct data exchange (slave-to-slave communication) | - |
| DPV1 | ✓ |
| Transmission speed, min. | 9.6 kbit/s |
| Transmission speed, max. | 12 Mbit/s |
| Automatic detection of transmission speed | - |

Technical data

| | |
|--------------------------------------|----------------------|
| Order no. | 317-4NE23 |
| Transfer memory inputs, max. | 244 Byte |
| Transfer memory outputs, max. | 244 Byte |
| Address areas, max. | 32 |
| User data per address area, max. | 32 Byte |
| Point-to-point communication | |
| PtP communication | ✓ |
| Interface isolated | ✓ |
| RS232 interface | - |
| RS422 interface | - |
| RS485 interface | ✓ |
| Connector | Sub-D, 9-pin, female |
| Transmission speed, min. | 150 bit/s |
| Transmission speed, max. | 115.5 kbit/s |
| Cable length, max. | 500 m |
| Point-to-point protocol | |
| ASCII protocol | ✓ |
| STX/ETX protocol | ✓ |
| 3964(R) protocol | ✓ |
| RK512 protocol | - |
| USS master protocol | ✓ |
| Modbus master protocol | ✓ |
| Modbus slave protocol | - |
| Special protocols | - |
| Functionality RJ45 interfaces | |
| Type | X5 |
| Type of interface | Ethernet 10/100 MBit |
| Connector | RJ45 |
| Electrically isolated | ✓ |
| PG/OP channel | ✓ |
| Number of connections, max. | 4 |
| Productive connections | - |
| Fieldbus | - |
| | |
| Type | X8 |
| Type of interface | Ethernet 10/100 MBit |
| Connector | RJ45 |

| | |
|--|---|
| Order no. | 317-4NE23 |
| Electrically isolated | ✓ |
| PG/OP channel | ✓ |
| Number of connections, max. | 32 |
| Productive connections | ✓ |
| Fieldbus | - |
| Ethernet communication CP | |
| Number of configurable connections, max. | 64 |
| Number of productive connections by Siemens NetPro, max. | 16 |
| S7 connections | BSEND, BRCV, GET, PUT, Connection of active and passive data handling |
| User data per S7 connection, max. | 32 KB |
| TCP-connections | SEND, RECEIVE, FETCH PASSIV, WRITE PASSIV, Connection of active and passive data handling |
| User data per TCP connection, max. | 64 KB |
| ISO-connections | SEND, RECEIVE, FETCH PASSIV, WRITE PASSIV, Connection of active and passive data handling |
| User data per ISO connection, max. | 8 KB |
| ISO on TCP connections (RFC 1006) | SEND, RECEIVE, FETCH PASSIV, WRITE PASSIV, Connection of active and passive data handling |
| User data per ISO on TCP connection, max. | 32 KB |
| UDP-connections | SEND and RECEIVE |
| User data per UDP connection, max. | 2 KB |
| UDP-multicast-connections | SEND and RECEIVE (max. 16 Multicast groups) |
| UDP-broadcast-connections | SEND |
| Ethernet open communication | |
| Number of connections, max. | 8 |
| ISO on TCP connections (RFC 1006) | TSEND, TRCV, TCON, TDISCON |
| User data per ISO on TCP connection, max. | 8 KB |
| TCP-Connections native | TSEND, TRCV, TCON, TDISCON |
| User data per native TCP connection, max. | 8 KB |
| User data per ad hoc TCP connection, max. | 1460 Byte |
| UDP-connections | TUSEND, TURCV |
| User data per UDP connection, max. | 1472 Byte |
| Housing | |
| Material | PPE |
| Mounting | Rail System 300 |
| Mechanical data | |

Technical data

| | |
|---------------------------------|-------------------------|
| Order no. | 317-4NE23 |
| Dimensions (WxHxD) | 80 mm x 125 mm x 120 mm |
| Net weight | 440 g |
| Weight including accessories | - |
| Gross weight | - |
| Environmental conditions | |
| Operating temperature | 0 °C to 60 °C |
| Storage temperature | -25 °C to 70 °C |
| Certifications | |
| UL certification | yes |
| KC certification | yes |

5 Deployment CPU 317-4NE23

5.1 Assembly



Information about assembly and cabling: ↗ Chap. 3 'Assembly and installation guidelines' page 16

5.2 Start-up behavior

Turn on power supply

After the power supply has been switched on, the CPU changes to the operating mode the operating mode lever shows.

Default boot procedure, as delivered

When the CPU is delivered it has been reset. After a STOP→RUN transition the CPU switches to RUN without program.

Boot procedure with valid configuration in the CPU

The CPU switches to RUN with the program stored in the battery buffered RAM.

Boot procedure with empty battery

- The accumulator/battery is automatically loaded via the integrated power supply and guarantees a buffer for max. 30 days. If this time is exceeded, the battery may be totally discharged. This means that the battery buffered RAM is deleted.
- In this state, the CPU executes an overall reset. If a memory card is plugged, program code and data blocks are transferred from the memory card into the work memory of the CPU. If no memory card is plugged, the CPU transfers permanent stored "protected" blocks into the work memory if available.
- Depending on the position of the operating mode switch, the CPU switches to RUN, if OB 81 exists, res. remains in STOP. This event is stored in the diagnostic buffer as: "Start overall reset automatically (unbuffered PowerON)".



CAUTION!

After a power reset and with an empty battery the CPU starts with a BAT error and executes an overall reset. The BAT error can be deleted again, if once during power cycle the time between switching on and off the power supply is at least 30sec. and the battery is fully loaded. Otherwise with a short power cycle the BAT error still exists and an overall reset is executed.

5.3 Addressing

5.3.1 Overview

To provide specific addressing of the installed peripheral modules, certain addresses must be allocated in the CPU. At the start-up of the CPU, this assigns automatically peripheral addresses for digital in-/output modules starting with 0 and ascending depending on the slot location. If no hardware project engineering is available, the CPU stores at the addressing analog modules to even addresses starting with 256. Modules at the SPEED-Bus are also taken into account at the automatic address allocation. Here the digital I/Os are stored beginning with address 128 and analog I/Os, FMs and CPs beginning with address 2048.

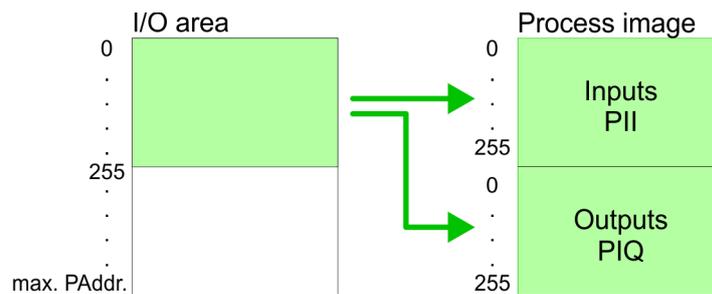
5.3.2 Addressing

Backplane bus periphery

The CPU 317-4NE23 provides an I/O area (address 0 ... max. peripheral address) and a process image of the in- and outputs (each address 0 ... 255). The process image stores the signal states additionally in a separate memory area.

The process image this divided into two parts:

- process image to the inputs (PII)
- process image to the outputs (PIQ)



The process image is updated automatically when a cycle has been completed.

Max. number of pluggable modules

Maximally 8 modules per row may be configured by the CPU 317-4NE23.

For the project engineering of more than 8 modules you may use line interface connections. For this you set in the hardware configurator the module IM 360 from the hardware catalog to slot 3 of your 1. profile rail. Now you may extend your system with up to 3 profile rails by starting each with an IM 361 from Siemens at slot 3. Considering the max total current with the CPU 317-4NE23 from Yaskawa up to 32 modules may be arranged in a row. Here the installation of the line connections IM 360/361 from Siemens is not required.

Further 10 modules at the SPEED-Bus may be connected. CPs and DP masters that are additionally virtual configured at the standard bus are taken into the count of 32 modules at the standard bus.

Define addresses by hardware configuration

You may access the modules with read res. write accesses to the peripheral bytes or the process image.

To define addresses a hardware configuration may be used. For this, click on the properties of the according module and set the wanted address.



CAUTION!

Please take care not to configure a double address assignment at connection via external PROFIBUS DP masters - required for project engineering of a SPEED-Bus system! At external DP master systems, the Siemens hardware configurator does not execute an address check!

Automatic addressing

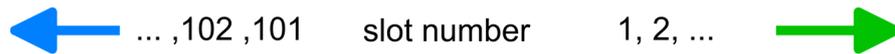
If you do not like to use a hardware configuration, an automatic addressing comes into force. At the automatic address allocation DIOs occupy depending on the slot location always 4byte and AIOs, FMs, CPs always 16byte at the standard bus and 256byte at the SPEED-Bus. Depending on the slot location the start address from where on the according module is stored in the address range is calculated with the following formulas:

Standard-Bus

- DIOs: Start address = $4 \times (\text{slot}-1)$
- AIOs, FMs, CPs: Start address = $16 \times (\text{slot}-1) + 256$

SPEED-Bus

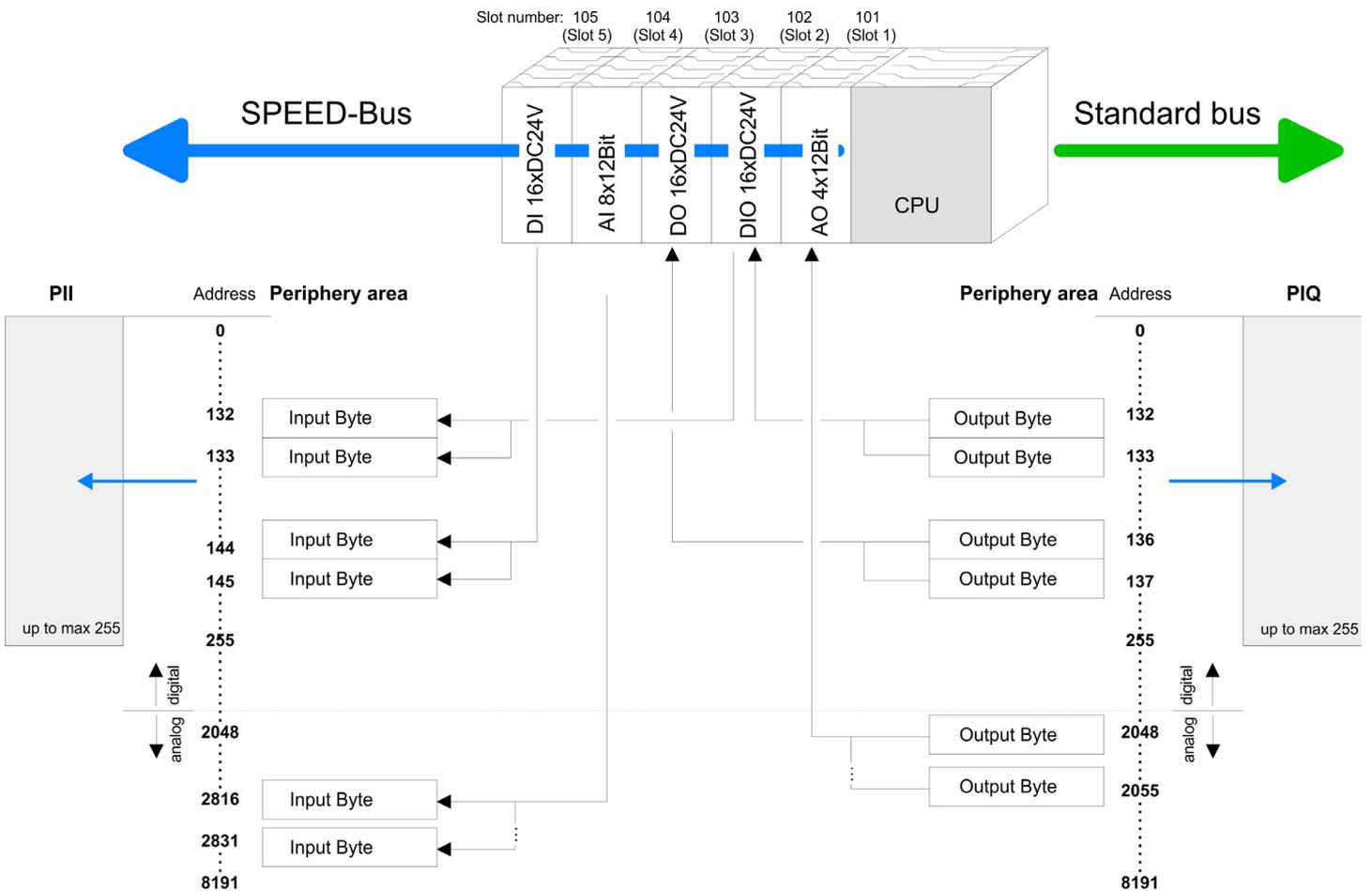
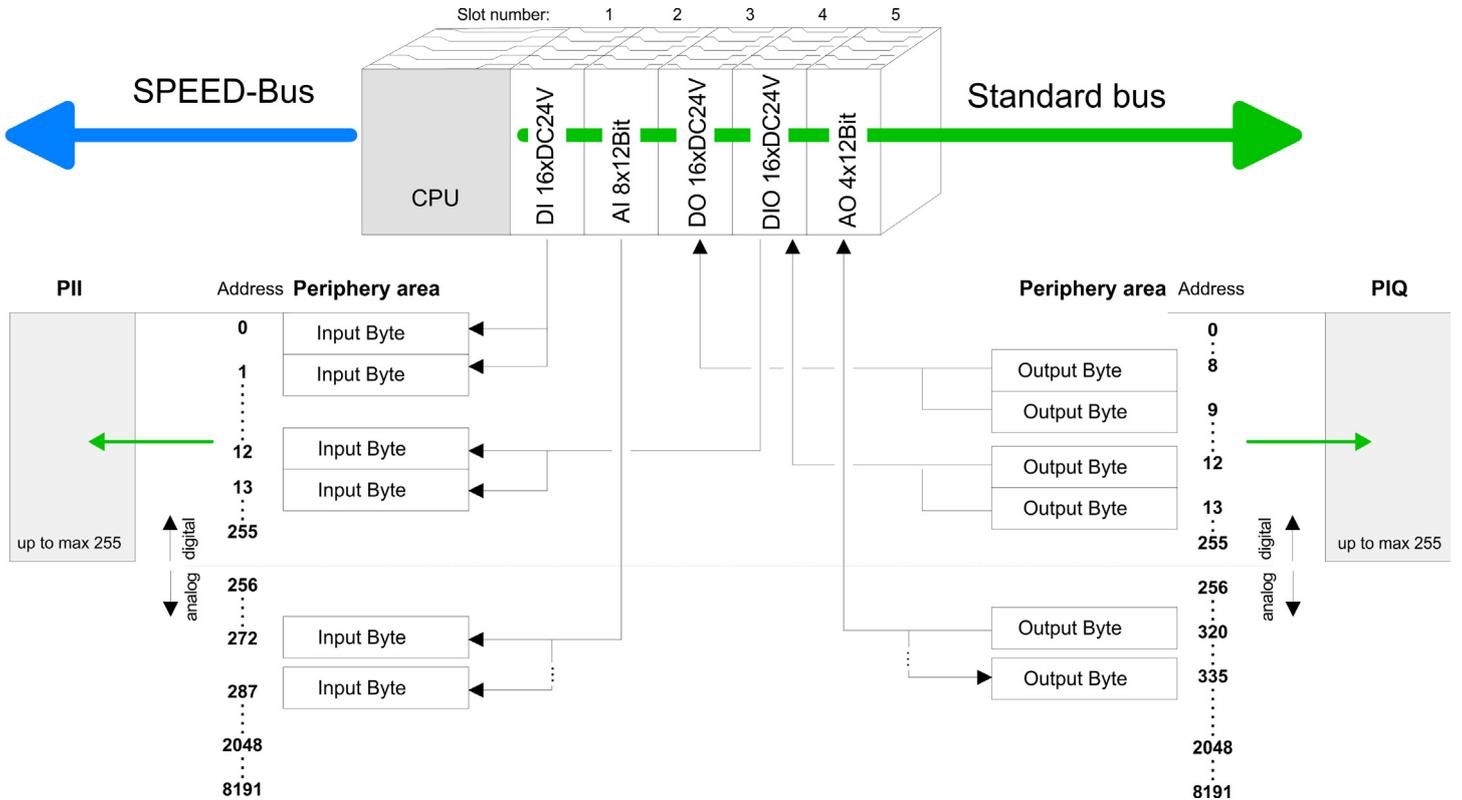
- DIOs: Start address = $4 \times (\text{slot}-101) + 128$
- AIOs, FMs, CPs: Start address = $256 \times (\text{slot}-101) + 2048$



| | 104 | 103 | 102 | 101 | | 1 | 2 | 3 | 4 |
|----------------------|------|------|------|------|------------|-----|-----|-----|-----|
| Start Address | | | | | CPU | | | | |
| digital: | 140 | 136 | 132 | 128 | | 0 | 4 | 8 | 12 |
| analog: | 2816 | 2560 | 2304 | 2048 | | 256 | 272 | 288 | 304 |

Example for automatic address allocation

The following sample shows the functionality of the automatic address allocation separated for standard bus and SPEED-Bus:



5.4 Hardware configuration - CPU

Precondition

The configuration of the CPU takes place at the Siemens *'hardware configurator'*. The hardware configurator is part of the Siemens SIMATIC Manager. It serves for project engineering. The modules, which may be configured here are listed in the hardware catalog. If necessary you have to update the hardware catalog with *'Options → Update Catalog'*.

For project engineering a thorough knowledge of the Siemens SIMATIC Manager and the Siemens hardware configurator is required.



*Please consider that this SPEED7-CPU has 4 ACCUs. After an arithmetic operation (+I, -I, *I, /I, +D, -D, *D, /D, MOD, +R, -R, *R, /R) the content of ACCU 3 and ACCU 4 is loaded into ACCU 3 and 2. This may cause conflicts in applications that presume an unmodified ACCU 2.*

For more information may be found in the manual "VIPA Operation list SPEED7" at "Differences between SPEED7 and 300V programming".

Proceeding

| Slot | Module |
|------|--------------------|
| 1 | |
| 2 | CPU 317-2DP |
| X1 | MPI/DP |
| X2 | DP |
| 3 | |

With the Siemens SIMATIC Manager the following steps should be executed:

1. ➤ Start the Siemens hardware configurator with a new project.
2. ➤ Insert a profile rail from the hardware catalog.
3. ➤ Place at *'Slot'* number 2 the Siemens CPU 317-2DP (6ES7 317-2AK14 V3.3).
4. ➤ The integrated PROFIBUS DP master (X3) is to be configured and connected via the sub module X2 (DP).

5.4.1 Switching CPU type to CPU 318-2AJ00

Overview

To use projects, which were configured with the Siemens CPU type 318-2AJ00, you can switch from original CPU type to CPU type 318-2AJ00 by means of a CMD auto command. The setting is retained even after power cycle, firmware update or battery failure. With reset to factory settings respectively with the corresponding CMD auto command the CPU type is reset to the original CPU type.

Switching

- CPU type 318
 - Switching takes place with the CMD auto command *CPUTYPE_318*. After this perform a power cycle.
 - ↪ *Chap. 5.19 'CMD - auto commands' page 78*

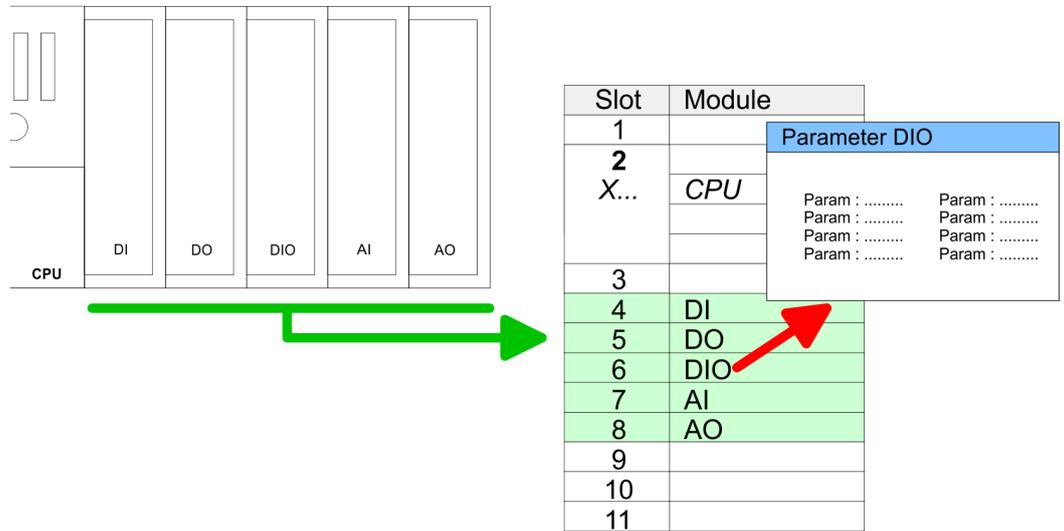
```
CMD_START
CPUTYPE_318
CMD_END
```
- CPU type original
 - The reset to the original type takes place with the CMD auto command *CPU-TYPE_ORIGINAL* respectively by ↪ *Chap. 5.16 'Reset to factory settings' page 75*.
 - ↪ *Chap. 5.19 'CMD - auto commands' page 78*

```
CMD_START
CPUTYPE_ORIGINAL
CMD_END
```

5.5 Hardware configuration - I/O modules

Hardware configuration of the modules

After the hardware configuration place the System 300 modules in the plugged sequence starting with slot 4.



Parametrization

For parametrization double-click during the project engineering at the slot overview on the module you want to parameterize. In the appearing dialog window you may set the wanted parameters. By using the SFCs 55, 56 and 57 you may alter and transfer parameters for wanted modules during runtime. For this you have to store the module specific parameters in so called "record sets". More detailed information about the structure of the record sets is to find in the according module description.

Bus extension with IM 360 and IM 361

For the project engineering of more than 8 modules you may use line interface connections. For this you set in the hardware configurator the module IM 360 from the hardware catalog to slot 3 of your 1. profile rail. Now you may extend your system with up to 3 profile rails by starting each with an IM 361 from Siemens at slot 3. Considering the max. total current with the VIPA SPEED7 CPUs up to 32 modules may be arranged in a row. Here the installation of the line connections IM 360/361 from Siemens is not required.

5.6 Hardware configuration - Ethernet PG/OP channel

Overview

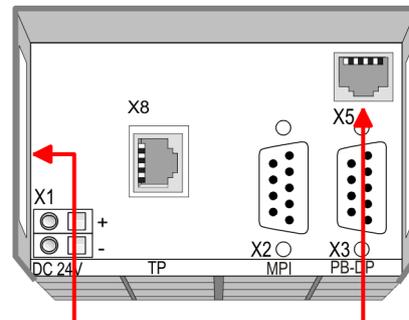
The CPU 317-4NE23 has an integrated Ethernet PG/OP channel. This channel allows you to program and remote control your CPU. The PG/OP channel also gives you access to the internal web page that contains information about firmware version, connected I/O devices, current cycle times etc. With the first start-up respectively after an overall reset the Ethernet PG/OP channel does not have any IP address. For online access to the CPU via Ethernet PG/OP channel valid IP address parameters have to be assigned to this by means of the Siemens SIMATIC Manager. This is called "initialization".

Assembly and commissioning

1. ➤ Install your System 300S with your CPU.
2. ➤ Wire the system by connecting cables for voltage supply and signals.
3. ➤ Connect the Ethernet jack of the Ethernet PG/OP channel to Ethernet
4. ➤ Switch on the power supply.
 - ⇒ After a short boot time the CP is ready for communication. He possibly has no IP address data and requires an initialization.

"Initialization" via PLC functions

The initialization via PLC functions takes place with the following proceeding:



Ethernet address

1. Ethernet PG/OP channel
2. CP 343

PG/OP channel

- Determine the current Ethernet (MAC) address of your Ethernet PG/OP channel. This always may be found as 1. address under the front flap of the CPU on a sticker on the left side.

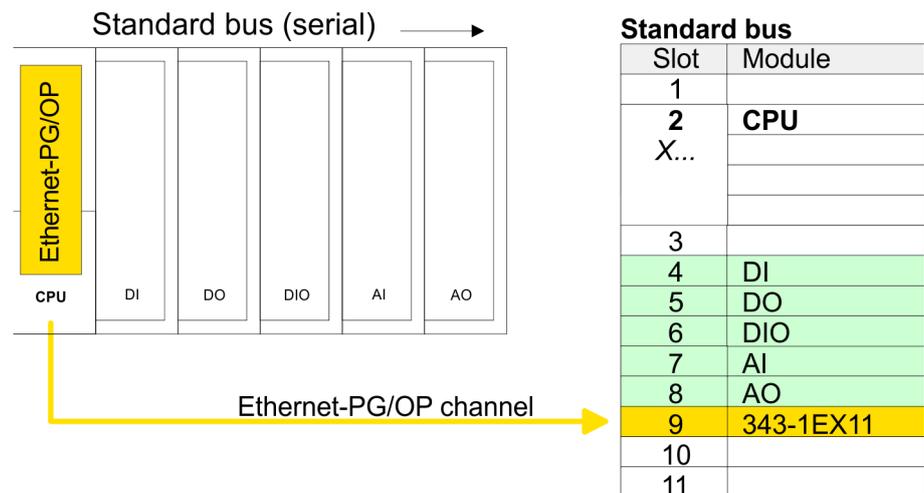
Assign IP address parameters

You get valid IP address parameters from your system administrator. The assignment of the IP address data happens online in the Siemens SIMATIC Manager starting with version V 5.3 & SP3 with the following proceeding:

1. ➤ Start the Siemens SIMATIC Manager and set via 'Options → Set PG/PC interface' the access path to 'TCP/IP -> Network card ...'.
2. ➤ Open with 'PLC → Edit Ethernet Node n' the dialog window with the same name.
3. ➤ To get the stations and their MAC address, use the [Browse] button or type in the MAC Address. The Mac address may be found at the 1. label beneath the front flap of the CPU.
4. ➤ Choose if necessary the known MAC address of the list of found stations.
5. ➤ Either type in the IP configuration like IP address, subnet mask and gateway.
6. ➤ Confirm with [Assign IP configuration].
 - ⇒ Direct after the assignment the Ethernet PG/OP channel may be reached online by these address data. The value remains as long as it is reassigned, it is overwritten by a hardware configuration or an factory reset is executed.

Take IP address parameters in project

1. ➤ Open the Siemens hardware configurator und configure the Siemens CPU 317-2DP (6ES7 317-2AK14 V3.3).
2. ➤ Configure the modules at the standard bus.
3. ➤ For the Ethernet PG/OP channel you have to configure a Siemens CP 343-1 (SIMATIC 300 \ CP 300 \ Industrial Ethernet \ CP 343-1 \ 6GK7 343-1EX11 0XE0) always below the really plugged modules.
4. ➤ Open the property window via double-click on the CP 343-1EX11 and enter for the CP at 'Properties' the IP address data, which you have assigned before.
5. ➤ Assign the CP to a 'Subnet'. Without assignment the IP address data are not used!
6. ➤ Transfer your project.



5.7 Hardware configuration - Communication

The hardware configuration is described at the following pages:

- ↪ Chap. 7.4 'Deployment as PROFIBUS DP master' page 101
- ↪ Chap. 7.5 'Deployment as PROFIBUS DP slave' page 102
- ↪ Chap. 6.3 'Deployment of RS485 interface for PtP' page 84
- ↪ Chap. 8.9 'Hardware configuration - CP 343' page 120

5.8 Hardware configuration - SPEED-Bus

5.8.1 Preconditions

Since the VIPA specific CPU parameters may be set and the modules at the SPEED-Bus may be configured, the installation of the SPEEDBUS.GSD from VIPA in the hardware catalog is necessary. The CPU and its SPEED-Bus modules may be configured in a PROFIBUS master after installation.

Installation of the SPEEDBUS.GSD

The GSD (Geräte-Stamm-Datei) is online available in the following language versions. Further language versions are available on inquire:

| Name | Language |
|--------------|------------------|
| SPEEDBUS.GSD | German (default) |
| SPEEDBUS.GSG | German |
| SPEEDBUS.GSE | English |

The GSD files may be found at www.yaskawa.eu.com at the service area.

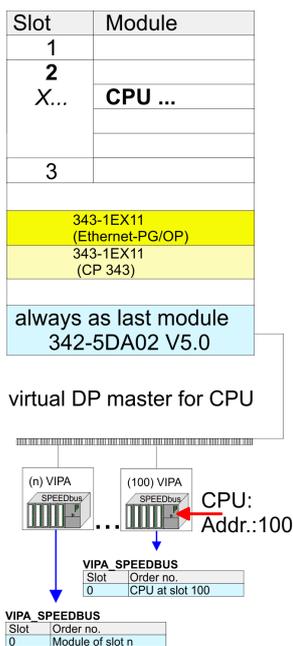
The integration of the SPEEDBUS.GSD takes place with the following proceeding:

1. ➤ Go to the service area of www.yaskawa.eu.com.
2. ➤ Load from the download area at 'Config files → PROFIBUS' the according file for your System 300S.
3. ➤ Extract the file to your work directory.
4. ➤ Start the hardware configurator from Siemens.
5. ➤ Close every project.
6. ➤ Select 'Options → Install new GSD-file'.
7. ➤ Navigate to the directory VIPA_System_300S and select **SPEEDBUS.GSD** an.
 - ⇒ The SPEED7 CPUs and modules of the System 300S from Yaskawa may now be found in the hardware catalog at PROFIBUS-DP / Additional field devices / I/O / VIPA_SPEEDBUS.

5.8.2 Proceeding

The embedding of the CPU 317-4NE23 and its modules at the SPEED-Bus happens by means of a virtual PROFIBUS master system with the following approach:

1. ➤ Perform a hardware configuration for the CPU. ↪ *Chap. 5.4 'Hardware configuration - CPU' page 47*
2. ➤ Since the SPEED-Bus modules are to be linked as a virtual PROFIBUS system, configure always as last module a Siemens DP master CP 342-5 (342-5DA02 V5.0). Link the DP master to a new PROFIBUS net and switch it to DP master operating mode.
3. ➤ To this master system you assign every SPEED-Bus module as "VIPA_SPEEDBUS" slave starting with the CPU. Here the PROFIBUS address corresponds to the slot number beginning with 100 for the CPU. Place at slot 0 of every slave the assigned module



Due to the fact that some SPEED-Bus CPs from VIPA are similar in project engineering and parametrization to the corresponding CP from Siemens, for each SPEED-Bus CP a corresponding Siemens CP is to be placed and linked at the standard bus.

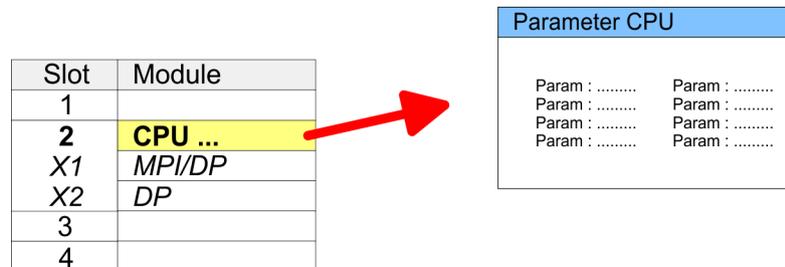
More information about the configuration of the according SPEED-Bus module may be found in the according manual.

5.9 Setting standard CPU parameters

5.9.1 Parameterization via Siemens CPU

Parameterization via Siemens CPU

Since the CPU is to be configured as Siemens CPU 317-2DP (6ES7 317-2AK14 V3.3) in the Siemens hardware configurator, the standard parameters of the VIPA CPU may be set with "Object properties" of the CPU 317-2 DP during hardware configuration. Via a double-click on the CPU 317-2 DP the parameter window of the CPU may be accessed. Using the registers you get access to every standard parameter of the CPU.



5.9.2 Parameters CPU

Supported parameters

The CPU does not evaluate each parameter, which may be set at the hardware configuration. The following parameters are supported by the CPU at this time:

General

- Short description: The short description of the Siemens CPU is CPU 317-2DP (6ES7 317-2AK14 V3.3).
- Order No. / Firmware: Order number and firmware are identical to the details in the "hardware catalog" window.
- Name: The Name field provides the short description of the CPU. If you change the name the new name appears in the Siemens SIMATIC Manager.
- Plant designation: Here is the possibility to specify a plant designation for the CPU. This plant designation identifies parts of the plant according to their function. Its structure is hierarchic according to IEC 1346-1.
- Comment: In this field information about the module may be entered.

Startup

- Startup when expected/actual configuration differs: If the checkbox for '*Startup when expected/actual configuration differ*' is deselected and at least one module is not located at its configured slot or if another type of module is inserted there instead, then the CPU does not switch to RUN mode and remains in STOP mode. If the checkbox for '*Startup when expected/actual configuration differ*' is selected, then the CPU starts even if there are modules not located in their configured slots or if another type of module is inserted there instead, such as during an initial system start-up.
- Monitoring time for ready message by modules [100ms]: This operation specifies the maximum time for the ready message of every configured module after PowerON. Here connected PROFIBUS DP slaves are also considered until they are parameterized. If the modules do not send a ready message to the CPU by the time the monitoring time has expired, the actual configuration becomes unequal to the preset configuration. Monitoring time for ready message by modules [100ms]
- Transfer of parameters to modules [100ms]: The maximum time for the transfer of parameters to parameterizable modules. If not every module has been assigned parameters by the time this monitoring time has expired; the actual configuration becomes unequal to the preset configuration.

Cycle/Clock memory

- Update OB1 process image cyclically: This parameter is not relevant.
- Scan cycle monitoring time: Here the scan cycle monitoring time in milliseconds may be set. If the scan cycle time exceeds the scan cycle monitoring time, the CPU enters the STOP mode.
Possible reasons for exceeding the time are:
 - Communication processes
 - a series of interrupt events
 - an error in the CPU program
- Minimum scan cycle time: This parameter is not relevant.
- Scan cycle load from Communication: This parameter is not relevant.
- Size of the process image input/output area: Here the size of the process image max. 2048 for the input/output periphery may be fixed.
- OB85 call up at I/O access error: The preset reaction of the CPU may be changed to an I/O access error that occurs during the update of the process image by the system. The VIPA CPU is preset such that OB 85 is not called if an I/O access error occurs and no entry is made in the diagnostic buffer either.
- Clock memory: Activate the check box if you want to use clock memory and enter the number of the memory byte.



The selected memory byte cannot be used for temporary data storage.

Retentive Memory

- Number of Memory bytes from MB0: Enter the number of retentive memory bytes from memory byte 0 onwards.
- Number of S7 Timers from T0: Enter the number of retentive S7 timers from T0 onwards. Each S7 timer occupies 2bytes.
- Number of S7 Counters from C0: Enter the number of retentive S7 counter from C0 onwards.
- Areas: This parameter is not supported.

Interrupts

- Priority: Here the priorities are displayed, according to which the hardware interrupt OBs are processed (hardware interrupt, time-delay interrupt, async. error interrupts).

Time-of-day interrupts

- Priority: Here the priorities may be specified according to which the time-of-day interrupt is processed. With priority "0" the corresponding OB is deactivated.
- Active: Activate the check box of the time-of-day interrupt OBs if these are to be automatically started on complete restart.
- Execution: Select how often the interrupts are to be triggered. Intervals ranging from every minute to yearly are available. The intervals apply to the settings made for *start date and time*.
- Start date/time: Enter date and time of the first execution of the time-of-day interrupt.
- Process image partition: This parameter is not supported.

Cyclic interrupts

- Priority: Here the priorities may be specified according to which the corresponding cyclic interrupt is processed. With priority "0" the corresponding interrupt is deactivated.
- Execution: Enter the time intervals in ms, in which the watchdog interrupt OBs should be processed. The start time for the clock is when the operating mode switch is moved from STOP to RUN.

- Phase offset: Enter the delay time in ms for current execution for the watch dog interrupt. This should be performed if several watchdog interrupts are enabled. Phase offset allows to distribute processing time for watchdog interrupts across the cycle.
- Process image partition: This parameter is not supported.

Diagnostics/Clock

- Report cause of STOP: Activate this parameter, if the CPU should report the cause of STOP to PG respectively OP on transition to STOP.
- Number of messages in the diagnostics buffer: Here the number of diagnostics are displayed, which may be stored in the diagnostics buffer (circular buffer).
- Synchronization type: Here you specify whether clock should synchronize other clocks or not.
 - as slave: The clock is synchronized by another clock.
 - as master: The clock synchronizes other clocks as master.
 - none: There is no synchronization
- Time interval: Time intervals within which the synchronization is to be carried out.
- Correction factor: Lose or gain in the clock time may be compensated within a 24 hour period by means of the correction factor in ms. If the clock is 1s slow after 24 hours, you have to specify a correction factor of "+1000" ms.

Protection

- Level of protection: Here 1 of 3 protection levels may be set to protect the CPU from unauthorized access.
 - *Protection level 1 (default setting):*
No password adjustable, no restrictions
 - *Protection level 2 with password:*
Authorized users: read and write access
Unauthorized user: read access only
 - *Protection level 3:*
Authorized users: read and write access
Unauthorized user: no read and write access

5.9.3 Parameters for DP

The properties dialog of the PROFIBUS part is opened via a double click to the sub module DP.

General

- Short description: Here the short description "DP" for PROFIBUS DP is specified.
- Order no.: Nothing is shown here.
- Name: Here "DP" is shown. If you change the name, the new name appears in the Siemens SIMATIC Manager.
- Interface: The PROFIBUS address is shown here.
- Properties: With this button the properties of the PROFIBUS DP interface may be preset.
- Comment: You can enter the purpose of the PROFIBUS interface.

Address

- Diagnostics: A diagnostics address for PROFIBUS DP is to be preset here. In the case of an error the CPU is informed via this address.
- Operating mode: Here the operating mode of the PROFIBUS part may be preset. More may be found at chapter "Deployment PROFIBUS Communication".
- Configuration: Within the operating mode "DP-Slave" you may configure your slave system. More may be found at chapter "Deployment PROFIBUS communication".
- Clock: These parameters are not supported.

5.9.4 Parameters for MPI/DP

The properties dialog of the MPI interface is opened via a double click to the sub module MPI/DP.

General

- Short description: Here the short description "MPI/DP" for the MPI interface is specified.
- Order no.: Nothing is shown here.
- Name: At *Name* "MPI/DP" for the MPI interface is shown. If you change the name, the new name appears in the Siemens SIMATIC Manager.
- Type: Please regard only the type "MPI" is supported by the VIPA CPU.
- Interface: Here the MPI address is shown.
- Properties: With this button the properties of the MPI interface may be preset.
- Comment: You can enter the purpose of the MPI interface.

Address

- Diagnostics: A diagnostics address for the MPI interface is to be preset here. In the case of an error the CPU is informed via this address.
- Operating mode, Configuration, Clock: These parameters are not supported.

5.10 Setting VIPA specific CPU parameters

5.10.1 Proceeding

Overview

Except of the VIPA specific CPU parameters the CPU parameterization takes place in the parameter dialog of the CPU from Siemens. With installing of the SPEEDBUS.GSD the VIPA specific parameters may be set during hardware configuration. Here the following parameters may be accessed:

- Function RS485 X3 (PtP, Synchronization between DP master and CPU)
- Token Watch
- Number remanence flag, timer, counter
- Priority OB 28, OB 29, OB 33, OB 34
- Execution OB 33, OB 34
- Phase offset OB 33, OB 34
- Call OB 80 on cyclic interrupt error

Requirements

Since the VIPA specific CPU parameters may be set, the installation of the SPEEDBUS.GSD from VIPA in the hardware catalog is necessary. The CPU may be configured in a PROFIBUS master system and the appropriate parameters may be set after installation.

Installation of the SPEEDBUS.GSD

The GSD (Geräte-Stamm-Datei) is online available in the following language versions. Further language versions are available on inquires:

| Name | Language |
|--------------|------------------|
| SPEEDBUS.GSD | German (default) |
| SPEEDBUS.GSG | German |
| SPEEDBUS.GSE | English |

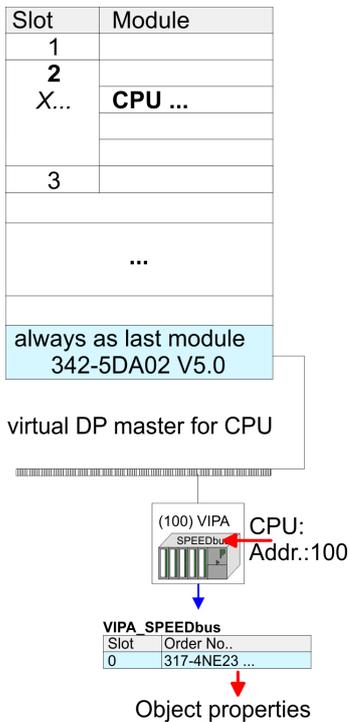
The GSD files may be found at www.yaskawa.eu.com at the service area.

The integration of the SPEEDBUS.GSD takes place with the following proceeding:

1. ➤ Go to the service area of www.yaskawa.eu.com.
2. ➤ Load from the download area at 'Config files → PROFIBUS' the according file for your System 300S.
3. ➤ Extract the file to your work directory.
4. ➤ Start the hardware configurator from Siemens.
5. ➤ Close every project.
6. ➤ Select 'Options → Install new GSD-file'.
7. ➤ Navigate to the directory VIPA_System_300S and select **SPEEDBUS.GSD** an.
 - ⇒ The SPEED7 CPUs and modules of the System 300S from Yaskawa may now be found in the hardware catalog at PROFIBUS-DP / Additional field devices / I/O / VIPA_SPEEDBUS.

Hardware configuration

The embedding of the CPU 317-4NE23 happens by means of a virtual PROFIBUS master system with the following approach:



1. ➤ Perform a hardware configuration for the CPU. ↪ Chap. 5.4 'Hardware configuration - CPU' page 47
2. ➤ Configure always as last module a Siemens DP master CP 342-5 (342-5DA02 V5.0). Connect and parameterize it at operation mode "DP-Master".
3. ➤ Connect the slave system "VIPA_SPEEDbus". After installing the SPEEDBUS.GSD this may be found in the hardware catalog at Profibus-DP / Additional field devices / I/O / VIPA / VIPA_SPEEDBUS.
4. ➤ For the slave system set the PROFIBUS address 100.
5. ➤ Configure at slot 0 the VIPA CPU 317-4NE23 of the hardware catalog from VIPA_SPEEDbus.
6. ➤ By double clicking the placed CPU 317-4NE23 the properties dialog of the CPU may be opened.

The hardware configuration, which is shown here, is only required, if you want to customize the VIPA specific parameters.

5.10.2 Yaskawa specific parameters

The following parameters may be accessed by means of the properties dialog of the Yaskawa CPU.

5.10.2.1 Function RS485 X3

Using this parameter the RS485 interface may be switched to PtP communication (point to point) respectively the synchronization between DP master system and CPU may be set:

| | |
|----------------------------|---|
| Deactivated | Deactivates the RS485 interface. |
| PtP | With this operating mode the PROFIBUS DP master is deactivated and the RS485 interface acts as an interface for serial point-to-point communication. Here data may be exchanged between two stations by means of protocols. |
| PROFIBUS DP async | PROFIBUS DP master operation asynchronous to CPU cycle The RS485 interface is preset at default to PROFIBUS DP async. Here CPU cycle and cycles of every Yaskawa PROFIBUS DP master run independently. |
| PROFIBUS DP syncIn | The CPU is waiting for DP master input data. |
| PROFIBUS DP syncOut | The DP master system is waiting for CPU output data. |
| PROFIBUS DP syncInOut | CPU and DP master system are waiting on each other and form thereby a cycle. |
| Default: PROFIBUS DP async | |

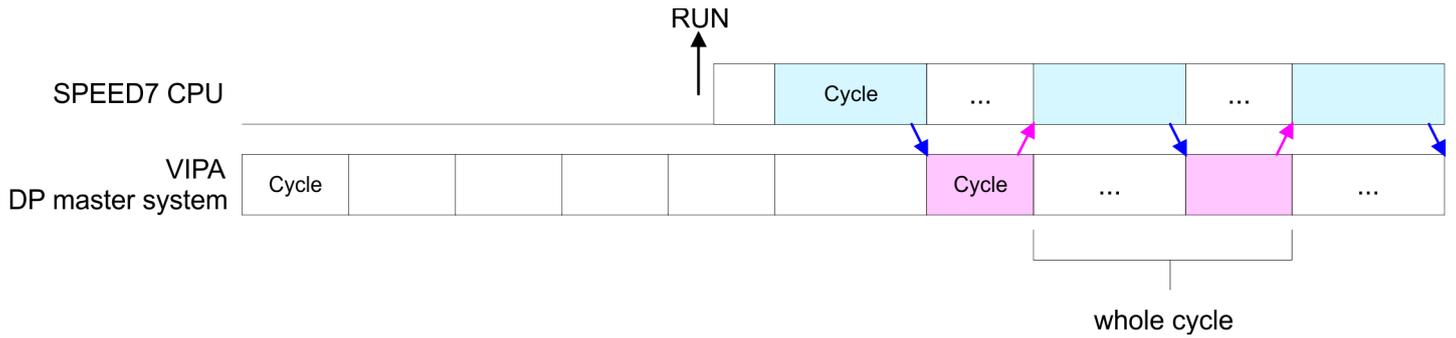
5.10.2.1.1 Synchronization between master system and CPU

Overview

Normally the cycles of CPU and DP master run independently. The cycle time of the CPU is the time needed for one OB1 cycle and for reading respectively writing the inputs respectively outputs. The cycle time of a DP master depends among others on the number of connected slaves and the baud rate, thus every plugged DP master has its own cycle time. Due to the asynchronism of CPU and DP master the whole system gets relatively high response times. The synchronization behavior between every Yaskawa PROFIBUS DP master and the CPU may be configured by means of a hardware configuration as shown above. The different modes for the synchronization are in the following described.

PROFIBUS DP SyncInOut

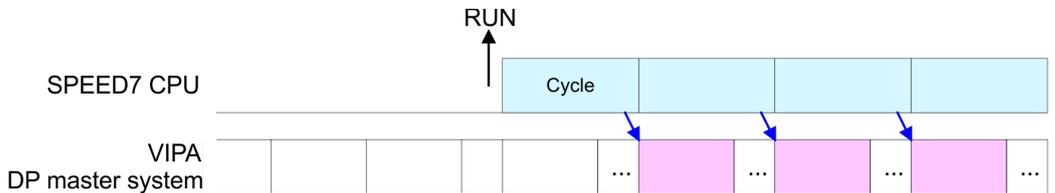
In PROFIBUS DP SyncInOut mode CPU and DP master system are waiting on each other and form thereby a cycle. Here the whole cycle is the sum of the longest DP master cycle and CPU cycle. By this synchronization mode you receive global consistent in-/output data, since within the total cycle the same input and output data are handled successively by CPU and DP master system. If necessary the time of the Watchdog of the bus parameters should be increased at this mode.



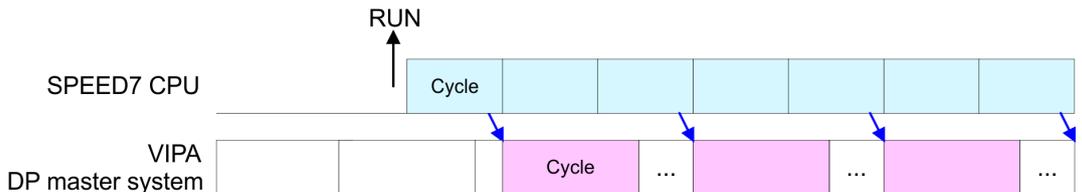
PROFIBUS DP SyncOut

In this operating mode the cycle time of the Yaskawa DP master system depends on the CPU cycle time. After CPU start-up the DP master gets synchronized. As soon as their cycle is passed they wait for the next synchronization impulse with output data of the CPU. So the response time of your system can be improved because output data were directly transmitted to the DP master system. If necessary the time of the Watchdog of the bus parameters should be increased at this mode.

**Cycle CPU > DPM
"1-tier CPU cycle"**



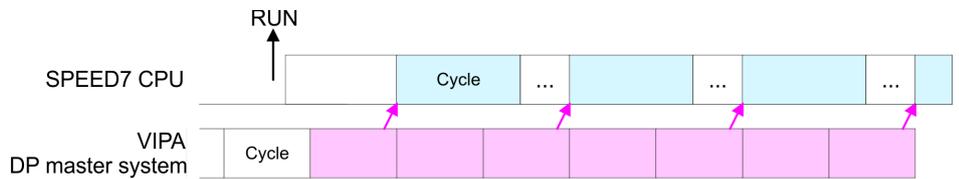
**Cycle CPU < DPM
"n-tier CPU cycle"**



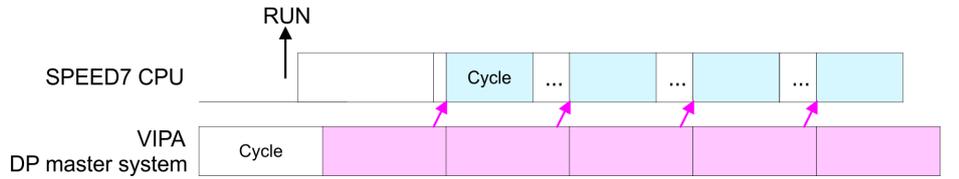
PROFIBUS-DP SyncIn

In the operating mode PROFIBUS DP SyncIn the CPU cycle is synchronized to the cycle of the Yaskawa PROFIBUS DP master system. Here the CPU cycle depends on the Yaskawa DP master with the longest cycle time. If the CPU gets into RUN it is synchronized with each PROFIBUS DP master. As soon as the CPU cycle is passed, it waits for the next synchronization impulse with input data of the DP master system. If necessary the Scan Cycle Monitoring Time of the CPU should be increased.

**Cycle CPU > DPM
"n-tier longest DP master cycle"**



**Cycle CPU < DPM
"1-tier longest DP master cycle"**



5.10.2.2 Token Watch

By presetting the PROFIBUS bus parameters within the hardware configuration a token time for the PROFIBUS results. The token time defines the duration until the token reaches the DP master again. Per default this time is supervised. Due to this monitoring disturbances on the bus can affect a reboot of the DP master. Here with the parameter Token Watch the monitoring of the token time can be switched off respectively on.

Default: On

5.10.2.3 Number remanence flag

Here the number of flag bytes may be set. With 0 the value Retentive memory > Number of memory bytes starting with MB0 set at the parameters of the Siemens CPU is used. Otherwise the adjusted value (1 ... 8192) is used. Default: 0

5.10.2.4 Phase offset and execution of OB 33 and OB 34

The CPU offers additional cyclic interrupts, which interrupt the cyclic processing in certain distances. Point of start of the time interval is the change of operating mode from STOP to RUN. To avoid that the cyclic interrupts of different cyclic interrupt OBs receive a start request at the same time and so a time out may occur, there is the possibility to set a phase offset respectively a time of execution.

- The *phase offset* (0 ... 60000ms) serves for distribution processing times for cyclic interrupts across the cycle. Default: 0
- The time intervals, in which the cyclic interrupt OB should be processed may be entered with *execution* (1 ... 60000ms). Default: OB 33: 500ms, OB 34: 200ms

5.10.2.5 Priority of OB 28, OB 29, OB 33 and OB 34

The priority fixes the order of interrupts of the corresponding interrupt OB. Here the following priorities are supported: 0 (Interrupt-OB is deactivated), 2, 3, 4, 9, 12, 16, 17, 24. Default: 24

5.10.2.6 Call OB 80 on cyclic interrupt error

Once during a cyclic interrupt OB (OB 28, 29, 32 ... 35) the same cyclic interrupt is requested, the interrupt requests are collected and processed sequentially. Via the parameter '*OB 80 for cyclic interrupt*' you can set here for the corresponding cyclic interrupt group that on a cyclic interrupt instead of the sequential processing the OB 80 is to be called. With this parameter you have the following settings:

- Deactivated (default)
 - At a cyclic interrupt error the interrupt requests are collected and processed sequentially.
- for OB...
 - At a cyclic interrupt error of the corresponding cyclic interrupt OB, the OB 80 is called.

5.11 Project transfer

Overview

There are the following possibilities for project transfer into the CPU:

- Transfer via MPI/PROFIBUS
- Transfer via Ethernet
- Transfer via memory card

5.11.1 Transfer via MPI/PROFIBUS

General

For transfer via MPI/PROFIBUS the CPU has the following interface:

- X2: MPI interface
- X3: PROFIBUS interface

Net structure

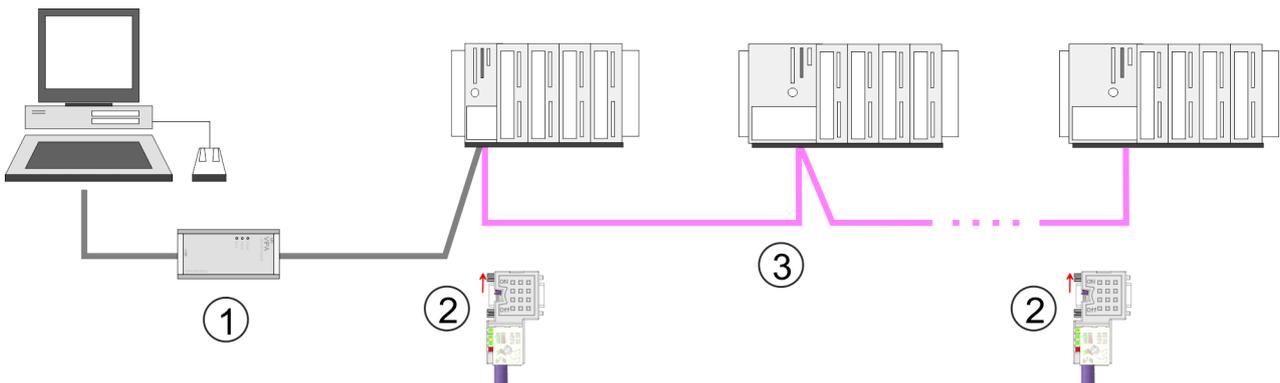
The structure of a MPI net is electrically identical with the structure of a PROFIBUS net. This means the same rules are valid and you use the same components for the build-up. The single participants are connected with each other via bus interface plugs and PROFIBUS cables. Per default the MPI net runs with 187.5kbaud. Yaskawa CPUs are delivered with MPI address 2.

MPI programming cable

The MPI programming cables are available at Yaskawa in different variants. The cables provide a RS232 res. USB plug for the PC and a bus enabled RS485 plug for the CPU. Due to the RS485 connection you may plug the MPI programming cables directly to an already plugged plug on the RS485 jack. Every bus participant identifies itself at the bus with an unique address, in the course of the address 0 is reserved for programming devices.

Terminating resistor

A cable has to be terminated with its surge impedance. For this you switch on the terminating resistor at the first and the last participant of a network or a segment. Please make sure that the participants with the activated terminating resistors are always power supplied. Otherwise it may cause interferences on the bus.



- 1 MPI programming cable
- 2 Activate the terminating resistor via switch
- 3 MPI network

Proceeding transfer via MPI interface

1. ➤ Connect your PC to the MPI jack of your CPU via a MPI programming cable.
2. ➤ Load your project in the Siemens SIMATIC Manager.
3. ➤ Choose in the menu 'Options ➔ Set PG/PC interface'.
4. ➤ Select in the according list the "PC Adapter (MPI)"; if appropriate you have to add it first, then click on [Properties].

5. ➤ Set in the register MPI the transfer parameters of your MPI net and type a valid *address*.
6. ➤ Switch to the register *Local connection*.
7. ➤ Set the COM port of the PC and the transfer rate 38400baud for the MPI programming cable.
8. ➤ Transfer your project via '*PLC → Load to module*' via MPI to the CPU and save it with '*PLC → Copy RAM to ROM*' on a memory card if one is plugged.

Proceeding transfer via PROFIBUS interface

1. ➤ Connect your PC to the PROFIBUS jack of your CPU via a MPI programming cable.
2. ➤ Load your project in the Siemens SIMATIC Manager.
3. ➤ Choose in the menu '*Options → Set PG/PC interface*'.
4. ➤ Select in the according list the "PC Adapter (PROFIBUS)"; if appropriate you have to add it first, then click at [Properties].
5. ➤ Set in the register PROFIBUS the transfer parameters of your PROFIBUS net and enter a valid *PROFIBUS address*. The *PROFIBUS address* must be assigned to the DP master by a project before.
6. ➤ Switch to the register *Local connection*.
7. ➤ Set the COM port of the PC and the transfer rate 38400baud for the MPI programming cable.
8. ➤ Transfer your project via '*PLC → Load to module*' via PROFIBUS to the CPU and save it with '*PLC → Copy RAM to ROM*' on a memory card if one is plugged.



Transfer via PROFIBUS is available by DP master, if projected as master and assigned with a PROFIBUS address before.

Within selecting the slave mode you have additionally to select the option "Test, commissioning, routing".

5.11.2 Transfer via Ethernet

For transfer via Ethernet the CPU has the following interface:

- X5: Ethernet PG/OP channel
- X8: CP 343 communication processor

Initialization

So that you may access the Ethernet PG/OP channel you have to assign IP address parameters by means of the "initialization". ↪ '*Assign IP address parameters*' page 49,

Transfer

1. ➤ For the transfer, connect, if not already done, the appropriate Ethernet port to your Ethernet.
2. ➤ Open your project with the Siemens SIMATIC Manager.
3. ➤ Set via '*Options → Set PG/PC Interface*' the access path to "TCP/IP → Network card".
4. ➤ Click to '*PLC → Download*' Download → the dialog "Select target module" is opened. Select your target module and enter the IP address parameters of the Ethernet PG/OP channel for connection. Provided that no new hardware configuration is transferred to the CPU, the entered Ethernet connection is permanently stored in the project as transfer channel.

5. ➤ With [OK] the transfer is started.



System dependent you get a message that the projected system differs from target system. This message may be accepted by [OK].

→ Your project is transferred and may be executed in the CPU after transfer.

5.11.3 Transfer via memory card

Proceeding transfer via memory card

The memory card serves as external storage medium. There may be stored several projects and sub-directories on a memory card. Please regard that your current project is stored in the root directory and has one of the following file names:

- S7PROG.WLD
- AUTOLOAD.WLD

1. ➤ Start the Siemens SIMATIC Manager with your project.
2. ➤ Create with 'File → Memory Card File → New' a new wld file.
3. ➤ Copy the blocks from the project blocks folder and the *System data* into the wld file.
4. ➤ Copy the wld file at a suited memory card. Plug this into your CPU and start it again.

⇒ The transfer of the application program from the memory card into the CPU takes place depending on the file name after an overall reset or PowerON.

S7PROG.WLD is read from the memory card after overall reset.

AUTOLOAD.WLD is read from the memory card after PowerON.

The short flashing of the MC LED of the CPU indicates the transfer process. Please regard that your user memory serves for enough space for your user program, otherwise your user program is not completely loaded and the SF LED gets on.

5.12 Accessing the web server

Access to the web server



There is a web server, which can be accessed via the IP address of the Ethernet PG/OP channel with an Internet browser. At the web page information about the CPU and its connected modules can be found. [Chap. 5.6 'Hardware configuration - Ethernet PG/OP channel' page 49](#)

It is assumed that there is a connection between PC and CPU with Internet browser via the Ethernet PG/OP channel. This may be tested by Ping to the IP address of the Ethernet PG/OP channel.

Structure of the web page

The web page is built dynamically and depends on the number of modules, which are connected to the CPU. The web page only shows information. The shown values cannot be changed.

Info - Overview

CPU

| Name | Value |
|---------------|-----------|
| Ordering Info | 317-4NE23 |
| Serial | 26164 |
| Version | 01V00 |
| HW Revision | 01 |
| Software | 3.5.9.14 |

Here order number, serial number and the version of firmware and hardware of the CPU are listed. [Expert View] takes you to the advanced "Expert View".

Info - Expert View

| Runtime Information | | |
|-----------------------|--|---|
| Operation Mode | STOP | CPU: Status information |
| Mode Switch | RUNP | |
| System Time | 01.09.09 00:35:30:812 | CPU: Date, time |
| OB1-Cycle Time | cur = 0us, min = 0us, max = 0us, avg = 0us | CPU: Cyclic time: min = minimum cur = current max = maximum avg = average |
| Interface Information | | |
| X2 (RS485/COM1) | MPI | Operating mode RS485 ■ MPI: MPI operation |

Accessing the web server

| | | | |
|---------------------------------------|---|---|--|
| X3 (RS485/COM2) | PtP | ■ DPM: DP master operation or PtP: point to point operation | |
| X5 | PG/OP Ethernet Port | | |
| Card Information | | | |
| Type | SD | | |
| Product S/N | 6BC34010 | | |
| Size | 493617152 bytes | | |
| Free | 492355584 bytes | | |
| Active Feature Set Information | | | |
| Status | Memory Extension present | | |
| Memory Usage | | | |
| LoadMem | 0 / 8388608 Bytes | CPU: Information to memory configuration Load memory, working memory (code/data) | |
| WorkMemCode | 0 / 2097152 Bytes | | |
| WorkMemData | 0 / 2097152 Bytes | | |
| PG/OP Network Information | | | |
| Device Name | Yaskawa 317-4NE23 CPU | Ethernet PG/OP channel: | |
| IP Address | 172.16.129.210 | Address information | |
| Subnet Mask | 255.255.255.0 | | |
| Gateway Address | 172.16.129.210 | | |
| MAC Address | 00:20:D5:77:30:36 | | |
| CPU Firmware Information | | | |
| File System | V1.0.2 | Information for the support | |
| PRODUCT | Yaskawa 317-4NE23 V3.7.3 Px000282.pkg | Name, firmware version, package | |
| HARDWARE | V0.1.0.0 5679H-V20 HX000027.110 | CPU: Information for the support | |
| Bx000227 | V6.6.29.255 | | |
| Ax000086 | V1.2.1.0 | | |
| Ax000056 | V0.2.2.0 | | |
| fx000007.wld | V1.1.8.0 | | |
| ARM Processor Load | | | |
| Last Value | 0% | | |
| Maximum load | 41% | | |

Data

Currently nothing is displayed here.

Parameter

Currently nothing is displayed here.

IP

Here the IP address data of your Ethernet PG/OP channel are shown.

Info - Overview

DP master

Info - Expert View

| Internal Information | Slot 201 | Yaskawa 342-1DA70 |
|------------------------------------|--|--|
| Module Type | 0xCB2C0010 | |
| Module Firmware Information | | |
| PRODUCT | Yaskawa 342-1DA70 V3.3.5 Px000182.pkg | Name, firmware-version, package |
| BB000218 | V5.3.0.0 | Information for support |
| AB000068 | V4.1.7.0 | |
| Runtime Information | | |
| Cycle Time | cur = 0us, min = 65535000us, max = 0us, avg = 0us, cnt = 0 | CPU cycle time: min = minimal cur = current max = maximal |

Accessing the web server

Info - Overview

CP 343

Slot100 (VIPA 31x-xxxx CPU)
System: (SPEED-Bus)
Slot201 (VIPA)
• Slot 206 (VIPA 31x-xxx)
System: (VBUS/KBUS)
...

| Name | Value |
|---------------|----------------|
| Ordering Info | VIPA 31x-xxxxx |
| Version | V1.1.0 |

[\[Expert View ... \]](#)

Info - Expert View

| Internal Information | | CPU component: CP 343 |
|------------------------------------|---|-------------------------|
| Module Type | 0xACDB0080 | Information for support |
| Module Firmware Information | | |
| Bb000429 | V1.1.0.12 | |
| AB000125 | V0.1.0.3 | |
| PRODUCT | Yaskawa 317-4NE23 V3.1.1 Px000299.pkg | |
| Hx000075 | V1.1.0.0 | |

Info - Overview

SPEED-Bus modules

Slot100 (VIPA 31x-xxxx CPU)
System: (SPEED-Bus)
• Slot 101 (VIPA 321-1BH70)
Slot 102 (VIPA 322-1BH70)
System: (VBUS/KBUS)
...

Info Data

Device (VIPA 321-1BH70) information

| Name | Value |
|---------------|----------------|
| Ordering Info | VIPA 321-1BH70 |
| Version | V1.0.3 |

[Expert View ...]

Info - Expert View

| Internal Information | | 321-1BH70 |
|-----------------------------|--|---------------------------------|
| Module Type | 0x1FC20001 | Information for support |
| Module Firmware Information | | |
| BB000189 | V1.0.1.0 | |
| AB000076 | V1.0.2.0 | |
| PRODUCT | VIPA 321-1BH70 V1.0.3.0 Px000029.pkg | Name, firmware-version, package |
| Hx000013 | V1.1.0.0 | |

Data - Input data

| Offset | Width | Value (dec) | Value (hex) |
|--------|-------|-------------|-------------|
| 132 | 1 | 0 | 00 |
| 133 | 1 | 0 | 00 |
| 134 | 1 | 0 | 00 |
| 135 | 1 | 0 | 00 |

Info - Expert View

| Internal Information | | 322-1BH70 |
|-----------------------------|------------|-------------------------|
| Module Type | 0xAFD00001 | Information for support |
| Module Firmware Information | | |
| BB000190 | V1.0.1.0 | |
| AB000077 | V1.0.0.2 | |

Accessing the web server

| | | |
|---------|--|---------------------------------|
| PRODUCT | VIPA 322-1BH70 V1.0.1.0 Px000030.pkg | Name, firmware-version, package |
| Hxxxxxx | V0.0.0.0 | |

Data - Output data

| Offset | Width | Value (dec) | Value (hex) | New Value (hex) |
|--------|-------|-------------|-------------|-----------------|
| 128 | 1 | 0 | 00 | 00 |
| 129 | 1 | 0 | 00 | 00 |
| 130 | 1 | 0 | 00 | 00 |
| 131 | 1 | 0 | 00 | 00 |

Info - Overview

VBUS - Digital In/Out 16

Slot100 (... 31x-xxxx CPU)
System: (SPEED-Bus)
...

System: (VBUS/KBUS)
R0/Slot4 (Digital In/Out 16)
• R0/Slot5 (Analog Input 8)
R0/Slot6 (Analog Output 4)

Info
Data

Digital In/Out 16 - information

| Name | Value |
|---------------|-------------------|
| Ordering Info | Digital In/Out 16 |

[Expert View ...]

Data - Input data

| Offset | Width | Value (dec) | Value (hex) |
|--------|-------|-------------|-------------|
| 0 | 1 | 0 | 00 |
| 1 | 1 | 0 | 00 |

Data - Output data

| Offset | Width | Value (dec) | Value (hex) | New Value (hex) |
|--------|-------|-------------|-------------|-----------------|
| 0 | 1 | 0 | 00 | 00 |
| 1 | 1 | 0 | 00 | 00 |

5.13 Operating modes

5.13.1 Overview

The CPU can be in one of 4 operating modes:

- Operating mode STOP
- Operating mode START-UP
- Operating mode RUN
- Operating mode HOLD

Certain conditions in the operating modes START-UP and RUN require a specific reaction from the system program. In this case the application interface is often provided by a call to an organization block that was included specifically for this event.

Operating mode STOP

- The application program is not processed.
- If there has been a processing before, the values of counters, timers, flags and the process image are retained during the transition to the STOP mode.
- Outputs are inhibited, i.e. all digital outputs are disabled.
- RUN-LED off
- STOP-LED on

Operating mode START-UP

- During the transition from STOP to RUN a call is issued to the start-up organization block OB 100. The processing time for this OB is not monitored. The START-UP OB may issue calls to other blocks.
- All digital outputs are disabled during the START-UP, i.e. outputs are inhibited.
- RUN-LED
blinks as soon as the OB 100 is operated and for at least 3s, even if the start-up time is shorter or the CPU gets to STOP due to an error. This indicates the start-up.
- STOP-LED off

When the CPU has completed the START-UP OB, it assumes the operating mode RUN.

Operating mode RUN

- The application program in OB 1 is processed in a cycle. Under the control of alarms other program sections can be included in the cycle.
- All timers and counters being started by the program are active and the process image is updated with every cycle.
- The BASP-signal (outputs inhibited) is deactivated, i.e. all digital outputs are enabled.
- RUN-LED on
- STOP-LED off

Operating mode HOLD

The CPU offers up to 3 breakpoints to be defined for program diagnosis. Setting and deletion of breakpoints happens in your programming environment. As soon as a breakpoint is reached, you may process your program step by step.

Precondition

For the usage of breakpoints, the following preconditions have to be fulfilled:

- Testing in single step mode is possible with STL. If necessary switch the view via 'View → STL' to STL.
- The block must be opened online and must not be protected.

Approach for working with breakpoints

1. ➤ Activate 'View → Breakpoint Bar'.
2. ➤ Set the cursor to the command line where you want to insert a breakpoint.

3. ➤ Set the breakpoint with *'Debug → Set Breakpoint'*.
⇒ The according command line is marked with a circle.
4. ➤ To activate the breakpoint click on *'Debug → Breakpoints Active'*.
⇒ The circle is changed to a filled circle.
5. ➤ Bring your CPU into RUN.
⇒ When the program reaches the breakpoint, your CPU switches to the state HOLD, the breakpoint is marked with an arrow and the register contents are monitored.
6. ➤ Now you may execute the program code step by step via *'Debug → Execute Next Statement'* or run the program until the next breakpoint via *'Debug → Resume'*.
7. ➤ Delete (all) breakpoints with the option *'Debug → Delete All Breakpoints'*.

Behavior in operating state HOLD

- The RUN-LED blinks and the STOP-LED is on.
- The execution of the code is stopped. No level is further executed.
- All times are frozen.
- The real-time clock runs is just running.
- The outputs were disabled (BASP is activated).
- Configured CP connections remain exist.



The usage of breakpoints is always possible. Switching to the operating mode test operation is not necessary.

With more than 2 breakpoints, a single step execution is not possible.

5.13.2 Function security

The CPUs include security mechanisms like a Watchdog (100ms) and a parameterizable cycle time surveillance (parameterizable min. 1ms) that stop res. execute a RESET at the CPU in case of an error and set it into a defined STOP state. The Yaskawa CPUs are developed function secure and have the following system properties:

| Event | concerns | Effect |
|-------------------------|-------------------------|--|
| RUN → STOP | general | BASP (Befehls-Ausgabe-Sperre, i.e. command output disable) is set. |
| | central digital outputs | The outputs are disabled. |
| | central analog outputs | The outputs are disabled. <ul style="list-style-type: none"> ■ Voltage outputs issue 0V ■ Current outputs 0...20mA issue 0mA ■ Current outputs 4...20mA issue 4mA If configured also substitute values may be issued. |
| | decentral outputs | Same behavior as the central digital/analog outputs. |
| | decentral inputs | The inputs are cyclically be read by the decentralized station and the recent values are put at disposal. |
| STOP → RUN res. PowerON | general | First the PII is deleted, then OB 100 is called. After the execution of the OB, the BASP is reset and the cycle starts with: Delete PIO → Read PII → OB 1. |
| | decentral inputs | The inputs are once be read by the decentralized station and the recent values are put at disposal. |
| RUN | general | The program execution happens cyclically and can therefore be foreseen: Read PII → OB 1 → Write PIO. |

PII: Process image inputs, PIO: Process image outputs

5.14 Overall reset

Overview

During the overall reset the entire user memory is erased. Data located in the memory card is not affected. If you have assigned IP address data to your CP 343, these remain until there is a new PowerON.

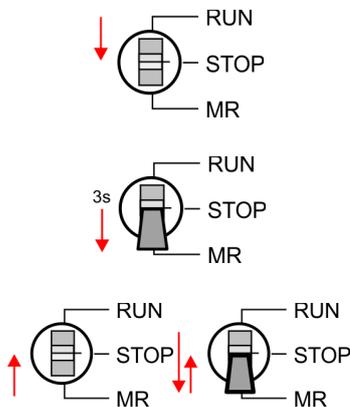
You have 2 options to initiate an overall reset:

- initiate the overall reset by means of the operating mode switch
- initiate the overall reset by means of the Siemens SIMATIC Manager



You should always issue an overall reset to your CPU before loading an application program into your CPU to ensure that all blocks have been cleared from the CPU.

Overall reset by means of the operating mode switch



Proceeding

1. ➤ Your CPU must be in STOP mode. For this switch the operating mode switch of the CPU to STOP.
 - ⇒ The ST LED is on.
2. ➤ Switch the operating mode switch to MR position for about 3 seconds.
 - ⇒ The ST LED changes from blinking to permanently on.
3. ➤ Place the operating mode switch in the position STOP and switch it to MR and quickly back to STOP within a period of less than 3 seconds.
 - ⇒ The overall reset is carried out. Here the ST LED flashes.
4. ➤ The overall reset has been completed when the ST LED is permanently on.

Overall reset by means of the Siemens SIMATIC Manager

For the following proceeding you must be online connected to your CPU.

1. ➤ For an overall reset the CPU must be switched to STOP state. You may place the CPU in STOP by the menu command *'PLC → Operating mode'*.
2. ➤ You may request the overall reset by means of the menu command *'PLC → Clean/Reset'*.
 - ⇒ A dialog window opens. Here you can bring your CPU in STOP state, if not already done, and start the overall reset. During the overall reset procedure the ST LED blinks. When the ST LED is on permanently the overall reset procedure has been completed.

Automatic reload

If there is a project S7PROG.WLD on the MMC, the CPU attempts to reload this project from MMC.

→ The MC LED is on. When the reload has been completed the LED expires. The operating mode of the CPU will be STOP respectively RUN, depending on the position of the operating mode switch.

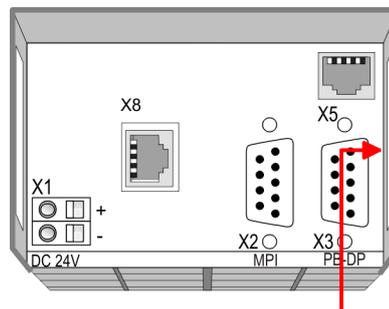
Reset to factory setting

The *Reset to factory setting* deletes completely the internal RAM of the CPU and resets this to delivery state. Please regard that the MPI address is also set back to default 2!
 ↪ Chap. 5.16 *'Reset to factory settings'* page 75

5.15 Firmware update

Overview

- There is the opportunity to execute a firmware update for the CPU and its components via memory card. For this an accordingly prepared memory card must be in the CPU during the startup.
- So a firmware files can be recognized and assigned with startup, a pkg file name is reserved for each updateable component an hardware release, which begins with "px" and differs in a number with six digits. The pkg file name of every updateable component may be found at a label right down the front flap of the module.
- After PowerON and CPU STOP the CPU checks if there is a *.pkg file on the memory card. If this firmware version is different to the existing firmware version, this is indicated by blinking of the LEDs and the firmware may be installed by an update request.



**Firmware package
and Version**

Latest firmware at www.yaskawa.eu.com

The latest firmware versions are to be found in the service area at www.yaskawa.eu.com. For example the following files are necessary for the firmware update of the CPU 317-4NE23 and its components with hardware release 1:

- 317-4NE23, Hardware release 01: Px000282.pkg
- PROFIBUS DP master: Px000182.pkg
- Ethernet-CP 343: Px000299.pkg



CAUTION!

- When installing a new firmware you have to be extremely careful. Under certain circumstances you may destroy the CPU, for example if the voltage supply is interrupted during transfer or if the firmware file is defective. In this case, please call the VIPA-Hotline!
- Please regard that the version of the update firmware has to be different from the existing firmware otherwise no update is executed.

Display the firmware version of the SPEED7 system via Web Site

The CPU has an integrated website that monitors information about firmware version of the SPEED7 components. The Ethernet PG/OP channel provides the access to this web site. The CPU has an integrated website that monitors information about firmware version of the SPEED7 components. The Ethernet PG/OP channel provides the access to this web site. *'PLC → Assign Ethernet Address'*. After that you may access the PG/OP channel with a web browser via the IP address of the project engineering. ↪ *Chap. 5.12 'Accessing the web server' page 63*

Load firmware and transfer it to memory card

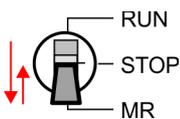
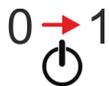
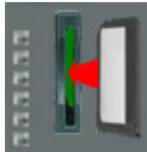
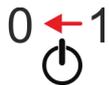
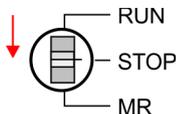
- Go to www.yaskawa.eu.com
- Click on 'Service → Download → Firmware'.
- Navigate via 'System 300S → CPU' to your CPU and download the zip file to your PC.
- Extract the zip file and copy the extracted pkg files to your memory card.



CAUTION!

With a firmware update an overall reset is automatically executed. If your program is only available in the load memory of the CPU it is deleted! Save your program before executing a firmware update! After the firmware update you should execute a [↗ Chap. 5.16 'Reset to factory settings' page 75](#).

Transfer firmware from memory card into CPU

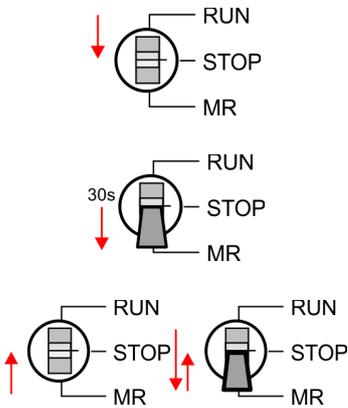


1. ➤ Switch the operating mode switch of your CPU in position STOP.
2. ➤ Turn off the power supply.
3. ➤ Plug the memory card with the firmware files into the CPU. Please take care of the correct plug-in direction of the memory card.
4. ➤ Turn on the power supply.
 - ⇒ After a short boot-up time, the alternate blinking of the LEDs SF and FC shows that at least a more current firmware file was found at the memory card.
5. ➤ You start the transfer of the firmware as soon as you tip the operating mode switch downwards to MR within 10s and then leave the switch in STOP position.
 - ⇒ During the update process, the LEDs SF and FC are alternately blinking and the MC LED is on. This may last several minutes.
6. ➤ The update is successful finished when the LEDs PW, ST, SF, FC and MC are on. If they are blinking fast, an error occurred.
7. ➤ Turn power OFF and ON.
 - ⇒ Now it is checked by the CPU, whether further firmware updates are to be executed. If so, again the LEDs SF and FC flash after a short start-up period. Continue with step 5. If the LEDs do not flash, the firmware update is finished.
8. ➤ Now execute a *Reset to factory setting*. After that the CPU is ready for duty.
 - ↗ [Chap. 5.16 'Reset to factory settings' page 75](#)

5.16 Reset to factory settings

Proceeding

- With the following proceeding the internal RAM of the CPU is completely deleted and the CPU is reset to delivery state.
- Please regard that the MPI address is also reset to default 2 and the IP address of the Ethernet PG/OP channel is reset to 0.0.0.0!
- A factory reset may also be executed by the command `FACTORY_RESET`. ↪ *Chap. 5.19 'CMD - auto commands' page 78*



1. ➔ Switch the CPU to STOP.

2. ➔ Push the operating mode switch down to position MR for 30 seconds. Here the ST LED blinks. After a few seconds the ST LED changes to static light. Now the ST LED changes between static light and blinking. Start here to count the static light of the ST LED.

3. ➔ After the 6. Static light release the operating mode switch and tip it downwards to MR.

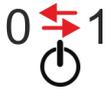
⇒ For the confirmation of the resetting procedure the green RN LED lights up once. This means that the RAM was deleted completely.



If the ST LED is on, only an overall reset has been performed and the reset to factory setting has been failed. In this case you can repeat the procedure. A factory reset can only be executed if the ST LED has static light for exact 6 times.

4. ➔ The update is successful finished when the LEDs PW, ST, SF, FC and MC are on.

5. ➔ Turn power OFF and ON.



After a firmware update of the CPU you always should execute a factory reset.

5.17 Deployment storage media - MMC, MCC

Overview

At this slot the following storage media can be plugged:

- SD respectively MMC (**M**ultimedia **c**ard)
 - External memory card for programs and firmware.
- MCC - **M**emory **c**onfiguration **c**ard
 - External memory card (MMC) for programs and firmware with the possibility to unlock additional work memory.
 - The additional memory can be purchased separately.
 - To activate the corresponding card is to be installed and an *overall reset* is to be established. ↪ *Chap. 5.14 'Overall reset' page 72*

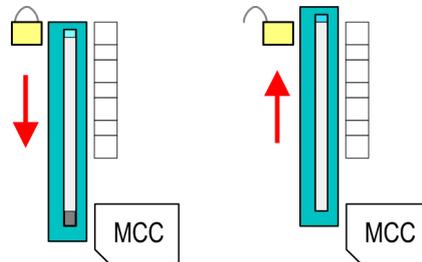


To avoid malfunctions, you should use memory cards of Yaskawa. These correspond to the industrial standard. A list of the currently available memory cards can be found at www.yaskawa.eu.com

You can cause the CPU to load a project automatically respectively to execute a command file by means of pre-defined file names.

MMC

- The MMCs of Yaskawa are pre-formatted with the PC format FAT and can be accessed via a card reader.
- After PowerON respectively an overall reset the CPU checks, if there is a memory card plugged with data valid for the CPU.
- Push the memory card into the slot until it snaps in led by a spring mechanism. This ensures contacting. By sliding down the sliding mechanism, a just installed memory card can be protected against drop out.



To remove, slide the sliding mechanism up again and push the storage media against the spring pressure until it is unlocked with a click.



CAUTION!

If the media was already unlocked by the spring mechanism, with shifting the sliding mechanism, a just installed memory card can jump out of the slot!



Please note that the write protection function of SD cards is not evaluated!

MCC

- The MCC is a MMC with the possibility to unlock additional work memory.
- By plugging the MCC into the MCC slot and then an overall reset the according memory expansion is released. There may only one memory expansion be activated at one time.
- On the MCC there is the file `memory.key`. This file may not be altered or deleted.

- You may use the MCC also as "normal" MMC for storing your project.
- If the memory expansion on the MCC exceeds the maximum extendible memory range of the CPU, the maximum possible memory of the CPU is automatically used.
- You may determine the recent memory extension and the remaining time after pulling the MCC via the integrated web page. ↪ *Chap. 5.12 'Accessing the web server' page 63*
- When the MCC memory configuration has been taken over you may find the diagnostics entry 0xE400 in the diagnostics buffer of the CPU.
- After pulling the MCC the entry 0xE401 appears in the diagnostics buffer, the SF-LED is on and after 72 hours the CPU switches to STOP. A reboot is only possible after plugging-in the MCC again or after an overall reset.
- After re-plugging the MCC, the SF LED extinguishes and 0xE400 is entered into the diagnostics buffer. You may reset the memory configuration of your CPU to the initial status at any time by executing an overall reset without MCC.

**CAUTION!**

Please regard that the MCC must remain plugged when you've executed the memory expansion at the CPU. Otherwise the CPU switches to STOP after 72 hours. The MCC cannot be exchanged with a MCC of the same memory configuration. The activation code is fixed to the MCC by means of an unique serial number. Here the functionality as an external memory card is not affected.

Accessing the storage medium

To the following times an access takes place on a storage medium:

After overall reset

- The CPU checks if a MCC is plugged. If so, the according additional memory is unlocked.
- The CPU checks whether a project S7PROG.WLD exists. If so, it is automatically loaded.

After PowerON

- The CPU checks whether a project AUTOLOAD.WLD exists. If so, an overall reset is executed and the project is automatically loaded.
- The CPU checks whether a command file with the name VIPA_CMD.MMC exists. If so the command file is loaded and the commands are executed.
- After PowerON and CPU STOP the CPU checks if there is a *.pkg file (firmware file). If so, this is shown by the CPU by blinking LEDs and the firmware may be installed by an update request. ↪ *Chap. 5.15 'Firmware update' page 73*

Once in STOP state

- If a memory card is plugged, which contains a command file VIPA_CMD.MMC, the command file is loaded and the containing instructions are executed.



The FC/SFC 208 ... FC/SFC 215 and FC/SFC 195 allow you to include the memory card access into your user application. More can be found in the manual operation list (HB00_OPL_SP7) of your CPU.

5.18 Extended know-how protection

Overview

Besides the "standard" Know-how protection the SPEED7 CPUs from Yaskawa provide an "extended" know-how protection that serves a secure block protection for accesses of 3. persons.

- Standard protection
 - The standard protection from Siemens transfers also protected blocks to the PG but their content is not displayed.
 - But with according manipulation the know-how protection is not guaranteed.
- Extended protection
 - The "extended" know-how protection developed by Yaskawa offers the opportunity to store blocks permanently in the CPU.
 - With the "extended" protection you transfer the protected blocks to a memory card into a WLD-file named protect.wld.
 - By plugging the memory card and then an overall reset the blocks in the protect.wld are permanently stored in the CPU.
 - You may protect OBs, FBs and FCs.
 - When back-reading the protected blocks into the PG, exclusively the block header are loaded. The block code that is to be protected remains in the CPU and cannot be read.

Protect blocks with protect.wld

1. ➤ Create a new wld file in your project engineering tool with 'File ➔ Memory Card file ➔ New'.
2. ➤ Rename the wld file to "protect.wld".
3. ➤ Transfer the according blocks into the file by dragging them with the mouse from the project to the file window of protect.wld.
4. ➤ Transfer the file protect.wld to a memory card.
5. ➤ Plug the memory card into the CPU and execute an *overall reset*. ↪ Chap. 5.14 'Overall reset' page 72
 - ⇒ The overall reset stores the blocks in protect.wld permanently in the CPU protected from accesses of 3. persons.

Protection behaviour

Protected blocks are overwritten by a new protect.wld. Using a PG 3. persons may access protected blocks but only the block header is transferred to the PG. The block code that is to be protected remains in the CPU and cannot be read.

Change respectively delete protected blocks

Protected blocks in the RAM of the CPU may be substituted at any time by blocks with the same name. This change remains up to next overall reset. Protected blocks may permanently be overwritten only if these are deleted at the protect.wld before. By transferring an empty protect.wld from the memory card with an overall reset, you may delete all protected blocks in the CPU.

Usage of protected blocks

Due to the fact that reading of a "protected" block from the CPU monitors no symbol labels it is convenient to provide the "block covers" for the end user. For this, create a project of all protected blocks. Delete all networks in the blocks so that these only contain the variable definitions in the according symbolism.

5.19 CMD - auto commands

Overview

A *command* file at a memory card is automatically executed under the following conditions:

- CPU is in STOP and memory card is stuck
- After each PowerON

Command file

The *command* file is a text file, which consists of a command sequence to be stored as **vipa_cmd.mmc** in the root directory of the memory card. The file has to be started by *CMD_START* as 1. command, followed by the desired commands (no other text) and must be finished by *CMD_END* as last command.

Text after the last command *CMD_END* e.g. comments is permissible, because this is ignored. As soon as the command file is recognized and executed each action is stored at the memory card in the log file logfile.txt. In addition for each executed command a diagnostics entry may be found in the diagnostics buffer.

Commands

Please regard the command sequence is to be started with *CMD_START* and ended with *CMD_END*.

| Command | Description | Diagnostics entry |
|------------------|---|-------------------|
| CMD_START | In the first line <i>CMD_START</i> is to be located. | 0xE801 |
| | There is a diagnostic entry if <i>CMD_START</i> is missing | 0xE8FE |
| WAIT1SECOND | Waits about 1 second. | 0xE803 |
| WEBPAGE | The current web page of the CPU is stored at the memory card as "webpage.htm". | 0xE804 |
| LOAD_PROJECT | The function "Overall reset and reload from MMC" is executed. The wld file located after the command is loaded else "s7prog.wld" is loaded. | 0xE805 |
| SAVE_PROJECT | The recent project (blocks and hardware configuration) is stored as "s7prog.wld" at the memory card. If the file just exists it is renamed to "s7prog.old". If your CPU is password protected so you have to add this as parameter. Otherwise there is no project written. Example: <i>SAVE_PROJECT</i> password | 0xE806 |
| FACTORY_RESET | Executes "factory reset". | 0xE807 |
| DIAGBUF | The current diagnostics buffer of the CPU is stored as "diagbuff.txt" at the memory card. | 0xE80B |
| SET_NETWORK | IP parameters for Ethernet PG/OP channel may be set by means of this command. The IP parameters are to be given in the order IP address, subnet mask and gateway in the format x.x.x.x each separated by a comma. Enter the IP address if there is no gateway used. | 0xE80E |
| SET_MPI_ADDRESS | This lets you adjust the MPI interface on the value that follows the command. The setting is retained even after power cycle, firmware update or battery failure. With ↪ Chap. 5.16 'Reset to factory settings' page 75 you get the default setting. | 0xE814 |
| CPUTYPE_318 | To use projects, which were configured with the CPU type 318-2AJ00, with this command you can switch from original CPU type to CPU type 318-2AJ00. The setting is retained even after power cycle, firmware update or battery failure. | 0xE82A |
| CPUTYPE_ORIGINAL | With ↪ Chap. 5.16 'Reset to factory settings' page 75 or with this command the CPU type is reset to the original CPU type. | 0xE82B |
| CMD_END | In the last line <i>CMD_END</i> is to be located. | 0xE802 |

Examples

The structure of a command file is shown in the following. The corresponding diagnostics entry is put in parentheses.

Example 1

| | |
|------------------------|--|
| CMD_START | Marks the start of the command sequence (0xE801) |
| LOAD_PROJECT proj.wld | Execute an overall reset and load "proj.wld" (0xE805) |
| WAIT1SECOND | Wait ca. 1s (0xE803) |
| WEBPAGE | Store web page as "webpage.htm" (0xE804) |
| DIAGBUF | Store diagnostics buffer of the CPU as "diagbuff.txt" (0xE80B) |
| CMD_END | Marks the end of the command sequence (0xE802) |
| ... arbitrary text ... | Text after the command CMD_END is not evaluated. |

Example 2

| | |
|---|--|
| CMD_START | Marks the start of the command sequence (0xE801) |
| LOAD_PROJECT proj2.wld | Execute an overall reset and load "proj2.wld" (0xE805) |
| WAIT1SECOND | Wait ca. 1s (0xE803) |
| WAIT1SECOND | Wait ca. 1s (0xE803) |
| | IP parameter (0xE80E) |
| SET_NETWORK 172.16.129.210,255.255.224.0,172.16.129.210 | |
| WAIT1SECOND | Wait ca. 1s (0xE803) |
| WAIT1SECOND | Wait ca. 1s (0xE803) |
| SET_MPI_ADDRESS 4 | MPI address 4 is set (0xE814) |
| CPUTYPE_318 | Switches the CPU type to CPU 318-2AJ00 (0xE82A) |
| WEBPAGE | Store web page as "webpage.htm" (0xE804) |
| DIAGBUF | Store diagnostics buffer of the CPU as "diagbuff.txt" (0xE80B) |
| CMD_END | Marks the end of the command sequence (0xE802) |
| ... arbitrary text ... | Text after the command CMD_END is not evaluated. |



The parameters IP address, subnet mask and gateway may be received from the system administrator.

Enter the IP address if there is no gateway used.

5.20 Diagnostic entries

Accessing diagnostic data [↪ Appendix A 'System specific event IDs' page 169](#)

- You may read the diagnostics buffer of the CPU via the Siemens SIMATIC Manager. Besides of the standard entries in the diagnostics buffer, the Yaskawa CPUs support some additional specific entries as Event-IDs.
- To monitor the diagnostics entries you choose in the Siemens SIMATIC manager 'PLC → Module information'. Via the register "Diagnostics Buffer" you reach the diagnostics window.

- The current content of the diagnostic buffer is stored at the memory card by means of the CMD DIAGBUF. ↪ *Chap. 5.19 'CMD - auto commands' page 78*
- The diagnostic is independent from the operating mode of the CPU. You may store a max. of 100 diagnostic entries in the CPU.

5.21 Control and monitoring of variables with test functions

Overview

- For troubleshooting purposes and to display the status of certain variables you can access certain test functions via the menu item **Debug** of the Siemens SIMATIC Manager.
- The status of the operands and the RLO can be displayed by means of the test function *'Debug → Monitor'*.
- The status of the operands and the RLO can be displayed by means of the test function *'PLC → Monitor/Modify Variables'*.

'Debug → Monitor'

- This test function displays the current status and the RLO of the different operands while the program is being executed.
- It is also possible to enter corrections to the program.
- The processing of the states may be interrupted by means of jump commands or by timer and process-related interrupts.
- At the breakpoint the CPU stops collecting data for the status display and instead of the required data it only provides the PG with data containing the value 0.
- The interruption of the processing of statuses does not change the execution of the program. It only shows that the data displayed is no longer valid.



When using the test function "Monitor" the PLC must be in RUN mode!

For this reason, jumps or time and process alarms can result in the value displayed during program execution remaining at 0 for the items below:

- the result of the logical operation RLO
- Status / ACCU 1
- ACCU 2
- Condition byte
- absolute memory address SAZ. In this case SAZ is followed by a "?".

**'PLC
→ Monitor/Modify
Variables'**

This test function returns the condition of a selected operand (inputs, outputs, flags, data word, counters or timers) at the end of program execution. This information is obtained from the corresponding area of the selected operands. During the controlling of variables respectively in operating mode STOP the input area is directly read. Otherwise only the process image of the selected operands is displayed.

- Control of outputs
 - Serves to check the wiring and proper operation of output modules.
 - If the CPU is in RUN mode, so only outputs can be controlled, which are not controlled by the user program. Otherwise values would be instantly overwritten.
 - If the CPU is in STOP - even without user program, so you need to disable the command output lock BASP ('Enable PO'). Then you can control the outputs arbitrarily
- Controlling variables
 - The following variables may be modified: I, Q, M, T, C and D.
 - The process image of binary and digital operands is modified independently of the operating mode of the CPU.
 - When the operating mode is RUN the program is executed with the modified process variable. When the program continues they may, however, be modified again without notification.
- Forcing variables
 - You can pre-set individual variables of a user program with fixed values so that they can not be changed or overwritten by the user program of the CPU.
 - By pre-setting of variables with fixed values, you can set certain situations for your user program and thus test the programmed functions.

**CAUTION!**

Please consider that controlling of output values represents a potentially dangerous condition.

Even after a power cycle forced variables remain forced with its value, until the force function is disabled.

These functions should only be used for test purposes respectively for troubleshooting. More information about the usage of these functions may be found in the manual of your configuration tool.

6 Deployment PtP communication

6.1 Fast introduction

General

The CPU has a PROFIBUS/PtP interface with a fix pinout. After an overall reset the interface is deactivated. By appropriate configuration the PtP function (**point to point**) can be enabled:

- PtP functionality
 - Using the PtP functionality the RS485 interface is allowed to connect via serial point-to-point connection to different source res. target systems.
 - The activation of the PtP functionality happens by embedding the SPEEDBUS.GSD from VIPA in the hardware catalog. After the installation the CPU may be configured in a PROFIBUS master system and here the interface may be switched to PtP communication.

Protocols

The protocols res. procedures ASCII, STX/ETX, 3964R, USS and Modbus are supported.

Parametrization

The parametrization of the serial interface happens during runtime using the FC/SFC 216 (SER_CFG). For this you have to store the parameters in a DB for all protocols except ASCII.

Communication

The FCs/SFCs are controlling the communication. Send takes place via FC/SFC 217 (SER_SND) and receive via FC/SFC 218 (SER_RCV). The repeated call of the FC/SFC 217 SER_SND delivers a return value for 3964R, USS and Modbus via RetVal that contains, among other things, recent information about the acknowledgement of the partner station. The protocols USS and Modbus allow to evaluate the receipt telegram by calling the FC/SFC 218 SER_RCV after SER_SND. The FCs/SFCs are included in the consignment of the CPU.

Overview FCs/SFCs for serial communication

The following FCs/SFCs are used for the serial communication:

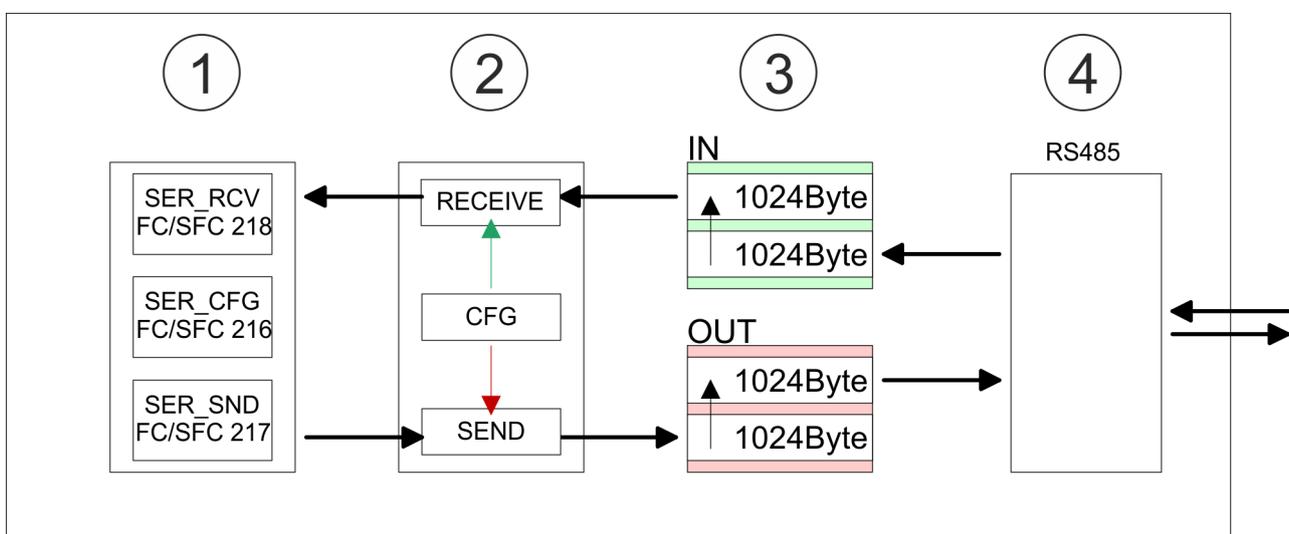
| FC/SFC | | Description |
|------------|---------|--------------------|
| FC/SFC 216 | SER_CFG | RS485 parameterize |
| FC/SFC 217 | SER_SND | RS485 send |
| FC/SFC 218 | SER_RCV | RS485 receive |



More information about the usage of these blocks may be found in the manual "SPEED7 Operation List" from Yaskawa.

6.2 Principle of the data transfer

- RS485 PtP communication** The data transfer is handled during runtime by using FC/SFCs. The principle of data transfer is the same for all protocols and is shortly illustrated in the following.
- Data, which are written into the according data channel by the CPU, is stored in a FIFO send buffer (first in first out) with a size of 2x1024byte and then put out via the interface.
 - When the interface receives data, this is stored in a FIFO receive buffer with a size of 2x1024byte and can there be read by the CPU.
 - If the data is transferred via a protocol, the embedding of the data to the according protocol happens automatically.
 - In opposite to ASCII and STX/ETX, the protocols 3964R, USS and Modbus require the acknowledgement of the partner.
 - An additional call of the FC/SFC 217 SER_SND causes a return value in RetVal that includes among others recent information about the acknowledgement of the partner.
 - Further on for USS and Modbus after a SER_SND the acknowledgement telegram must be evaluated by a call of the FC/SFC 218 SER_RCV.



- 1 Program
- 2 Protocol
- 3 FIFO buffer
- 4 Interface

6.3 Deployment of RS485 interface for PtP

Activate RS485 to PtP operation

Per default, the RS485 interface is deactivated. Via hardware configuration the RS485 interfaces may be switched to PtP operation (point to point) via the parameter *Function RS485* of the *Properties*.

Requirements

Since the VIPA specific CPU parameters may be set, the installation of the SPEEDBUS.GSD from VIPA in the hardware catalog is necessary. The CPU may be configured in a PROFIBUS master system and the appropriate parameters may be set after installation.

Installation of the SPEEDBUS.GSD

The GSD (Geräte-Stamm-Datei) is online available in the following language versions. Further language versions are available on inquire:

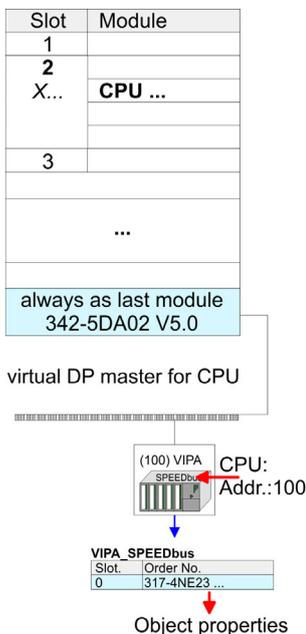
| Name | Language |
|--------------|------------------|
| SPEEDBUS.GSD | German (default) |
| SPEEDBUS.GSG | German |
| SPEEDBUS.GSE | English |

The GSD files may be found at www.yaskawa.eu.com at the service area.

The integration of the SPEEDBUS.GSD takes place with the following proceeding:

1. ➤ Go to the service area of www.yaskawa.eu.com.
2. ➤ Load from the download area at 'Config files → PROFIBUS' the according file for your System 300S.
3. ➤ Extract the file to your work directory.
4. ➤ Start the hardware configurator from Siemens.
5. ➤ Close every project.
6. ➤ Select 'Options → Install new GSD-file'.
7. ➤ Navigate to the directory VIPA_System_300S and select **SPEEDBUS.GSD** an.
 - ⇒ The SPEED7 CPUs and modules of the System 300S from Yaskawa may now be found in the hardware catalog at PROFIBUS-DP / Additional field devices / I/O / VIPA_SPEEDBUS.

Proceeding



The embedding of the CPU 317-4NE23 happens by means of a virtual PROFIBUS master system with the following approach:

1. ➤ Perform a hardware configuration for the CPU ↗ *Chap. 5.4 'Hardware configuration - CPU' page 47*
2. ➤ Configure always as last module a Siemens DP master CP 342-5 (342-5DA02 V5.0). Connect and parameterize it at operation mode "DP-Master".
3. ➤ Connect the slave system "VIPA_SPEEDbus". After installing the SPEEDBUS.GSD this may be found in the hardware catalog at PROFIBUS DP / Additional field devices / I/O / VIPA / VIPA_SPEEDBUS.
4. ➤ For the slave system set the PROFIBUS address 100.
5. ➤ Configure at slot 0 the VIPA CPU 317-4NE23 of the hardware catalog from VIPA_SPEEDbus.
6. ➤ By double clicking the placed CPU 317-4NE23 the properties dialog of the CPU may be opened.

As soon as the project is transferred together with the PLC user program to the CPU, the parameters will be taken after start-up.



The hardware configuration, which is shown here, is only required, if you want to customize the VIPA specific parameters.

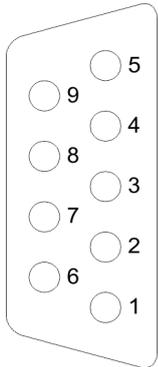
Setting PtP parameters

1. ➔ By double clicking the CPU 317-4NE23 placed in the slave system the properties dialog of the CPU may be opened.
2. ➔ Switch the Parameter '*Function RS485 X3*' to '*PtP*'.

Properties RS485

- Logical states represented by voltage differences between the two cores of a twisted pair cable
- Serial bus connection in two-wire technology using half duplex mode
- Data communications up to a max. distance of 500m
- Data communication rate up to 115.2kbaud

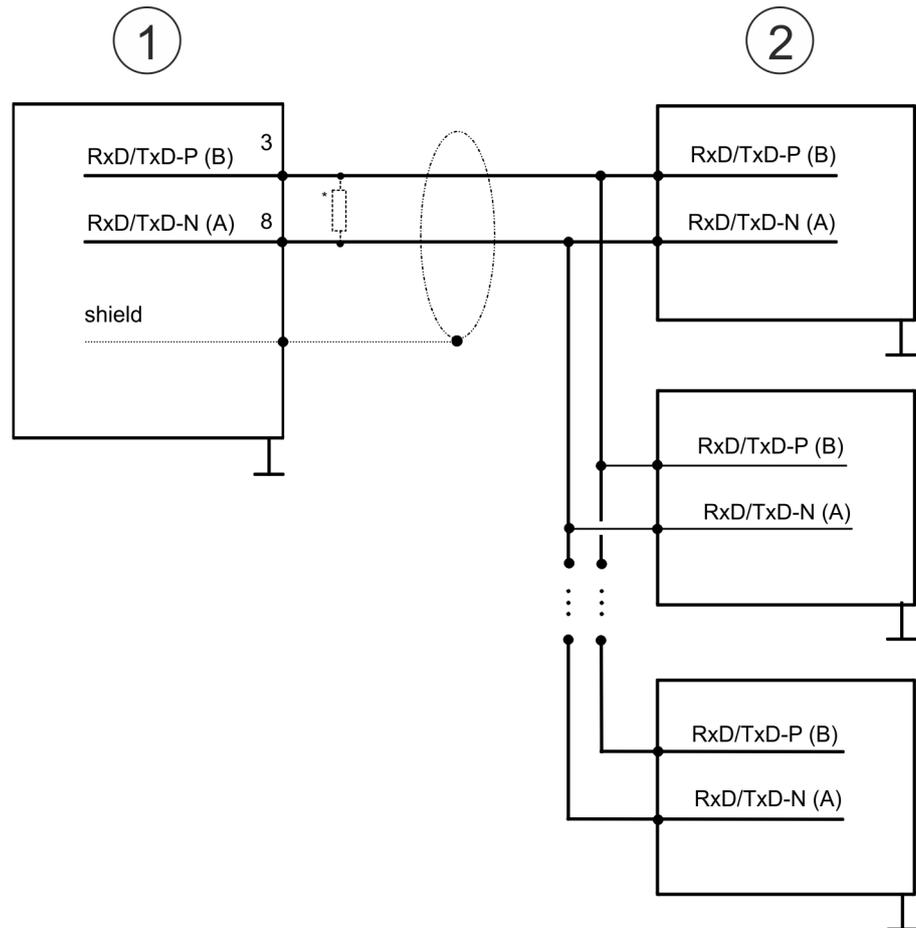
RS485



9pin SubD jack

| Pin | RS485 |
|-----|--------------------|
| 1 | n.c. |
| 2 | M24V |
| 3 | RxD/TxD-P (Line B) |
| 4 | RTS |
| 5 | M5V |
| 6 | P5V |
| 7 | P24V |
| 8 | RxD/TxD-N (Line A) |
| 9 | n.c. |

Connection



- 1 RS485 interface
- 2 Periphery



*) For traffic-free data transfer use a terminating resistor of approximately 120Ω .

6.4 Parametrization

6.4.1 FC/SFC 216 - SER_CFG - Parametrization PtP

The parametrization happens during runtime deploying the FC/SFC 216 (SER_CFG). You have to store the parameters for STX/ETX, 3964R, USS and Modbus in a DB.

6.5 Communication

6.5.1 FC/SFC 217 - SER_SND - Send to PtP

This block sends data via the serial interface. The repeated call of the FC/SFC 217 SER_SND delivers a return value for 3964R, USS and Modbus via RETVAL that contains, among other things, recent information about the acknowledgement of the partner station. The protocols USS and Modbus require to evaluate the receipt telegram by calling the FC/SFC 218 SER_RCV after SER_SND.

6.5.2 FC/SFC 218 - SER_RCV - Receive from PtP

This block receives data via the serial interface. Using the FC/SFC 218 SER_RCV after SER_SND with the protocols USS and Modbus the acknowledgement telegram can be read.



More information about the usage of these blocks may be found in the manual "SPEED7 Operation List" from Yaskawa.

6.6 Protocols and procedures

Overview

The CPU supports the following protocols and procedures:

- ASCII communication
- STX/ETX
- 3964R
- USS
- Modbus

ASCII

ASCII data communication is one of the simple forms of data exchange. Incoming characters are transferred 1 to 1. At ASCII, with every cycle the read FC/SFC is used to store the data that is in the buffer at request time in a parametrized receive data block. If a telegram is spread over various cycles, the data is overwritten. There is no reception acknowledgement. The communication procedure has to be controlled by the concerning user application. For this you can use the FB 1 - Receive_ASCII.



More information about the usage of this block may be found in the manual "SPEED7 Operation List" from Yaskawa.

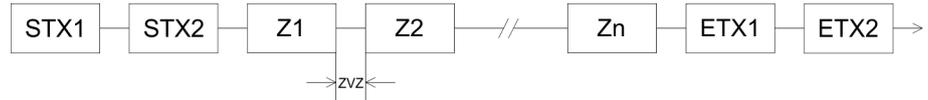
STX/ETX

STX/ETX is a simple protocol with start and end ID, where STX stands for **Start of Text** and ETX for **End of Text**.

- Any data transferred from the periphery must be preceded by a Start followed by the data characters and the end character. Depending of the byte width the following ASCII characters can be transferred: 5bit: not allowed: 6bit: 20...3Fh, 7bit: 20...7Fh, 8bit: 20...FFh.
- The effective data, which includes all the characters between Start and End are transferred to the CPU when the End has been received.
- When data is send from the CPU to a peripheral device, any user data is handed to the FC/SFC 217 (SER_SND) and is transferred with added Start- and End-ID to the communication partner.
- You may work with 1, 2 or no Start- and with 1, 2 or no End-ID.
- If no End-ID is defined, all read characters are transferred to the CPU after a parameterizable character delay time (Timeout).

As Start-res. End-ID all Hex values from 01h to 1Fh are permissible. Characters above 1Fh are ignored. In the user data, characters below 20h are not allowed and may cause errors. The number of Start- and End-IDs may be different (1 Start, 2 End res. 2 Start, 1 End or other combinations). For not used start and end characters you have to enter FFh in the hardware configuration.

Message structure:

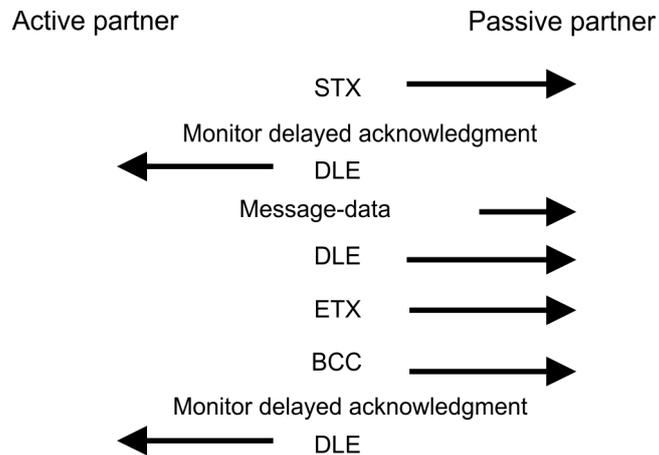
**3964**

The 3964R procedure controls the data transfer of a point-to-point link between the CPU and a communication partner. The procedure adds control characters to the message data during data transfer. These control characters may be used by the communication partner to verify the complete and error free receipt.

The procedure employs the following control characters:

- **STX: Start of Text**
- **DLE: Data Link Escape**
- **ETX: End of Text**
- **BCC: Block Check Character**
- **NAK: Negative Acknowledge**

You may transfer a maximum of 255byte per message.

Procedure

When a DLE is transferred as part of the information it is repeated to distinguish between data characters and DLE control characters that are used to establish and to terminate the connection (DLE duplication). The DLE duplication is reversed in the receiving station.

The 3964R procedure requires that a lower priority is assigned to the communication partner. When communication partners issue simultaneous send commands, the station with the lower priority will delay its send command.

USS

The USS protocol (**U**niverselle **s**erielle **S**chnittstelle = universal serial interface) is a serial transfer protocol defined by Siemens for the drive and system components. This allows to build-up a serial bus connection between a superordinated master and several slave systems. The USS protocol enables a time cyclic telegram traffic by presetting a fix telegram length.

The following features characterize the USS protocol:

- Multi point connection
- Master slave access procedure
- Single master system
- Max. 32 participants
- Simple and secure telegram frame

It is essential:

- You may connect 1 master and max. 31 slaves at the bus
- The single slaves are addressed by the master via an address sign in the telegram.
- The communication happens exclusively in half-duplex operation.
- After a send command, the acknowledgement telegram must be read by a call of the FC/SFC 218 SER_RCV.

The telegrams for send and receive have the following structure:

Master slave telegram

| | | | | | | | | | | | | | |
|-----|-----|-----|-----|---|-----|---|-----|---|-----|---|-----|---|-----|
| STX | LGE | ADR | PKE | | IND | | PWE | | STW | | HSW | | BCC |
| 02h | | | H | L | H | L | H | L | H | L | H | L | |

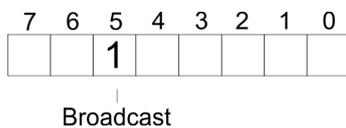
Slave master telegram

| | | | | | | | | | | | | | |
|-----|-----|-----|-----|---|-----|---|-----|---|-----|---|-----|---|-----|
| STX | LGE | ADR | PKE | | IND | | PWE | | ZSW | | HIW | | BCC |
| 02h | | | H | L | H | L | H | L | H | L | H | L | |

with

- STX - Start sign
- STW - Control word
- LGE - Telegram length
- ZSW - State word
- ADR - Address
- HSW - Main set value
- PKE - Parameter ID
- HIW - Main effective value
- IND - Index
- BCC - Block Check Character
- PWE - Parameter value

Broadcast with set bit 5 in ADR byte



A request can be directed to a certain slave or be send to all slaves as broadcast message. For the identification of a broadcast message you have to set bit 5 to 1 in the ADR byte. Here the slave addr. (bit 0 ... 4) is ignored. In opposite to a "normal" send command, the broadcast does not require a telegram evaluation via FC/SFC 218 SER_RCV. Only write commands may be sent as broadcast.

Modbus

- The Modbus protocol is a communication protocol that fixes a hierarchic structure with one master and several slaves.
- Physically, Modbus works with a serial half-duplex connection. There are no bus conflicts occurring, because the master can only communicate with one slave at a time.
- After a request from the master, this waits for a preset delay time for an answer of the slave. During the delay time, communication with other slaves is not possible.

- After a send command, the acknowledgement telegram must be read by a call of the FC/SFC 218 SER_RCV.
- The request telegrams send by the master and the respond telegrams of a slave have the following structure:

Telegram structure

| | | | | | |
|------------|---------------|---------------|------|--------------|----------|
| Start sign | Slave address | Function Code | Data | Flow control | End sign |
|------------|---------------|---------------|------|--------------|----------|

Broadcast with slave address = 0

- A request can be directed to a special slave or at all slaves as broadcast message.
- To mark a broadcast message, the slave address 0 is used.
- In opposite to a "normal" send command, the broadcast does not require a telegram evaluation via FC/SFC 218 SER_RCV.
- Only write commands may be sent as broadcast.

ASCII, RTU mode

Modbus offers 2 different transfer modes. The mode selection happens during runtime by using the FC/SFC 216 SER_CFG.

- ASCII mode: Every byte is transferred in the 2 sign ASCII code. The data are marked with a start and an end sign. This causes a transparent but slow transfer.
- RTU mode: Every byte is transferred as one character. This enables a higher data pass through as the ASCII mode. Instead of start and end sign, a time control is used.

Supported Modbus protocols

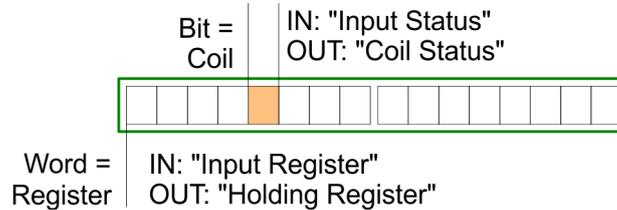
The following Modbus Protocols are supported by the RS485 interface:

- Modbus RTU Master
- Modbus ASCII Master

6.7 Modbus - Function codes

Naming convention

Modbus has some naming conventions:

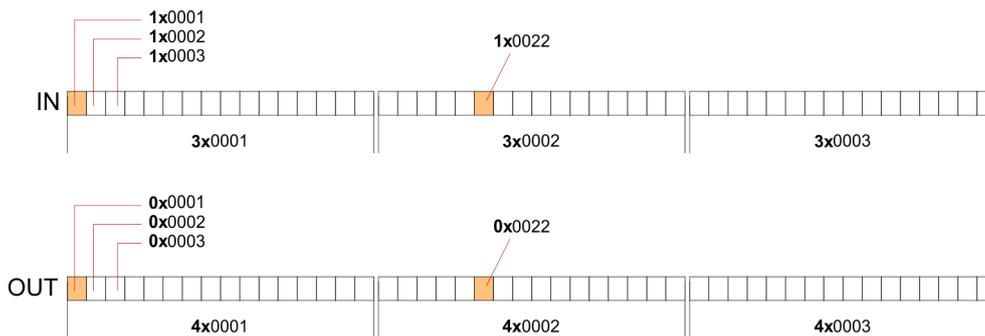


- Modbus differentiates between bit and word access; bits = "Coils" and words = "Register".
- Bit inputs are referred to as "Input-Status" and bit outputs as "Coil-Status".
- word inputs are referred to as "Input-Register" and word outputs as "Holding-Register".

Range definitions

Normally the access at Modbus happens by means of the ranges 0x, 1x, 3x and 4x. 0x and 1x gives you access to digital bit areas and 3x and 4x to analog word areas. For the CPs from Yaskawa is not differentiating digital and analog data, the following assignment is valid:

- 0x - Bit area for master output data
Access via function code 01h, 05h, 0Fh
- 1x - Bit area for master input data
Access via function code 02h
- 3x - word area for master input data
Access via function code 04h
- 4x - word area for master output data
Access via function code 03h, 06h, 10h



A description of the function codes follows below.

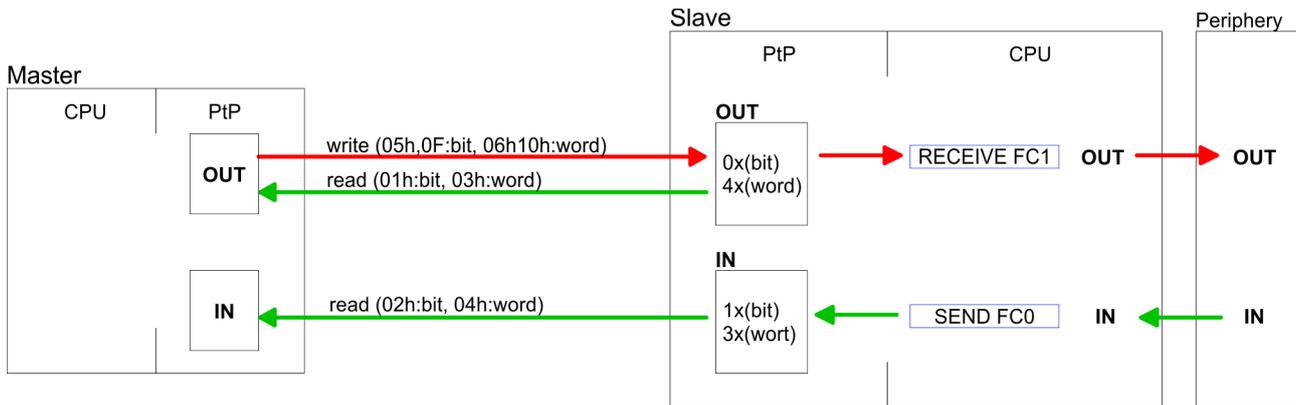
Overview

With the following Modbus function codes a Modbus master can access a Modbus slave:
With the following Modbus function codes a Modbus master can access a Modbus slave.
The description always takes place from the point of view of the master:

| Code | Command | Description |
|------|---------------|--|
| 01h | Read n bits | Read n bits of master output area 0x |
| 02h | Read n bits | Read n bits of master input area 1x |
| 03h | Read n words | Read n words of master output area 4x |
| 04h | Read n words | Read n words master input area 3x |
| 05h | Write 1 bit | Write 1 bit to master output area 0x |
| 06h | Write 1 word | Write 1 word to master output area 4x |
| 0Fh | Write n bits | Write n bits to master output area 0x |
| 10h | Write n words | Write n words to master output area 4x |

Point of View of "Input" and "Output" data

The description always takes place from the point of view of the master. Here data, which were sent from master to slave, up to their target are designated as "output" data (OUT) and contrary slave data received by the master were designated as "input" data (IN).



Respond of the slave

If the slave announces an error, the function code is send back with an "ORed" 80h. Without an error, the function code is sent back.

| | | |
|---------------|----------------------|---------|
| Slave answer: | Function code OR 80h | → Error |
| | Function code | → OK |

Byte sequence in a word

| | |
|-----------|----------|
| 1 word | |
| High-byte | Low-byte |

Check sum CRC, RTU, LRC

The shown check sums CRC at RTU and LRC at ASCII mode are automatically added to every telegram. They are not shown in the data block.

Read n bits 01h, 02h

Code 01h: Read n bits of master output area 0x
 Code 02h: Read n bits of master input area 1x

Command telegram

| Slave address | Function code | Address 1. bit | Number of bits | Check sum CRC/LRC |
|---------------|---------------|----------------|----------------|-------------------|
| 1byte | 1byte | 1word | 1word | 1word |

Respond telegram

| Slave address | Function code | Number of read bytes | Data 1. byte | Data 2. byte | ... | Check sum CRC/LRC |
|---------------|---------------|----------------------|--------------|--------------|-----|-------------------|
| 1byte | 1byte | 1byte | 1byte | 1byte | | 1word |
| | | | max. 250byte | | | |

Read n words 03h, 04h

03h: Read n words of master output area 4x

04h: Read n words master input area 3x

Command telegram

| Slave address | Function code | Address 1. bit | Number of words | Check sum CRC/LRC |
|---------------|---------------|----------------|-----------------|-------------------|
| 1byte | 1byte | 1word | 1word | 1word |

Respond telegram

| Slave address | Function code | Number of read bytes | Data 1. word | Data 2. word | ... | Check sum CRC/LRC |
|---------------|---------------|----------------------|---------------|--------------|-----|-------------------|
| 1byte | 1byte | 1byte | 1word | 1word | | 1word |
| | | | max. 125words | | | |

Write 1 bit 05h

Code 05h: Write 1 bit to master output area 0x

A status change is via "Status bit" with following values:

"Status bit" = 0000h → Bit = 0

"Status bit" = FF00h → Bit = 1

Command telegram

| Slave address | Function code | Address bit | Status bit | Check sum CRC/LRC |
|---------------|---------------|-------------|------------|-------------------|
| 1byte | 1byte | 1word | 1word | 1word |

Respond telegram

| Slave address | Function code | Address bit | Status bit | Check sum CRC/LRC |
|---------------|---------------|-------------|------------|-------------------|
| 1byte | 1byte | 1word | 1word | 1word |

Write 1 word 06h

Code 06h: Write 1 word to master output area 4x

Command telegram

| Slave address | Function code | Address word | Value word | Check sum CRC/LRC |
|---------------|---------------|--------------|------------|----------------------|
| 1byte | 1byte | 1word | 1word | 1word |

Respond telegram

| Slave address | Function code | Address word | Value word | Check sum CRC/LRC |
|---------------|---------------|--------------|------------|----------------------|
| 1byte | 1byte | 1word | 1word | 1word |

Write n bits 0Fh

Code 0Fh: Write n bits to master output area 0x

Please regard that the number of bits has additionally to be set in byte.

Command telegram

| Slave address | Function code | Address 1. bit | Number of bits | Number of bytes | Data 1. byte | Data 2. byte | ... | Check sum CRC/LRC |
|---------------|---------------|----------------|----------------|-----------------|--------------|--------------|-------|----------------------|
| 1byte | 1byte | 1word | 1word | 1byte | 1byte | 1byte | 1byte | 1word |
| | | | | | max. 250byte | | | |

Respond telegram

| Slave address | Function code | Address 1. bit | Number of bits | Check sum CRC/LRC |
|---------------|---------------|----------------|----------------|----------------------|
| 1byte | 1byte | 1word | 1word | 1word |

Write n words 10h

Code 10h: Write n words to master output area 4x

Command telegram

| Slave address | Function code | Address 1. word | Number of words | Number of bytes | Data 1. word | Data 2. word | ... | Check sum CRC/LRC |
|---------------|---------------|-----------------|-----------------|-----------------|---------------|--------------|-------|----------------------|
| 1byte | 1byte | 1word | 1word | 1byte | 1word | 1word | 1word | 1word |
| | | | | | max. 125words | | | |

Respond telegram

| Slave address | Function code | Address 1. word | Number of words | Check sum CRC/LRC |
|---------------|---------------|-----------------|-----------------|----------------------|
| 1byte | 1byte | 1word | 1word | 1word |

6.8 Modbus - Example communication

Overview

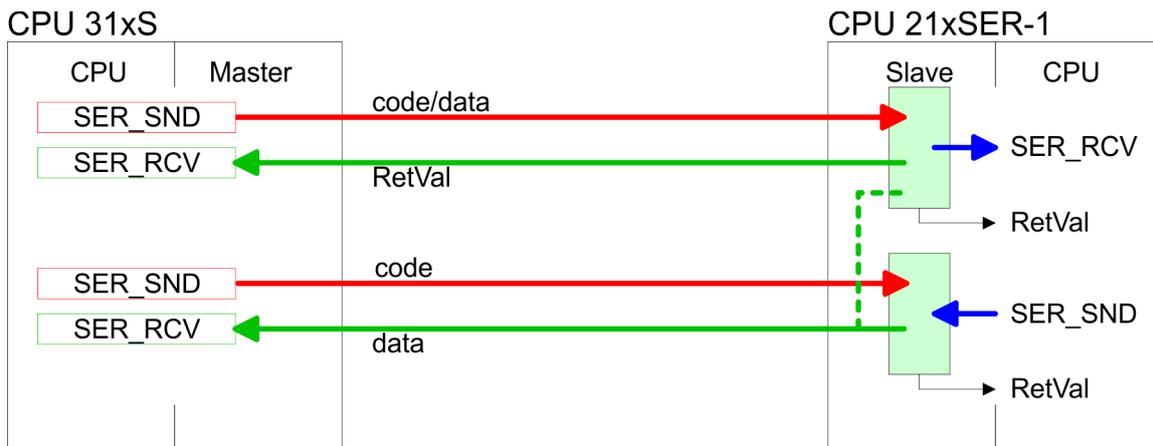
The example establishes a communication between a master and a slave via Modbus. The following combination options are shown:

- CPU 31xS as Modbus RTU master
- CPU 21xSER-1 as Modbus RTU slave
- Siemens SIMATIC Manager and possibilities for the project transfer
- Modbus cable connection

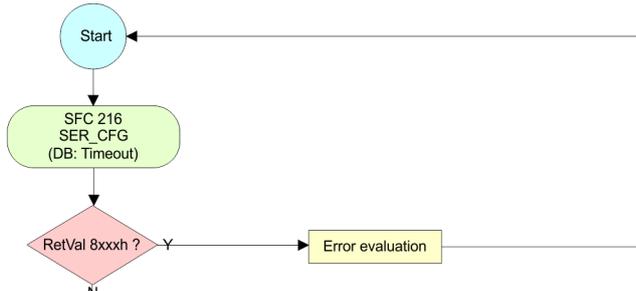
Approach

1. ➤ Assemble a Modbus system consisting of a CPU 31xS as Modbus master and a CPU 21xSER-1 as Modbus slave and Modbus cable.
2. ➤ Execute the project engineering of the master! For this you create a PLC user application with the following structure:
 - OB 100: Call SFC 216 (configuration as Modbus RTU master) with timeout setting and error evaluation.
 - OB 1: Call SFC 217 (SER_SND) where the data is send with error evaluation. Here you have to build up the telegram according to the Modbus rules. Call SFC 218 (SER_RCV) where the data is received with error evaluation.
3. ➤ Execute the project engineering of the slave! The PLC user application at the slave has the following structure:
 - OB 100: Call SFC 216 (configuration as Modbus RTU slave) with timeout setting and Modbus address in the DB and error evaluation.
 - OB 1: Call SFC 217 (SER_SND) for data transport from the slave CPU to the output buffer. Call SFC 218 (SER_RCV) for the data transport from the input buffer to the CPU. Allow an according error evaluation for both directions.

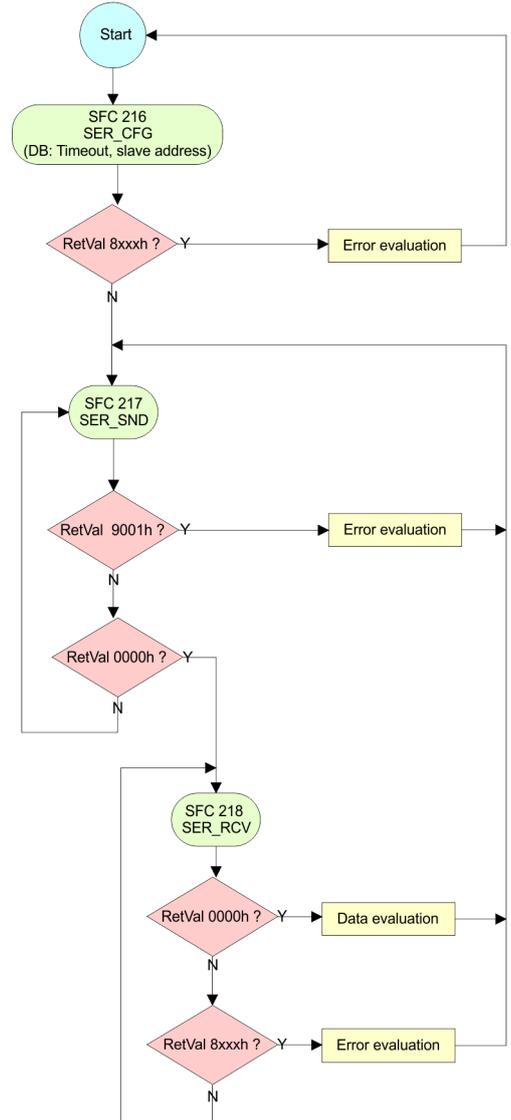
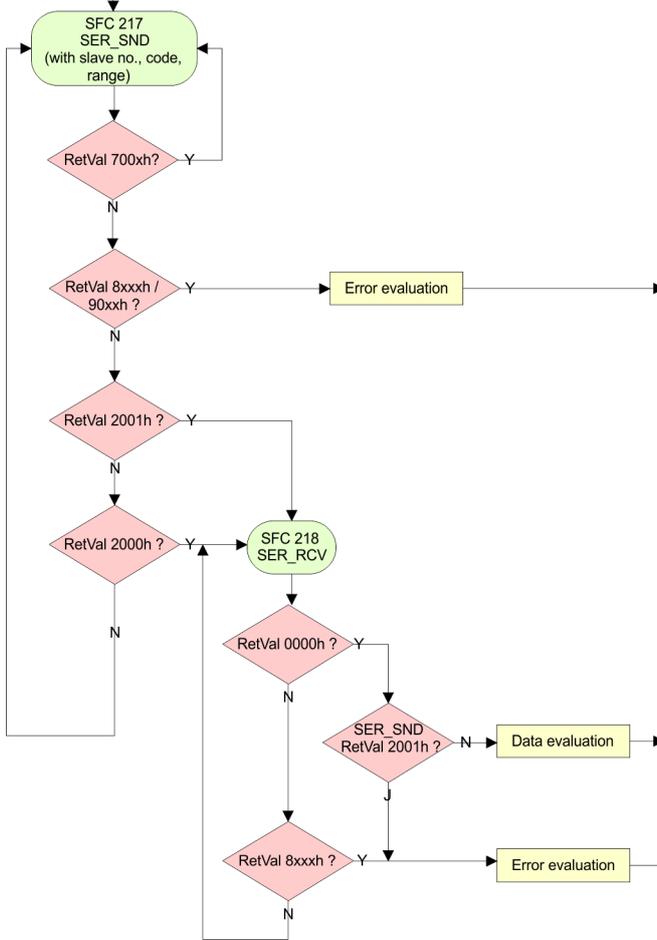
Structure for the according PLC programs for master and slave:



OB100:



OB1:



7 Deployment PROFIBUS communication

7.1 Overview

PROFIBUS DP

- PROFIBUS is an international standard applicable to an open and serial field bus for building, manufacturing and process automation that can be used to create a low (sensor-/actuator level) or medium (process level) performance network of programmable logic controllers.
- PROFIBUS comprises an assortment of compatible versions. The following details refer to PROFIBUS DP.
- PROFIBUS DP is a special protocol intended mainly for automation tasks in a manufacturing environment. DP is very fast, offers Plug'n'Play facilities and provides a cost-effective alternative to parallel cabling between PLC and remote I/O. PROFIBUS DP was designed for high-speed data communication on the sensor-actuator level.
- The data transfer referred to as "Data Exchange" is cyclical. During one bus cycle, the master reads input values from the slaves and writes output information to the slaves.

CPU with DP master

The PROFIBUS DP master is to be configured in the hardware configurator from Siemens. Therefore the configuration happens by the sub module X1 (MPI/DP) of the Siemens CPU.

After the transmission of the data to the CPU, the configuration data are internally passed on to the PROFIBUS master part.

During the start-up the DP master automatically includes his data areas into the address range of the CPU. Project engineering in the CPU is not required.

Deployment of the DP master with CPU

Via the PROFIBUS DP master PROFIBUS DP slaves may be coupled to the CPU. The DP master communicates with the DP slaves and links up its data areas with the address area of the CPU.

At every POWER ON res. overall reset the CPU fetches the I/O mapping data from the master. At DP slave failure, the ER-LED is on and the OB 86 is requested. If this is not available, the CPU switches to STOP and BASP is set. As soon as the BASP signal comes from the CPU, the DP master is setting the outputs of the connected periphery to zero. The DP master remains in the operating mode RUN independent from the CPU.

DP slave operation

For the deployment in a super-ordinated master system you first have to project your slave system as Siemens CPU in slave operation mode with configured in-/output areas. Afterwards you configure your master system. Couple your slave system to your master system by dragging the CPU 31x from the hardware catalog at *Configured stations* onto the master system, choose your slave system and connect it.

7.2 Fast introduction

Overview

The PROFIBUS DP master is to be configured in the hardware configurator. Here the configuration happens by means of the sub module X2 (DP) of the Siemens CPU.

Steps of configuration

For the configuration of the PROFIBUS DP master please follow the following approach:

- **Hardware configuration - CPU**
- **Deployment as DP master or Deployment as DP slave**
- **Transfer of the complete project to CPU** ↪ Chap. 5.11 'Project transfer' page 60



With the Siemens SIMATIC Manager the CPU 317-4NE23 from VIPA is to be configured as

CPU 317-2DP (6ES7 317-2AK14 V3.3).

The integrated PROFIBUS DP master (X3) is to be configured and connected via the sub module X2 (DP). The Ethernet PG/OP channel of the 317-4NE23 is always to be configured as 1. module after the really plugged modules at the standard bus as CP343-1 (343-1EX11) from Siemens.

The CP 343 of the CPU is always to be configured below the before configured PG/OP channel also as CP343-1 (343-1EX11).

7.3 Hardware configuration - CPU

Precondition

The configuration of the CPU takes place at the Siemens 'hardware configurator'. The hardware configurator is part of the Siemens SIMATIC Manager. It serves for project engineering. The modules, which may be configured here are listed in the hardware catalog. If necessary you have to update the hardware catalog with 'Options → Update Catalog'.

For project engineering a thorough knowledge of the Siemens SIMATIC Manager and the Siemens hardware configurator is required.



Please consider that this SPEED7-CPU has 4 ACCUs. After an arithmetic operation (+I, -I, *I, /I, +D, -D, *D, /D, MOD, +R, -R, *R, /R) the content of ACCU 3 and ACCU 4 is loaded into ACCU 3 and 2. This may cause conflicts in applications that presume an unmodified ACCU 2.

For more information may be found in the manual "VIPA Operation list SPEED7" at "Differences between SPEED7 and 300V programming".

Proceeding

| Slot | Module |
|------|--------------------|
| 1 | |
| 2 | CPU 317-2DP |
| X1 | MPI/DP |
| X2 | DP |
| 3 | |

With the Siemens SIMATIC Manager the following steps should be executed:

1. ➤ Start the Siemens hardware configurator with a new project.
2. ➤ Insert a profile rail from the hardware catalog.
3. ➤ Place at 'Slot' number 2 the Siemens CPU 317-2DP (6ES7 317-2AK14 V3.3).
4. ➤ The integrated PROFIBUS DP master (X3) is to be configured and connected via the sub module X2 (DP).

7.3.1 Switching CPU type to CPU 318-2AJ00

Overview

To use projects, which were configured with the Siemens CPU type 318-2AJ00, you can switch from original CPU type to CPU type 318-2AJ00 by means of a CMD auto command. The setting is retained even after power cycle, firmware update or battery failure. With reset to factory settings respectively with the corresponding CMD auto command the CPU type is reset to the original CPU type.

Switching

■ CPU type 318

- Switching takes place with the CMD auto command *CPUTYPE_318*. After this perform a power cycle.

- ↪ *Chap. 5.19 'CMD - auto commands' page 78*

```
CMD_START
CPUTYPE_318
CMD_END
```

■ CPU type original

- The reset to the original type takes place with the CMD auto command *CPU-TYPE_ORIGINAL* respectively by ↪ *Chap. 5.16 'Reset to factory settings' page 75*.

- ↪ *Chap. 5.19 'CMD - auto commands' page 78*

```
CMD_START
CPUTYPE_ORIGINAL
CMD_END
```

7.4 Deployment as PROFIBUS DP master

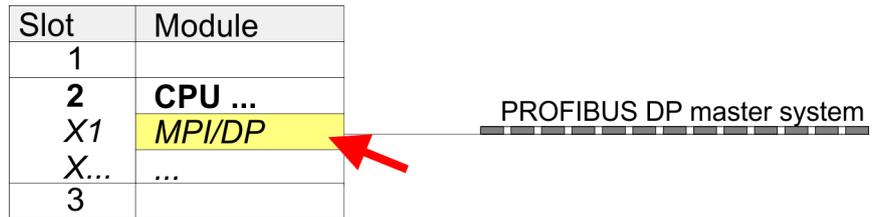
Precondition

The hardware configuration described before was established.

Proceeding

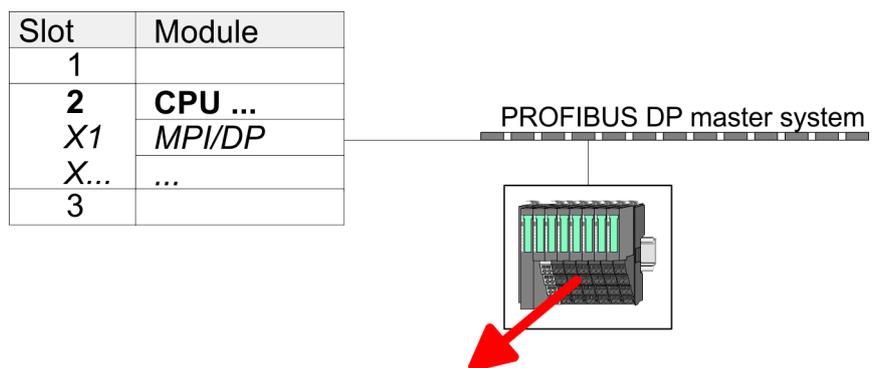
1. ➤ Open the properties dialog of the DP interface of the CPU by means of a double-click at 'MPI/DP'.
2. ➤ Set Interface type to "PROFIBUS"
3. ➤ Connect to PROFIBUS and preset an address (preferably 2) and confirm with [OK].
4. ➤ Switch at Operating mode to "DP master" and confirm the dialog with [OK]. A PROFIBUS DP master system is inserted.

⇒ A PROFIBUS DP master system is inserted:



Now the project engineering of your PROFIBUS DP master is finished. Please link up now your DP slaves with periphery to your DP master.

1. ➤ For the project engineering of PROFIBUS DP slaves you search the concerning PROFIBUS DP slave in the hardware catalog and drag&drop it in the subnet of your master.
2. ➤ Assign a valid PROFIBUS address to the DP slave.
3. ➤ Link up the modules of your DP slave system in the plugged sequence and add the addresses that should be used by the modules.
4. ➤ If needed, parameterize the modules.
5. ➤ Save, compile and transfer your project.



| Slot | Module | Order number | |
|------|--------|--------------|--|
| 1 | ... | | |
| 2 | Module | | |
| 3 | ... | | |
| 4 | | | |
| 5 | | | |
| ... | | | |

7.5 Deployment as PROFIBUS DP slave

Fast introduction

In the following the deployment of the PROFIBUS section as "intelligent" DP slave on master system is described, which exclusively may be configured in the Siemens SIMATIC Manager. The following steps are required:

1. ➤ Configure a station with a CPU with operating mode DP slave.
2. ➤ Connect to PROFIBUS and configure the in-/output area for the slave section.
3. ➤ Save and compile your project.
4. ➤ Configure another station with another CPU with operating mode DP master.
5. ➤ Connect to PROFIBUS and configure the in-/output ranges for the master section.
6. ➤ Save, compile and transfer your project to your CPU.

Project engineering of the slave section

1. ➤ Start the Siemens SIMATIC Manager and configure a CPU as described at "Hardware configuration - CPU".
2. ➤ Designate the station as "...DP slave".
3. ➤ Add your modules according to the real hardware assembly.
4. ➤ Open the properties dialog of the DP interface of the CPU by means of a double-click at 'MPI/DP'.
5. ➤ Set Interface type to "PROFIBUS".
6. ➤ Connect to PROFIBUS and preset an address (e.g. 3) and confirm with [OK].
7. ➤ Switch at Operating mode to "DP slave" .
8. ➤ Via Configuration you define the in-/output address area of the slave CPU, which are to be assigned to the DP slave.
9. ➤ Save, compile and transfer your project to your CPU.

Slave section

| Standard bus | |
|--------------|---------|
| Slot | Module |
| 1 | |
| 2 | CPU ... |
| X1 | MPI/DP |
| X... | ... |
| 3 | |
| 4 | ... |
| 5 | Modules |
| 6 | ... |

Object properties

Operating mode: DP slave
 Connect: PROFIBUS
 PROFIBUS address: > 1

Configuration:
 Input area
 Output area

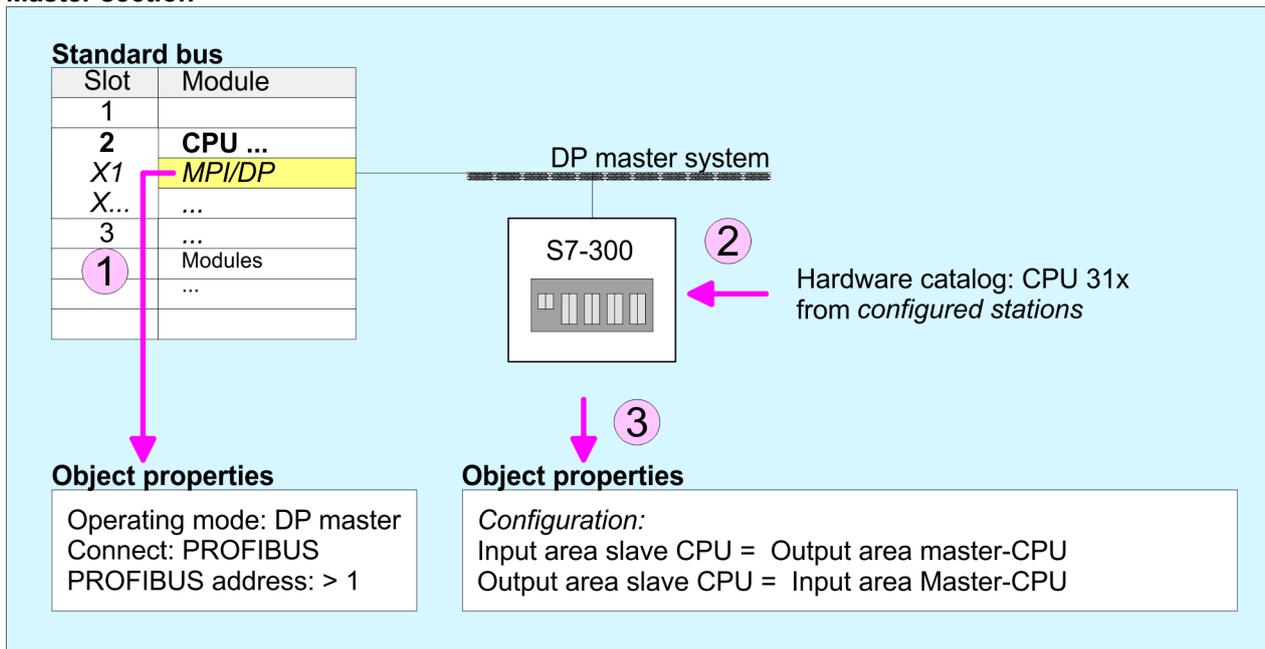
Project engineering master section

DP master and DP slave are in the same project

1. ➤ Insert another station and configure a CPU.
2. ➤ Designate the station as "...DP master".
3. ➤ Add your modules according to the real hardware assembly.
4. ➤ Open the properties dialog of the DP interface of the CPU by means of a double-click at 'MPI/DP'.
5. ➤ Set Interface: type to "PROFIBUS".
6. ➤ Connect to PROFIBUS and preset an address (e.g. 2) and confirm with [OK].

7. ➤ Switch at Operating mode to "DP master" and confirm the dialog with [OK].
8. ➤ Connect your slave system to this master system by dragging the "CPU 31x" from the hardware catalog at Configured stations onto the master system and select your slave system to be coupled.
9. ➤ Open the *Configuration at Object properties* of your slave system.
10. ➤ Via double click to the according configuration line you assign the according input address area on the master CPU to the slave output data and the output address area to the slave input data.
11. ➤ Save, compile and transfer your project to your CPU.

Master section



DP master and DP slave are in different projects

1. ➤ Create a new project, add a station and configure a CPU.
2. ➤ Designate the station as "...DP master".
3. ➤ Add your modules according to the real hardware assembly.
4. ➤ Open the properties dialog of the DP interface of the CPU by means of a double-click at 'DP'.
5. ➤ Set Interface: type to "PROFIBUS".
6. ➤ Connect to PROFIBUS and preset an address (e.g. 2) and confirm with [OK].
7. ➤ Switch at Operating mode to "DP master" and confirm the dialog with [OK].
8. ➤ For further configuration, install the GSD file from the appropriately configured Siemens slave CPU.
9. ➤ Choose via 'Additional field devices → PLC → SIMATIC' the Siemens slave CPU.
10. ➤ Connect your slave system to the master system by dragging the slave CPU via PROFIBUS onto the master system.
11. ➤ Via the slots configure the I/O area of your slave system.
12. ➤ Save, compile and transfer your project to your CPU.

7.6 PROFIBUS installation guidelines

PROFIBUS in general

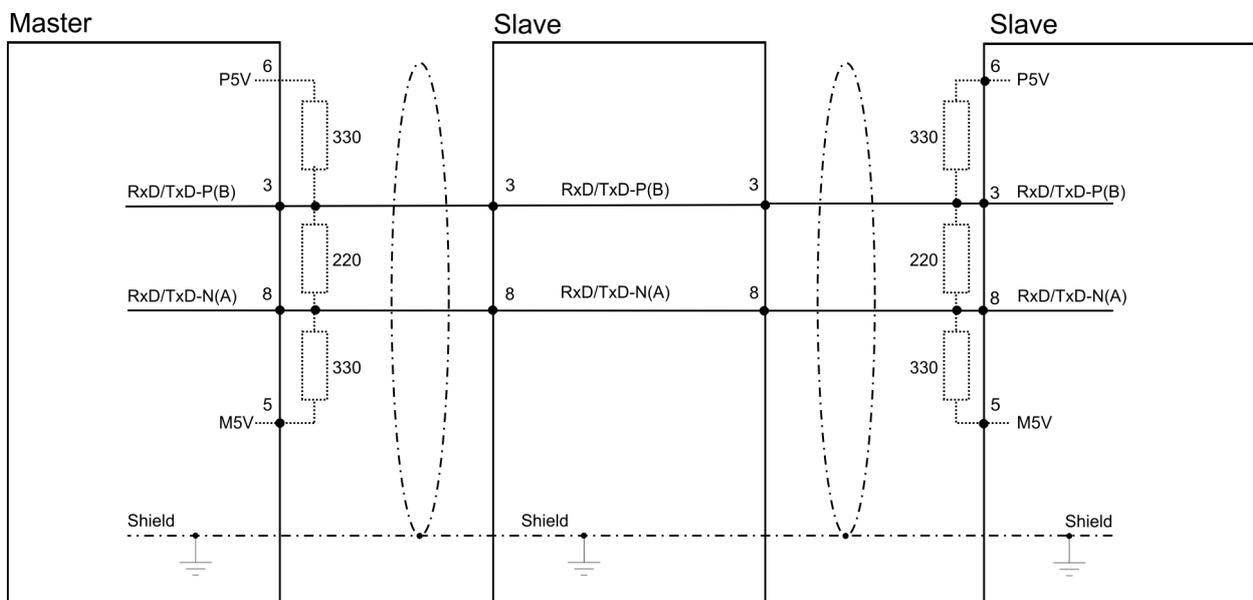
- A PROFIBUS DP network may only be built up in linear structure.
- PROFIBUS DP consists of minimum one segment with at least one master and one slave.
- A master has always been deployed together with a CPU.
- PROFIBUS supports max. 126 participants.
- Per segment a max. of 32 participants is permitted.
- The max. segment length depends on the transfer rate:
 - 9.6 ... 187.5bit/s → 1000m
 - 500kbit/s → 400m
 - 1.5Mbit/s → 200m
 - 3 ... 12Mbit/s → 100m
- Max. 10 segments may be built up. The segments are connected via repeaters. Every repeater counts for one participant.
- The bus respectively a segment is to be terminated at both ends.
- All participants are communicating with the same transfer rate. The slaves adjust themselves automatically on the transfer rate.

Transfer medium

- As transfer medium PROFIBUS uses an isolated twisted-pair cable based upon the RS485 interface.
- The RS485 interface is working with voltage differences. Though it is less irritable from influences than a voltage or a current interface. You are able to configure the network as well linear as in a tree structure.
- Max. 32 participants per segment are permitted. Within a segment the members are linear connected. The segments are connected via repeaters. The maximum segment length depends on the transfer rate.
- PROFIBUS DP uses a transfer rate between 9.6kbit/s and 12Mbit/s, the slaves are following automatically. All participants are communicating with the same transfer rate.
- The bus structure under RS485 allows an easy connection res. disconnection of stations as well as starting the system step by step. Later expansions don't have any influence on stations that are already integrated. The system realizes automatically if one partner had a fail down or is new in the network.

Bus connection

The following picture illustrates the terminating resistors of the respective start and end station.



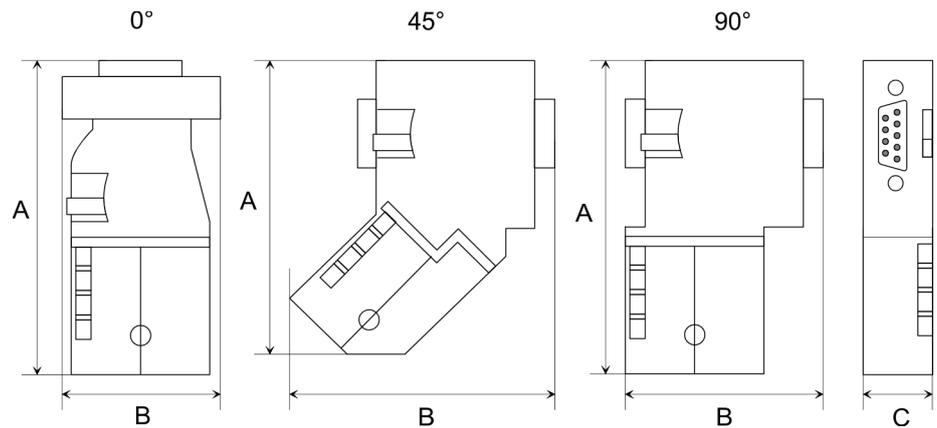


The PROFIBUS line has to be terminated with its ripple resistor. Please make sure to terminate the last participants on the bus at both ends by activating the terminating resistor.

EasyConn bus connector



In PROFIBUS all participants are wired parallel. For that purpose, the bus cable must be feed-through. Via the order number 972-0DP10 you may order the bus connector "EasyConn" from Yaskawa. This is a bus connector with switchable terminating resistor and integrated bus diagnostic.



| Dimensions in mm | 0° | 45° | 90° |
|------------------|------|------|------|
| A | 64 | 61 | 66 |
| B | 34 | 53 | 40 |
| C | 15.8 | 15.8 | 15.8 |



To connect this EasyConn plug, please use the standard PROFIBUS cable type A (EN50170). Starting with release 5 you also can use highly flexible bus cable:

Lapp cable order no: 2170222, 2170822, 2170322.

With the order no. 905-6AA00 Yaskawa offers the "EasyStrip" de-isolating tool that makes the connection of the EasyConn much easier.

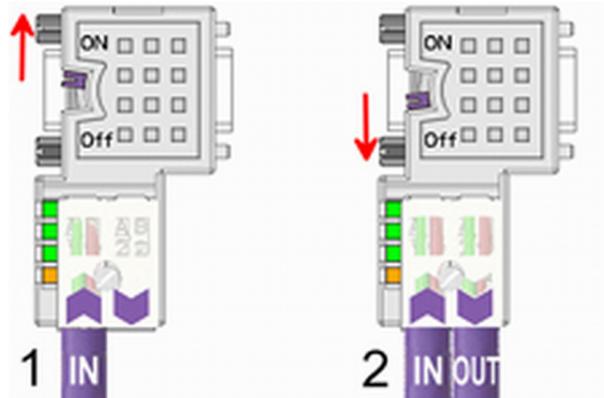


Dimensions in mm

Termination with "EasyConn"

The "EasyConn" bus connector is provided with a switch that is used to activate a terminating resistor.

Wiring



- [1] 1./last bus participant
- [2] further participants



CAUTION!

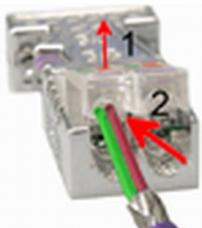
The terminating resistor is only effective, if the connector is installed at a bus participant and the bus participant is connected to a power supply.

The tightening torque of the screws to fix the connector to a device must not exceed 0.02Nm!



A complete description of installation and deployment of the terminating resistors is delivered with the connector.

Assembly



1. Loosen the screw.
2. Lift contact-cover.
3. Insert both wires into the ducts provided (watch for the correct line colour as below!)
4. Please take care not to cause a short circuit between screen and data lines!



5. Close the contact cover.
6. Tighten screw (max. tightening torque 0.08Nm).



The green line must be connected to A, the red line to B!

7.7 Commissioning and Start-up behavior

Start-up on delivery

In delivery the CPU is overall reset. The PROFIBUS part is deactivated and its LEDs are off after Power ON.

Online with bus parameter without slave project

The DP master can be served with bus parameters by means of a hardware configuration. As soon as these are transferred the DP master goes online with his bus parameter. This is shown by the RUN LED. Now the DP master can be contacted via PROFIBUS by means of his PROFIBUS address. In this state the CPU can be accessed via PROFIBUS to get configuration and DP slave project.

Slave configuration

If the master has received valid configuration data, he switches to *Data Exchange* with the DP slaves. This is indicated by the DE-LED.

CPU state controls DP master

After PowerON respectively a receipt of a new hardware configuration the configuration data and bus parameter were transferred to the DP master. Dependent on the CPU state the following behavior is shown by the DP master:

Master behavior at CPU STOP

- The global control command "Clear" is sent to the slaves by the master. Here the DE-LED is blinking.
- DP slaves with fail safe mode were provided with output telegram length "0".
- DP slaves without fail safe mode were provided with the whole output telegram but with output data = 0.
- The input data of the DP slaves were further cyclically transferred to the input area of the CPU.

Master behavior at CPU RUN

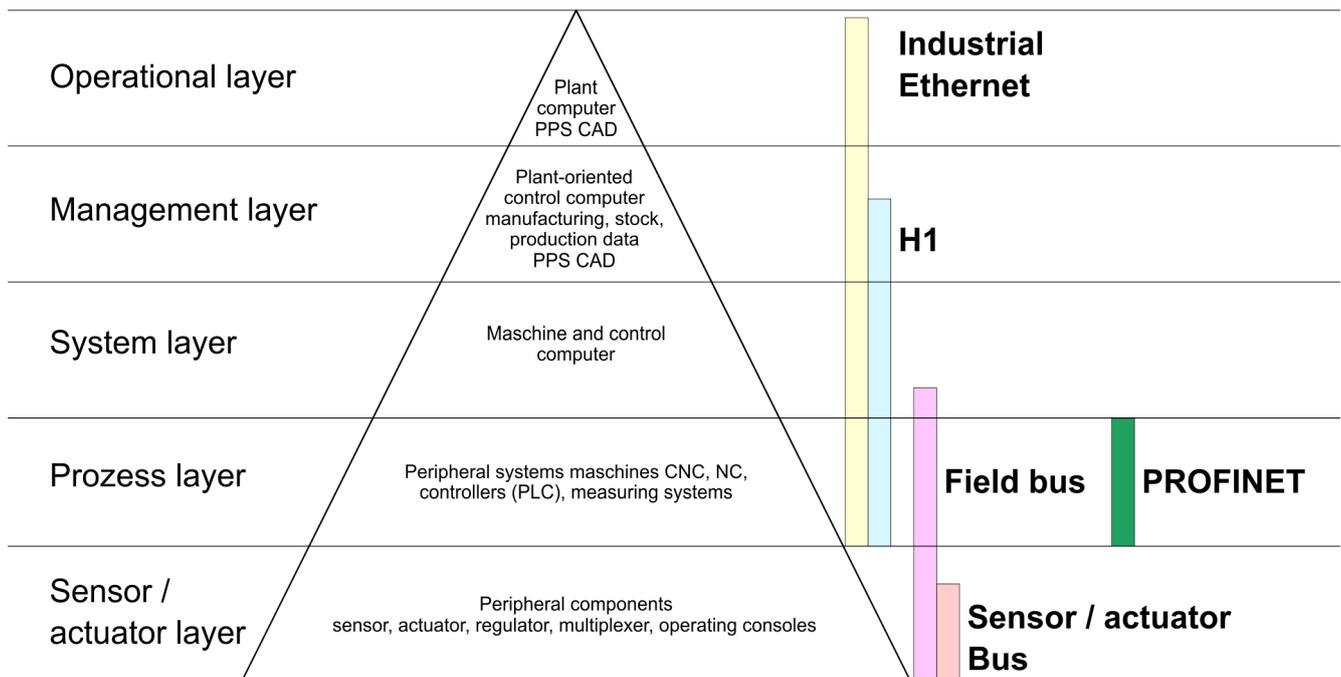
- The global control command "Operate" is sent to the slaves by the master. Here the DE-LED is on.
- Every connected DP slave is cyclically attended with an output telegram containing recent output data.
- The input data of the DP slaves were cyclically transferred to the input area of the CPU.

8 Deployment Ethernet communication - productive

8.1 Basics - Industrial Ethernet in automation

Overview

The flow of information in a company presents a vast spectrum of requirements that must be met by the communication systems. Depending on the area of business the bus system or LAN must support a different number of users, different volumes of data must be transferred and the intervals between transfers may vary, etc. It is for this reason that different bus systems are employed depending on the respective task. These may be subdivided into different classes. The following model depicts the relationship between the different bus systems and the hierarchical structures of a company:



Industrial Ethernet

Industrial Ethernet is an electrical net based on shielded twisted pair cabling or optical net based on optical fibre. Industrial Ethernet is defined by the international standard IEEE 802.3

The net access of Industrial Ethernet corresponds to IEEE 802.3 - CSMA/CD (**C**arrier **S**ense **M**ultiple **A**ccess/**C**ollision **D**etection) scheme:

- Every station "listens" on the bus cable and receives communication messages that are addressed to it.
- Stations will only initiate a transmission when the line is unoccupied.
- In the event that two participants should start transmitting simultaneously, they will detect this and stop transmitting to restart after a random delay time has expired.
- Using switches there is the possibility for communication without collisions.

8.2 Basics - ISO/OSI reference model

Overview

The ISO/OSI reference model is based on a proposal that was developed by the International Standards Organization (ISO). This represents the first step towards an international standard for the different protocols. It is referred to as the ISO-OSI layer model. OSI is the abbreviation for **O**pen **S**ystem **I**nterconnection, the communication between open systems. The ISO/OSI reference model does not represent a network architecture as it does not define the services and protocols used by the different layers. The model simply specifies the tasks that the different layers must perform. All current communication systems are based on the ISO/OSI reference model, which is defined by the ISO 7498 standard. The reference model structures communication systems into 7 layers that cover different communication tasks. In this manner the complexity of the communication between different systems is divided amongst different layers to simplify the task.

The following layers have been defined:

- Layer 7 - Application Layer
- Layer 6 - Presentation Layer
- Layer 5 - Session Layer
- Layer 4 - Transport Layer
- Layer 3 - Network Layer
- Layer 2 - Data Link Layer
- Layer 1- Physical Layer

Depending on the complexity and the requirements of the communication mechanisms a communication system may use a subset of these layers.

Layer 1 - Bit communication layer (physical layer)

The bit communication layer (physical layer) is concerned with the transfer of data bits via the communication channel. This layer is therefore responsible for the mechanical, electrical and the procedural interfaces and the physical communication medium located below the bit communication layer:

- Which voltage represents a logical 0 or a 1?
- The minimum time the voltage is present to be recognized as a bit.
- The pin assignment of the respective interface.

Layer 2 - Security layer (data link layer)

This layer performs error-checking functions for bit strings transferred between two communicating partners. This includes the recognition and correction or flagging of communication errors and flow control functions. The security layer (data link layer) converts raw communication data into a sequence of frames. This is where frame limits are inserted on the transmitting side and where the receiving side detects them. These limits consist of special bit patterns that are inserted at the beginning and at the end of every frame. The security layer often also incorporates flow control and error detection functions. The data security layer is divided into two sub-levels, the LLC and the MAC level. The MAC (**M**edia **A**ccess **C**ontrol) is the lower level and controls how senders are sharing a single transmit channel. The LLC (**L**ogical **L**ink **C**ontrol) is the upper level that establishes the connection for transferring the data frames from one device into the other.

Layer 3 - Network layer

The network layer is an agency layer. Business of this layer is to control the exchange of binary data between stations that are not directly connected. It is responsible for the logical connections of layer 2 communications. Layer 3 supports the identification of the single network addresses and the establishing and disconnecting of logical communication channels. Additionally, layer 3 manages the prior transfer of data and the error processing of data packets. IP (Internet Protocol) is based on Layer 3.

Layer 4 - Transport layer

Layer 4 connects the network structures with the structures of the higher levels by dividing the messages of higher layers into segments and passes them on to the network layer. Hereby, the transport layer converts the transport addresses into network addresses. Common transport protocols are: TCP, SPX, NWLink and NetBEUI.

- Layer 5 - Session layer** The session layer is also called the communication control layer. It relieves the communication between service deliverer and the requestor by establishing and holding the connection if the transport system has a short time fail out. At this layer, logical users may communicate via several connections at the same time. If the transport system fails, a new connection is established if needed. Additionally this layer provides methods for control and synchronization tasks.
- Layer 6 - Presentation layer** This layer manages the presentation of the messages, when different network systems are using different representations of data. Layer 6 converts the data into a format that is acceptable for both communication partners. Here compression/decompression and encrypting/decrypting tasks are processed. This layer is also called interpreter. A typical use of this layer is the terminal emulation.
- Layer 7 - Application layer** The application layer is the link between the user application and the network. The tasks of the application layer include the network services like file, print, message, data base and application services as well as the according rules. This layer is composed from a series of protocols that are permanently expanded following the increasing needs of the user.

8.3 Basics - Terms

Network (LAN)

A network res. LAN (Local Area Network) provides a link between different stations that enables them to communicate with each other. Network stations consist of PCs, IPCs, TCP/IP adapters, etc. Network stations are separated by a minimum distance and connected by means of a network cable. The combination of network stations and the network cable represent a complete segment. All the segments of a network form the Ethernet (physics of a network).

Twisted Pair

In the early days of networking the Triaxial- (yellow cable) or thin Ethernet cable (Cheapernet) was used as communication medium. This has been superseded by the twisted-pair network cable due to its immunity to interference. The CPU has a twisted-pair connector. The twisted-pair cable consists of 8 cores that are twisted together in pairs. Due to these twists this system provides an increased level of immunity to electrical interference. For linking please use twisted pair cable which at least corresponds to the category 5. Where the coaxial Ethernet networks are based on a bus topology the twisted-pair network is based on a point-to-point scheme. The network that may be established by means of this cable has a star topology. Every station is connected to the star coupler (hub/switch) by means of a separate cable. The hub/switch provides the interface to the Ethernet.

Hub (repeater)

The hub is the central element that is required to implement a twisted-pair Ethernet network. It is the job of the hub to regenerate and to amplify the signals in both directions. At the same time it must have the facility to detect and process segment wide collisions and to relay this information. The hub is not accessible by means of a separate network address since it is not visible to the stations on the network. A hub has provisions to interface to Ethernet or to another hub res. switch.

Switch

A switch also is a central element for realizing Ethernet on Twisted Pair. Several stations res. hubs are connected via a switch. Afterwards they are able to communicate with each other via the switch without interfering the network. An intelligent hardware analyses the incoming telegrams of every port of the switch and passes them collision free on to the destination stations of the switch. A switch optimizes the bandwidth in every connected segment of a network. Switches enable exclusive connections between the segments of a network changing at request.

8.4 Basics - Protocols

Overview

Protocols define a set of instructions or standards that enable computer to establish communication connections and exchange information as error free as possible. A commonly established protocol for the standardization of the complete computer communication is the so called ISO/OSI layer model, a model based upon seven layers with rules for the usage of hardware and software ↪ *Chap. 8.2 'Basics - ISO/OSI reference model' page 109*

The following protocols are used:

- Communication connections
 - Siemens S7 connections
 - TCP/IP
 - UDP
 - RFC1006 (ISO-ON-TCP)
 - ISO transport (once H1)
- Open communication
 - TCP native according to RFC 793
 - ISO on TCP according to RFC 1006
 - UDP according to RFC 768

Siemens S7 connections

With the Siemens S7 connection large data sets may be transferred between PLC systems based on Siemens STEP®7. Here the stations are connected via Ethernet. Precondition for the Siemens S7 communication is a configured connection table, which contains the defined connections for communication. Here NetPro from Siemens may be used.

Properties:

- A communication connection is specified by a connection ID for each connection partner.
- The acknowledgement of the data transfer is established from the partner station at level 7 of the ISO/OSI reference model.
- At the PLC side FB/SFB Yaskawa handling blocks are necessary for data transfer for the Siemens S7 connections.



More information about the usage of these blocks may be found in the manual "SPEED7 Operation List" from Yaskawa.

TCP/IP

TCP/IP protocols are available on all major systems. At the bottom end this applies to simple PCs, through to the typical mini-computer up to mainframes. For the wide spread of Internet accesses and connections, TCP/IP is often used to assemble heterogeneous system pools. TCP/IP (**T**ransmission **C**ontrol **P**rotocol / **I**nternet **P**rotocol) collects a various range of protocols and functions. TCP and IP are only two of the protocols required for the assembly of a complete architecture.

- TCP/IP
 - The application layer provides programs like "FTP" and "Telnet" for the PC. The application layer of the Ethernet CP is defined with the user application using the standard handling blocks. These user applications use the transport layer with the protocols TCP or UDP for the data transfer which themselves communicate via the IP protocol with the Internet layer.
 - Besides of the IP address ports are used for the addressing. A port address should be within the range of 2000...65535.
 - Not depending on the used protocol, the PLC needs the VIPA handling blocks AG_SEND (FC 5) and AG_RECV (FC 6) for data transfer.
- IP
 - IP covers the network layer (Layer 3) of the ISO/OSI layer model.
 - The purpose of IP is to send data packages from on PC to another passing several other PCs. These data packages are referred to as datagrams. The IP doesn't neither guarantee the correct sequence of the datagrams nor the delivery at the receiver.
 - For the unambiguous identification between sender and receiver 32Bit addresses (IP addresses) are used that are normally written as four octets (exactly 8bit), e.g. 172.16.192.11. These Internet addresses are defined and assigned worldwide, thus every user may communicate with all other TCP/IP users.
 - One part of the address specifies the network; the rest serves the identification of the participants inside the network. The boarder between the network and the host part is variable and depends on the size of the network.
 - To save IP addresses, so called NAT router are used that have one official IP address and cover the network. Then the network can use any IP address.
- TCP
 - TCP bases directly on the IP and thus covers the transport layer (layer 4) of the ISO/OSI layer model.
 - TCP is a connection orientated end-to-end protocol and serves the logic connection between two partners.
 - TCP guarantees the correct sequence and reliability of the data transfer. Therefore you need a relatively large protocol overhead that slows down the transfer speed
 - Every datagram gets a header of at least 20Byte. This header also contains a sequence number identifying the series. This has the consequence that the single datagrams may reach the destination on different ways through the network.
 - Using TCP connections, the telegram length is not transmitted. This means that the recipient has to know how many bytes belong to a message.
 - To transfer data with variable length you may begin the user data with the length information and evaluate this at the counter station.

UDP

UDP (**U**ser **D**atagramm **P**rotocol) is a connection free transport protocol. It has been defined in the RFC768 (**R**quest for **C**omment). Compared to TCP, it has much fewer characteristics. The addressing happens via port numbers. UDP is a fast unsafe protocol for it doesn't neither care about missing data packages nor about their sequence.

ISO-on-TCP RFC1006

The TCP transport service works stream orientated. This means that data packages assembled by the user not necessarily have to receive the partner in the same packaging. Depending on the data amount, packages may though come in the correct

sequence but differently packed. This causes that the recipient may not recognize the package borders anymore. For example you may send 2x 10Byte packages but the counter station receives them as 20Byte package. But for most of the applications the correct packaging is important. Due to this you need another protocol above TCP. This purpose is defined in the protocol extension RFC1006 (ISO-on-TCP).

- RFC1006 describes the function of an ISO transport interface (ISO 8072) basing upon the transport interface TCP (RFC793).
- The basic protocol of RFC1006 is nearly identical to TP0 (Transport Protocol, Class 0) in ISO 8073.
- For RFC1006 is run as protocol for TCP, the decoding takes place in the data section of the TCP package.
- In contrast to TCP here the receipt of a telegram is confirmed.
- Instead of ports TSAPs are used for the addressing besides of the IP address. The TSAP length may be 1 ... 16 characters. The entry may happen in ASCII or Hex format.
- Not depending on the used protocol, the PLC needs the VIPA handling blocks AG_SEND (FC 5) and AG_RECV (FC 6) for data transfer.
- Contrary to TCP different telegram lengths can be received using RFC1006.

ISO transport (once H1)

With ISO transport connections there is the possibility for program and event controlled communication via Industrial Ethernet. Here data blocks may be exchanged bi-directional. The ISO transport connection offers services for a safety transfer of data by means of configured connections. Large data blocks may be transferred by means of blocking. The transmission reliability is very high by the automatic repetition, by additional block test mechanisms and by the receipt acknowledgement at the receiver side.

- The ISO transport service (ISO 8073 class 4) corresponds to the transport layer (Layer 4) of the ISO/OSI reference model.
- ISO transport connections are exclusively transferred via Industrial Ethernet and they are optimized for the deployment in a closed manufacturing area.
- The receipt of data is acknowledged by the partner station. Here different telegram lengths may be processed.
- For deployment of the ISO transport connections they must be enabled in the Ethernet properties of the CP within your project. Here there is the possibility to assign the CP to a MAC address.
- The addressing happens by MAC address (Ethernet address) and TSAPs (Transport **S**ervice **A**ccess **P**oint).
- The data transfer is made by the services SEND/RECEIVE and FETCH/WRITE.
- Not depending on the used protocol, the PLC needs the VIPA handling blocks AG_SEND (FC 5) and AG_RECV (FC 6) for data transfer.

Open communication

In the *'open communication'* the communication takes place via the user program by means of handling blocks. These blocks are also part of the Siemens SIMATIC Manager. You will find these in the *'Standard Library'* at *'Communication Blocks'*.

- *Connection-oriented protocols:*

Connection-oriented protocols establish a (logical) connection to the communication partner before data transmission is started. And if necessary they terminate the connection after the data transfer was finished. Connection-oriented protocols are used for data transmission when reliable, guaranteed delivery is of particular importance. In general, many logical connections can exist on one physical line. The following connection-oriented protocols are supported with FBs for open communication via Industrial Ethernet:

- *TCP native accord. to RFC 793:*

During data transmission, no information about the length or about the start and end of a message is transmitted. However, the receiver has no means of detecting where one message ends in the data stream and the next one begins. The transfer is stream-oriented. For this reason, it is recommended that the data length of the FBs is identical for the sending and receiving station. If the number of received data does not fit to the preset length you either will get not the whole data, or you will get data of the following job.

- *ISO on TCP accord. to RFC 1006:*

During data transmission, information on the length and the end of the message is also transmitted. If you have specified the length of the data to be received greater than the length of the data to be sent, the receive block will copy the received data completely into the receive range.

- *Connection-less protocol:*

There is thus no establishment and termination of a connection with a remote partner. Connection-less protocols transmit data with no acknowledge and with no reliable guaranteed delivery to the remote partner.

- *UDP accord. to RFC 768:*

In this case, when calling the sending block you have to specify the address parameters of the receiver (IP address and port number). During data transmission, information on the length and the end of the message is also transmitted. In order to be able to use the sending and receiving blocks first you have to configure the local communications access point at both sides. With each new call of the sending block, you re-reference the remote partner by specifying its IP address and its port number.

8.5 Basics - IP address and subnet

IP address structure

Exclusively IPv4 is supported. At IPv4 the IP address is a 32bit address that must be unique within the network and consists of 4 numbers that are separated by a dot. Every IP address is a combination of a *Net-ID* and a *Host-ID* and has the following

Structure: **xxx.xxx.xxx.xxx**

Range: 000.000.000.000 to 255.255.255.255

Net-ID, Host-ID

The **Network-ID** identifies a network res. a network controller that administrates the network. The **Host-ID** marks the network connections of a participant (host) to this network.

Subnet mask

The **Host-ID** can be further divided into a *Subnet-ID* and a new *Host-ID* by using a bit for bit AND assignment with the Subnet mask.

The area of the original **Host-ID** that is overwritten by 1 of the Subnet mask becomes the **Subnet-ID**, the rest is the new **Host-ID**.

| | | | |
|------------------------------|----------------|----------------|-------------|
| Subnet mask | binary all "1" | binary all "0" | |
| IPv4 address | Net-ID | Host-ID | |
| Subnet mask and IPv4 address | Net-ID | Subnet-ID | new Host-ID |

Address at first start-up

At the first start-up of the CPU, the Ethernet PG/OP channel and the CP 343 do not have an IP address.

Information about the assignment of IP address data to the Ethernet PG/OP channel may be found in [Chap. 5.6 'Hardware configuration - Ethernet PG/OP channel' page 49](#).

Information about the assignment of IP address data to the CP 343 may be found in [Chap. 8.8 'Commissioning and initialization' page 119](#)

Address classes

For IPv4 addresses there are five address formats (class A to class E) that are all of a length of 4byte = 32bit.

| | | | |
|---------|-------|----------------------|-----------------|
| Class A | 0 | Network-ID (1+7bit) | Host-ID (24bit) |
| Class B | 10 | Network-ID (2+14bit) | Host-ID (16bit) |
| Class C | 110 | Network-ID (3+21bit) | Host-ID (8bit) |
| Class D | 1110 | Multicast group | |
| Class E | 11110 | Reserved | |

The classes A, B and C are used for individual addresses, class D for multicast addresses and class E is reserved for special purposes. The address formats of the 3 classes A, B, C are only differing in the length of Network-ID and Host-ID.

Private IP networks

These addresses can be used as net-ID by several organizations without causing conflicts, for these IP addresses are neither assigned in the Internet nor are routed in the Internet. To build up private IP-Networks within the Internet, RFC1597/1918 reserves the following address areas:

| Network class | from IP | to IP | Standard subnet mask |
|---------------|---------------------|-------------------------|-----------------------|
| A | 10. <u>0.0.0</u> | 10. <u>255.255.255</u> | 255. <u>0.0.0</u> |
| B | 172.16. <u>0.0</u> | 172.31. <u>255.255</u> | 255.255. <u>0.0</u> |
| C | 192.168.0. <u>0</u> | 192.168.255. <u>255</u> | 255.255.255. <u>0</u> |

(The Host-ID is underlined.)

Reserved Host-IDs

Some Host-IDs are reserved for special purposes.

| | |
|---|---------------------------------------|
| Host-ID = "0" | Identifier of this network, reserved! |
| Host-ID = maximum (binary complete "1") | Broadcast address of this network |



Never choose an IP address with Host-ID=0 or Host-ID=maximum! (e.g. for class B with subnet mask = 255.255.0.0, the "172.16.0.0" is reserved and the "172.16.255.255" is occupied as local broadcast address for this network.)

8.6 Basics - MAC address and TSAP

MAC address

There is a unique MAC address (**Media Access Control**) necessary for each CP. Usually a module is labelled with its MAC address by the manufacturer. This address should be used for project engineering of the CP. The MAC address has a length of 6bytes. On delivery the first three bytes specify the manufacturer. These bytes are assigned by the IEEE committee. The last 3 bytes may be assigned by the manufacturer. In a network several stations with the same MAC address may not exist. The MAC address may be changed at any time. You will get a valid MAC address from your network administrator.

- Broadcast address
 - The MAC address, with which all bits are set to 1, is:
FF-FF-FF-FF-FF-FF
This address is used as Broadcast address and addresses all participants in the net.
- Address at first start-up
 - Each CP of a Yaskawa CPU has an unique MAC address. This may be found on a label beneath the front flap.

TSAP

TSAP means **T**ransport **S**ervice **A**ccess **P**oint. ISO transport connections support TSAP length of 1...16byte. TSAPs may be entered in ASCII format or hexadecimal.

Address parameters

| Station A | | | | Station B |
|---------------|---|---------------|---|---------------|
| remote TSAP | → | ISO transport | → | local TSAP |
| local TSAP | ← | connection | ← | remote TSAP |
| MAC address A | | | | MAC address B |

An ISO transport connection is specified by a local and a remote connection endpoint. The TSAPs of an ISO transport connection must match as follows:

- Remote TSAP (in CP) = local TSAP (in destination station)
- Local TSAP (in CP) = remote TSAP (in destination station)

8.7 Fast introduction

Overview

At the first start-up respectively at an over all reset with an PowerON again, the Ethernet PG/OP channel and CP 343 do not have any IP address. These may only be reached via its MAC address. IP address parameters may be assigned to the corresponding component by means of the MAC addresses, which may be found on labels beneath the front flap with the sequence 1. address PG/OP channel and beneath address of the CP 343. The assignment takes place directly via the hardware configuration of the Siemens SIMATIC Manager.

Steps of configuration

For the configuration of the CP 343 for productive connections please follow the following approach:

- Assembly and commissioning
- Hardware configuration - CPU
- Configure connections
 - Communication connections
(Configuration via Siemens NetPro, communication via VIPA handling blocks)
 - Open communication
(Configuration and communication happens by standard handling blocks)
- Transfer of the complete project to CPU



With the Siemens SIMATIC Manager the CPU 317-4NE23 from VIPA is to be configured as

CPU 317-2DP (6ES7 317-2AK14 V3.3).

The integrated PROFIBUS DP master (X3) is to be configured and connected via the sub module X2 (DP). The Ethernet PG/OP channel of the 317-4NE23 is always to be configured as 1. module after the really plugged modules at the standard bus as CP343-1 (343-1EX11) from Siemens.

The CP 343 of the CPU is always to be configured below the before configured PG/OP channel also as CP343-1 (343-1EX11).

8.8 Commissioning and initialization

Assembly and commissioning

1. ➤ Install your System 300S with your CPU.
2. ➤ Wire the system by connecting cables for voltage supply and signals
3. ➤ Connect your CP 343 with Ethernet.
4. ➤ Switch on the power supply.
 - ⇒ After a short boot time, the CP is in idle. At the first commissioning res. after an overall reset of the CPU, the CP 343 and the Ethernet PG/OP channel have no IP address.

Assign IP address parameters



Please regard this function is available with CP firmware version 1.7.4 and up.

You get valid IP address parameters from your system administrator. The assignment of the IP address data happens online in the Siemens SIMATIC Manager starting with version V 5.3 & SP3 with the following proceeding:

1. ➤ Start the Siemens SIMATIC Manager and set via 'Options → Set PG/PC interface' the access path to 'TCP/IP -> Network card'.
2. ➤ Open with 'PLC → Edit Ethernet Node n' the dialog window with the same name.
3. ➤ To get the stations and their MAC address, use the [Browse] button or type in the MAC Address. The Mac address may be found at the 2. label beneath the front flap of the CPU.
4. ➤ Choose if necessary the known MAC address of the list of found stations.
5. ➤ Either type in the IP configuration like IP address, subnet mask and gateway. Or your station is automatically provided with IP parameters by means of a DHCP server. Depending of the chosen option the DHCP server is to be supplied with MAC address, equipment name or client ID. The client ID is a numerical order of max. 63 characters. The following characters are allowed: "hyphen", 0-9, a-z, A-Z
6. ➤ Confirm with [Assign IP configuration].



Directly after the assignment the CP 343 is online reachable using the set IP address data.

Since the IP address data, which were assigned here, are deleted at PowerOFF, you have to take them to a project by means of the hardware configuration.

8.9 Hardware configuration - CP 343

Precondition

The configuration of the CPU takes place at the Siemens *'hardware configurator'*. The hardware configurator is part of the Siemens SIMATIC Manager. It serves for project engineering. The modules, which may be configured here are listed in the hardware catalog. If necessary you have to update the hardware catalog with *'Options → Update Catalog'*.

For project engineering a thorough knowledge of the Siemens SIMATIC Manager and the Siemens hardware configurator is required.

Proceeding

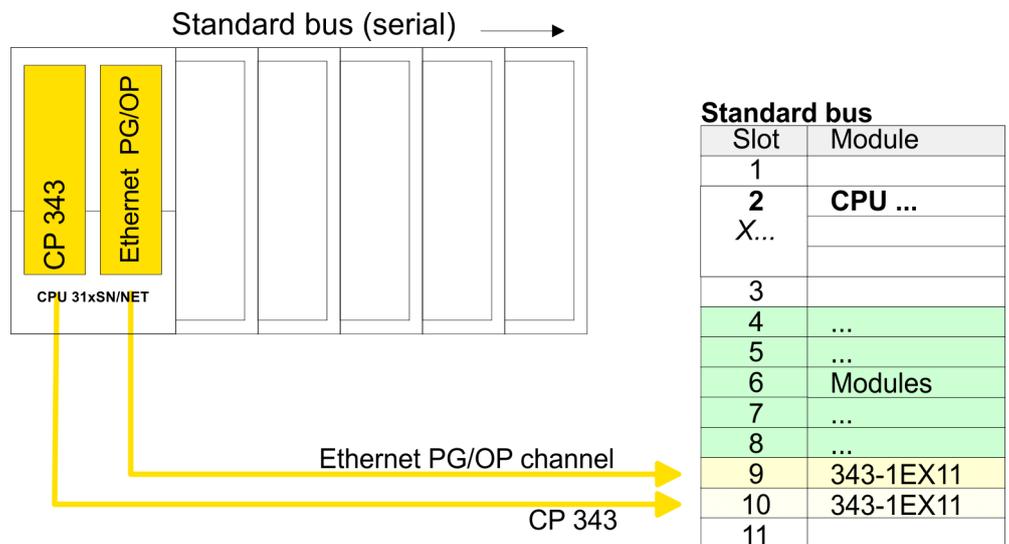
| Slot | Module |
|------|--------------------|
| 1 | |
| 2 | CPU 317-2DP |
| X1 | MPI/DP |
| X2 | DP |
| 3 | |

With the Siemens SIMATIC Manager the following steps should be executed:

1. ➤ Start the Siemens hardware configurator with a new project.
2. ➤ Insert a profile rail from the hardware catalog.
3. ➤ Place at *'Slot'* number 2 the Siemens CPU 317-2DP (6ES7 317-2AK14 V3.3).
4. ➤ The integrated PROFIBUS DP master (X3) is to be configured and connected via the sub module X2 (DP).

Project engineering Ethernet PG/OP channel and CP 343

1. ➤ Place for the internal Ethernet PG/OP channel always as 1. module below the really plugged modules a Siemens CP 343-1 (SIMATIC 300 \ CP 300 \ Industrial Ethernet \ CP 343-1 \ 6GK7 343-1EX11 0XE0).
2. ➤ Configure the integrated CP 343 of the CPU also as CP 343-1 (343-1EX11) but always below the before configured CP 343-1.



3. ➤ Open the property window of the CP via double-click on the CP.
4. ➤ Enter at *'General'* a device name. The device name must be unique at the Ethernet subnet.
5. ➤ On [Properties] for the CP enter the IP address, subnet mask and gateway and select the wanted subnet.

8.9.1 Time-of-day synchronization

NTP method

In the NTP mode (**N**etwork **T**ime **P**rotocol) the module sends as client time-of-day queries at regular intervals to all configured NTP servers within the sub net. You can define up to 4 NTP server. Based on the response from the servers, the most reliable and most exact time-of-day is determined. Here the time with the lowest *stratum* is used. *Stratum 0* is the time standard (atomic clock). *Stratum 1* are directly linked to this NTP server. Using the NTP method, clocks can be synchronized over subnet boundaries. The configuration of the NTP servers is carried out in the Siemens SIMATIC Manager via the CP, which is already configured.



Please note that the integrated CP only supports the functions described in this manual, even if the Siemens CP used for the configuration offers further functions! Since NTP is not supported by the Siemens CP 343-1EX11, the Siemens CP 343-1EX21 must be used to configure the NTP method.

| Slot | Module |
|------|-----------|
| 1 | |
| 2 | CPU 31... |
| X... | |
| | |
| 9 | |
| 10 | 343-1EX21 |
| 11 | |
| ... | |

1. ➤ Configure the Siemens CP 343-1EX21 for the integrated Yaskawa CP 343.
2. ➤ Open the properties dialog via double-click on the CP 343-1EX21.
3. ➤ Select the tab 'Time-of-day synchronization'.
4. ➤ Activate the NTP method by enabling 'Activate NTP time-of-day synchronization'.
5. ➤ Click at [Add] and add the corresponding NTP server.
6. ➤ Select your 'Time zone'. In the NTP method, UTC (**U**niversal **T**ime **C**oordinated) is generally transmitted; this corresponds to GMT (Greenwich Mean Time). By configuring the local time zone, you can set a time offset to UTC.
7. ➤ Close the dialog with [OK].
8. ➤ Save and transfer your project to the CPU.
 - ⇒ After transmission, the NTP time is requested by each configured time server and the best response for the time synchronization is used.



Please note that although the time zone is evaluated, an automatic changeover from winter to summer time is not supported. Industrial systems with time-of-day synchronization should always be set in accordance to the winter time.

With the FC 61 you can determine the local time in the CPU. More information about the usage of this block may be found in the manual "SPEED7 Operation List" from Yaskawa.

When used with the Siemens SIMATIC Manager, there are the following limitations:

- The parameter 'Time-of-day synchronization on the full minute' is not supported.
- The parameter 'Accept time-of-day from synchronized NTP servers' is not supported.
- The parameter 'Forwarding time-of-day to station' is not supported.

8.10 Configure connections

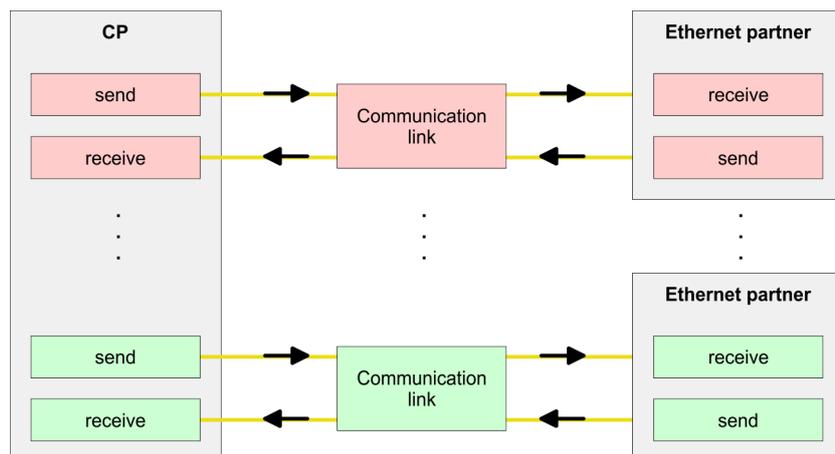
8.10.1 Overview

The project engineering of connections i.e. the "link-up" between stations happens in NetPro from Siemens. NetPro is a graphical user interface for the link-up of stations. A communication connection enables the program controlled communication between two participants at the Industrial Ethernet. The communication partners may here be part of the same project or - at multi projects - separated within related part projects. Communication connections to partners outside of a project are configured via the object "In unknown project" or via deputy objects like "Other stations" or Siemens "SIMATIC S5 Station". The communication is controlled by the user program with Yaskawa handling blocks. To use this blocks, configured communication connections are always necessary in the active station.

Properties communication connection

The following properties are characterizing a communication connection:

- One station always executes an active connection establishment.
- Bi-directional data transfer (Send and receive on one connection)
- Both participant have equal rights, i.e. every participant may initialize the send res. receive process event controlled.
- Except of the UDP connection, at a communication connection the address of the communication partner is set via the project engineering. Here the connection is active established by one station.



Requirements

- Siemens SIMATIC Manager V 5.3 SP3 or higher and SIMATIC NET are installed.
- With the hardware configuration the CP was assigned with IP address data by the properties.



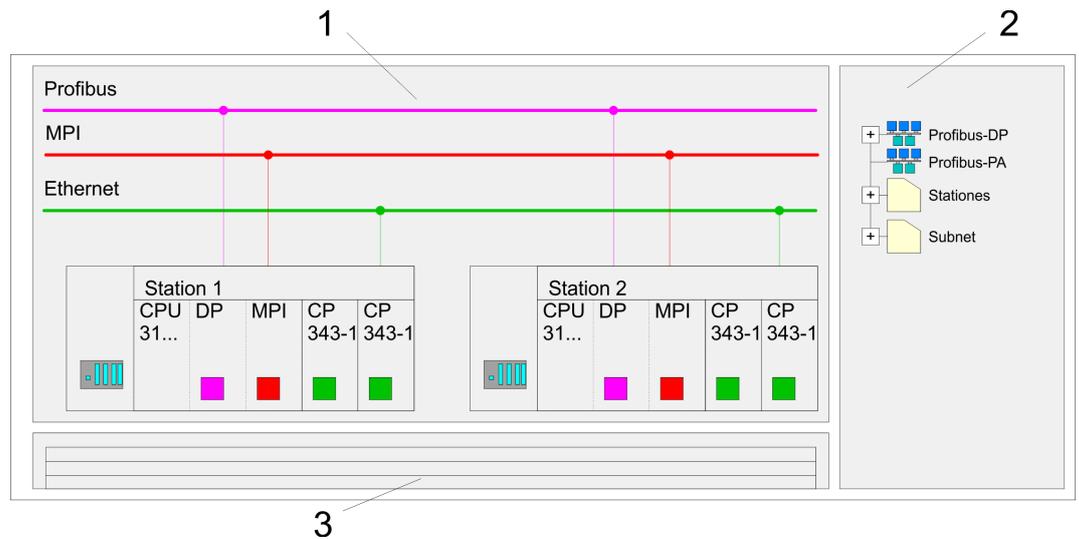
Every station outside of the recent project must be configured as replacement objects like e.g. Siemens "SIMATIC S5" or "other station" or with the object "In unknown project". When creating a connection you may also choose the partner type "unspecified" and set the required remote parameter directly in the connection dialog.

8.10.2 Siemens NetPro

Work environment of NetPro

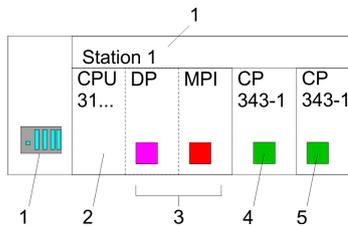
For the project engineering of connections, a thorough knowledge with NetPro from Siemens is required! The following passage only describes the basic usage of NetPro. More detailed information about NetPro is to be found in the according online manual res. documentation. Start NetPro by clicking on a "net" in the Siemens SIMATIC Manager or on "connections" within the CPU.

The environment of NetPro has the following structure:



- 1 **Graphic net view:** All stations and networks are displayed in a graphic view. By clicking on the according component you may access and alter the concerning properties.
- 2 **Net objects:** This area displays all available net objects in a directory view. By dragging a wanted object to the net view you may include further net objects and open them in the hardware configurator.
- 3 **Connection table:** The connection table lists all connections in a table. This list is only shown when you highlighted a connectable module like e.g. a CPU. You may insert new connections into this table with the according command.

PLC stations

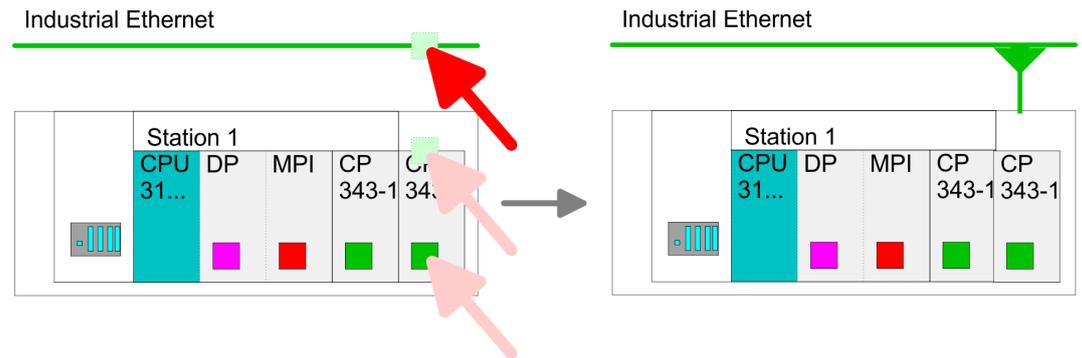


You receive the following graphical display for every PLC station and their component. By selecting the single components, the context menu offers you several functions:

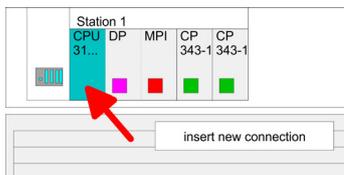
- 1 **Station:** This includes a PLC station with rack, CPU and communication components. Via the context menu you may configure a station added from the net objects and its concerning components in the hardware configurator. After returning to NetPro, the new configured components are shown.
- 2 **CPU:** A click onto the CPU shows the connection table. The connection table shows all connections that are configured for the CPU.
- 3 **Internal communication components:** This shows the communication components that are available in your CPU. For the NET-CPU is configured as Siemens CPU, the internal components do not show the CP. Due to this, the internal CPs of the NET-CPU must be configured as external CPs behind the really plugged modules. The CPs are then also shown in NetPro as external CPs (4, 5) in the station.
- 4 **Ethernet PG/OP channel:** The internal Ethernet PG/OP channel must always be configured as external CP in the hardware configuration. This CP only serves the PG/OP communication. Configurable connections are not possible.
- 5 The internal CP 343 must always be configured as external 2. CP in the hardware configuration after the Ethernet PG/OP channel.

Link up stations

NetPro offers you the option to link-up the communicating stations. You may link-up the stations via the properties in the hardware configuration or graphically via NetPro. For this you point the mouse on the coloured net mark of the according CP and drag and drop it to the net you want to link. Now the CP is linked up to the wanted net by means of a line.



Projecting connections

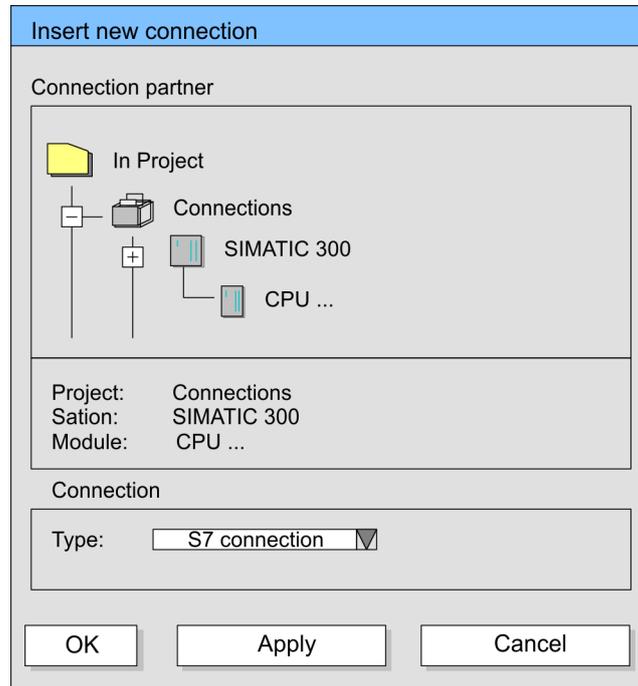


1. For the project engineering of connections, open the connection list by selecting the according CPU. Open 'Context menu → Insert new connection':
 - Connection partner (partner station)
 - A dialog window opens where you may choose the *connection partner* and the *Connection type*.
 - Specified connection partner
 - Each station configured in the Siemens SIMATIC manager is listed in the table of connection partner.
 - These stations are unique *specified* by an IP address and a subnet mask.
 - Unspecified connection partner
 - Here the connection partner may exist in the current project or in an unknown project.
 - Connection jobs to an unknown project must be defined by a unique connection name, which is to be used in the projects of both stations.
 - Due to this allocation the connection remains *unspecified*.
 - All broadcast stations
 - Exclusive at UDP connections you may send to every reachable participant.
 - The receipt of user data is not possible.
 - The broadcast participants are specified by one port and one broadcast address at sender and receiver.
 - Per default, broadcasts that are only serving the Ethernet communication, like e.g. ARP-Requests (Search MAC <> IP address), are received and accordingly processed.
 - For the identification of the broadcast participants within the net, you have to define a valid broadcast address as partner IP during project engineering of a broadcast connection.
 - Additionally to the broadcast address you have to set a common port for sender and receiver.
 - All multicast stations
 - By selecting 'All Multicast stations' you define that UDP telegrams have to be sent respectively received by all participants of a multicast group.
 - In contrast to broadcast here a reception is possible.
 - For the identification of the multicast participants within the net, you have to define one valid multicast group address and one port for sender and receiver. The maximum number of multicast circles, which are supported by the CP, is identical to the maximum number of connections.
 - Connection types

The following connection types are available for communication:

 - *Siemens S7 connections, Send/Receive connections* (TCP, ISO-on-TCP and ISO transport) for secured data transfer of data blocks between two Ethernet stations.
 - *UDP* for not secured data transfer of data blocks between two Ethernet stations.

2. ➤ Select the connection partner and the type of connection and confirm with [OK].
 - ⇒ If activated, a properties dialog for the according connection opens as link to your PLC user program.



3. ➤ After every connection was configured by this way, you may "save and compile" your project and exit NetPro.

8.10.3 Connection type - S7

Siemens S7 connection

- For data transfer with Siemens S7 connections the FB/SFB Yaskawa handling blocks are necessary; the deployment is described in the manual "Operation list" of your CPU.
- At Siemens S7 connections the communication connections are specified by a connection ID for each communication partner.
- A connection is specified by the local and partner connection end point.
- At Siemens S7 connections the TSAPs must be congruent crosswise. The following parameters define a connection end point:

The following parameters define a connection end point:

| Station A | | | | Station B |
|-------------|---|---------------|---|-------------|
| remote TSAP | → | Siemens | → | local TSAP |
| local TSAP | ← | S7 connection | ← | remote TSAP |
| ID A | | | | ID B |

Combination options with deployment of the FB/SFB Yaskawa handling blocks

| Connection partner | Connection establishing | Connection |
|---|-------------------------|---|
| specified in NetPro (in the current project) | active/passive | specified |
| unspecified in NetPro (in the current project) | active | specified |
| | passive | unspecified |
| unspecified in NetPro (in the unknown project) | active/passive | specified (connection name in an other project) |

In the following every relevant parameter of a Siemens S7 connection is described:

- **Local connection end point:**
Here you may define how the connection is to be established. Since the Siemens SIMATIC Manager can identify the communication options by means of the end points, some options are already preset and may not be changed.
 - **Establish an active connection:**
An established connection is precondition for data transfer. By activating the option Establish an active connection the local station establishes the connection. Please regard not every station is able to establish a connection. Here the job is to be made by the partner station.
 - **One-way:**
If activated only one-way communication blocks like PUT and GET may be used for communication in the user program. Here the partner station acts as server, which neither may send active nor receive active
- **Block parameters**
 - **Local ID:**
The ID is the link to your PLC program. The ID must be identical to the ID of the call interface of the FB/SFB Yaskawa handling block.
 - **[Default]:**
As soon as you click at [Default], the ID is reset to system generated ID.
- **Connection path:**
In this part of the dialog window the connection path between the local and the partner station may be set. Depending on the linking of the modules the possible interfaces for communication are listed in a selection field.
 - **[Address details]:**
With this button a dialog window is opened, which shows address information about the local and partner station. The parameters may also be changed.
 - **TSAP:**
With Siemens S7 connections a TSAP is automatically generated of the connection resource (one-way/two-way) and state of place (rack/slot respectively system internal ID at PC stations).
 - **Connection resource:**
The connection resource is part of the TSAP of the local station respectively of the partner. Not every connection resource may be used for every connection type. Depending on the connection partner and the connection type the range of values is limited respectively the connection resource is fix specified.

Siemens S7 connection - Communication functions

With the SPEED7 CPUs of Yaskawa there are two possibilities for the deployment of the communication functions:

- *Siemens S7-300 communication functions:*
By integration of the function blocks FB 12 ... FB 15 from Yaskawa you may access the Siemens S7-300 communication functions.
- *Siemens S7-400 communication functions:*
For the Siemens S7-400 communication functions the SFB 12 ... SFB 15 are to be used, which were integrated to the operating system of the CPU. Here copy the interface description of the SFBs from the standard library at system function block to the directory container, generate an instance data block for each call and call the SFB with the associated instance data block.

Function blocks

| FB/SFB | Label | Description |
|-----------|-------|--|
| FB/SFB 12 | BSEND | <p>Sending data in blocks:</p> <p>FB/SFB 12 BSEND sends data to a remote partner FB/SFB of the type BRCV (FB/SFB 13). The data area to be transmitted is segmented. Each segment is sent individually to the partner. The last segment is acknowledged by the partner as it is received, independently of the calling up of the corresponding FB/SFB/FB BRCV. With this type of data transfer, more data can be transported between the communications partners than is possible with all other communication FBs/SFBs for configured S7 connections, namely 65534bytes.</p> |
| FB/SFB 13 | BRCV | <p>Receiving data in blocks:</p> <p>The FB/SFB 13 BRCV can receive data from a remote partner FB/SFB of the type BSEND (FB/SFB 12). The parameter R_ID of both FB/SFBs must be identical. After each received data segment an acknowledgement is sent to the partner FB/SFB and the LEN parameter is updated.</p> |
| FB/SFB 14 | GET | <p>Remote CPU read:</p> <p>The FB/SFB 14 GET can be used to read data from a remote CPU. The respective CPU must be in RUN mode or in STOP mode.</p> |
| FB/SFB 15 | PUT | <p>Remote CPU write:</p> <p>The FB/SFB 15 PUT can be used to write data to a remote CPU. The respective CPU may be in RUN mode or in STOP mode.</p> |

8.10.4 Connection type - Send/Receive

Send/Receive connections At the PLC side for data transfer with these connections the VIPA handling blocks AG_SEND (FC 5) and AG_RECV (FC 6) are to be used.

Send/receive connections are the following connections:

- TCP (SEND-RECEIVE, FETCH-WRITE PASSIVE)
- ISO-on-TCP (SEND-RECEIVE, FETCH-WRITE PASSIVE)
- ISO-on-TCP (SEND-RECEIVE, FETCH-WRITE PASSIVE)
- UDP (SEND-RECEIVE)

The following parameters define a connection end point:

| Station A | | | | Station B |
|--------------|---|------------|---|--------------|
| remote port: | → | TCP | → | local port |
| local port | ← | connection | ← | remote port |
| IP address A | | | | IP address B |

| Station A | | | | Station B |
|--------------|---|------------|---|--------------|
| remote TSAP | → | ISO TCP | → | local TSAP |
| local TSAP | ← | connection | ← | remote TSAP |
| IP address A | | | | IP address B |

| Station A | | | | Station B |
|---------------|---|---------------|---|---------------|
| remote TSAP | → | ISO transport | → | local TSAP |
| local TSAP | ← | connection | ← | remote TSAP |
| MAC address A | | | | MAC address B |

| Station A | | | | Station B |
|--------------|---|------------|---|--------------|
| remote port | → | UDP | → | local port |
| local port | ← | connection | ← | remote port |
| IP address A | | | | IP address B |

Combination options with the different operating modes

| Connection partner | Connection type | Connection establishment | Connection | Operating mode |
|--|----------------------------------|--------------------------|---|--|
| specified in NetPro (in current project) | TCP / ISO-on-TCP / ISO-Transport | active/passive | specified | SEND/RECEIVE |
| | UDP | - | | |
| unspecified in NetPro (in current project) | TCP / ISO-on-TCP / ISO-Transport | active | specified | SEND/RECEIVE |
| | | passive | part specified (Port/TSAP) | SEND/RECEIVE FETCH PASSIVE |
| | | | unspecified | WRITE PASSIVE |
| | UDP | - | specified | SEND/RECEIVE |
| unspecified in NetPro (in unknown project) | TCP / ISO-on-TCP / ISO-Transport | active | specified (connection name in an other project) | SEND/RECEIVE |
| | | passive | | SEND/RECEIVE FETCH PASSIVE WRITE PASSIVE |
| | | | | SEND/RECEIVE |
| | UDP | - | | SEND/RECEIVE |

| Connection partner | Connection type | Connection establishment | Connection | Operating mode |
|------------------------|-----------------|--------------------------|--------------------------------------|----------------|
| All broadcast stations | UDP | - | specified (Port, Broadcast addr.) | SEND |
| All multicast stations | UDP | - | specified (Port, Multicast group) | SEND/RECEIVE |

In the following each relevant parameters of the different connection types are described:

■ **General**

In this tab the general connection parameters are listed, which identify the local connection end point.

– **ID**

This entry is identical to the entry of the connection table. The value may always be changed. Please also regard to adjust the ID parameter of the call interface of the FC.

– **Name**

This field contains the name of the connection. The name is generated by the system and may be changed on every time.

– **Via CP [Route]**

Here is the CP listed, which should be used for connection. With the button [Route] the appropriate CP may be selected for communication. Do not select the 1. CP of the route for communication connections. The 1. CP is always the Ethernet PG/OP channel, which does not support configurable connections.

– **Active connection establishment**

If activated the connection to the partner is active established by the local station. Here the partner is to be specified in the tab 'Addresses'. At an unspecified connection the connection is passive established.

■ **Block parameters**

- Here the parameters **ID** and **LADDR** for your user program are shown. Both are parameters, which are to be preset if you use the FC 5 and FC 6 (AG_SEND, AG_RECEIVE). Please always use the VIPA FCs, which you may receive from VIPA.

■ **Addresses**

The Addresses tab displays the relevant local and remote address information as proposed values. Depending on the kind of communication the address information may remain unspecified.

– **Port**

Ports respectively port addresses are defining the access point to the user application within the station/CPU. These must be unique. A port address should be within the range of 2000...65535.

– **TSAP**

ISO-on-TCP and ISO transport support TSAP lengths (Transport Service Access Point) of 1...16byte. You may enter the TSAP in ASCII or hexadecimal format. The calculation of the length happens automatically.

■ Options

Depending on the specification of the connecting partner the following *operating modes* may be set respectively displayed:

– SEND/RECEIVE

The SEND/RECEIVE interface allows the program-controlled communication to any partner station via a configured connection. Here the data transfer happens by a call from your user application. The FC5 and FC6 that are part of the VIPA block library are serving as interface. This enables your PLC to send messages depending on process events.

– FETCH/WRITE PASSIVE

With the help of FETCH/WRITE services partner systems have the direct access to memory areas of the CPU. These are "passive" communication connections that have to be configured. The connections are "actively" established by the connection partner.

– FETCH PASSIVE (request data)

FETCH allows a partner system to request data.

– WRITE PASSIVE (write data)

This allows a partner system to write data in the data area of the CPU.

■ Overview

Here every configured connections of this station and its partner are displayed. These data are information and may not be changed.



- *If a CP is exchanged by another one, this must at least provide the same services and must at least have the same version level. Only this can guarantee the connections configured via the CP to remain consistent and useable.*
- *By appropriate shift respectively delete activities in the Siemens SIMATIC manager connections may lose the allocation to the CP. These connections are marked with "!" at ID of the overview.*

8.10.4.1 FC 5 - AG_SEND / FC 6 - AG_RECV - CP 343 communication

Overview

The two blocks serve the processing of the Ethernet-CP 343 connection commands on the side of the PLC. Including these blocks in the cycle block OB1 you may send and receive data cyclically.

Within these blocks, the SFCs 205 and 206 are called that are stored as special function blocks in the CPU.



Please regard that you may only use the SEND/RECV-FCs from VIPA in your user application for the communication with VIPA-CPs. At a change to VIPA-CPs in an already existing project, the present AG_SEND / AG_LSEND res. AG_RECV / AG_LRECV may be replaced by AG_SEND res. AG_RECV from VIPA without adjustment. Due to the fact that the CP automatically adjusts itself to the length of the data to transfer, the L variant of SEND res. RECV is not required for VIPA CPs.

Communication blocks

For the communication between CPU and Ethernet-CP 343, the following FCs are available:

AG_SEND (FC 5)

This block transfers the user data from the data area given in *SEND* to the CP specified via *ID* and *LADDR*. As data area you may set a PA, bit memory or data block area. When the data area has been transferred without errors, "order ready without error" is returned.

AG_RECV (FC 6)

The block transfers the user data from the CP into a data area defined via *RECV*. As data area you may set a PA, bit memory or data block area. When the data area has been transferred without errors, "order ready without error" is returned.

Status displays

The CP processes send and receive commands independently from the CPU cycle and needs for this transfer time. The interface with the FC blocks to the user application is here synchronized by means of acknowledgements/receipts.

For status evaluation the communication blocks return parameters that may be evaluated directly in the user application.

These status displays are updated at every block call.

Deployment at high communication load

Do not use cyclic calls of the communication blocks in OB 1. This causes a permanent communication between CPU and CP. Program instead the communication blocks within a time OB where the cycle time is higher res. event controlled.

FC call is faster than CP transfer time

If a block is called a second time in the user application before the data of the last time is already completely send res. received, the FC block interface reacts like this:

AG_SEND

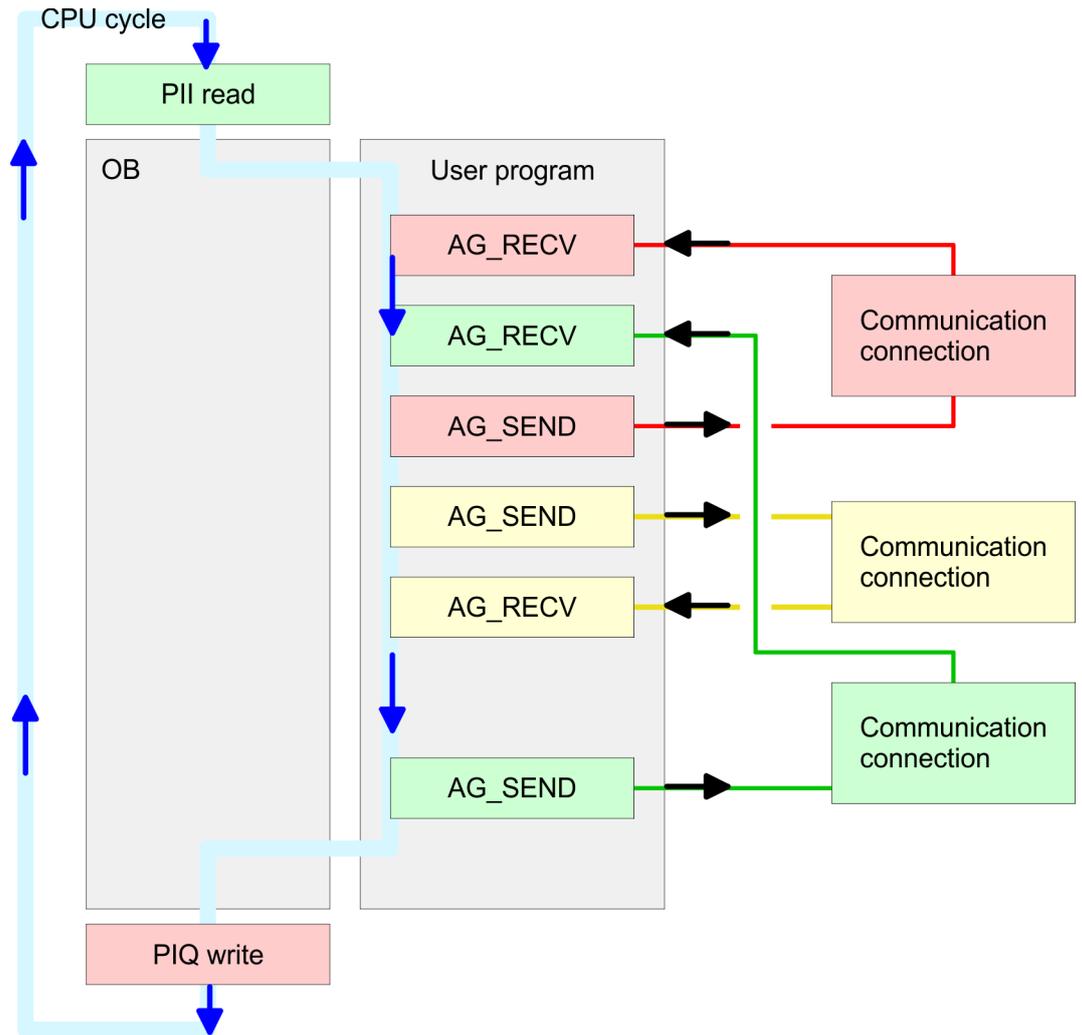
No command is accepted until the data transfer has been acknowledged from the partner via the connection. Until this you receive the message "Order running" before the CP is able to receive a new command for this connection.

AG_RECV

The order is acknowledged with the message "No data available yet" as long as the CP has not received the receive data completely.

AG_SEND, AG_RECV in the user application

The following illustration shows a possible sequence for the FC blocks together with the organizations and program blocks in the CPU cycle:



The FC blocks with concerning communication connection are summed up by colour. Here you may also see that your user application may consist of any number of blocks. This allows you to send or receive data (with AG_SEND res. AG_RECV) event or program driven at any wanted point within the CPU cycle. You may also call the blocks for **one** communication connection several times within one cycle.

AG_SEND (FC 5)

By means of AG_SEND the data to send are transferred from the CPU to an Ethernet CP 343.

Parameters

| Parameter | Declaration | Data type | Description |
|-----------|-------------|-----------|---|
| ACT | INPUT | BOOL | Activation of the sender 0: Updates <i>DONE</i> , <i>ERROR</i> and <i>STATUS</i> 1: The data area defined in <i>SEND</i> with the length <i>LEN</i> is send |
| ID | INPUT | INT | Connection number 1 ... 16 (identical with <i>ID</i> of NetPro) |
| LADDR | INPUT | WORD | Logical basic address of the CP (identical with <i>LADDR</i> of NetPro) |
| SEND | INPUT | ANY | Data area |

| Parameter | Declaration | Data type | Description |
|-----------|-------------|-----------|--|
| LEN | INPUT | INT | Number of bytes from data area to transfer |
| DONE | OUTPUT | BOOL | Status parameter for the order 0: Order running 1: Order ready without error |
| ERROR | OUTPUT | BOOL | Error message 0: Order running (at <i>DONE</i> = 0) 0: Order ready without error (at <i>DONE</i> = 1) 1: Order ready with error |
| STATUS | OUTPUT | WORD | Status message returned with <i>DONE</i> and <i>ERROR</i> . More details are to be found in the following table. |

AG_RECV (FC 6)

With the 1. call of AG_RECV a receive buffer for the communication between CPU and an Ethernet CP 343 is established. From now on received data are automatically stored in this buffer. As soon as after calling AG_RECV the return value of *NDR* = 1 is returned, valid data are present.

Since with a further call of AG_RECV the receive buffer is established again for the receipt of new data, you have to save the previous received data.

Parameters

| Parameter | Declaration | Data type | Description |
|-----------|-------------|-----------|--|
| ID | INPUT | INT | Connection number 1 ... 16 (identical with <i>ID</i> of NetPro) |
| LADDR | INPUT | WORD | Logical basic address of the CP (identical with <i>LADDR</i> of NetPro) |
| RECV | INPUT | ANY | Data area for the received data. |
| NDR | OUTPUT | BOOL | Status parameter for the order 0: Order running 1: Order ready data received without error |
| ERROR | OUTPUT | BOOL | Error message 0: Order running (at <i>NDR</i> = 0) 0: Order ready without error (at <i>NDR</i> = 1) 1: Order ready with error |
| STATUS | OUTPUT | WORD | Status message returned with <i>NDR</i> and <i>ERROR</i> . More details are to be found in the following table. |
| LEN | OUTPUT | INT | Number of bytes that have been received |

DONE, ERROR, STATUS

The following table shows all messages that can be returned by the Ethernet CP 343 after a SEND res. RECV command.

A "-" means that this message is not available for the concerning SEND res. RECV command.

Configure connections > Connection type - Send/Receive

| DONE (SEND) | NDR (RECV) | ERROR | STATUS | Description |
|-------------|------------|-------|--------|---|
| 1 | - | 0 | 0000h | Order ready without error. |
| - | 1 | 0 | 0000h | New data received without error. |
| 0 | - | 0 | 0000h | No order present. |
| - | 0 | 0 | 8180h | No data available yet. |
| 0 | 0 | 0 | 8181h | Order running |
| 0 | 0 | 1 | 8183h | No CP project engineering for this order. |
| 0 | - | 1 | 8184h | System error |
| - | 0 | 1 | 8184h | System error (destination data area failure). |
| 0 | - | 1 | 8185h | Parameter <i>LEN</i> exceeds source area <i>SEND</i> . |
| | 0 | 1 | 8185h | Destination buffer (RECV) too small. |
| 0 | 0 | 1 | 8186h | Parameter <i>ID</i> invalid (not within 1 ...16). |
| 0 | - | 1 | 8302h | No receive resources at destination station, receive station is not able to process received data fast enough res. has no receive resources reserved. |
| 0 | - | 1 | 8304h | The connection is not established. The send command shouldn't be sent again before a delay time of > 100ms. |
| - | 0 | 1 | 8304h | The connection is not established. The receive command shouldn't be sent again after a delay time of > 100ms. |
| 0 | - | 1 | 8311h | Destination station not available under the defined Ethernet address. |
| 0 | - | 1 | 8312h | Ethernet error in the CP. |
| 0 | | 1 | 8F22h | Source area invalid, e.g. when area in DB not present Parameter <i>LEN</i> < 0 |
| - | 0 | 1 | 8F23h | Source area invalid, e.g. when area in DB not present Parameter <i>LEN</i> < 0 |
| 0 | - | 1 | 8F24h | Range error at reading a parameter. |
| - | 0 | 1 | 8F25h | Range error at writing a parameter. |
| 0 | - | 1 | 8F28h | Orientation error at reading a parameter. |
| - | 0 | 1 | 8F29h | Orientation error at writing a parameter. |
| - | 0 | 1 | 8F30h | Parameter is within write protected 1. recent data block |
| - | 0 | 1 | 8F31h | Parameter is within write protected 2. recent data block |
| 0 | 0 | 1 | 8F32h | Parameter contains oversized DB number. |
| 0 | 0 | 1 | 8F33h | DB number error |
| 0 | 0 | 1 | 8F3Ah | Area not loaded (DB) |
| 0 | - | 1 | 8F42h | Acknowledgment delay at reading a parameter from peripheral area. |
| - | 0 | 1 | 8F43h | Acknowledgment delay at writing a parameter from peripheral area. |

| DONE (SEND) | NDR (RECV) | ERROR | STATUS | Description |
|-------------|------------|-------|--------|---|
| 0 | - | 1 | 8F44h | Address of the parameter to read locked in access track |
| - | 0 | 1 | 8F45h | Address of the parameter to write locked in access track |
| 0 | 0 | 1 | 8F7Fh | Internal error e.g. invalid ANY reference e.g. parameter <i>LEN</i> = 0. |
| 0 | 0 | 1 | 8090h | Module with this module start address not present or CPU in STOP. |
| 0 | 0 | 1 | 8091h | Module start address not within double word grid. |
| 0 | 0 | 1 | 8092h | reference contains type setting unequal BYTE. |
| - | 0 | 1 | 80A0h | Negative acknowledgment at reading the module. |
| 0 | 0 | 1 | 80A4h | reserved |
| 0 | 0 | 1 | 80B0h | Module doesn't recognize record set. |
| 0 | 0 | 1 | 80B1h | The length setting (in parameter <i>LEN</i>) is invalid. |
| 0 | 0 | 1 | 80B2h | reserved |
| 0 | 0 | 1 | 80C0h | Record set not readable. |
| 0 | 0 | 1 | 80C1h | The set record set is still in process. |
| 0 | 0 | 1 | 80C2h | Order accumulation. |
| 0 | 0 | 1 | 80C3h | The operating sources (memory) of the CPU are temporarily occupied. |
| 0 | 0 | 1 | 80C4h | Communication error (occurs temporarily; a repetition in the user application is reasonable). |
| 0 | 0 | 1 | 80D2h | Module start address is wrong. |

Status parameter at reboot At a reboot of the CP, the output parameters are set as follows:

- DONE = 0
- NDR = 0
- ERROR = 0
- STATUS = 8180h (at AG_RECV)
STATUS = 8181h (at AG_SEND)

8.11 Configure Open Communication

Connection-oriented protocols

- Connection-oriented protocols establish a (logical) connection to the communication partner before data transmission is started.
- And if necessary they terminate the connection after the data transfer was finished.
- Connection-oriented protocols are used for data transmission when reliable, guaranteed delivery is of particular importance.
- In general, many logical connections can exist on one physical line.

The following connection-oriented protocols are supported with FBs for open communication via Industrial Ethernet:

- *TCP/IP native according to RFC 793 (connection types 01h and 11h):*
 - During data transmission, no information about the length or about the start and end of a message is transmitted.
 - The receiver has no means of detecting where one message ends in the data stream and the next one begins.
 - The transfer is stream-oriented. For this reason, it is recommended that the data length of the FBs is identical for the sending and receiving station.
 - If the number of received data does not fit to the preset length you either will get not the whole data, or you will get data of the following job. The receive block copies as many bytes into the receive area as you have specified as length. After this, it will set NDR to TRUE and write RCVD_LEN with the value of LEN. With each additional call, you will thus receive another block of sent data.
- *ISO on TCP according to RFC 1006:*
 - During data transmission, information on the length and the end of the message is also transmitted.
 - The transfer is block-oriented
 - If you have specified the length of the data to be received greater than the length of the data to be sent, the receive block will copy the received data completely into the receive range. After this, it will set NDR to TRUE and write RCVD_LEN with the length of the sent data.
 - If you have specified the length of the data to be received less than the length of the sent data, the receive block will not copy any data into the receive range but instead will supply the following error information: ERROR = 1, STATUS = 8088h.

Connection-less protocol

- There is thus no establishment and termination of a connection with a remote partner.
- Connection-less protocols transmit data with no acknowledge and with no reliable guaranteed delivery to the remote partner.

The following connection-oriented protocol is supported with FBs for open communication via Industrial Ethernet:

- *UDP according to RFC 768 (with connection type 13h):*
 - In this case, when calling the sending block you have to specify the address parameters of the receiver (IP address and port number).
 - During data transmission, information on the length and the end of the message is also transmitted.
 - In order to be able to use the sending and receiving blocks first you have to configure the local communications access point at both sides.
 - With each new call of the sending block, you re-reference the remote partner by specifying its IP address and its port number.
 - If you have specified the length of the data to be received greater than the length of the data to be sent, the receive block will copy the received data completely into the receive range. After this, it will set NDR to TRUE and write RCVD_LEN with the length of the sent data.
 - If you have specified the length of the data to be received less than the length of the sent data, the receive block will not copy any data into the receive range but instead will supply the following error information: ERROR = 1, STATUS = 8088h.

Handling blocks

Those in the following listed UTDs and FBs serve for "open communication" with other Ethernet capable communication partners via your user program. These blocks are part of the Siemens SIMATIC Manager. You will find these in the "Standard Library" at "Communication Blocks". Please consider when using the blocks for open communication that the partner station does not have to be configured with these blocks. This can be configured with AG_SEND / AG_RECEIVE or IP_CONFIG.

UDTs

| FB | Label | Connection-oriented protocols: TCP native as per RFC 793, ISO on TCP as per RFC 1006 | Connectionless protocol: UDP as per RFC 768 |
|--------|----------|--|---|
| UDT 65 | TCON_PAR | Data structure for assigning connection parameters | Data structure for assigning parameters for the local communications access point |
| UDT 66 | TCON_ADR | | Data structure for assigning addressing parameters for the remote partner |

FBs

| FB | Label | Connection-oriented protocols: TCP native as per RFC 793, ISO on TCP as per RFC 1006 | Connectionless protocol: UDP as per RFC 768 |
|-------|---------|--|---|
| FB 63 | TSEND | Sending data | |
| FB 64 | TRCV | Receiving data | |
| FB 65 | TCON | Establishing a connection | Configuring the local communications access point |
| FB 66 | TDISCON | Terminating a connection | Closing the local communications access point |
| FB 67 | TUSEND | | Sending data |
| FB 68 | TURCV | | Receiving data |

8.12 NCM diagnostic - Help for error diagnostic

NCM diagnostics - Help for error diagnostics

This page shall help you with the error diagnostics. The following check list shows a number of typical problems and their probable causes:

| Question | Remedy with "no" |
|--|--|
| CPU in RUN? | <ul style="list-style-type: none"> ■ Check DC 24V power supply. ■ Set the operating mode switch to position RUN. ■ Check PLC program and transfer it again. |
| AG_SEND, AG_RECV in user application? | These 2 blocks are required in the user application for the data transfer between CP and CPU. Both blocks must also be called with a passive connection. |
| Is CP able to connect? | <ul style="list-style-type: none"> ■ Check Ethernet cable (at a point-to-point connection a crossed Ethernet cable is to be used). ■ Check IP address. |
| Can data be transferred? | <ul style="list-style-type: none"> ■ Check Port no. for read and write. ■ Check source and destination areas. ■ Check if the 2. CP is selected in the route. ■ Enlarge the receive respectively send buffer defined via the ANY pointer. |
| Is the complete data block sent at ISO-on-TCP? | <ul style="list-style-type: none"> ■ Check the LEN parameter at AG_SEND. ■ Set the receive respectively send buffer defined via the ANY pointer to the required size. |

Siemens NCM S7 diagnostic

The CP supports the Siemens NCM diagnostic tool. The NCM diagnostic tool is part of the Siemens SIMATIC manager. This tool delivers information about the operating state of the communication functions of the online CPs dynamically.

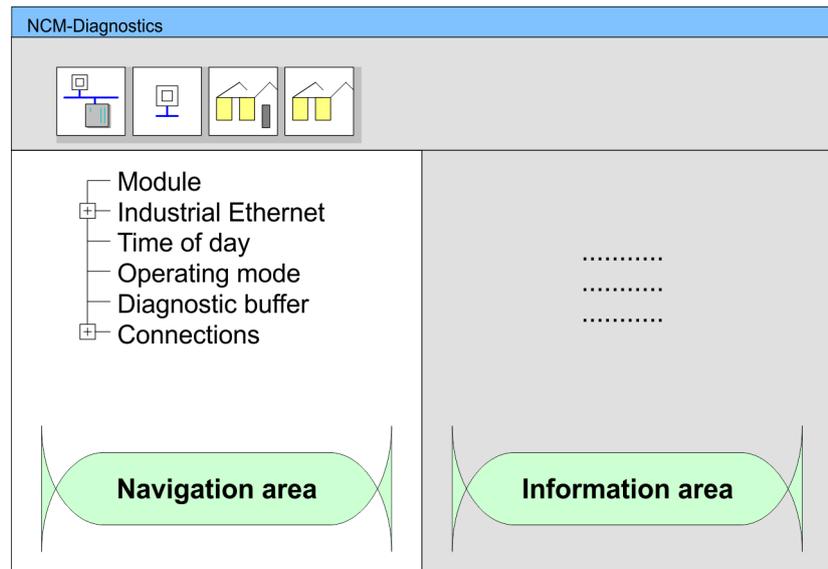
The following diagnostic functions are available:

- Check operating state at Ethernet
- Read the diagnostic buffer of the CP
- Diagnostics of connections

Start NCM diagnostic

The diagnostic tool is started by '*Windows-START menu* → *SIMATIC* → ... *NCM S7* → *Diagnostic*'.

Structure



The working surface of the diagnostic tool has the following structure:

- The *'navigation area'* at the left side contains the hierarchical listed diagnostic objects. Depending on CP type and configured connections there is an adjusted object structure in the navigation area.
- The *'information area'* at the right side always shows the result of the navigation function you chose in the navigation area.

No diagnostic without connection

A diagnostic always requires an online connection to the CP you want to control. For this click at  the symbol bar.

The following dialog window appears:

The screenshot shows the 'NCM S7-Diagnostics: Online Path' dialog window. It has a 'Gateway' section with a dropdown menu showing '...'. Below that is the 'Destination station' section, which includes an 'Attachment ...:' dropdown menu set to 'Ind. Ethernet TCP/IP'. The 'Node address:' field contains '172 . 16 . 129 . 200'. The 'Rack/Slot:' field contains '0' and '5' separated by a slash. At the bottom of the dialog, there are three buttons: 'Set PG/PC Interface', 'OK', and 'Cancel'.

Set the following parameters at *'Destination station'*:

- *Attachment ...:*
Ind. Ethernet TCP/IP
- *Node addr.:*
Enter the IP address of the CP
- *Rack/slot:*
Enter the module rack and slot of the CP 343 that you've placed at the 2. slot. Set your PG/PC interface to "TCP/IP -> Network card ". Via [OK] you start the online diagnostic.

Read diagnostic buffer

The CP has a diagnostic buffer. This has the architecture of a ring memory and may store up to 100 diagnostic messages. The NCM diagnostic allows you to monitor and evaluate the diagnostic messages via the diagnostic object *Diagnostic buffer*. Via a double click on a diagnostic message the NCM diagnostic shows further information.

Approach for diagnostic

You execute a diagnostic by clicking on a diagnostic object in the navigation area. More functions are available via the menu and the symbol bar.



Please always control the preconditions for an operative communication using the check list. ↗ 'NCM diagnostics - Help for error diagnostics' page 138

For the aimed diagnostic deployment the following approach is convenient:

1. ➤ Start diagnostic.
2. ➤ Open the dialog for the online connection with , enter connection parameters and establish the online connection with [OK].
3. ➤ Identify the CP and check the recent state of the CP via module status.
4. ➤ Check the connections for particularities like:
 - Connection status
 - Receive status
 - Send status
5. ➤ Control and evaluate the diagnostic buffer of the CP via *'Diagnostic buffer'*.
6. ➤ As needed, alter project engineering respectively programming and restart diagnostic.

8.13 Coupling to other systems

Overview

The operating mode FETCH/WRITE supported at TCP res. ISO-on-TCP can be used for accesses of partner devices to the PLC system memory. To be able to use this access also for example for implementation in PC applications you have to know the telegram structure for orders. The specific headers for request and acknowledgement telegrams have per default a length of 16Byte and are described at the following pages.

ORG format

The organization format is the abbreviated description of a data source or a data destination in a PLC environment. The available ORG formats are listed in the following table. The ERW-identifier is used for the addressing of data blocks. In this case the data block number is entered into this identifier. The start address and quantity provide the address for the memory area and they are stored in HIGH-/LOW- format (Motorola-formatted addresses)

| Description | Type | Range |
|----------------|----------|---------|
| ORG identifier | BYTE | 1...x |
| ERW identifier | BYTE | 1...255 |
| Start address | HILOWORD | 0...y |
| Length | HILOWORD | 1...z |

The following table contains a list of available ORG-formats. The "length" must not be entered as -1 (FFFFh).

ORG identifier 01h-04h

| CPU area | DB | MB | EB | AB |
|----------------------------|--|--|--|---|
| ORG identifier | 01h | 02h | 03h | 04h |
| Description | Source/destination data from/into data Block in main memory. | Source/destination data from/into flag memory area | Source/destination data from/into process image of the inputs (PII). | Source/destination data from/into process image of the outputs (PIQ). |
| ERW identifier (DBNO) | DB, from where the source data is retrieved or to where the destination data is transferred. | irrelevant | irrelevant | irrelevant |
| Start address significance | DBB-No., from where the data is retrieved or where the data is saved. | MB-No., from where the data is retrieved or where the data is saved. | IB-No., from where the data is retrieved or where the data is saved. | QB-No., from where the data is retrieved or where the data is saved. |
| Length significance | Length of the source/destination data block in <u>words</u> . | Length of the source/destination data block in bytes | Length of the source/destination data block in bytes | Length of the source/destination data block in bytes |

ORG identifier 05h-07h

| CPU area | PB | ZB | TB |
|----------------------------|---|---|---|
| ORG identifier | 05h | 06h | 07h |
| Description | source/destination data from/into peripheral modules. Input module for source data, output module for destination data. | source/destination data from/into counter cells. | Source/destination data from/into timer cells. |
| ERW identifier (DBNO) | irrelevant | irrelevant | irrelevant |
| Start address Significance | PB-No., from where the data can be retrieved or where it is saved. | ZB-No., from where the data can be retrieved or where it is saved. | TB-No., from where the data can be retrieved or where it is saved. |
| Length Significance | Length of the source/destination data block in bytes. | Length of the source/destination data block in words (counter cell = 1 word). | Length of the source/destination data block in words (counter cell = 1 word). |

Transfer of blocks with numbers >255*ORG identifier 81h-FFh*

To transfer data blocks of the number range 256 ... 32768 you may use the ORG identifier 81h-FFh. For the setting of a DB No. >255 needs a length of one word, the $DBNO_{new}$ is assembled from the content of the ORG identifier and the DBNO. $DBNO_{new}$ is created as word as follows:

 $DBNO_{new}$

| High-Byte | | | | | | | | Low-Byte | | | | | | | |
|---------------------------|---|---|---|---|---|---|---|----------------|---|---|---|---|---|---|---|
| 1 | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x |
| ORG identifier (0XXXXXXX) | | | | | | | | DBNR (XXXXXXX) | | | | | | | |

Coupling to other systems

If the highest bit of the ORG identifier is set, the Low-Byte of $DBNO_{new}$ is defined via DBNO and the High-Byte of $DBNO_{new}$ via ORG identifier, where the highest bit of the ORG identifier is eliminated. The following formula illustrates this:

$$DBNO_{new} = 256 \times (\text{ORG-identifier AND } 7Fh) + DBNO$$

Structure of PLC-Header

For every FETCH and WRITE the CP generates PLC header for request and acknowledgment messages. Normally the length of these headers is 16Bytes and have the following structure:

WRITE

| <i>Request telegram Remote Station</i> | <i>Acknowledgement telegram CP</i> |
|---|---|
| System ID = "S5" (Word) | System ID ="S5" (Word) |
| Length Header = 10h (Byte) | Length Header =10h (Byte) |
| ID OP-Code = 01h (Byte) | ID OP-Code =01h (Byte) |
| Length OP-Code = 03h (Byte) | Length OP-Code =03h (Byte) |
| OP-Code = 03h (Byte) | OP-Code =04h (Byte) |
| ORG block = 03h (Byte) | Ackn. block = 0Fh (Byte) |
| Length ORG block = 08h (Byte) | Length Ack. block = 03h (Byte) |
| <i>ORG identifier* (Byte)</i> | Error no. (Byte) |
| <i>ERW identifier (Byte)</i> | Empty block = FFh (Byte) |
| <i>Start address (Word)</i> | Length empty block = 07h (Byte) |
| <i>Length (Word)</i> | 5 empty bytes attached |
| Empty block = FFh (Byte) | |
| Length empty block = 02h (Byte) | |
| Data up to 64kByte (only if error no.=0) | |

FETCH

| <i>Request telegram Remote Station</i> | <i>Acknowledgement telegram CP</i> |
|---|---|
| System ID = "S5" (Word) | System ID ="S5" (Word) |
| Length Header = 10h (Byte) | Length Header =10h (Byte) |
| ID OP-Code = 01h (Byte) | ID OP-Code =01h (Byte) |
| Length OP-Code = 03h (Byte) | Length OP-Code =03h (Byte) |
| OP-Code = 05h (Byte) | OP-Code =06h (Byte) |
| ORG block = 03h (Byte) | Ackn. block = 0Fh (Byte) |
| Length ORG block = 08h (Byte) | Length Ack. block = 03h (Byte) |
| <i>ORG identifier* (Byte)</i> | Error no. (Byte) |
| <i>ERW identifier (Byte)</i> | Empty block = FFh (Byte) |
| <i>Start address (Word)</i> | Length empty block = 07h (Byte) |

| Request telegram Remote Station | Acknowledgement telegram CP |
|--|------------------------------------|
| Length (Word) | 5 empty bytes attached |
| Empty block = FFh (Byte) | Data up to 64kByte |
| Length empty block = 02h (Byte) | (only if error no.=0) |

*) More details to the data area is to be found at "ORG-Format" above.



Please regard that in opposite to Siemens-S5 systems, the block addressing of these CPUs takes the start address as byte number and the length as number of words.

Messages of error no.

The following messages can be returned via *error no.*:

| Error no. | Message |
|------------------|--|
| 00h | No error occurred |
| 01h | The defined area cannot be read res. written |

9 WinPLC7

9.1 System conception

General

WinPLC7 is a programming and simulation software from Yaskawa for every PLC programmable with Siemens STEP®7. This tool allows you to create user applications in FBD, LAD and STL. Besides of a comfortable programming environment, WinPLC7 has an integrated simulator that enables the simulation of your user application at the PC without additional hardware. This "Soft-PLC" is handled like a real PLC and offers the same error behavior and diagnostics options via diagnostics buffer, USTACK and BSTACK.



Detailed information and programming samples may be found at the online help respectively in the online documentation of WinPLC7.

Alternatives

There is also the possibility to use according configuration tools from Siemens instead of WinPLC7 from Yaskawa. Here the proceeding is part of this manual.

System requirements

- Windows XP (SP3)
- Windows Vista
- Windows 7 (32 and 64 bit)
- Windows 8 (32 and 64 bit)

Source

You may receive a *demo version* from Yaskawa. Without any activation with the *demo version* the CPUs 11x of the System 100V from Yaskawa may be configured. To configure the SPEED7 CPUs a license for the "profi" version is necessary. This may be online be received from Yaskawa and activated.

There are the following sources to get WinPLC7:

- Online
 - At www.yaskawa.eu.com in the service area at Downloads a link to the current demo version and the updates of WinPLC7 may be found.
- CD
 - SW211C1DD: WinPLC7 Single license, CD, with documentation in German
 - SW211C1ED: WinPLC7 Single license, CD, with documentation in English

9.2 Installation

Precondition

The project engineering of a SPEED7 CPU from VIPA with WinPLC7 is only possible using an activated "Profi" version of WinPLC7.

Installation WinPLC7 Demo

The installation and the registration of WinPLC7 has the following approach:

1. ➤ For installation of WinPLC7 start the setup program of the corresponding CD respectively execute the online received exe file.
2. ➤ Select the according language.
3. ➤ Accept the licensing agreement.
4. ➤ Set an installation directory and a group assignment and start the installation.

Activation of the "Profi" version

1. Start WinPLC7.
 - ⇒ A 'Demo' dialog is shown
2. Click at [Activate Software].
 - ⇒ The following dialog for activation is shown:

3. Fill in the following fields:
 - Email-Addr.
 - Your Name
 - Serial number
 - The serial number may be found on a label at the CD case of WinPLC7.
4. If your computer is connected to Internet you may online request the Activation Key by [Get activation key via Internet]. Otherwise click at [This PC has no access to the Internet] and follow the instructions.
 - ⇒ With successful registration the activation key is listed in the dialog window respectively is sent by email.
5. Enter this at 'Activation code' and click at [OK].
 - ⇒ Now, WinPLC7 is activated as "Profi" version.

Installation of WinPCAP for station search via Ethernet

To find a station via Ethernet (accessible nodes) you have to install the WinPCAP driver. This driver may be found on your PC in the installation directory at WinSPS-S7-V5/WinPcap_... .exe. Execute this file and follow the instructions.

9.3 Example project engineering**9.3.1 Job definition**

In the example a FC 1 is programmed, which is cyclically called by the OB 1. By setting of 2 comparison values (value1 and value2) during the FC call, an output of the PLC-System should be activated depending on the comparison result.

Here it should apply:

- if value1 = value2 activate output Q 124.0
- if value1 > value2 activate output Q 124.1
- if value1 < value2 activate output Q 124.2

Precondition

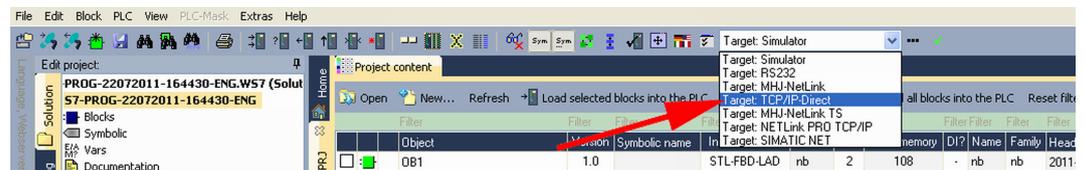
- You have administrator rights for your PC.
- WinPLC7 is installed and activated as "Profi" version.
- One SPEED7 CPU and one digital output module are installed and cabled.
- The Ethernet PG/OP channel of the CPU is connected to your Ethernet network. Your CPU may be connected to your PC with an Ethernet cable either directly or via hub/switch.
- WinPCap for station search via Ethernet is installed.
- The power supply of the CPU and the I/O periphery are activated and the CPU is in STOP state.

9.3.2 Project engineering

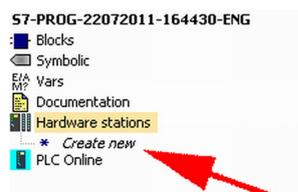
1. Start WinPLC7 ("Profi" version)
2. Create and open a new project with [Create a new solution].

Hardware configuration

1. For the call of the hardware configurator it is necessary to set WinPLC7 from the Simulator-Mode to the Offline-Mode. For this and the communication via Ethernet set "Target: TCP/IP Direct".



2. Double click to 'Hardware stations' and here at 'Create new'.



3. Enter a station name. Please consider that the name does not contain any spaces.
4. After the load animation choose in the register Select PLC-System the system "VIPA SPEED7" and click to [Create]. A new station is created.
5. Save the empty station with [Strg]+[S].
6. By double click or drag&drop the according VIPA CPU in the hardware catalog at 'CPU SPEED7' the CPU is inserted to your configuration.
7. For output place a digital output module, assign the start address 124 and save the hardware configuration.

Establish online access via Ethernet PG/OP channel:

1. ➤ Open the CPU-Properties, by double clicking to the CPU at slot 2 in the hardware configurator.
2. ➤ Click to the button [Ethernet CP-Properties (PG/OP-channel)].
⇒ The dialog 'Properties CP343' is opened.
3. ➤ Chose the register 'Common Options'.
4. ➤ Click to [Properties Ethernet].
5. ➤ Choose the subnet 'PG_OP_Ethernet'.
6. ➤ Enter a valid IP address-and a subnet mask. You may get this from your system administrator.
7. ➤ Close every dialog window with [OK].
8. ➤ Select, if not already done, 'Target: External TCP/IP direct'.
9. ➤ Open with 'Online → Send configuration to the CPU' a dialog with the same name.
10. ➤ Click to [Accessible nodes]. Please regard to use this function it is necessary to install WinPCap before!
11. ➤ Choose your network card and click to [Determining accessible nodes].
⇒ After a waiting time every accessible station is listed. Here your CPU with IP 0.0.0.0 is listed, too. To check this the according MAC address is also listed. This MAC address may be found at a label beneath the front flap of the CPU.
12. ➤ For the temporary setting of an IP address select you CPU and click to [Temporary setting of the IP parameters]. Please enter the same IP parameters, you configured in the CPU properties and click to [Write Parameters].
13. ➤ Confirm the message concerning the overall reset of the CPU.
⇒ The IP parameters are transferred to the CPU and the list of accessible stations is refreshed.
14. ➤ Select your CPU and click to [Confirm].
⇒ Now you are back in the dialog "Send configuration".

Transfer hardware configuration

- Choose your network card and click to [Send configuration].
⇒ After a short time a message is displayed concerning the transfer of the configuration is finished.

The hardware configuration is finished, now and the CPU may always be accessed by the IP parameters as well by means of WinPLC7.

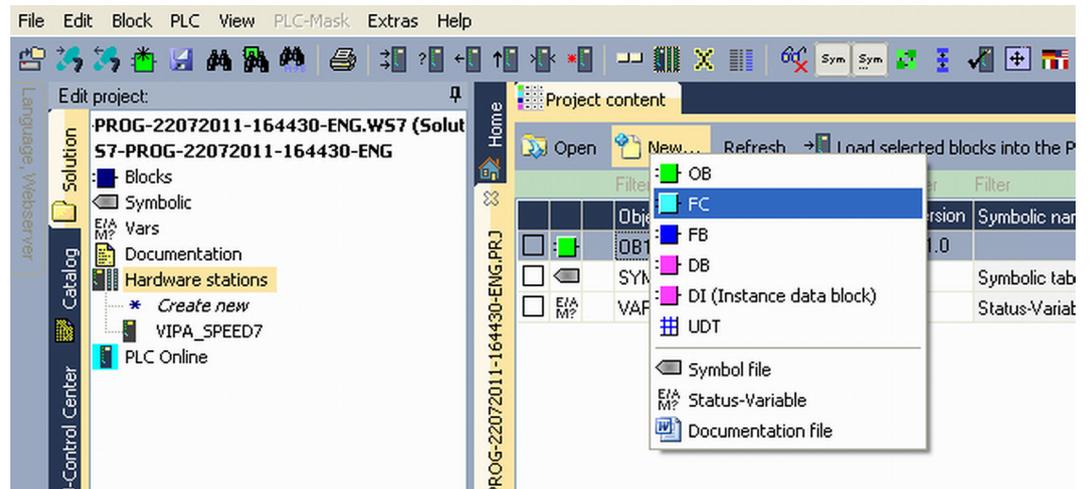


Usually the online transfer of the hardware configuration happens within the hardware configurator. With 'File → Save active station in the WinPL7 sub project' there is also the possibility to store the hardware configuration as a system file in WinPLC7 to transfer it from WinPLC7 to the CPU.

Programming of the FC 1

The PLC programming happens by WinPLC7. Close the hardware configurator and return to your project in WinPLC7. The PLC program is to be created in the FC 1.

1. In 'Project content' choose 'New → FC'.



2. Enter "FC1" as block and confirm with [OK].
⇒ The editor for FC 1 is called.

Creating parameters

In the upper part of the editor there is the parameter table. In this example the 2 integer values *value1* and *value2* are to be compared together. Since both values are read only by the function, these are to be defined as "in".

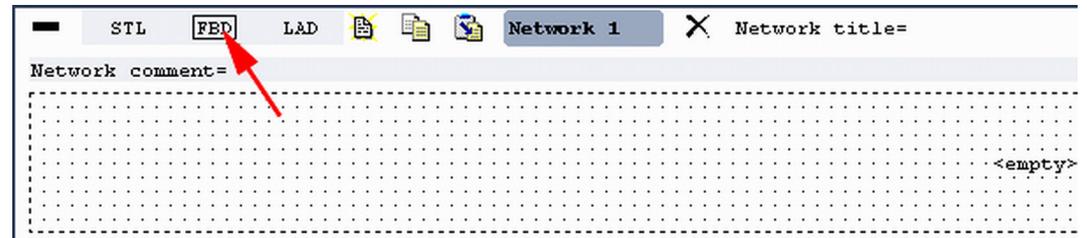
1. Select the 'in →' row at the 'parameter table' and enter at the field 'Name' "value1". Press the [Return] key.
⇒ The cursor jumps to the column with the data type.
2. The data type may either directly be entered or be selected from a list of available data types by pressing the [Return] key. Set the data type to INT and press the [Return] key.
⇒ Now the cursor jumps to the 'Comment' column.
3. Here enter "1. compare value" and press the [Return] key.
⇒ A new 'in →' row is created and the cursor jumps to 'Name'.
4. Proceed for *value2* in the same way as described for *value1*.
5. Save the block. A note that the interface of the block was changed may be acknowledged with [Yes].
⇒ The parameter table shows the following entries, now:

| Address | Declaration | Name | Type | Initial value | Comment |
|---------|-------------|--------|------|---------------|------------------|
| 0.0 | in → | value1 | INT | | 1. compare value |
| 2.0 | in → | value2 | INT | | 2. compare value |
| | out <→ | | | | |
| | in_out <→ | | | | |

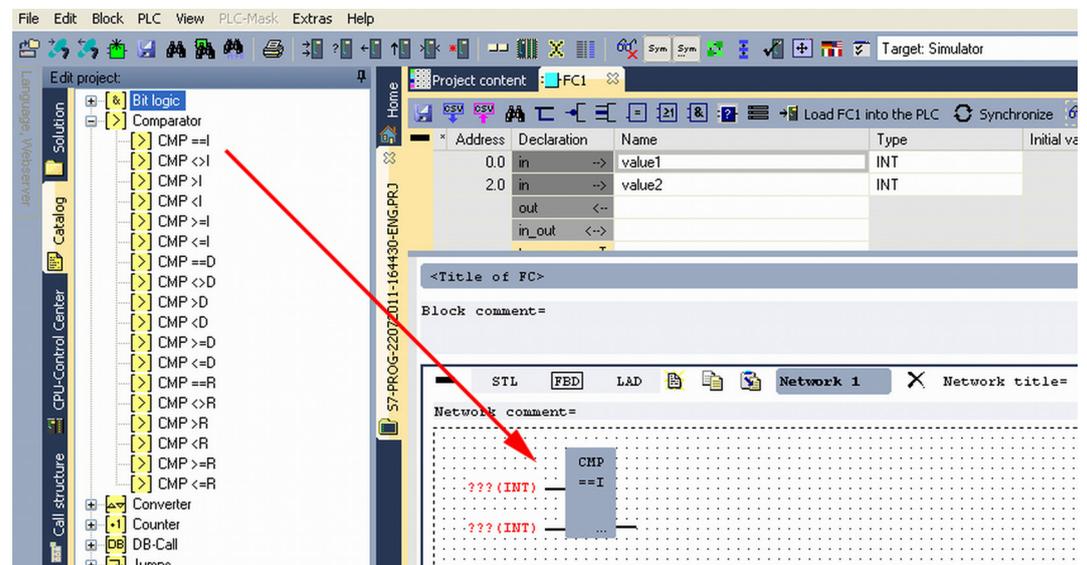
Enter the program

As requested in the job definition, the corresponding output is activated depending on the comparison of *value1* and *value2*. For each comparison operation a separate network is to be created.

1. The program is to be created as FBD (function block diagram). Here change to the FBD view by clicking at 'FBD'.



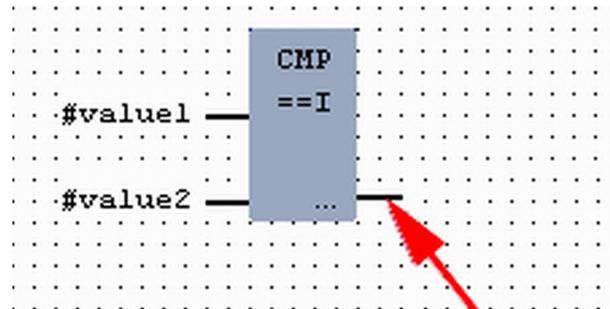
2. Click to the input field designated as "<empty>". The available operations may be added to your project by drag&drop from the *hardware catalog* or by double click at them in the *hardware catalog*.
3. Open in the *catalog* the category "Comparator" and add the operation 'CMP==I' to your network.



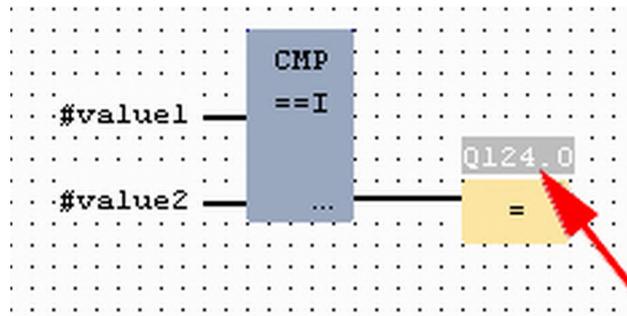
4. Click to the input left above and insert *value1*. Since these are block parameters a selection list of block parameters may be viewed by entering "#".
5. Type in "#" and press the [Return] key.
6. Choose the corresponding parameter of the list and confirm it with the [Return] key.
7. Proceed in the same way with the parameter *value2*.

The allocation to the corresponding output, here Q 124.0, takes place with the following proceeding:

1. ➤ Click to the output at the right side of the operator.



2. ➤ Open in the *catalog* the category '*Bit logic*' and select the function '*--[=]*'. The inserting of '*--[=]*' corresponds to the WinPLC7 shortcut *[F7]*.
3. ➤ Insert the output Q 124.0 by clicking to the operand.



⇒ Network1 is finished, now.

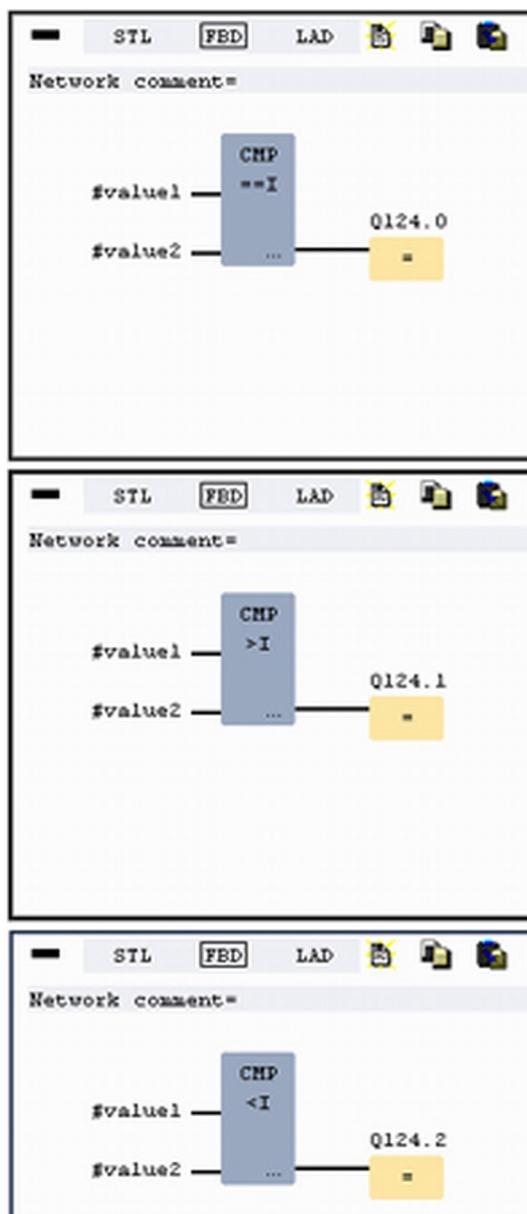
Adding a new network

For further comparisons the operations "CMP>I" at Q 124.1 and "CMP<I" at Q 124.2 are necessary. Create a network for both operations with the following proceeding:

1. ➤ Move your mouse at an arbitrary position on the editor window and press the right mouse key.
2. ➤ Select at '*context menu* → *Insert new network*'.
 - ⇒ A dialog field is opened to enter the position and number of the networks.
3. ➤ Proceed as described for "Network 1".

4. Save the FC 1 with 'File → Save content of focused window' respectively press [Strg]+[S].

⇒ After you have programmed the still missing networks, the FC 1 has the following structure:



Creating the block OB 1

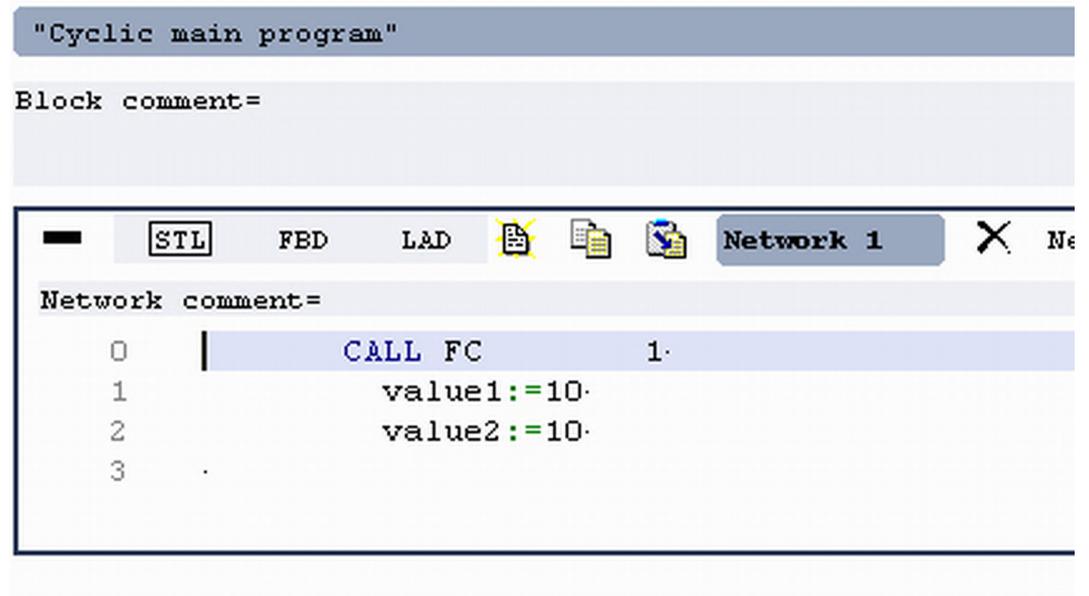
The FC 1 is to be called from the cycle OB 1.

1. Go to OB 1, which was automatically created with starting the project.
2. Go to 'Project content' or to 'Solution' and open the OB 1 by a double click.
3. Change to the STL view.

Example project engineering > Test the PLC program in the Simulator

4. Type in "Call FC 1" and press the *[Return]* key.

⇒ The FC parameters are automatically displayed and the following parameters are assigned:



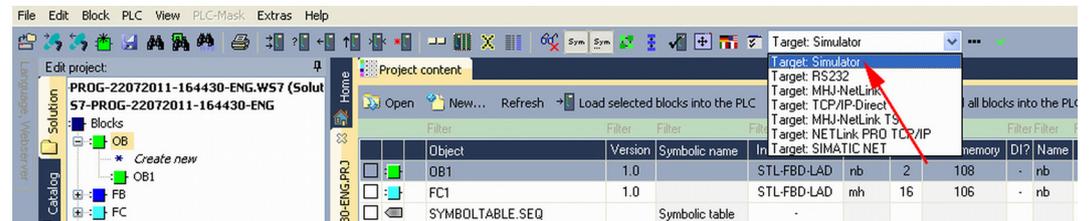
5. Save the OB 1 with respectively press *[Strg]+[S]*.

9.3.3 Test the PLC program in the *Simulator*

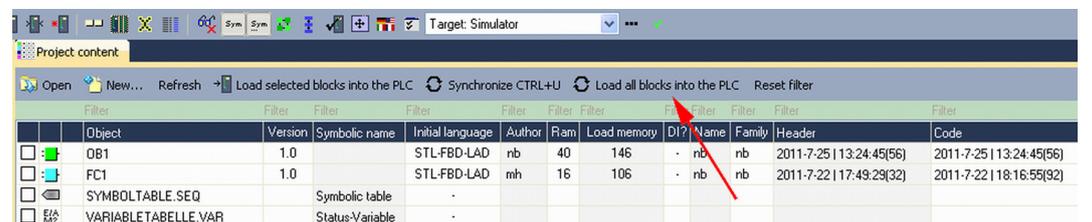
Proceeding

With WinPLC7 there is the possibility to test your project in a *Simulator*.

1. Here select 'Target: Simulator'.



2. Transfer the blocks to the simulator with *[Load all blocks into the PLC]*.



3. Switch the CPU to RUN, by clicking at 'RUN' in the 'CPU Control Center' of 'Edit project'.

⇒ The displayed state changes from STOP to RUN.

4. To view the process image select 'View → Display process image window' or click at .

⇒ The various areas are displayed.

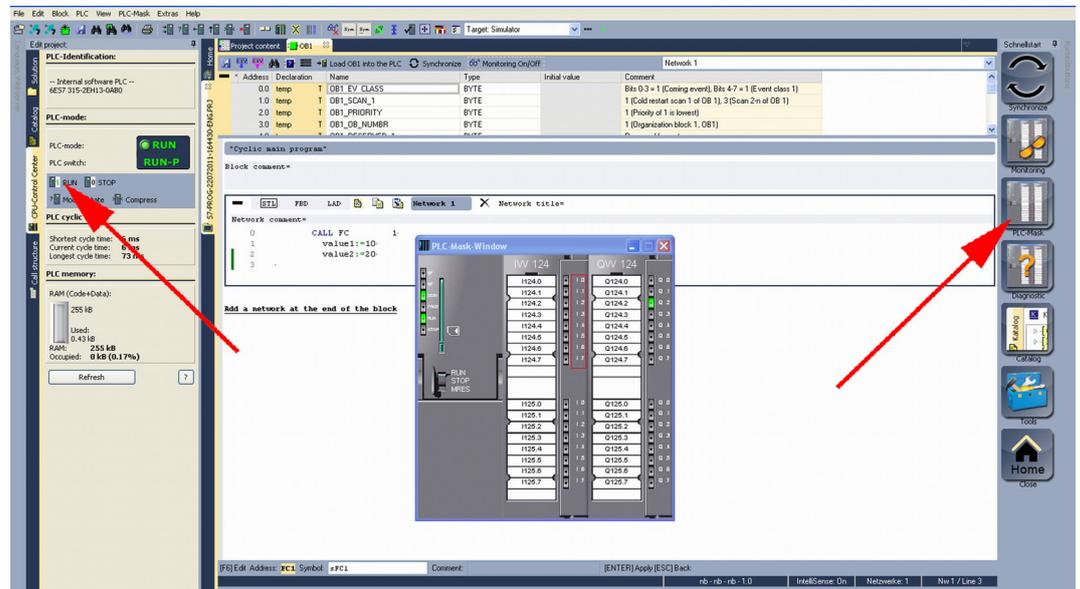
5. Double click to the process image and enter at 'Line 2' the address PQB 124. Confirm your input with *[OK]*. A value marked by red color corresponds to a logical "1".

6. ➤ Open the OB 1.
7. ➤ Change the value of one variable, save the OB 1 and transfer it to the simulator.
 - ⇒ According to your settings the process image changes immediately. The status of your blocks may be displayed with *'Block → Monitoring On/Off'*.

Visualization via PLC mask

A further component of the simulator is the *PLC mask*. Here a CPU is graphically displayed, which may be expanded by digital and analog peripheral modules. As soon as the CPU of the simulator is switched to RUN state, inputs may be activated by mouse and outputs may be displayed.

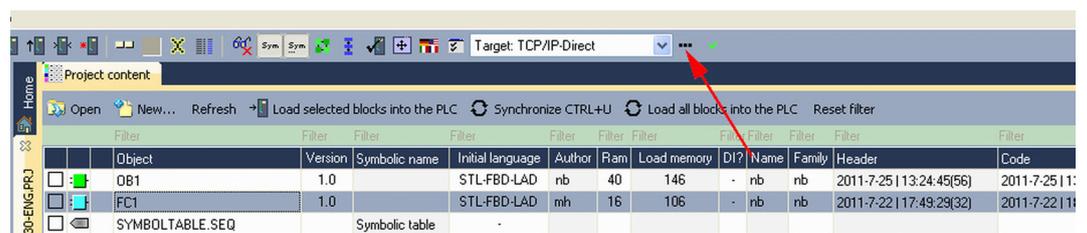
1. ➤ Open the *PLC mask* with *'view → PLC mask'*.
 - ⇒ A CPU is graphically displayed.
2. ➤ Double-click to the output module, open its properties dialog and enter the Module address 124.
3. ➤ Switch the operating mode switch to RUN by means of the mouse.
 - ⇒ Your program is executed and displayed in the simulator, now.



9.3.4 Transfer PLC program to CPU and its execution

Proceeding

1. ➤ For transfer to the CPU set the transfer mode to "Target: TCP/IP-Direct".
2. ➤ If there are more network adapters in your PC, the network adapter may be selected via *'Extras → Select network adapter'*.
3. ➤ For presetting the Ethernet data click to [...] and click to [Accessible nodes].



4. ➤ Click at [Determining accessible nodes].
 - ⇒ After a waiting time every accessible station is listed.

5. ➤ Choose your CPU, which was provided with TCP/IP address parameters during the hardware configuration and click to [Confirm].
6. ➤ Close the dialog '*Ethernet properties*' with [OK].
7. ➤ Transfer your project to your CPU with '*PLC ➔ Send all blocks*'.
8. ➤ Switch your CPU to RUN state.
9. ➤ Open the OB 1 by double click.
10. ➤ Change the value of one variable, save the OB 1 and transfer it to the CPU.
 - ⇒ According to your settings the process image changes immediately. The status of your blocks may be displayed with '*Block ➔ Monitoring On/Off*'.

10 Configuration with TIA Portal

10.1 TIA Portal - Work environment

10.1.1 General

General

In this chapter the project engineering of the Yaskawa CPU in the Siemens TIA Portal is shown. Here only the basic usage of the Siemens TIA Portal together with a Yaskawa CPU is shown. Please note that software changes can not always be considered and it may thus be deviations to the description. TIA means **T**otally integrated **A**utomation from Siemens. Here your Yaskawa PLCs may be configured and linked. For diagnostics online tools are available.

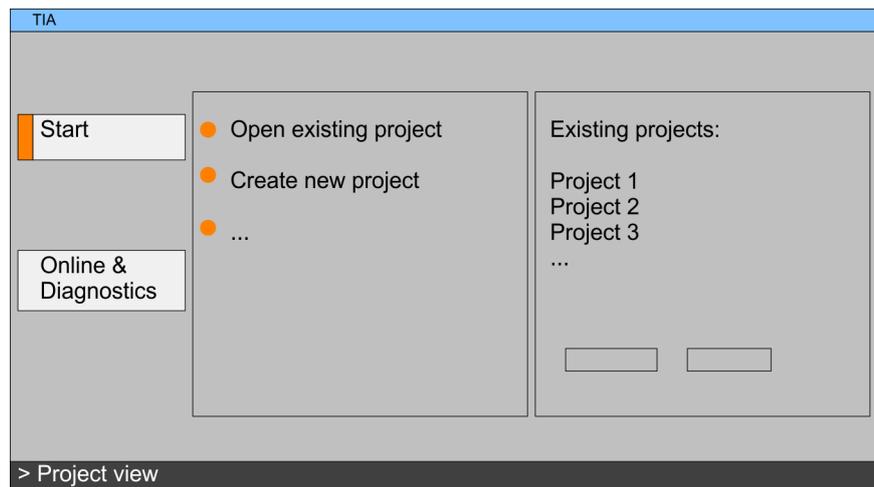


Information about the Siemens TIA Portal can be found in the online help respectively in the according online documentation.

Starting the TIA Portal

To start the Siemens TIA Portal with Windows select 'Start → Programs → Siemens Automation → TIA ...'

Then the TIA Portal opens with the last settings used.



Exiting the TIA Portal

With the menu 'Project → Exit' in the 'Project view' you may exit the TIA Portal. Here there is the possibility to save changes of your project before.

10.1.2 Work environment of the TIA Portal

Basically, the TIA Portal has the following 2 views. With the button on the left below you can switch between these views:

Portal view

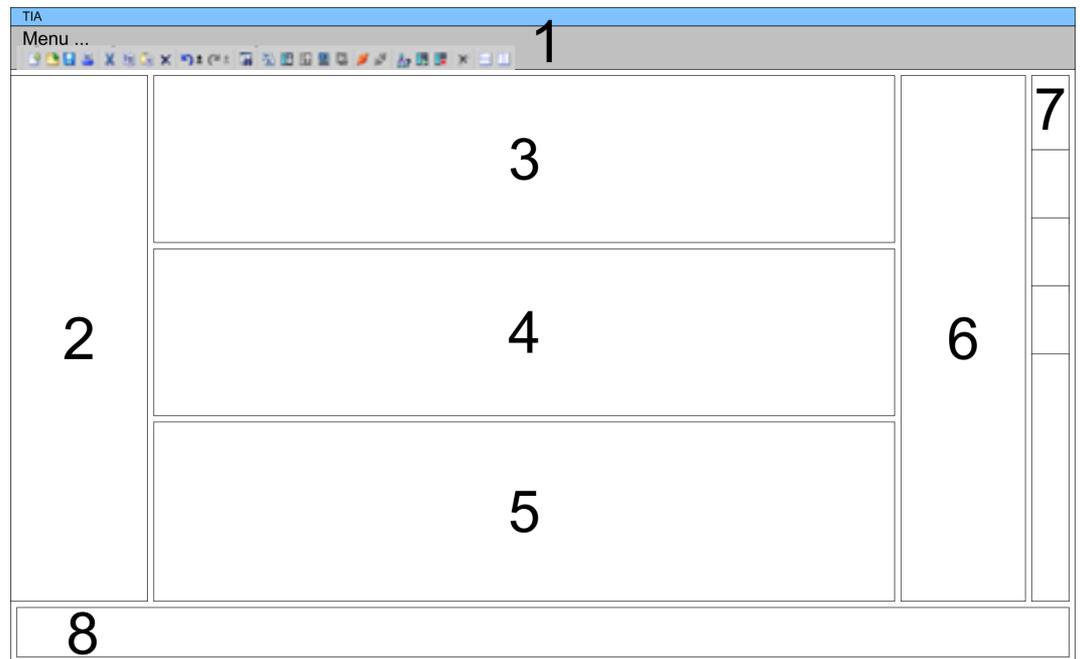
The *'Portal view'* provides a "task oriented" view of the tools for processing your project. Here you have direct access to the tools for a task. If necessary, a change to the Project view takes place automatically for the selected task.

Project view

The *'Project view'* is a "structured" view to all constituent parts of your project.

Areas of the Project view

The Project view is divided into the following areas:



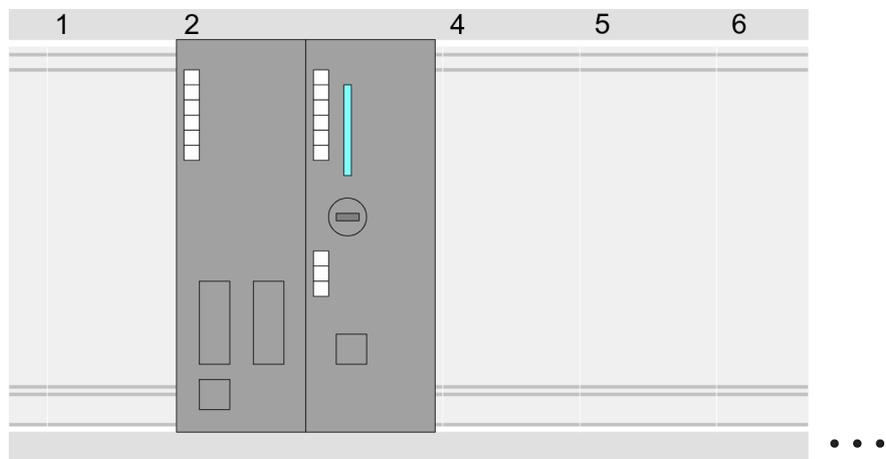
- 1 Menu bar with toolbars
- 2 Project tree with Details view
- 3 Project area
- 4 Device overview of the project respectively area for block programming
- 5 Properties dialog of a device (parameter) respectively information area
- 6 Hardware catalog and tools
- 7 "Task-Cards" to select hardware catalog, tasks and libraries
- 8 Jump to Portal or Project view

10.2 TIA Portal - Hardware configuration - CPU

Configuration Siemens CPU

With the Siemens TIA Portal the CPU 317-4NE23 from VIPA is to be configured as CPU 317-2DP (6ES7 317-2AK14 V3.3) from Siemens.

1. ➤ Start the Siemens TIA Portal.
2. ➤ Create a new project in the *Portal view* with 'Create new project'.
3. ➤ Switch to the *Project view*.
4. ➤ Click in the *Project tree* at 'Add new device'.
5. ➤ Select the following CPU in the input dialog:
SIMATIC S7-300 > CPU 317-2DP (6ES7 317-2AK14 V3.3)
⇒ The CPU is inserted with a profile rail.



Device overview:

| Module | ... | Slot | ... | Type | ... |
|------------------|-----|------|-----|------------------|-----|
| PLC ... | | 2 | | CPU 317-2DP | |
| MPI/DP interface | | 2 X1 | | MPI/DP interface | |
| DP interface | | 2 X2 | | DP interface | |
| ... | | ... | | ... | |

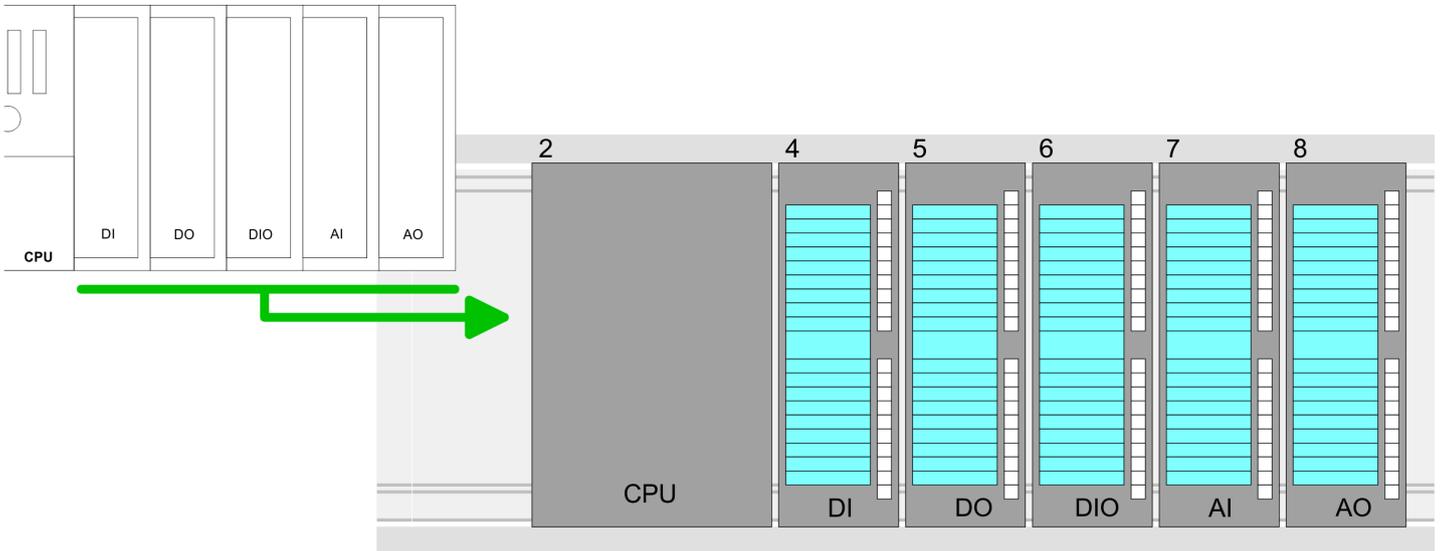
Setting standard CPU parameters

Since the CPU from VIPA is configured as Siemens CPU, so the setting of the parameters takes place via the Siemens CPU. For parametrization click in the *Project area* respectively in the *Device overview* at the CPU part. Then the parameters of the CPU part are shown in the *Properties dialog*. Here you can make your parameter settings. ↪ [Chap. 5.9.2 'Parameters CPU' page 52](#)

10.3 TIA Portal - Hardware configuration - I/O modules

Hardware configuration of the modules

After the hardware configuration of the CPU place the System 300 modules at the bus in the plugged sequence. For this drag&drop the according module from the Hardware catalog to the according position of the profile rail in the *Project area* or in the *Device overview*



Device overview

| Module | ... | Slot | ... | Type | ... |
|--------|-----|------|-----|---------|-----|
| PLC... | | 2 | | CPU ... | |
| ... | | ... | | ... | |
| | | 3 | | | |
| DI... | | 4 | | DI... | |
| DO... | | 5 | | DO... | |
| DIO... | | 6 | | DIO... | |
| AI... | | 7 | | AI... | |
| AO... | | 8 | | AO... | |
| | | | | | |
| | | | | | |

Parametrization

For parametrization click in the *Project area* respectively in the *Device overview* on the module you want to parameterize. The parameters of the module appear in the Properties dialog. Here you can make your parameter settings.

10.4 TIA Portal - Hardware configuration - Ethernet PG/OP channel

Overview

The CPU has an integrated Ethernet PG/OP channel. This channel allows you to program and remote control your CPU.

- The Ethernet PG/OP channel also gives you access to the internal web page that contains information about firmware version, connected I/O devices, current cycle times etc.
- At the first commissioning respectively after a factory reset the Ethernet PG/OP channel has no IP address.
- For online access to the CPU via the Ethernet PG/OP channel, valid IP address parameters have to be assigned to this. This is called "initialization".
- This can be done with the Siemens TIA Portal.

Assembly and commissioning

1. ➤ Install your System 300S with your CPU.
2. ➤ Wire the system by connecting cables for voltage supply and signals.
3. ➤ Connect the Ethernet jack of the Ethernet PG/OP channel to Ethernet.
4. ➤ Switch on the power supply.
 - ⇒ After a short boot time the CP is ready for communication. He possibly has no IP address data and requires an initialization.

"Initialization" via Online functions

The initialization via the Online functions takes place with the following proceeding:

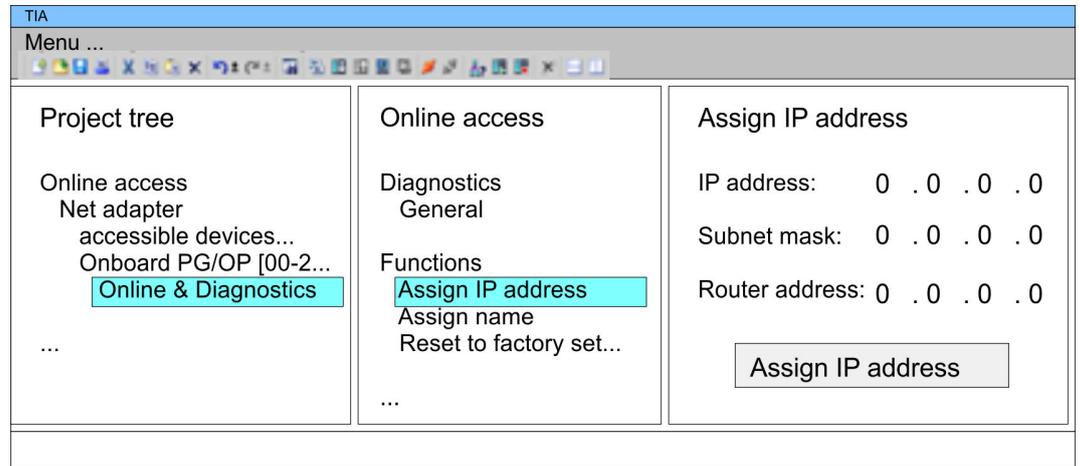
- Determine the current Ethernet (MAC) address of your Ethernet PG/OP channel. This can be found as 1. address under the front flap of the CPU on a sticker on the left side.

Assign IP address parameters

You get valid IP address parameters from your system administrator. The assignment of the IP address data happens online in the Siemens TIA Portal with the following proceeding:

1. ➤ Start the Siemens TIA Portal.
2. ➤ Switch to the 'Project view'.
3. ➤ Click in the 'Project tree' at 'Online access' and choose here by a doubleclick your network card, which is connected to the Ethernet PG/OP channel.
4. ➤ To get the stations and their MAC address, use the 'Accessible device'. The MAC address can be found at the 1. label beneath the front flap of the CPU.
5. ➤ Choose from the list the module with the known MAC address (Onboard PG/OP [MAC address]) and open with "Online & Diagnostics" the diagnostics dialog in the Project area.
6. ➤ Navigate to *Functions > Assign IP address*. Type in the IP configuration like IP address, subnet mask and gateway.

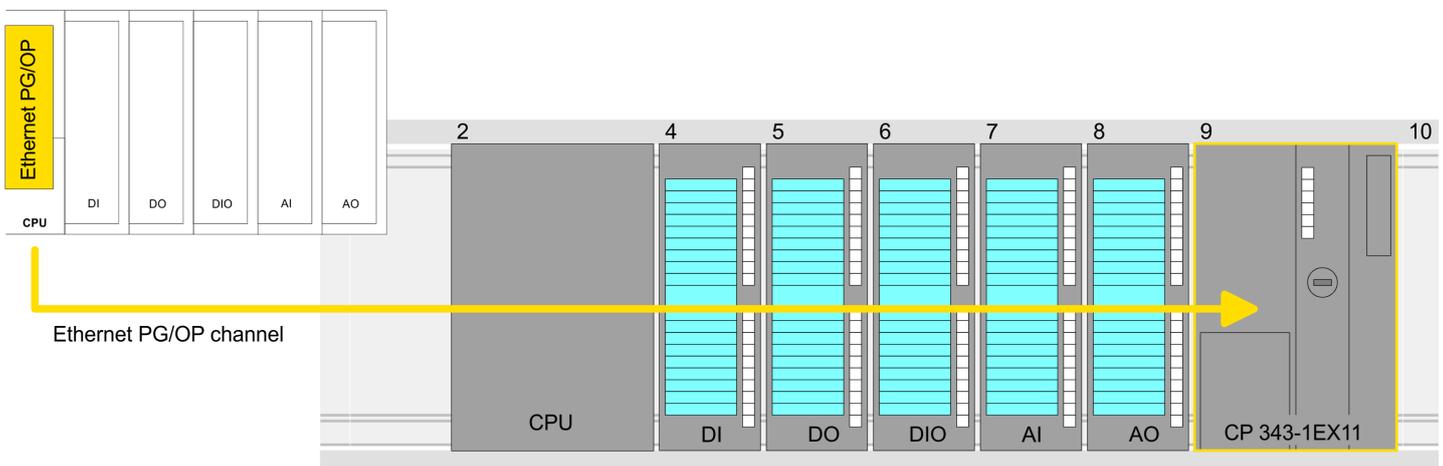
7. ➤ Confirm with [Assign IP configuration].
 - ⇒ Directly after the assignment the Ethernet PG/OP channel is online reachable using the set IP address data. The value remains as long as it is reassigned, it is overwritten by a hardware configuration or an factory reset is executed.



i Due to the system you may get a message that the IP address could not be assigned. This message can be ignored.

Take IP address parameters in project

1. ➤ Open your project.
2. ➤ If not already done, configure in the 'Device configuration' a Siemens CPU 317-2DP (6ES7 317-2AK14 V3.3).
3. ➤ Configure the System 300 modules.
4. ➤ For the Ethernet PG/OP channel you have to configure a Siemens CP 343-1 (6GK7 343-1EX11 0XE0) always as last module after the really plugged modules.
5. ➤ Open the "Property" dialog by clicking on the CP 343-1EX11 and enter for the CP at "Properties" at "Ethernet address" the IP address data, which you have assigned before.
6. ➤ Transfer your project.



Device overview:

| Module | ... | Slot | ... | Type | ... |
|--|-----|------|-----|----------|-----|
| PLC... | | 2 | | CPU ... | |
| ... | | ... | | ... | |
| | | 3 | | | |
| DI... | | 4 | | DI... | |
| DO... | | 5 | | DO... | |
| DIO... | | 6 | | DIO... | |
| AI... | | 7 | | AI... | |
| AO... | | 8 | | AO... | |
|  CP 343-1 | | 9 | | CP 343-1 | |

10.5 TIA Portal - Setting VIPA specific CPU parameters

Requirements

Since the VIPA specific CPU parameters may be set, the installation of the SPEEDBUS.GSD from VIPA in the hardware catalog is necessary. The CPU may be configured in a PROFIBUS master system and the appropriate parameters may be set after installation.

Installation of the SPEEDBUS.GSD

The GSD (Geräte-Stamm-Datei) is online available in the following language versions. Further language versions are available on inquire:

| Name | Language |
|--------------|------------------|
| SPEEDBUS.GSD | German (default) |
| SPEEDBUS.GSG | German |
| SPEEDBUS.GSE | English |

The GSD files may be found at www.yaskawa.eu.com at the service area.

The integration of the SPEEDBUS.GSD takes place with the following proceeding:

1.  Go to the service area of www.yaskawa.eu.com.
2.  Load from the download area at '*Config files* → *PROFIBUS*' the according file for your System 300S.
3.  Extract the file to your work directory.
4.  Start the hardware configurator from Siemens.
5.  Close every project.
6.  Select '*Options* → *Install new GSD-file*'.
7.  Navigate to the directory `VIPA_System_300S` and select **SPEEDBUS.GSD** an.
 - ⇒ The SPEED7 CPUs and modules of the System 300S from Yaskawa may now be found in the hardware catalog at PROFIBUS-DP / Additional field devices / I/O / VIPA_SPEEDBUS.

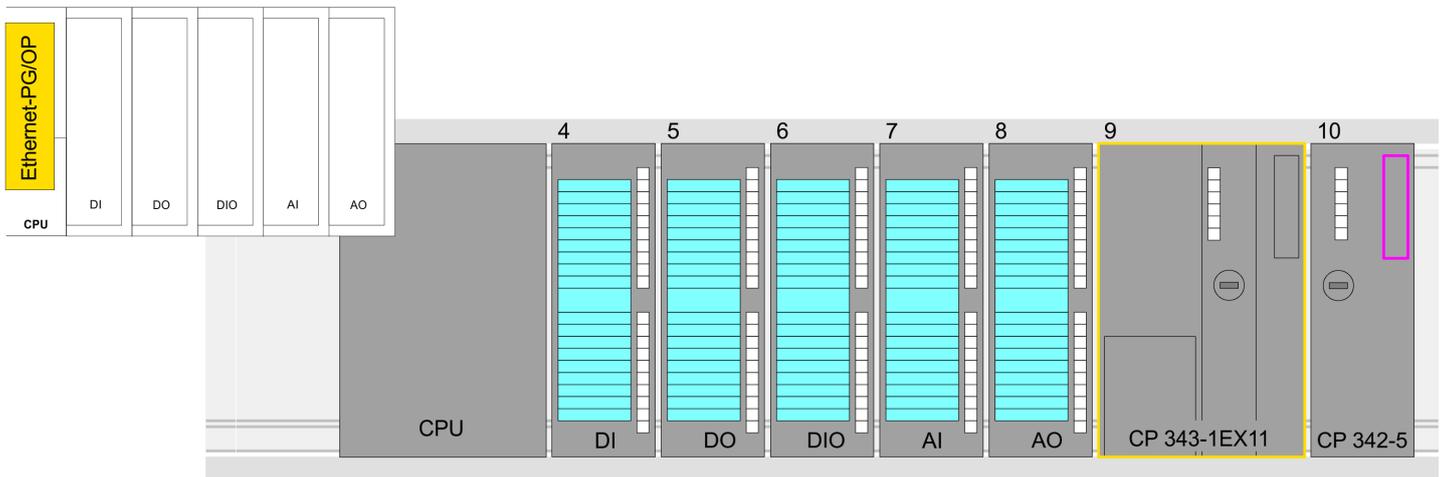


Thus, the VIPA components can be displayed, you have to deactivate the "Filter" of the hardware catalog.

Proceeding

The embedding of the CPU 317-4NE23 happens by means of a virtual PROFIBUS master system with the following approach:

1. ➤ Start the Siemens TIA Portal.
2. ➤ Configure in the Device configuration the according Siemens CPU.
3. ➤ Configure your System 300 modules.
4. ➤ Configure your Ethernet PG/OP channel always as last module after the really plugged modules.
5. ➤ Configure always as last module a Siemens DP master CP 342-5 (342-5DA02 V5.0). Connect and parameterize it at operation mode "DP-Master".



Device overview

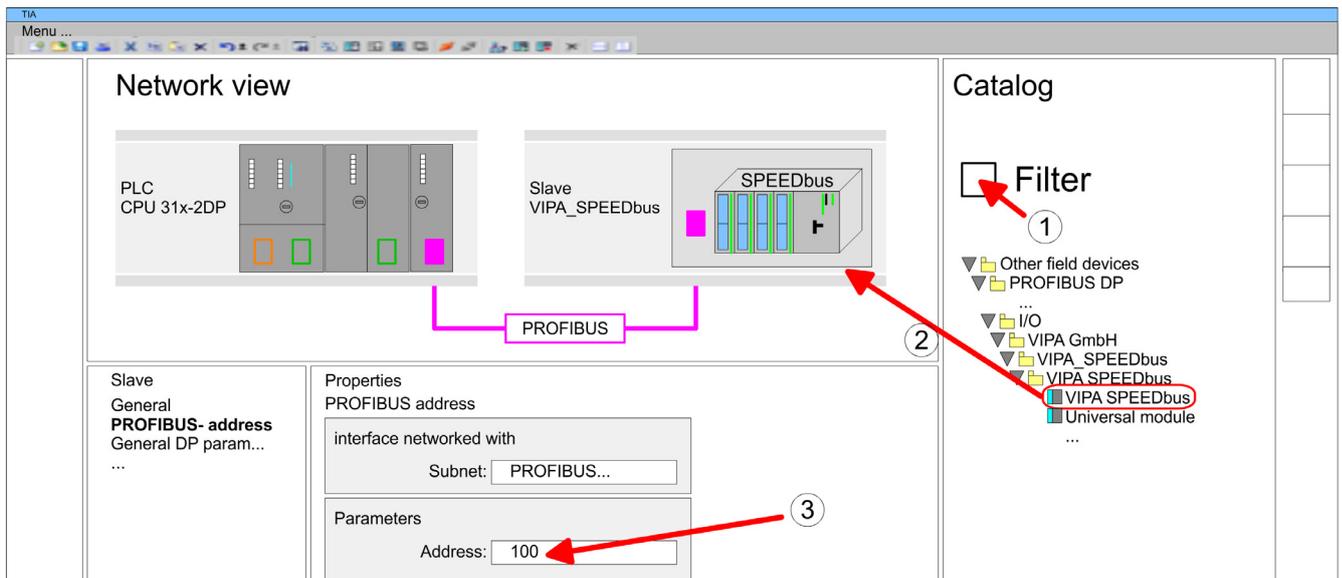
| Module | ... | Slot | ... | Type | ... |
|----------|-----|------|-----|----------|-----|
| PLC... | | 2 | | CPU ... | |
| ... | | ... | | ... | |
| | | 3 | | | |
| DI... | | 4 | | DI... | |
| DO... | | 5 | | DO... | |
| DIO... | | 6 | | DIO... | |
| AI... | | 7 | | AI... | |
| AO... | | 8 | | AO... | |
| CP 343-1 | | 9 | | CP 343-1 | |
| CP 342-5 | | 10 | | CP 342-5 | |



Thus, the VIPA components can be displayed, you have to deactivate the "Filter" of the hardware catalog.

Connect VIPA_SPEEDbus

1. ➔ Switch in the *Project area* to *Network view*.
2. ➔ Connect the slave system "VIPA_SPEEDbus". After installing the SPEEDBUS.GSD this may be found in the hardware catalog at: *Other field devices > PROFIBUS DP > I/O > VIPA GmbH > VIPA_SPEEDbus*.
3. ➔ Set for the SPEEDbus slave system the PROFIBUS address 100.



4. ➔ Click at the slave system and open the 'Device overview' in the *Project area*.
5. ➔ Configure at slot 1 the VIPA CPU 317-4NE23 of the hardware catalog from VIPA_SPEEDbus.
6. ➔ By double clicking the placed CPU 317-4NE23 the properties dialog of the CPU is showed.

Device overview

| Module | ... | Slot | ... | Type | ... |
|-----------|-----|------|-----|---------------|-----|
| Slave ... | | 0 | | VIPA SPEEDbus | |
| 317-4NE23 | | 1 | | 317-4NE23 ... | |
| | | 2 | | | |

⇒ As soon as the project is transferred together with the PLC user program to the CPU, the parameters will be taken after start-up.

10.6 TIA Portal - Yaskawa-Include library

Overview

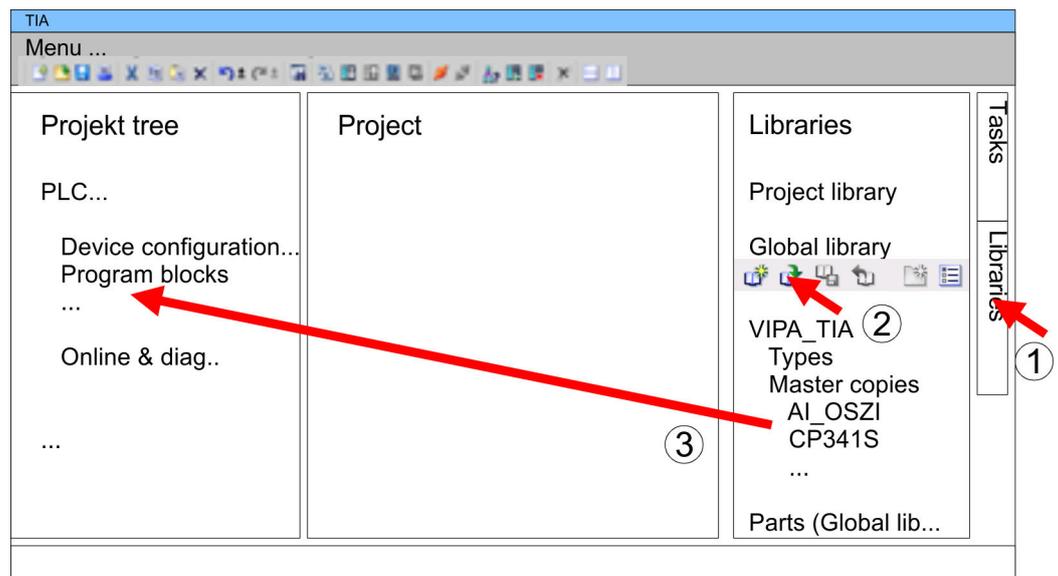
- The Yaskawa specific blocks can be found in the "Service" area of www.yaskawa.eu.com as library download file at *Downloads > VIPA LIB*.
- The library is available as packed zip file for the corresponding TIA Portal version.
- As soon as you want to use Yaskawa specific blocks you have to import them into your project.
Execute the following steps:
 - Load and unzip the file ...TIA_Vxx.zip (note TIA Portal version)
 - Open library and transfer blocks into the project

Unzip ...TIA_Vxx.zip

Start your un-zip application with a double click on the file TIA_Vxx.zip and copy all the files and folders in a work directory for the Siemens TIA Portal.

Open library and transfer blocks into the project

1. Start the Siemens TIA Portal with your project.
2. Switch to the *Project view*.
3. Choose "Libraries" from the task cards on the right side.
4. Click at "Global libraries".
5. Click at "Open global libraries".
6. Navigate to your directory and load the file ...TIA.alxx.



7. Copy the necessary blocks from the library into the "Program blocks" of the *Project tree* of your project. Now you have access to the Yaskawa specific blocks via your user application.

10.7 TIA Portal - Project transfer

Overview

There are the following possibilities for project transfer into the CPU:

- Transfer via MPI
- Transfer via Ethernet
- Transfer via memory card

Transfer via MPI

Currently the VIPA programming cables for transfer via MPI are not supported. This is only possible with the programming cable from Siemens.

1. ➤ Establish a connection to the CPU via MPI with an appropriate programming cable. Information may be found in the corresponding documentation of the programming cable.
2. ➤ Switch-ON the power supply of your CPU and start the Siemens TIA Portal with your project.
3. ➤ Select in the *Project tree* your CPU and choose '*Context menu* → *Download to device* → *Hardware configuration*' to transfer the hardware configuration.
4. ➤ To transfer the PLC program choose '*Context menu* → *Download to device* → *Software*'. Due to the system you have to transfer hardware configuration and PLC program separately.

Transfer via Ethernet

For transfer via Ethernet the CPU has the following interface:

- X5: Ethernet PG/OP channel

Initialization

So that you may the according Ethernet interface, you have to assign IP address parameters by means of the "initialization".

Please consider to use the same IP address data in your project for the CP 343-1.

Transfer

1. ➤ For the transfer, connect, if not already done, the appropriate Ethernet jack to your Ethernet.
2. ➤ Open your project with the Siemens TIA Portal.
3. ➤ Click in the *Project tree* at *Online access* and choose here by a double-click your network card, which is connected to the Ethernet PG/OP interface.
4. ➤ Select in the *Project tree* your CPU and click at [Go online].
5. ➤ Set the access path by selecting "PN/IE" as type of interface, your network card and the according subnet. Then a net scan is established and the corresponding station is listed.
6. ➤ Establish with [Connect] a connection.
7. ➤ Click to '*Online* → *Download to device*'.
 - ⇒ The according block is compiled and by a request transferred to the target device. Provided that no new hardware configuration is transferred to the CPU, the entered Ethernet connection is permanently stored in the project as transfer channel.

Transfer via memory card

The memory card serves as external storage medium. There may be stored several projects and sub-directories on a memory card. Please regard that your current project is stored in the root directory and has one of the following file names:

- S7PROG.WLD
- AUTOLOAD.WLD

1.  Create in the Siemens TIA Portal a wld file with '*Project → Memory card file → New*'.
 - ⇒ The wld file is shown in the *Project tree* at "SIMATIC Card Reader" as "Memory card file".
2.  Copy the blocks from the *Program blocks* to the wld file. Here the hardware configuration data are automatically copied to the wld file as "System data".

Transfer memory card → CPU

The transfer of the application program from the memory card into the CPU takes place depending on the file name after an overall reset or PowerON.

- S7PROG.WLD is read from the memory card after overall reset.
- AUTOLOAD.WLD is read from the memory card after PowerON.

The blinking of the MC LED of the CPU marks the active transfer. Please regard that your user memory serves for enough space for your user program, otherwise your user program is not completely loaded and the SF LED gets on.

Transfer CPU → Memory card

When a memory card has been installed, the write command stores the content of the RAM as S7PROG.WLD on the memory card. The write command can be found in the Siemens TIA Portal in the Task card "Online tools" in the command area at "Memory" as button [Copy RAM to ROM]. The MC LED blinks during the write access. When the LED expires, the write process is finished. If this project is to be loaded automatically from the memory card with PowerON, you have to rename this to on the memory card to AUTOLOAD.WLD.



Please note that in the Siemens TIA Portal with some CPU types the [Copy RAM to ROM] button is not available. Instead please use the CMD auto command SAVE PROJECT. ↪ Chap. 5.19 'CMD - auto commands' page 78

Checking the transfer operation

After accessing the memory card you can find a diagnostics entry in the CPU. To monitor the diagnostics entries, you select *Online & Diagnostics* in the Siemens TIA Portal. Here you can access the "Diagnostics buffer". ↪ Chap. 5.20 'Diagnostic entries' page 80

Appendix

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| C | SSL partial list | 221 |

A System specific event IDs

Event IDs

↪ Chap. 5.20 'Diagnostic entries' page 80

| Event ID | Description |
|------------------------|---|
| 0x115C | Manufacture interrupt for EtherCAT / PROFINET IO |
| | OB: OB number |
| | ZINFO1: Logical address of the slave station that triggered the interrupt |
| | ZINFO2: Interrupt type |
| | 0: Reserved |
| | 1: Diagnostic interrupt (incoming) |
| | 2: Process interrupt |
| | 3: Pull interrupt |
| | 4: Plug interrupt |
| | 5: Status interrupt |
| | 6: Update interrupt |
| | 7: Redundancy interrupt |
| | 8: Controlled by the supervisor |
| | 9: Enabled |
| | 10: Wrong sub module plugged |
| | 11: Recurrence of the sub module |
| | 12: Diagnostic interrupt (outgoing) |
| | 13: Cross traffic connection message |
| | 14: Neighbourhood change message |
| | 15: Synchronisation message (bus) |
| | 16: Synchronisation message (device) |
| | 17: Network component message |
| | 18: Clock synchronisation message (bus) |
| | 31: Pull interrupt component |
| | 32: Vendor-specific interrupt min. |
| | 33: Vendor-specific interrupt topology change |
| | 127: Vendor-specific interrupt max. |
| ZINFO3: CoE error code | |
| 0xE003 | Error in access to periphery |
| | ZINFO1: Transfer type |
| | ZINFO2: Periphery address |
| | ZINFO3: Slot |
| 0xE004 | Multiple configuration of a periphery address |
| | ZINFO1: Periphery address |
| | ZINFO2: Slot |

| Event ID | Description |
|----------|---|
| 0xE005 | Internal error - Please contact the hotline! |
| | ZINFO1: Not user relevant |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| 0xE007 | Configured input/output bytes do not fit in the periphery area |
| 0xE008 | Internal error - Please contact the hotline! |
| 0xE009 | Error on accessing the standard backplane bus |
| 0xE010 | Non-defined component recognised at the standard backplane bus |
| | ZINFO2: Slot |
| | ZINFO3: Type identifier |
| 0xE011 | Master project engineering at slave CPU not possible or wrong slave configuration |
| 0xE012 | Error at configuration standard backplane bus |
| 0xE013 | Error at shift register access to standard backplane bus digital modules |
| 0xE014 | Error in Check_Sys |
| 0xE015 | Error in access to master |
| | ZINFO2: Slot of the master |
| | ZINFO2: Page frame master |
| 0xE016 | Maximum block size exceeded in master transfer |
| | ZINFO1: Periphery address |
| | ZINFO2: Slot |
| 0xE017 | Error in access to integrated slave |
| 0xE018 | Error in mapping the master periphery |
| 0xE019 | Error on standard backplane bus system detection |
| 0xE01A | Error at detection of the operating mode (8/9 bit) |
| 0xE01B | Error: Maximum number of plug-in components exceeded |
| 0xE020 | Error: Interrupt information undefined |
| | ZINFO2: Slot |
| | ZINFO3: Not user relevant |
| | DatID: Interrupt type |
| 0xE030 | Error of the standard backplane bus |
| 0xE033 | Internal error - Please contact the hotline! |
| 0xE0B0 | SPEED7 is not stoppable |
| | ZINFO1: Not user relevant |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xE0C0 | Not enough memory space in the working memory for code block (block too large) |
| 0xE0CB | Error on SSL access |

| Event ID | Description |
|----------|--|
| | ZINFO1: Error |
| | 4: SSL wrong |
| | 5: Sub-SSL wrong |
| | 6: Index wrong |
| | ZINFO2: SZL-ID |
| | ZINFO3: Index |
| 0xE0CC | Communication error |
| | ZINFO1: Error code |
| | 1: Wrong priority |
| | 2: Buffer overrun |
| | 3: Telegram format error |
| | 4: Wrong SSL request (SSL-ID invalid) |
| | 5: Wrong SSL request (SSL-Sub-ID invalid) |
| | 6: Wrong SSL request (SSL-Index invalid) |
| | 7: Wrong value |
| | 8: Wrong return value |
| | 9: Wrong SAP |
| | 10: Wrong connection type |
| | 11: Wrong sequence number |
| | 12: Faulty block number in the telegram |
| | 13: Faulty block type in the telegram |
| | 14: Inactive function |
| | 15: Wrong size in the telegram |
| | 20: Error in writing on MMC |
| | 90: Faulty buffer size |
| | 98: Unknown error |
| | 99: Internal error |
| 0xE0CD | Error at DP-V1 job management |
| | ZINFO1: Not user relevant |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xE0CE | Error: Time out when sending i-slave diagnostics |
| 0xE100 | Memory card access error |
| 0xE101 | Memory card error file system |
| 0xE102 | Memory card error FAT |
| 0xE104 | Memory card error at saving |
| | ZINFO3: Not user relevant |

| Event ID | Description |
|----------------------|---|
| 0xE200 | Memory card writing finished (Copy Ram2Rom) |
| | OB: Not user relevant |
| | PK: Not user relevant |
| 0xE210 | Memory card reading finished (reload after memory reset) |
| | OB: Not user relevant |
| | PK: Not user relevant |
| | ZINFO1 - Position 0: Not user relevant |
| 0xE21D | Memory card reading: Error on reload (after memory reset), error in the block header |
| | ZINFO1: Block type |
| | 56: OB |
| | 65: DB |
| | 66: SDB |
| | 67: FC |
| | 68: SFC |
| | 69: FB |
| | 70: SFB |
| | 97: VDB |
| | 98: VSDB |
| | 99: VFC |
| | 100: VSFC |
| | 101: VFB |
| | 102: VSFB |
| | 111: VOB |
| | ZINFO2: Block number |
| ZINFO3: Block length | |
| 0xE21E | Memory card reading: Error in recharging (after memory reset), "Protect.wld" file too large |
| | OB: Not user relevant |
| 0xE21F | Memory card reading: Error at reload (after memory reset), checksum error when reading |
| | OB: Not user relevant |
| | PK: Not user relevant |
| | ZINFO1: Not user relevant |
| | ZINFO2: Block type |
| | 56: OB |
| | 65: DB |
| | 66: SDB |
| | 67: FC |
| | 68: SFC |
| | 69: FB |

| Event ID | Description |
|----------|---|
| | 70: SFB |
| | 97: VDB |
| | 98: VSDB |
| | 99: VFC |
| | 100: VSFC |
| | 101: VFB |
| | 102: VSFB |
| | 111: VOB |
| | ZINFO3: Block number |
| 0xE300 | Internal flash writing completed (copy Ram2Rom) |
| 0xE310 | Internal flash reading completed (recharging after battery failure) |
| 0xE400 | FSC card was plugged |
| | OB: FSC activated from this slot (PK) |
| | OB: The inserted FSC is the activated FSC |
| | OB: The inserted FSC is compatible with the CPU |
| | PK: FSC source |
| | 0: CPU |
| | 1: Card |
| | ZINFO1: FSC(CRC) |
| | 1146: 955-C000070 |
| | 1736: 955-C0NE040 |
| | 2568: FSC-C0ME040 |
| | 3450: 955-C000M30 |
| | 3903: 955-C000S30 |
| | 4361: FSC-C000M30 |
| | 4940: FSC-C000S30 |
| | 5755: 955-C0ME040 |
| | 6843: FSC-C0NE040 |
| | 8561: FSC-C000S20 |
| | 9012: FSC-C000M20 |
| | 13895: 955-C000060 |
| | 15618: 955-C000S20 |
| | 16199: 955-C000M20 |
| | 17675: FSC-C000S00 |
| | 18254: FSC-C000M00 |
| | 20046: FSC-C000040 |
| | 21053: 955-C000040 |
| | 22904: 955-C000S00 |

| Event ID | Description |
|----------|--|
| | 23357: 955-C000M00 |
| | 24576: 955-C000050 |
| | 35025: 955-C00MC10 |
| | 36351: FSC-C000S40 |
| | 36794: FSC-C000M40 |
| | 37260: 955-C000S40 |
| | 37833: 955-C000M40 |
| | 38050: FSC-C00MC10 |
| | 41460: 955-C000M50 |
| | 41526: 955-C0PE040 |
| | 42655: FSC-C00MC00 |
| | 47852: 955-C00MC00 |
| | 48709: FSC-C0PE040 |
| | 50574: 955-C000M70 |
| | 52366: 955-C000030 |
| | 53501: FSC-C000030 |
| | 58048: FSC-C000020 |
| | 63411: 955-C000M60 |
| | 65203: 955-C000020 |
| | ZINFO2: FSC serial number (high word) |
| | ZINFO3: FSC serial number (low word) |
| 0xE401 | FSC card was removed |
| | OB: Action after the end of the trial time |
| | 0: No action |
| | 1: CPU STOP |
| | 2: CPU STOP and FSC deactivated |
| | 3: Factory reset |
| | 255: FSC was not activated |
| | PK: FSC source |
| | 0: CPU |
| | 1: Card |
| | ZINFO1: FSC(CRC) |
| | 1146: 955-C000070 |
| | 1736: 955-C0NE040 |
| | 2568: FSC-C0ME040 |
| | 3450: 955-C000M30 |
| | 3903: 955-C000S30 |
| | 4361: FSC-C000M30 |

| Event ID | Description |
|----------|--|
| | 4940: FSC-C000S30 |
| | 5755: 955-C0ME040 |
| | 6843: FSC-C0NE040 |
| | 8561: FSC-C000S20 |
| | 9012: FSC-C000M20 |
| | 13895: 955-C000060 |
| | 15618: 955-C000S20 |
| | 16199: 955-C000M20 |
| | 17675: FSC-C000S00 |
| | 18254: FSC-C000M00 |
| | 20046: FSC-C000040 |
| | 21053: 955-C000040 |
| | 22904: 955-C000S00 |
| | 23357: 955-C000M00 |
| | 24576: 955-C000050 |
| | 35025: 955-C00MC10 |
| | 36351: FSC-C000S40 |
| | 36794: FSC-C000M40 |
| | 37260: 955-C000S40 |
| | 37833: 955-C000M40 |
| | 38050: FSC-C00MC10 |
| | 41460: 955-C000M50 |
| | 41526: 955-C0PE040 |
| | 42655: FSC-C00MC00 |
| | 47852: 955-C00MC00 |
| | 48709: FSC-C0PE040 |
| | 50574: 955-C000M70 |
| | 52366: 955-C000030 |
| | 53501: FSC-C000030 |
| | 58048: FSC-C000020 |
| | 63411: 955-C000M60 |
| | 65203: 955-C000020 |
| | ZINFO2: FSC serial number (high word) |
| | ZINFO3: FSC serial number (low word) |
| | DatID: FeatureSet Trialtime in minutes |
| 0xE402 | A configured functionality is not activated. The configuration is accepted, but the PLC can not go to RUN. |
| | ZINFO1: Required FSC: PROFIBUS |
| | ZINFO1: Required FSC: MOTION |

| Event ID | Description |
|----------|--------------------------------------|
| | ZINFO2: Number of released axes |
| | ZINFO3: Number of configured axes |
| 0xE403 | FSC can not be activated in this CPU |
| | OB: FCS error code |
| | PK: FSC source |
| | 0: CPU |
| | 1: Card |
| | ZINFO1: FSC(CRC) |
| | 1146: 955-C000070 |
| | 1736: 955-C0NE040 |
| | 2568: FSC-C0ME040 |
| | 3450: 955-C000M30 |
| | 3903: 955-C000S30 |
| | 4361: FSC-C000M30 |
| | 4940: FSC-C000S30 |
| | 5755: 955-C0ME040 |
| | 6843: FSC-C0NE040 |
| | 8561: FSC-C000S20 |
| | 9012: FSC-C000M20 |
| | 13895: 955-C000060 |
| | 15618: 955-C000S20 |
| | 16199: 955-C000M20 |
| | 17675: FSC-C000S00 |
| | 18254: FSC-C000M00 |
| | 20046: FSC-C000040 |
| | 21053: 955-C000040 |
| | 22904: 955-C000S00 |
| | 23357: 955-C000M00 |
| | 24576: 955-C000050 |
| | 35025: 955-C00MC10 |
| | 36351: FSC-C000S40 |
| | 36794: FSC-C000M40 |
| | 37260: 955-C000S40 |
| | 37833: 955-C000M40 |
| | 38050: FSC-C00MC10 |
| | 41460: 955-C000M50 |
| | 41526: 955-C0PE040 |
| | 42655: FSC-C00MC00 |

| Event ID | Description |
|----------|---|
| | 47852: 955-C00MC00 |
| | 48709: FSC-C0PE040 |
| | 50574: 955-C000M70 |
| | 52366: 955-C000030 |
| | 53501: FSC-C000030 |
| | 58048: FSC-C000020 |
| | 63411: 955-C000M60 |
| | 65203: 955-C000020 |
| | ZINFO2: FSC serial number (high word) |
| | ZINFO3: FSC serial number (low word) |
| 0xE404 | Feature set deleted due to CRC error |
| 0xE405 | The trial time of a feature set/memory card has expired |
| | OB: Action after the end of the trial time |
| | 0: No action |
| | 1: CPU STOP |
| | 2: CPU STOP and FSC deactivated |
| | 3: Factory reset |
| | 255: FSC was not activated |
| | PK: FSC source |
| | 0: CPU |
| | 1: Card |
| | ZINFO1: FSC(CRC) |
| | 1146: 955-C000070 |
| | 1736: 955-C0NE040 |
| | 2568: FSC-C0ME040 |
| | 3450: 955-C000M30 |
| | 3903: 955-C000S30 |
| | 4361: FSC-C000M30 |
| | 4940: FSC-C000S30 |
| | 5755: 955-C0ME040 |
| | 6843: FSC-C0NE040 |
| | 8561: FSC-C000S20 |
| | 9012: FSC-C000M20 |
| | 13895: 955-C000060 |
| | 15618: 955-C000S20 |
| | 16199: 955-C000M20 |
| | 17675: FSC-C000S00 |
| | 18254: FSC-C000M00 |

| Event ID | Description |
|----------|--|
| | 20046: FSC-C000040 |
| | 21053: 955-C000040 |
| | 22904: 955-C000S00 |
| | 23357: 955-C000M00 |
| | 24576: 955-C000050 |
| | 35025: 955-C00MC10 |
| | 36351: FSC-C000S40 |
| | 36794: FSC-C000M40 |
| | 37260: 955-C000S40 |
| | 37833: 955-C000M40 |
| | 38050: FSC-C00MC10 |
| | 41460: 955-C000M50 |
| | 41526: 955-C0PE040 |
| | 42655: FSC-C00MC00 |
| | 47852: 955-C00MC00 |
| | 48709: FSC-C0PE040 |
| | 50574: 955-C000M70 |
| | 52366: 955-C000030 |
| | 53501: FSC-C000030 |
| | 58048: FSC-C000020 |
| | 63411: 955-C000M60 |
| | 65203: 955-C000020 |
| | ZINFO2: FSC serial number (high word) |
| | ZINFO3: FSC serial number (low word) |
| | DatID: FeatureSet Trialtime in minutes |
| 0xE406 | The inserted feature set is corrupt |
| | PK: FSC source |
| | 0: CPU |
| | 1: Card |
| 0xE410 | A CPU feature set was activated |
| | PK: FSC source |
| | 0: CPU |
| | 1: Card |
| | ZINFO1: FSC(CRC) |
| | 1146: 955-C000070 |
| | 1736: 955-C0NE040 |
| | 2568: FSC-C0ME040 |
| | 3450: 955-C000M30 |

| Event ID | Description |
|----------|---|
| | 3903: 955-C000S30 |
| | 4361: FSC-C000M30 |
| | 4940: FSC-C000S30 |
| | 5755: 955-C0ME040 |
| | 6843: FSC-C0NE040 |
| | 8561: FSC-C000S20 |
| | 9012: FSC-C000M20 |
| | 13895: 955-C000060 |
| | 15618: 955-C000S20 |
| | 16199: 955-C000M20 |
| | 17675: FSC-C000S00 |
| | 18254: FSC-C000M00 |
| | 20046: FSC-C000040 |
| | 21053: 955-C000040 |
| | 22904: 955-C000S00 |
| | 23357: 955-C000M00 |
| | 24576: 955-C000050 |
| | 35025: 955-C00MC10 |
| | 36351: FSC-C000S40 |
| | 36794: FSC-C000M40 |
| | 37260: 955-C000S40 |
| | 37833: 955-C000M40 |
| | 38050: FSC-C00MC10 |
| | 41460: 955-C000M50 |
| | 41526: 955-C0PE040 |
| | 42655: FSC-C00MC00 |
| | 47852: 955-C00MC00 |
| | 48709: FSC-C0PE040 |
| | 50574: 955-C000M70 |
| | 52366: 955-C000030 |
| | 53501: FSC-C000030 |
| | 58048: FSC-C000020 |
| | 63411: 955-C000M60 |
| | 65203: 955-C000020 |
| | ZINFO2: FSC serial number (high word) |
| | ZINFO3: FSC serial number (low word) |
| 0xE500 | Memory management: Deleted block without corresponding entry in BstList |
| | ZINFO2: Block type |

| Event ID | Description |
|----------------------|--|
| | 56: OB |
| | 65: DB |
| | 66: SDB |
| | 67: FC |
| | 68: SFC |
| | 69: FB |
| | 70: SFB |
| | 97: VDB |
| | 98: VSDB |
| | 99: VFC |
| | 100: VSFC |
| | 101: VFB |
| | 102: VSFB |
| | 111: VOB |
| | ZINFO3: Block number |
| 0xE501 | Parser error |
| | ZINFO1: Error code |
| | 1: Parser error: SDB structure |
| | 2: Parser error: SDB is not a valid SDB type |
| | ZINFO2: SDB type |
| | ZINFO3: SDB number |
| 0xE502 | Error in protect.wld |
| | ZINFO2: Block type |
| | 56: OB |
| | 65: DB |
| | 66: SDB |
| | 67: FC |
| | 68: SFC |
| | 69: FB |
| | 70: SFB |
| | 97: VDB |
| | 98: VSDB |
| | 99: VFC |
| | 100: VSFC |
| | 101: VFB |
| | 102: VSFB |
| 111: VOB | |
| ZINFO3: Block number | |

| Event ID | Description |
|--------------------|--|
| 0xE503 | Inconsistency of code sizes and block sizes in the working memory |
| | ZINFO1: Code size |
| | ZINFO2: Block size (high word) |
| | ZINFO3: Block size (low word) |
| 0xE504 | Additional information for CRC error in the working memory |
| | ZINFO2: Block address (high word) |
| | ZINFO3: Block address (low word) |
| 0xE505 | Internal error - Please contact the hotline! |
| | ZINFO1: Cause for MemDump |
| | 0: Unknown |
| | 1: Manual request |
| | 2: Invalid OP value |
| | 3: CRC code error |
| | 4: Processor exception |
| | 5: Processor exception with dump after reboot |
| 6: Block-CRC error | |
| 0xE604 | Multiple configuration of a periphery address for Ethernet PG/OP channel |
| | ZINFO1: Periphery address |
| | ZINFO3: 0: periphery address is input, 1: periphery address is output |
| 0xE605 | Too many productive connections configured |
| | ZINFO1: Interface slot |
| | ZINFO2: Number of configured connections |
| | ZINFO3: Number of admissible connections |
| 0xE610 | On-board PROFIBUS/MPI: Bus error removed |
| | PK: Not user relevant |
| | ZINFO1: Interface |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xE701 | Internal error - Please contact the hotline! |
| | ZINFO1: Not user relevant |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xE703 | Internal error - Please contact the hotline! |
| | PK: Not user relevant |
| | ZINFO1: Master system ID |
| | ZINFO2: Slave address |

| Event ID | Description |
|----------|---|
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xE705 | Too many PROFIBUS slaves configured |
| | ZINFO1: Diagnostic address of the PROFIBUS master |
| | ZINFO2: Number of configured slaves |
| | ZINFO3: Number of admissible slaves |
| 0xE710 | On-board PROFIBUS/MPI: Bus error occurred |
| | PK: Not user relevant |
| | ZINFO1: Interface |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xE720 | Internal error - Please contact the hotline! |
| | ZINFO1: Slave no |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Master system ID |
| 0xE721 | Internal error - Please contact the hotline! |
| | ZINFO1: Not user relevant |
| | ZINFO2: Master system ID |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xE722 | Internal error - Please contact the hotline! |
| | ZINFO1: Channel-Event |
| | 0: Channel offline |
| | 1: Bus error |
| | 2: Internal error |
| | ZINFO2: Master system ID |
| | DatID: Not user relevant |
| 0xE723 | Internal error - Please contact the hotline! |
| | ZINFO1: Error code |
| | 1: Parameter error |
| | 2: Configuration error |
| | ZINFO2: Master system ID |
| | DatID: Not user relevant |
| 0xE780 | Internal error - Please contact the hotline! |
| 0xE781 | Address range exceeds process image limit |
| | ZINFO1: Address |

| Event ID | Description |
|----------|---|
| | ZINFO2: Length of the address range |
| | ZINFO3: Size of the process image |
| | DatID: Address range |
| 0xE801 | CMD - auto command: CMD_START recognized and executed |
| 0xE802 | CMD - auto command: CMD_End recognized and executed |
| 0xE803 | CMD - auto command: WAIT1SECOND recognized and executed |
| 0xE804 | CMD - auto command: WEBPAGE recognized and executed |
| 0xE805 | CMD - auto command: LOAD_PROJECT recognized and executed |
| 0xE806 | CMD - auto command: SAVE_PROJECT recognized and executed |
| | ZINFO3: Status |
| | 0: Error |
| | 1: OK |
| | 32768: Wrong password |
| 0xE807 | CMD - auto command: FACTORY_RESET recognized and executed |
| 0xE808 | Internal error - Please contact the hotline! |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| 0xE809 | Internal error - Please contact the hotline! |
| | ZINFO3: Not user relevant |
| 0xE80A | Internal error - Please contact the hotline! |
| | ZINFO3: Status |
| | 0: OK |
| | 65153: File create error |
| | 65185: File writing error |
| | 65186: Odd address for reading |
| 0xE80B | CMD - auto command: DIAGBUF recognized and executed |
| | ZINFO3: Status |
| | 0: OK |
| | 65153: File create error |
| | 65185: File writing error |
| | 65186: Odd address for reading |
| 0xE80C | Internal error - Please contact the hotline! |
| | ZINFO3: Status |
| | 0: OK |
| | 65153: File create error |
| | 65185: File writing error |
| | 65186: Odd address for reading |
| 0xE80D | Internal error - Please contact the hotline! |

| Event ID | Description |
|----------|--|
| 0xE80E | CMD - auto command: SET_NETWORK recognized and executed |
| 0xE80F | Internal error - Please contact the hotline! ZINFO3: Status 0: OK 65153: File create error 65185: File writing error 65186: Odd address for reading |
| 0xE810 | Internal error - Please contact the hotline! |
| 0xE811 | Internal error - Please contact the hotline! |
| 0xE812 | Internal error - Please contact the hotline! |
| 0xE813 | Internal error - Please contact the hotline! |
| 0xE814 | CMD - auto command: SET_MPI_ADDRESS identified |
| 0xE816 | CMD - auto command: SAVE_PROJECT recognized but not executed, because the CPU memory is empty |
| 0xE817 | Internal error - Please contact the hotline! ZINFO3: Not user relevant |
| 0xE820 | Internal message |
| 0xE821 | Internal message |
| 0xE822 | Internal message |
| 0xE823 | Internal message |
| 0xE824 | Internal message |
| 0xE825 | Internal message |
| 0xE826 | Internal message |
| 0xE827 | Internal message |
| 0xE828 | Internal message |
| 0xE829 | Internal message |
| 0xE82A | CMD - auto command: CPUTYPE_318 recognized and executed ZINFO3: Error code |
| 0xE82B | CMD - auto command: CPUTYPE_ORIGINAL recognized and executed ZINFO3: Error code |
| 0xE82C | CMD - auto command: WEBVISU_PGOP_ENABLE recognized and executed |
| 0xE82D | CMD - auto command: WEBVISU_PGOP_DISABLE recognized and executed |
| 0xE82E | CMD - auto command: WEBVISU_CP_ENABLE recognized and executed |
| 0xE82F | CMD - auto command: WEBVISU_CP_DISABLE recognized and executed |
| 0xE8FB | CMD - auto command: Error: Initialization of the Ethernet PG/OP channel by means of SET_NETWORK is faulty |
| 0xE8FC | CMD - auto command: Error: Some IP parameters missing in SET_NETWORK |
| 0xE8FE | CMD - auto command: Error: CMD_START not found |
| 0xE8FF | CMD - auto command: Error while reading CMD file (memory card error) |

| Event ID | Description |
|----------|---|
| 0xE901 | Checksum error |
| | ZINFO1: Not user relevant |
| | ZINFO2: Not user relevant |
| | DatID: Not user relevant |
| 0xE902 | Internal error - Please contact the hotline! |
| | ZINFO1: Not user relevant |
| | ZINFO2: Not user relevant |
| | DatID: Not user relevant |
| 0xE904 | PG/OP: Multiple parametrization of a peripheral address |
| | ZINFO1: Peripheral address |
| | ZINFO2: Slot |
| | ZINFO3: Data width |
| | DatID: 0x54 Peripheral address is input address |
| | DatID: 0x55 Peripheral address is output address |
| 0xE910 | PG/OP: Input peripheral address out of peripheral area |
| | ZINFO1: Peripheral address |
| | ZINFO2: Slot |
| | ZINFO3: Data width |
| 0xE911 | PG/OP: Output peripheral address out of peripheral area |
| | ZINFO1: Peripheral address |
| | ZINFO2: Slot |
| | ZINFO3: Data width |
| 0xE920 | Configuration error PROFINET |
| | ZINFO1 - Position 0: Error code |
| 0xE980 | Error when loading the WebVisu project file |
| 0xE981 | Error in the configuration of the WebVisu project |
| 0xE982 | Internal error of the WebVisu server |
| 0xE983 | Hardware configuration of the control is not loaded, WebVisu is not started |
| 0xE984 | WebVisu is blocked by the user, start of the WebVisu was prevented |
| 0xE985 | WebVisu was started |
| 0xE986 | WebVisu was stopped |
| 0xE987 | WebVisu was enabled by the user |
| 0xE988 | WebVisu was disabled by the user |
| 0xEA00 | Internal error - Please contact the hotline! |
| | PK: Not relevant to user |
| | DatID: Not user relevant |
| 0xEA01 | Internal error - Please contact the hotline! |
| | PK: Not user relevant |

| Event ID | Description |
|----------|---|
| | ZINFO1: Slot |
| | DatID: Not user relevant |
| 0xEA02 | SBUS: Internal error (internal plugged sub module not recognized) |
| | PK: Not user relevant |
| | ZINFO1: Slot |
| | ZINFO2: Type identifier target |
| | ZINFO3: Type identifier |
| | DatID: Not user relevant |
| 0xEA03 | SBUS: Communication error between CPU and IO controller |
| | OB: Operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |
| | 6: STARTUP (restart/warm start) |
| | 7: STARTUP (hot restart) |
| | 9: RUN |
| | 10: HALT |
| | 11: COUPLING |
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| | PK: Not user relevant |
| | ZINFO1: Slot |
| | ZINFO2: Status |
| | 0: OK |
| | 1: Error |
| | 2: Empty |
| | 3: Busy |
| | 4: Time out |
| | 5: Internal blocking |
| | 6: Too many telegrams |

| Event ID | Description |
|----------|--|
| | 7: Not Connected |
| | 8: Unknown |
| | DatID: Not user relevant |
| 0xEA04 | SBUS: Multiple configuration of a peripheral address |
| | ZINFO1: Peripheral address |
| | ZINFO2: Slot |
| | ZINFO3: Data width |
| 0xEA05 | Internal error - Please contact the hotline! |
| 0xEA07 | Internal error - Please contact the hotline! |
| 0xEA08 | SBUS: Configured input data width not the same as the connected input data width |
| | ZINFO1: Configured input data width |
| | ZINFO2: Slot |
| | ZINFO3: Input data width of the connected component |
| 0xEA09 | SBUS: Configured output data width not the same as the connected output data width |
| | ZINFO1: Configured output data width |
| | ZINFO2: Slot |
| | ZINFO3: Output data width of the plugged component |
| 0xEA10 | SBUS: Input peripheral address outside the peripheral area |
| | ZINFO1: Peripheral address |
| | ZINFO2: Slot |
| | ZINFO3: Data width |
| 0xEA11 | SBUS: Output peripheral address outside the peripheral area |
| | ZINFO1: Peripheral address |
| | ZINFO2: Slot |
| | ZINFO3: Data width |
| 0xEA12 | SBUS: Error in writing dataset |
| | ZINFO1: Slot |
| | ZINFO2: Dataset number |
| | ZINFO3: Dataset length |
| 0xEA14 | SBUS: Multiple configuration of a peripheral address (diagnostic address) |
| | ZINFO1: Peripheral address |
| | ZINFO2: Slot |
| | ZINFO3: Data width |
| 0xEA15 | Internal error - Please contact the hotline! |
| | ZINFO2: Slot of the master |
| 0xEA18 | SBUS: Error in mapping the master peripheral |
| | ZINFO2: Slot of the master |
| 0xEA19 | Internal error - Please contact the hotline! |

| Event ID | Description |
|----------|--|
| | PK: Not user relevant |
| | ZINFO2: HW slot |
| | ZINFO3: Interface type |
| | DatID: Not user relevant |
| 0xEA1A | SBUS: Error in access to SBUS FPGA address table |
| | PK: Not user relevant |
| | ZINFO2: HW slot |
| | ZINFO3: Table |
| | 0: Read |
| | 1: Writing |
| | DatID: Not user relevant |
| 0xEA20 | Error: RS485 interface is not pre-set to PROFIBUS DP master bus a PROFIBUS DP master is configured |
| 0xEA21 | Error: Configuration RS485 interface X2/X3: PROFIBUS DP master is configured but missing |
| | ZINFO2: Interface X is configured incorrectly |
| 0xEA22 | Error: Configuration RS485 interface X2: Value is outside the limits |
| | ZINFO2: Configuration for X2 |
| 0xEA23 | Error: Configuration RS485 interface X3: Value is outside the limits |
| | ZINFO2: Configuration for X3 |
| 0xEA24 | Error: Configuration RS485 interface X2/X3: Interface/protocol missing, default settings are used |
| | ZINFO2: Configuration for X2 |
| | ZINFO3: Configuration for X3 |
| 0xEA30 | Internal error - Please contact the hotline! |
| | ZINFO1: Status |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| 0xEA40 | Internal error - Please contact the hotline! |
| | OB: Slot of the CP |
| | PK: File number |
| | ZINFO1: Version of the CP |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Line |
| 0xEA41 | Internal error - Please contact the hotline! |
| | OB: Slot of the CP |
| | PK: File number |
| | ZINFO1: Version of the CP |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |

| Event ID | Description |
|----------|--|
| | DatID: Line |
| 0xEA50 | PROFINET IO controller: Error in the configuration |
| | OB: Not user relevant |
| | PK: Not user relevant |
| | ZINFO1: Rack/slot of the controller |
| | ZINFO2: Device number |
| | ZINFO3: Slot at the device |
| | DatID: Not user relevant |
| 0xEA51 | PROFINET IO controller: There is no PROFINET IO controller at the configured slot |
| | PK: Not user relevant |
| | ZINFO1: Rack/slot of the controller |
| | ZINFO2: Recognized type identifier at the configured slot |
| | DatID: Not user relevant |
| 0xEA52 | PROFINET IO controller: Too many configured PROFINET IO controllers |
| | PK: Not user relevant |
| | ZINFO1: Number of configured controllers |
| | ZINFO2: Slot of the excessively configured controller |
| | DatID: Not user relevant |
| 0xEA53 | PROFINET IO controller: Too many configured PROFINET IO devices |
| | ZINFO1: Number of configured devices |
| | ZINFO2: Slot |
| | ZINFO3: Maximum possible number of devices |
| 0xEA54 | PROFINET IO controller: Multiple configuration of a periphery address |
| | PK: Not user relevant |
| | ZINFO1: Logical address of the IO system |
| | ZINFO2: Rack/slot of the controller |
| | ZINFO3: Base address of the block which is too large |
| | DatID: Not user relevant |
| 0xEA55 | PROFINET IO controller: Too many slots configured |
| | ZINFO1: Rack/slot of the controller |
| | ZINFO2: Device number |
| | ZINFO3: Number of configured slots |
| 0xEA56 | PROFINET IO controller: Too many subslots configured |
| | ZINFO1: Rack/slot of the controller |
| | ZINFO2: Device number |
| | ZINFO3: Number of configured subslots |
| 0xEA57 | PROFINET IO controller: The port configuration in the virtual SLIO device has no effect. |
| 0xEA61 | Internal error - Please contact the hotline! |

| Event ID | Description |
|----------|---|
| | OB: File number |
| | PK: Slot of the controller |
| | ZINFO1: Firmware major version |
| | ZINFO2: Firmware minor version |
| | DatID: Line |
| 0xEA62 | Internal error - Please contact the hotline! |
| | OB: File number. |
| | PK: Slot of the controller |
| | ZINFO1: Firmware major version |
| | ZINFO2: Firmware minor version |
| | DatID: Line |
| 0xEA63 | Internal error - Please contact the hotline! |
| | OB: File number |
| | PK: Slot of the controller |
| | ZINFO1: Firmware major version |
| | ZINFO2: Firmware minor version |
| | DatID: Line |
| 0xEA64 | PROFINET IO controller/EtherCAT-CP: Error in configuration |
| | PK: Interface |
| | ZINFO1 - Bit 0: Too many devices |
| | ZINFO1 - Bit 1: Too many devices per second |
| | ZINFO1 - Bit 2: Too many input bytes per millisecond |
| | ZINFO1 - Bit 3: Too many output bytes per millisecond |
| | ZINFO1 - Bit 4: Too many input bytes per device |
| | ZINFO1 - Bit 5: Too many output bytes per device |
| | ZINFO1 - Bit 6: Too many productive connections |
| | ZINFO1 - Bit 7: Too many input bytes in the process image |
| | ZINFO1 - Bit 8: Too many output bytes in the process image |
| | ZINFO1 - Bit 9: Configuration not available |
| | ZINFO1 - Bit 10: Configuration invalid |
| | ZINFO1 - Bit 11: Refresh interval too small |
| | ZINFO1 - Bit 12: Refresh interval too large |
| | ZINFO1 - Bit 13: Invalid device number |
| | ZINFO1 - Bit 14: CPU is configured as an I device |
| | ZINFO1 - Bit 15: Assume IP address in another way. Is not supported for the IP address of the controller. |
| | ZINFO2 - Bit 0: Incompatible configuration (SDB version not supported) |
| | ZINFO2 - Bit 1: EtherCAT: EoE configured but not supported (Possible cause is a too short cycle time of the EtherCAT master system. When using EoE terminals, at least a cycle time of 4ms must be configured.) |

| Event ID | Description |
|----------|---|
| | ZINFO2 - Bit 2: DC parameter invalid |
| | ZINFO2 - Bit 3: I device configuration invalid (slot gap) |
| | ZINFO2 - Bit 4: MRP configuration invalid (client) |
| 0xEA65 | Internal error - Please contact the hotline! |
| | PK: Platform |
| | 0: none |
| | 8: CP |
| | 9: Ethernet CP |
| | 10: PROFINET CP |
| | 12: EtherCAT CP |
| | 16: CPU |
| | ZINFO1: ServiceID in which the error occurred |
| | ZINFO2: Command in which the error occurred |
| | 1: Request |
| | 2: Connect |
| | 3: Error |
| 0xEA66 | PROFINET IO controller: Error in the communication stack |
| | OB: StackError.Service |
| | PK: Rack/slot |
| | ZINFO1: StackError.Error.Code |
| | ZINFO2: StackError.Error.Detail |
| | ZINFO3 - Position 0: StackError.Error.AdditionalDetail |
| | ZINFO3 - Position 8: StackError.Error.AreaCode |
| | DatID: StackError.DeviceRef |
| 0xEA67 | PROFINET IO controller: Error reading dataset |
| | OB: Rack/slot of the controller |
| | PK: Error type |
| | 0: Dataset error local |
| | 1: Dataset error stack |
| | 2: Dataset error station |
| | ZINFO1: Dataset number |
| | ZINFO2: Dataset handle (caller) |
| | ZINFO3: Internal error code from PN stack |
| | DatID: Device |
| 0xEA68 | PROFINET IO controller: Error writing dataset |
| | OB: Rack/slot of the controller |
| | PK: Error type |
| | 0: Dataset error local |

| Event ID | Description |
|----------|--|
| | 1: Dataset error stack |
| | 2: Dataset error station |
| | ZINFO1: Dataset number |
| | ZINFO2: Dataset handle (caller) |
| | ZINFO3: Internal error code from PN stack |
| | DatID: Device |
| 0xEA69 | Internal error - Please contact the hotline! |
| | ZINFO1: Minimum version for the FPGA |
| | ZINFO2: Loaded FPGA version |
| 0xEA6A | PROFINET IO controller: Service error in the communication stack |
| | OB: Service ID |
| | PK: Rack/slot |
| | ZINFO1: ServiceError.Code |
| | ZINFO2: ServiceError.Detail |
| | ZINFO3 - Position 0: ServiceError.AdditionalDetail |
| | ZINFO3 - Position 8: ServiceError.AreaCode |
| 0xEA6B | PROFINET IO controller: Incorrect Vendor-ID |
| | OB: Operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |
| | 6: STARTUP (restart/warm start) |
| | 7: STARTUP (hot restart) |
| | 9: RUN |
| | 10: HALT |
| | 11: COUPLING |
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| | PK: Rack/slot |
| | ZINFO1: Device ID |

| Event ID | Description |
|----------|---|
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xEA6C | PROFINET IO controller: Incorrect Device-ID |
| | OB: Operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |
| | 6: STARTUP (restart/warm start) |
| | 7: STARTUP (hot restart) |
| | 9: RUN |
| | 10: HALT |
| | 11: COUPLING |
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| | PK: Rack/slot |
| | ZINFO1: Device ID |
| 0xEA6D | PROFINET IO controller: No empty name |
| | OB: Operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |
| | 6: STARTUP (restart/warm start) |
| | 7: STARTUP (hot restart) |
| | 9: RUN |
| | 10: HALT |
| | 11: COUPLING |

| Event ID | Description |
|----------|---|
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| | PK: Rack/slot |
| | ZINFO1: Device ID |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xEA6E | PROFINET IO controller: Wait for RPC response |
| | OB: Operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |
| | 6: STARTUP (restart/warm start) |
| | 7: STARTUP (hot restart) |
| | 9: RUN |
| | 10: HALT |
| | 11: COUPLING |
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| | PK: Rack/slot |
| | ZINFO1: Device ID |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xEA6F | PROFINET IO controller: PROFINET module deviation |

| Event ID | Description |
|----------|--|
| | OB: Operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |
| | 6: STARTUP (restart/warm start) |
| | 7: STARTUP (hot restart) |
| | 9: RUN |
| | 10: HALT |
| | 11: COUPLING |
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| | PK: Rack/slot |
| | ZINFO1: Device ID |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xEA70 | PROFINET IO controller: PROFINET stack configuration error |
| | OB: UnsupportedApiError.api |
| | PK: Rack/slot |
| | ZINFO1: UnsupportedApiError.slot |
| | ZINFO2: UnsupportedApiError.subslot |
| | DatID: UnsupportedApiError.deviceID |
| 0xEA71 | Internal error - Please contact the hotline! |
| | PK: Rack/slot |
| | ZINFO1: functionIndex |
| | ZINFO2: Not user relevant |
| 0xEA72 | Internal error - Please contact the hotline! |
| | OB: Connection number |
| | PK: Slot of the controller |
| | ZINFO1: Error cause |

| Event ID | Description |
|----------|--|
| | 129: PNIO |
| | 207: RTA error |
| | 218: AlarmAck |
| | 219: IODConnectRes |
| | 220: IODReleaseRes |
| | 221: IOD/IOXControlRes |
| | 222: IODReadRes |
| | 223: IODWriteRes |
| | ZINFO2: ErrorDecode |
| | 128: PNIORW: Service Read Write |
| | 129: PNIO: Other Service or internal e.g. RPC errors |
| | 130: Vendor specific |
| | ZINFO3: Error code (PN spec. V2.722 chapter 5.2.6) |
| | DatID: Device ID |
| 0xEA81 | Internal error - Please contact the hotline! |
| | OB: Not user relevant |
| | PK: Not user relevant |
| | ZINFO1: Filenamehash[0-3] |
| | ZINFO2: Filenamehash[4-7] |
| | ZINFO3: Line |
| | DatID: SvnRevision |
| 0xEA82 | Internal error - Please contact the hotline! |
| | OB: Not user relevant |
| | PK: Not user relevant |
| | ZINFO1: Filenamehash[0-3] |
| | ZINFO2: Filenamehash[4-7] |
| | ZINFO3: Line |
| | DatID: SvnRevision |
| 0xEA83 | Internal error - Please contact the hotline! |
| | OB: Not user relevant |
| | PK: Not user relevant |
| | ZINFO1: Filenamehash[0-3] |
| | ZINFO2: Filenamehash[4-7] |
| | ZINFO3: Line |
| | DatID: SvnRevision |
| 0xEA91 | Internal error - Please contact the hotline! |
| | OB: Current OB number |
| | PK: Core status |

| Event ID | Description |
|----------|--|
| | 0: INIT |
| | 1: STOP |
| | 2: READY |
| | 3: PAUSE |
| | 4: RUN |
| | ZINFO1: Filenamehash[0-3] |
| | ZINFO2: Filenamehash[4-7] |
| | ZINFO3: Line |
| | DatID: Current job number |
| 0xEA92 | Internal error - Please contact the hotline! |
| | OB: Current OB number |
| | PK: Core status |
| | 0: INIT |
| | 1: STOP |
| | 2: READY |
| | 3: PAUSE |
| | 4: RUN |
| | ZINFO1: Filenamehash[0-3] |
| | ZINFO2: Filenamehash[4-7] |
| | ZINFO3: Line |
| | DatID: Current job number |
| 0xEA93 | Internal error - Please contact the hotline! |
| | OB: Current OB number |
| | PK: Core status |
| | 0: INIT |
| | 1: STOP |
| | 2: READY |
| | 3: PAUSE |
| | 4: RUN |
| | ZINFO1: Filenamehash[0-3] |
| | ZINFO2: Filenamehash[4-7] |
| | ZINFO3: Line |
| | DatID: Current job number |
| 0xEA97 | Internal error - Please contact the hotline! |
| | ZINFO3: Slot |
| 0xEA98 | Error in file reading via SBUS |
| | PK: Not user relevant |
| | ZINFO3: Slot |

| Event ID | Description |
|----------|--|
| | DatID: Not user relevant |
| 0xEA99 | Parameter assignment job could not be executed |
| | PK: Not user relevant |
| | ZINFO1: File version on MMC/SD (if not 0) |
| | ZINFO2: File version of the SBUS module (if not 0) |
| | ZINFO3: Slot |
| | DatID: Not user relevant |
| 0xEAA0 | Internal error - Please contact the hotline! |
| | OB: Current operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |
| | 6: STARTUP (restart/warm start) |
| | 7: STARTUP (hot restart) |
| | 9: RUN |
| | 10: HALT |
| | 11: COUPLING |
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| | ZINFO1: Diagnostic address of the master |
| | ZINFO2: Not user relevant |
| | ZINFO3: Number of errors which occurred |
| 0xEAB0 | Invalid link mode |
| | OB: Current operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |

| Event ID | Description |
|----------|---|
| | 6: STARTUP (restart/warm start) |
| | 7: STARTUP (hot restart) |
| | 9: RUN |
| | 10: HALT |
| | 11: COUPLING |
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| | ZINFO1: Diagnostic address of the master |
| | ZINFO2: Current connection mode |
| | 1: 10Mbit half-duplex |
| | 2: 10Mbit full-duplex |
| | 3: 100Mbit half-duplex |
| | 4: 100Mbit full-duplex |
| | 5: Connection mode undefined |
| | 6: Auto Negotiation |
| 0xEAC0 | Internal error - Please contact the hotline! |
| | ZINFO1: Error code |
| | 2: Internal error |
| | 3: Internal error |
| | 4: Internal error |
| | 5: Internal error |
| | 6: Internal error |
| | 7: Internal error |
| | 8: Internal error |
| | 8: Internal error |
| 0xEAD0 | SyncUnit configuration error |
| | ZINFO1: Status |
| 0xEB02 | System SLIO error: Preset configuration does not match actual configuration |
| | ZINFO1: Bit mask slots 1-16 |
| | ZINFO2: Bit mask slots 17-32 |
| | ZINFO3: Bit mask slots 33-48 |
| | DatID: Bit mask slots 49-64 |
| 0xEB03 | System SLIO error: IO mapping |

| Event ID | Description |
|----------|---|
| | PK: Not user relevant |
| | ZINFO1: Error type |
| | 1: SDB parser error |
| | 2: Configured address already used |
| | 3: Mapping error |
| | ZINFO2: Slot (0=cannot be determined) |
| | DatID: Not user relevant |
| 0xEB04 | SLIO-Bus: Multiple configuration of a periphery address |
| | ZINFO1: Periphery address |
| | ZINFO2: Slot |
| | DatID: Input |
| | DatID: Output |
| 0xEB05 | System SLIO error: Bus structure for isochronous process image not suitable |
| | PK: Not user relevant |
| | ZINFO2: Slot (0=cannot be determined) |
| | DatID: Not user relevant |
| 0xEB06 | System SLIO error: Timeout with the isochronous process image |
| 0xEB10 | System SLIO error: Bus error |
| | PK: Not user relevant |
| | ZINFO1: Error type |
| | 96: Bus enumeration error |
| | 128: General error |
| | 129: Queue execution error |
| | 130: Error interrupt |
| | ZINFO2: Error on bus enumeration error (ZINFO1) |
| | DatID: Not user relevant |
| 0xEB11 | System SLIO error: Error during bus initialization |
| | PK: Not user relevant |
| | DatID: Not user relevant |
| 0xEB20 | System SLIO error: Interrupt information undefined |
| 0xEB21 | System SLIO error: Accessing configuration data |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xEC02 | EtherCAT: configuration warning |
| | ZINFO1: Error code |
| | 1: Number of slave stations is not supported |
| | 2: Master system ID invalid |

| Event ID | Description |
|----------|---|
| | 3: Slot invalid |
| | 4: Master configuration invalid |
| | 5: Master type invalid |
| | 6: Slave diagnostic address invalid |
| | 7: Slave address invalid |
| | 8: Slave module IO configuration invalid |
| | 9: Logical address already in use |
| | 10: Internal error |
| | 11: IO mapping error |
| | 12: Error |
| | 13: Error in initialising the EtherCAT stack (is entered by the CP) |
| | 14: Slave station number already occupied by virtual SLIO device |
| | ZINFO2: Station number |
| 0xEC03 | EtherCAT: Configuration error |
| | PK: Not user relevant |
| | ZINFO1: Error code |
| | 1: Number of slave stations is not supported |
| | 2: Master system ID invalid |
| | 3: Slot invalid |
| | 4: Master configuration invalid |
| | 5: Master type invalid |
| | 6: Slave diagnostic address invalid |
| | 7: Slave address invalid |
| | 8: Slave module IO configuration invalid |
| | 9: Logical address already in use |
| | 10: Internal error |
| | 11: IO mapping error |
| | 12: Error |
| | 13: Error in initialising the EtherCAT stack (is entered by the CP) |
| | 14: Slave station number already occupied by virtual SLIO device |
| | ZINFO2: Station number |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xEC04 | EtherCAT: Multiple configuration of a periphery address |
| | PK: Not user relevant |
| | ZINFO1: Periphery address |
| | ZINFO2: Slot |
| | DatID: Not user relevant |

| Event ID | Description |
|---|---|
| 0xEC05 | EtherCAT: Check the set DC mode of the YASKAWA Sigma 5/7 drive |
| | OB: Operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |
| | 6: STARTUP (restart/warm start) |
| | 7: STARTUP (hot restart) |
| | 9: RUN |
| | 10: HALT |
| | 11: COUPLING |
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| | PK: Not user relevant |
| | ZINFO1: Station address of the EtherCAT device |
| | ZINFO2: Error code |
| | 1: WARNING: For the drive the DC Beckhoff mode is recommended (DC reference clock is not in Beckhoff Mode)! |
| | 2: NOTE: For the drive the DC Hilscher mode is recommended (DC reference clock is not in Beckhoff Mode)! |
| | 3: The station address could not be determined for checking (station address in ZINFO1 is accordingly 0) |
| | 4: The slave information could not be determined for checking (station address in ZINFO1 is accordingly 0) |
| | 5: The EtherCAT status of the drive could not be determined |
| | 6: Error when sending the SDO request (for further information, the (subsequent) event with the ID 0xED60 is to be analysed on the CP) |
| | 7: Drive returns error in the SDO response (for further information, the (subsequent) event with the ID 0xED60 is to be analysed on the CP) |
| 8: SDO time out, DC mode could not be determined (for further information, the (subsequent) event with the ID 0xED60 is to be analysed on the CP) | |
| ZINFO3: Not user relevant | |
| DatID: Not user relevant | |
| 0xEC10 | EtherCAT: Recurrence bus with all slaves |
| | ZINFO1 - Position 0: New status |

| Event ID | Description |
|--|---|
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO1 - Position 8: Previous status |
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO2: Diagnostic address of the station |
| | ZINFO3: Number of stations, which are not in the same state as the master |
| | DatID: Station not available |
| | DatID: Station available |
| | DatID: Input address |
| | DatID: Output address |
| | 0xEC11 |
| ZINFO1 - Position 0: New status | |
| 0: Undefined/Unkown | |
| 1: Init | |
| 2: PreOp | |
| 3: Bootstrap | |
| 4: SafeOp | |
| 8: Op | |
| ZINFO1 - Position 8: Previous status | |
| 0: Undefined/Unkown | |
| 1: Init | |
| 2: PreOp | |
| 3: Bootstrap | |
| 4: SafeOp | |
| 8: Op | |
| ZINFO2: Diagnostic address of the master | |
| ZINFO3: Number of stations which are not in the same state as the master | |
| DatID: Station not available | |
| DatID: Station available | |

| Event ID | Description |
|----------|---|
| | DatID: Input address |
| | DatID: Output address |
| 0xEC12 | EtherCAT: Recurrence slave |
| | ZINFO1 - Position 0: New status |
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO1 - Position 8: Previous status |
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO2: Diagnostic address of the station |
| | ZINFO3: AL status code |
| | DatID: Station not available |
| | DatID: Station available |
| | DatID: Input address |
| | DatID: Output address |
| 0xEC30 | EtherCAT: Topology OK |
| | ZINFO2: Diagnostic address of the master |
| 0xEC40 | Bus cycle time infringement resolved |
| | ZINFO2: Logical address of the IO system |
| 0xEC50 | EtherCAT: Distributed clocks (DC) out of sync |
| | OB: Operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |
| | 6: STARTUP (restart/warm start) |
| | 7: STARTUP (hot restart) |
| | 9: RUN |

| Event ID | Description |
|--|--|
| | 10: HALT |
| | 11: COUPLING |
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| | ZINFO2: Diagnostic address of the master |
| | ZINFO3: DC state change |
| | 0: DC master out of sync |
| | 1: DC slave stations out of sync |
| | 0xEC80 |
| ZINFO1: Logical address of the IO system | |
| ZINFO3 - Position 0: Station number | |
| ZINFO3 - Position 11: IO system ID | |
| ZINFO3 - Bit 15: System ID DP/PN | |
| 0xED10 | EtherCAT: Breakdown bus |
| | ZINFO1 - Position 0: New status |
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO1 - Position 8: Previous status |
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO2: Diagnostic address of the master |
| | ZINFO3: Number of stations which are not in the same state as the master |
| | DatID: Station available |
| | DatID: Station not available |
| | DatID: Input address |

| Event ID | Description |
|--|---|
| | DatID: Output address |
| 0xED12 | EtherCAT: Breakdown slave |
| | ZINFO1 - Position 0: New status |
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO1 - Position 8: Previous status |
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO2: Diagnostic address of the station |
| | ZINFO3: AIStatusCode |
| | 0: No error |
| | 1: Unspecified error |
| | 17: Invalid requested status change |
| | 18: Unknown requested status |
| | 19: Bootstrap not supported |
| | 20: No valid firmware |
| | 22: Invalid mailbox configuration |
| | 22: Invalid mailbox configuration |
| | 23: Invalid sync manager configuration |
| | 24: No valid inputs available |
| | 25: No valid outputs available |
| | 26: Synchronisation error |
| | 27: Sync manager watchdog |
| | 28: Invalid sync manager types |
| | 29: Invalid output configuration |
| | 30: Invalid input configuration |
| | 31: Invalid watchdog configuration |
| 32: Slave station needs cold start | |
| 33: Slave station needs to be in INIT state | |
| 34: Slave station needs to be in PreOp state | |

| Event ID | Description |
|----------|--|
| | 35: Slave station needs to be in SafeOp state |
| | 45: Invalid output FMMU configuration |
| | 46: Invalid input FMMU configuration |
| | 48: Invalid DC Sync configuration |
| | 49: Invalid DC Latch configuration |
| | 50: PLL error |
| | 51: Invalid DC IO error |
| | 52: Invalid DC time out error |
| | 66: Error in acyclic data exchange Ethernet Over EtherCAT |
| | 67: Error in acyclic data exchange CAN Over EtherCAT |
| | 68: Error in acyclic data exchange Fileaccess Over EtherCAT |
| | 69: Error in acyclic data exchange Servo Drive Profile Over EtherCAT |
| | 79: Error in acyclic data exchange Vendorspecific Over EtherCAT |
| | DatID: Station not available |
| | DatID: Station available |
| | DatID: Input address |
| | DatID: Output address |
| 0xED20 | EtherCAT: Bus state change without calling OB86 |
| | ZINFO1 - Position 0: New status |
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO1 - Position 8: Previous status |
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO2: Diagnostic address of the master |
| | ZINFO3: Number of stations which are not in the same state as the master |
| | DatID: Station not available |
| | DatID: Station available |
| | DatID: Input address |
| | DatID: Output address |

| Event ID | Description |
|--------------------------------------|--|
| 0xED21 | EtherCAT: Incorrect bus status change |
| | ZINFO1 - Position 0: New status |
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO1 - Position 8: Previous status |
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO2: Diagnostic address of the master |
| | ZINFO3: Error code |
| | 4: Cancel (master state change) |
| | 8: Busy |
| | 11: Invalid parameters |
| | 14: Invalid status |
| | 16: Time out |
| | DatID: Station available |
| | DatID: Station not available |
| | DatID: Output address |
| | DatID: Input address |
| | 0xED22 |
| ZINFO1 - Position 0: New status | |
| 0: Undefined/Unkown | |
| 1: Init | |
| 2: PreOp | |
| 3: Bootstrap | |
| 4: SafeOp | |
| 8: Op | |
| ZINFO1 - Position 8: Previous status | |
| 0: Undefined/Unkown | |
| 1: Init | |
| 2: PreOp | |

| Event ID | Description |
|----------|--|
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO2: Diagnostic address of the station |
| | ZINFO3: AIStatusCode |
| | 0: No error |
| | 1: Unspecified error |
| | 17: Invalid requested status change |
| | 18: Unknown requested status |
| | 19: Bootstrap not supported |
| | 20: No valid firmware |
| | 22: Invalid mailbox configuration |
| | 22: Invalid mailbox configuration |
| | 23: Invalid sync manager configuration |
| | 24: No valid inputs available |
| | 25: No valid outputs available |
| | 26: Synchronisation error |
| | 27: Sync manager watchdog |
| | 28: Invalid sync manager types |
| | 29: Invalid output configuration |
| | 30: Invalid input configuration |
| | 31: Invalid watchdog configuration |
| | 32: Slave station needs cold start |
| | 33: Slave station needs to be in INIT state |
| | 34: Slave station needs to be in PreOp state |
| | 35: Slave station needs to be in SafeOp state |
| | 45: Invalid output FMMU configuration |
| | 46: Invalid input FMMU configuration |
| | 48: Invalid DC Sync configuration |
| | 49: Invalid DC Latch configuration |
| | 50: PLL error |
| | 51: Invalid DC IO error |
| | 52: Invalid DC time out error |
| | 66: Error in acyclic data exchange Ethernet Over EtherCAT |
| | 67: Error in acyclic data exchange CAN Over EtherCAT |
| | 68: Error in acyclic data exchange Fileaccess Over EtherCAT |
| | 69: Error in acyclic data exchange Servo Drive Profile Over EtherCAT |
| | 79: Error in acyclic data exchange Vendorspecific Over EtherCAT |

| Event ID | Description |
|----------|--|
| | DatID: Station not available |
| | DatID: Station available |
| | DatID: Input address |
| | DatID: Output address |
| 0xED23 | EtherCAT: Time out while changing the master state to OP, after CPU has changed to RUN |
| | OB: Operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |
| | 6: STARTUP (restart/warm start) |
| | 7: STARTUP (hot restart) |
| | 9: RUN |
| | 10: HALT |
| | 11: COUPLING |
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| | ZINFO1: Master status |
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO2: EtherCAT configuration present |
| | 0: There is no EC configuration |
| | 1: There is an EC configuration |
| | ZINFO3: DC in sync |
| | 0: Not in sync |
| | 1: In sync |
| 0xED30 | EtherCAT: Topology deviation |

| Event ID | Description |
|----------|---|
| | ZINFO2: Diagnostic address of the master |
| 0xED31 | EtherCAT: Overflow of the interrupt queue |
| | ZINFO2: Diagnostic address of the master |
| 0xED40 | Bus cycle time infringement occurred |
| | ZINFO1: Logical address of the IO system |
| 0xED50 | EtherCAT: Distributed clocks (DC) in sync |
| | OB: Operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |
| | 6: STARTUP (restart/warm start) |
| | 7: STARTUP (hot restart) |
| | 9: RUN |
| | 10: HALT |
| | 11: COUPLING |
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| | ZINFO2: Diagnostic address of the master |
| | ZINFO3: DC state change |
| | 0: Master |
| | 1: Slave |
| 0xED60 | EtherCAT: Diagnostic buffer CP: Slave status change |
| | OB: Operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |
| | 6: STARTUP (restart/warm start) |

| Event ID | Description |
|----------|--|
| | 7: STARTUP (hot restart) |
| | 9: RUN |
| | 10: HALT |
| | 11: COUPLING |
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| | ZINFO1 - Position 0: New status |
| | 0: Undefined/Unkown |
| | 1: Init |
| | 2: PreOp |
| | 3: Bootstrap |
| | 4: SafeOp |
| | 8: Op |
| | ZINFO2: Slave address |
| | ZINFO3: AIstatusCode |
| | 0: No error |
| | 1: Unspecified error |
| | 17: Invalid requested status change |
| | 18: Unknown requested status |
| | 19: Bootstrap not supported |
| | 20: No valid firmware |
| | 22: Invalid mailbox configuration |
| | 22: Invalid mailbox configuration |
| | 23: Invalid sync manager configuration |
| | 24: No valid inputs available |
| | 25: No valid outputs available |
| | 26: Synchronisation error |
| | 27: Sync manager watchdog |
| | 28: Invalid sync manager types |
| | 29: Invalid output configuration |
| | 30: Invalid input configuration |
| | 31: Invalid watchdog configuration |
| | 32: Slave station needs cold start |

| Event ID | Description |
|----------|--|
| | 33: Slave station needs to be in INIT state |
| | 34: Slave station needs to be in PreOp state |
| | 35: Slave station needs to be in SafeOp state |
| | 45: Invalid output FMMU configuration |
| | 46: Invalid input FMMU configuration |
| | 48: Invalid DC Sync configuration |
| | 49: Invalid DC Latch configuration |
| | 50: PLL error |
| | 51: Invalid DC IO error |
| | 52: Invalid DC time out error |
| | 66: Error in acyclic data exchange Ethernet Over EtherCAT |
| | 67: Error in acyclic data exchange CAN Over EtherCAT |
| | 68: Error in acyclic data exchange Fileaccess Over EtherCAT |
| | 69: Error in acyclic data exchange Servo Drive Profile Over EtherCAT |
| | 79: Error in acyclic data exchange Vendorspecific Over EtherCAT |
| | DatID: Cause for slave status change |
| | 0: Regular slave status change |
| | 1: Slave failure |
| | 2: Recurrence slave |
| | 3: Slave is in an error state |
| | 4: Slave has unexpectedly changed its status |
| 0xED61 | EtherCAT: Diagnostic buffer CP: CoE emergency |
| | OB: EtherCAT station address (high byte) |
| | PK: EtherCAT station address (low byte) |
| | ZINFO1 - Position 0: Error register |
| | ZINFO1 - Position 8: MEF-Byte1 |
| | ZINFO2 - Position 0: MEF-Byte2 |
| | ZINFO2 - Position 8: MEF-Byte3 |
| | ZINFO3 - Position 0: MEF-Byte4 |
| | ZINFO3 - Position 8: MEF-Byte5 |
| | DatID: Error code |
| 0xED62 | EtherCAT: Diagnostic buffer CP: Error on SDO access |
| | OB: EtherCAT station address (high byte) |
| | PK: EtherCAT station address (low byte) |
| | ZINFO1: Index |
| | ZINFO2: SDO error code (high word) |
| | ZINFO3: SDO error code (low word) |
| | DatID: Sub index |

| Event ID | Description |
|--|--|
| 0xED63 | EtherCAT: Diagnostic buffer CP: Error in the response to an INIT command |
| | OB: EtherCAT station address (high byte) |
| | PK: EtherCAT station address (low byte) |
| | ZINFO1: Error type |
| | 0: Not defined |
| | 1: No response |
| | 2: Validation error |
| | 3: INIT command failed, requested station could not be reached |
| 0xED70 | EtherCAT: Diagnostic buffer CP: Twofold hot connect group recognised |
| | OB: Operating mode |
| | 0: Configuration in operating condition RUN |
| | 1: STOP (update) |
| | 2: STOP (memory reset) |
| | 3: STOP (auto initialization) |
| | 4: STOP (internal) |
| | 5: STARTUP (cold start) |
| | 6: STARTUP (restart/warm start) |
| | 7: STARTUP (hot restart) |
| | 9: RUN |
| | 10: HALT |
| | 11: COUPLING |
| | 12: UPDATING |
| | 13: DEFECTIVE |
| | 14: Error search mode |
| | 15: De-energised |
| | 253: Process image release in STOP |
| | 254: Watchdog |
| | 255: Not set |
| ZINFO1: Diagnostic address of the master | |
| ZINFO2: EtherCAT station address | |
| 0xED80 | Bus error occurred (receive time-out) |
| | ZINFO1: Logical address of the IO system |
| | ZINFO3 - Position 0: Station number |
| | ZINFO3 - Position 11: IO system ID |
| | ZINFO3 - Bit 15: System ID DP/PN |
| 0xEE00 | Additional information at UNDEF_OPCODE |
| | OB: Not user relevant |
| | ZINFO1: Not user relevant |

| Event ID | Description |
|----------|--|
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xEE01 | Internal error - Please contact the hotline! |
| | ZINFO3: SFB number |
| 0xEEEE | CPU was completely deleted, since after PowerON the start-up could not be finished |
| 0xEF00 | Internal error - Please contact the hotline! |
| | DatID: Not user relevant |
| 0xEF01 | Internal error - Please contact the hotline! |
| | ZINFO1: Not user relevant |
| | ZINFO2: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xEF11 | Internal error - Please contact the hotline! |
| 0xEF12 | Internal error - Please contact the hotline! |
| 0xEF13 | Internal error - Please contact the hotline! |
| 0xEFFE | Internal error - Please contact the hotline! |
| | PK: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xEFFF | Internal error - Please contact the hotline! |
| | PK: Not user relevant |
| | ZINFO3: Not user relevant |
| | DatID: Not user relevant |
| 0xF9C1 | Restart of the component |
| | OB: NCM_EVENT |
| | 1: OVS: Component start-up request was denied |
| | 3: Component data basis invalid |
| | 6: IP_CONFIG: New IP address assigned by STEP7 configuration |
| | 10: IP_CONFIG: A non-configured new IP address was assigned |
| | 13: HW reset at P bus (for CPU memory reset) |
| | 19: Switch actuation from STOP to RUN causes the restart of the component |
| | 20: MGT: PG command causes the restart of the component |
| | 21: MGT: Take-over of component data basis causes the hot restart of the component |
| | 23: Stopping the sub-system after having loaded the already existing consistency-secured SDBs xxxx by the rack component |
| | 25: The SIMATIC procedure has been selected for the time synchronisation of the component. |
| | 26: Component actively established a connection |
| | 28: The SDB xxxx loaded by the rack component is the consistency securing object (SDB type 0x3118) |

| Event ID | Description |
|----------|--|
| | 29: The component actively disconnected the system connection to the CPU |
| | 31: Inconsistency of the component data base by loading SDB xxxx by the rack component (SDB type 0x3100) |
| | 32: Periphery enabled by S7-CPU |
| | 33: Periphery disabled by S7-CPU |
| | 34: Component STOP due to switch actuation |
| | 35: Component STOP due to invalid configuration |
| | 36: Component STOP due to PG command |
| | 38: SDB xxxx is not registered in the still valid consistency securing object, or it has an incorrect time stamp (SDB type 0x3107), the error is being corrected |
| | 40: Memory reset executed |
| | 44: Consistency of the data base achieved after loading the SDBs xxxx by the rack component (SDB type xxxx) |
| | 45: Remanent part of the component data base is deleted by the rack component after being loaded |
| | 70: Restore factory defaults (same as memory reset of CPU!) |
| | 83: Network interface: automatic configuration, TP/ITP with 10 Mbit/s semi-duplex |
| | 96: The MAC address was retrieved from the system SDB. This is the configured address. |
| | 97: The MAC address was retrieved from the boot EPROM. This is the factory-provided address. |
| | 100: Restart of the component |
| | 101: Component STOP due to deletion of system SDBs |
| | 104: PG command start was denied due to missing or inconsistent configuration |
| | 105: Component STOP due to double IP address |
| | 107: Start-up request by switch actuation was denied due to missing or inconsistent configuration |
| | PK: NCM_SERVICE |
| | 2: Management |
| | 3: Object management system |
| | 6: Time synchronisation |
| | 10: IP_CONFIG |
| | 38: SEND/RECEIVE |

B Integrated blocks



More information about this may be found in the manual "SPEED7 Operation List" from Yaskawa.

| OB | Name | Description |
|--------|-----------------------|---------------------------|
| OB 1 | CYCL_EXC | Program Cycle |
| OB 10 | TOD_INT0 | Time-of-day Interrupt |
| OB 20 | DEL_INT0 | Time delay interrupt |
| OB 21 | DEL_INT1 | Time delay interrupt |
| OB 28 | CYC_INT_250us | Cyclic interrupt |
| OB 29 | CYC_INT_500us | Cyclic interrupt |
| OB 32 | CYC_INT2 | Cyclic interrupt |
| OB 33 | CYC_INT3 | Cyclic interrupt |
| OB 34 | CYC_INT4 | Cyclic interrupt |
| OB 35 | CYC_INT5 | Cyclic interrupt |
| OB 40 | HW_INT0 | Hardware interrupt |
| OB 55 | DP: STATUS ALARM | Status interrupt |
| OB 56 | DP: UPDATE ALARM | Update interrupt |
| OB 57 | DP: MANUFACTURE ALARM | Vendor specific interrupt |
| OB 80 | CYCL_FLT | Time error |
| OB 81 | PS_FLT | Power supply error |
| OB 82 | I/O_FLT1 | Diagnostics interrupt |
| OB 83 | I/O_FLT2 | Insert / remove module |
| OB 85 | OBNL_FLT | Priority class error |
| OB 86 | RACK_FLT | Slave failure / restart |
| OB 100 | COMPLETE RESTART | Start-up |
| OB 121 | PROG_ERR | Programming error |
| OB 122 | MOD_ERR | Periphery access error |

| SFB | Name | Description |
|-------|------|-----------------|
| SFB 0 | CTU | Up-counter |
| SFB 1 | CTD | Down-counter |
| SFB 2 | CTUD | Up-down counter |
| SFB 3 | TP | Create pulse |
| SFB 4 | TON | On-delay |

| SFB | Name | Description |
|---------|----------|--|
| SFB 5 | TOF | Create turn-off delay |
| SFB 7 | TIMEMESS | Time measurement |
| SFB 12 | BSEND | Sending data in blocks |
| SFB 13 | BRCV | Receiving data in blocks: |
| SFB 14 | GET | Remote CPU read |
| SFB 15 | PUT | Remote CPU write |
| SFB 31 | NOTIFY8P | Messages without acknowledge display (8x) |
| SFB 32 | DRUM | Realize a step-by-step switch |
| SFB 33 | ALARM | Messages with acknowledgement display |
| SFB 34 | ALARM_8 | Messages without associated values (8x) |
| SFB 35 | ALARM_8P | Messages with associated values (8x) |
| SFB 36 | NOTIFY8 | Messages without acknowledgement display |
| SFB 52 | RDREC | Read record set |
| SFB 53 | WRREC | Write record set |
| SFB 54 | RALRM | Receiving an interrupt from a periphery module |
| SFB 238 | EC_RWOD | Function is used internally |
| SFB 239 | FUNC | Function is used internally |
| SFB 240 | DPRAM | Function is used internally |

| SFC | Name | Description |
|--------|----------|--|
| SFC 0 | SET_CLK | Set system clock |
| SFC 1 | READ_CLK | Read system clock |
| SFC 2 | SET_RTM | Set run-time meter |
| SFC 3 | CTRL_RTM | Control run-time meter |
| SFC 4 | READ_RTM | Read run-time meter |
| SFC 5 | GADR_LGC | Logical address of a channel |
| SFC 6 | RD_SINFO | Read start information |
| SFC 7 | DP_PRAL | Triggering a hardware interrupt on the DP master |
| SFC 12 | D_ACT_DP | Activating and deactivating of DP slaves |
| SFC 13 | DPNRM_DG | Read diagnostic data of a DP salve |
| SFC 14 | DPRD_DAT | Read consistent data |
| SFC 15 | DPWR_DAT | Write consistent data |
| SFC 17 | ALARM_SQ | ALARM_SQ |
| SFC 18 | ALARM_SQ | ALARM_S |
| SFC 19 | ALARM_SC | Acknowledgement state last alarm |
| SFC 20 | BLKMOV | Block move |
| SFC 21 | FILL | Fill a field |

| SFC | Name | Description |
|--------|----------|---|
| SFC 22 | CREAT_DB | Create a data block |
| SFC 23 | DEL_DB | Deleting a data block |
| SFC 24 | TEST_DB | Test data block |
| SFC 25 | COMPRESS | Compressing the User Memory |
| SFC 28 | SET_TINT | Set time-of-day interrupt |
| SFC 29 | CAN_TINT | Cancel time-of-day interrupt |
| SFC 30 | ACT_TINT | Activate time-of-day interrupt |
| SFC 31 | QRY_TINT | Query time-of-day interrupt |
| SFC 32 | SRT_DINT | Start time-delay interrupt |
| SFC 33 | CAN_DINT | Cancel time-delay interrupt |
| SFC 34 | QRY_DINT | Query time-delay interrupt |
| SFC 36 | MSK_FLT | Mask synchronous errors |
| SFC 37 | MSK_FLT | Unmask synchronous errors |
| SFC 38 | READ_ERR | Read error register |
| SFC 39 | DIS_IRT | Disabling interrupts |
| SFC 40 | EN_IRT | Enabling interrupts |
| SFC 41 | DIS_AIRT | Delaying interrupts |
| SFC 42 | EN_AIRT | Enabling delayed interrupts |
| SFC 43 | RE_TRIGR | Re-trigger the watchdog |
| SFC 44 | REPL_VAL | Replace value to ACCU1 |
| SFC 46 | STP | STOP the CPU |
| SFC 47 | WAIT | Delay the application program |
| SFC 49 | LGC_GADR | Read the slot address |
| SFC 51 | RDSYSST | Read system status list SSL |
| SFC 52 | WR_USMSG | Write user entry into diagnostic buffer |
| SFC 53 | μS_TICK | Time measurement |
| SFC 54 | RD_DPARM | Reading predefined parameters |
| SFC 55 | WR_PARM | Write dynamic parameter |
| SFC 56 | WR_DPARM | Write default parameter |
| SFC 57 | PARM_MOD | Parametrize module |
| SFC 58 | WR_REC | Write record set |
| SFC 59 | RD_REC | Read record set |
| SFC 64 | TIME_TCK | Read system time tick |
| SFC 65 | X_SEND | Sending data |
| SFC 66 | X_RCV | Receiving data |
| SFC 67 | X_GET | Read data |

| SFC | Name | Description |
|---------|----------|---|
| SFC 68 | X_PUT | Write data |
| SFC 69 | X_ABORT | Disconnect |
| SFC 70 | GEO_LOG | Determining the start address of a module |
| SFC 71 | LOG_GEO | Determining the slot belonging to a logical address |
| SFC 75 | SET_ADDR | Set PROFIBUS MAC address |
| SFC 81 | UBLKMOV | Copy data area without gaps |
| SFC 101 | HTL_RTM | Handling runtime meters |
| SFC 102 | RD_DPARA | Reading predefined parameters |
| SFC 105 | READ_SI | Reading dynamic system resources |
| SFC 106 | DEL_SI | Releasing dynamic system resources |
| SFC 107 | ALARM_DQ | ALARM_DQ |
| SFC 108 | ALARM_DQ | ALARM_DQ |
| SFC 193 | AI_OSZI | Oscilloscope-/FIFO function |
| SFC 194 | DP_EXCH | Data exchange with CP 342S |
| SFC 195 | FILE_ATT | Change file attributes |
| SFC 208 | FILE_OPN | Open file |
| SFC 209 | FILE_CRE | Create file |
| SFC 210 | FILE_CLO | Close file |
| SFC 211 | FILE_RD | Read file |
| SFC 212 | FILE_WR | Write file |
| SFC 213 | FILE_SEK | Position pointer |
| SFC 214 | FILE_REN | Rename file |
| SFC 215 | FILE_DEL | Delete file |
| SFC 216 | SER_CFG | Parametrization PtP |
| SFC 217 | SER_SND | Send to PtP |
| SFC 218 | SER_RCV | Receive from PtP |
| SFC 219 | CAN_TLGR | CANopen communication |
| SFC 227 | TD_PRM | Parameterization of a text display |
| SFC 253 | IBS_ACC | IBS communication |
| SFC 254 | RW_SBUS | IBS communication |

C SSL partial list



More information about this may be found in the manual "SPEED7 Operation List" from Yaskawa.

| SSL-ID | SSL partial list |
|--------|---|
| xy11h | Module identification |
| xy12h | CPU characteristics |
| xy13h | User memory areas |
| xy14h | System areas |
| xy15h | Block Types |
| xy19h | Status of all LEDs |
| xy1Ch | Identification of the component |
| xy22h | Interrupt status |
| xy32h | Communication status data |
| xy37h | Ethernet details of the module |
| xy74h | Status of the LEDs |
| xy91h | Status information CPU |
| xy92h | Stations status information (DPM) |
| xy94h | Stations status information (DPM, PROFINET-IO and EtherCAT) |
| xy96h | Module status information (PROFIBUS DP, PROFINET-IO, EtherCAT) |
| xyA0h | Diagnostic buffer of the CPU |
| xyB1h | Module diagnostic information (record set 0) |
| xyB2h | Module diagnostic information (record set 1) via physical address |
| xyB3h | Module diagnostic information (record set 1) via logical address |
| xyB4h | Diagnostic data of a DP slave |
| xyE0h | Information EtherCAT master/slave |
| xyE1h | EtherCAT bus system |